

# **Quad Ultrahigh-Speed Pin Driver** with High-Z and V<sub>TERM</sub> Modes

AD53513

#### **FEATURES**

500 MHz Driver Operation (1 Gb/s)
Driver Inhibit Function
100 ps Edge Matching
Guaranteed Industry Specifications
20 Ω Output Impedance
5 V/ns Slew Rate

Variable Output Voltages for ECL, TTL, and CMOS High-Speed Differential Inputs for Maximum Flexibility Ultrasmall 100-Lead LQFP Package with Built-In Heat Sink

#### **APPLICATIONS**

Automatic Test Equipment
Semiconductor Test Systems
Board Test Systems
Instrumentation and Characterization Equipment

#### PRODUCT DESCRIPTION

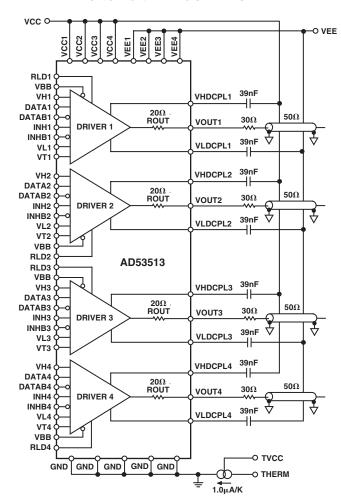
The AD53513 is a quad high-speed pin driver designed for use in digital or mixed-signal test systems. Combining a high-speed monolithic process with a convenient surface-mount package, this product attains superb electrical performance while preserving optimum packaging densities and long-term reliability in a 100-lead, LQFP package with built-in heat sink.

Featuring unity gain programmable output levels of  $-2.5\,\mathrm{V}$  to  $+5.5\,\mathrm{V}$ , with output swing capability of less than 200 mV to 8 V, the AD53513 is designed to stimulate ECL, TTL, and CMOS logic families, as well as high-speed memory. The  $1.0\,\mathrm{Gb/s}$  data rate capacity and matched output impedance allow for real-time stimulation of these digital logic families. To test I/O devices, the pin driver can be switched into a high impedance state (Inhibit Mode), electrically removing the driver from the path. The pin driver leakage current in inhibit is typically  $100\,\mathrm{nA}$  and output charge transfer entering inhibit is typically less than  $20\,\mathrm{pC}$ .

The AD53513 transition from HI/LO or to inhibit is controlled through the data and inhibit inputs. The input circuitry uses high-speed differential inputs with a common-mode range of  $\pm 2$  V. This allows for direct interface to precision differential ECL timing. The analog logic HI/LO inputs are equally easy to interface. Typically requiring 10  $\mu A$  of bias current, the AD53513 can be directly coupled to the output of a digital-to-analog converter.

Each channel of the AD53513 has a Mode Select Pin RLD, which is a single-sided logic input. The logic threshold is set by

#### FUNCTIONAL BLOCK DIAGRAM



the VBB input which is common to all four channels. The RLD Mode Select controls whether inhibit puts the driver in High-Z or  $V_{TERM}$  mode. (Refer to Table I.) All of the digital logic inputs (DATA, DATAB, INH, INHB, RLD, VBB), must share a common set of logic levels. The VBB threshold should be set to the midrange of the logic levels. For example, if ECL levels of -0.8~V to -1.8~V are used, VBB should be set to -1.3~V.

The AD53513 is available in a 100-lead, LQFP package with a built-in heat sink and is specified to operate over the ambient commercial temperature range of -25°C to +85°C.

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Parameter	Min	Typ*	Max	Unit	Test Conditions
DIFFERENTIAL INPUT CHARACTERISTICS					
(Data to $\overline{DATA}$ , INH to $\overline{INH}$ ), RLD, VBB					$V_{RR} = -1.3 \text{ V}$
Input Voltage	-2		0	Volts	
Differential Input Range		ECL			
Bias Current	-1	202	+1	mA	$V_{IN} = -2 \text{ V}, 0.0 \text{ V}$
VBB Threshold Input	1	Midrange		V	Set to Midrange of Logic Levels
					Set to Marange of Bogie Bevol
REFERENCE INPUTS $(V_L, V_H, V_T)$			. = 0		V V 0V
Bias Currents	-50		+50	μΑ	$V_L$ , $V_H = 2 V$
OUTPUT CHARACTERISTICS					
Logic High Range	-2.3		+5.5	Volts	DATA = H
Logic Low Range	-2.5		+5.3	Volts	DATA = L
Amplitude (V <sub>H</sub> –V <sub>L</sub> )	0.2		8.0	Volts	
Absolute Accuracy					
V <sub>H</sub> Offset	-100		+100	mV	DATA = H, $V_H = 0 \text{ V}$ , $V_L = -2 \text{ V}$ , $V_T = +3 \text{ V}$
V <sub>H</sub> Gain and Linearity Error	100	±0.3 ±5	. 200	$\%$ of $V_H + mV$	DATA = H, $V_H = -2 \text{ V to } +5 \text{ V}$ , $V_L = -2.5 \text{ V}$ ,
VH Gain and Emeanty Error		±0.5 ±5		70 OI VH 1 III V	$V_{\rm T} = +3 \text{ V}$
$V_L$ Offset	-100		+100	mV	DATA = L, $V_L = 0 \text{ V}$ , $V_H = +5 \text{ V}$ , $V_T = +4.5 \text{ V}$
V <sub>L</sub> Gain and Linearity Error	-100	±0.3 ±5	1100	$\%$ of $V_L + mV$	DATA = L, $V_L = -2 \text{ V to } +5 \text{ V}$ , $V_H = +5.5 \text{ V}$ ,
VL Gain and Emeanty Enoi		±0.5 ±5		70 OI VL 1 III V	$V_{\rm T} = +4.5  \text{V}$
$V_T$ Offset	-100		+100	mV	$V_{\rm T} = +4.5 \text{ V}$ Term Mode, $V_{\rm T} = 0 \text{ V}$ , $V_{\rm L} = -1 \text{ V}$ , $V_{\rm H} = +3 \text{ V}$
•	-100	10215	<b>T100</b>		, , , , , , , , , , , , , , , , , , , ,
V <sub>T</sub> Gain and Linearity Error		$\pm 0.3 \pm 5$		$\%$ of $V_T$ + m $V$	Term Mode, $V_T = -2.0 \text{ V}$ to $+5.0 \text{ V}$ , $V_L = 0$ ,
om mo v				****	$V_H = +3 \text{ V}$
Offset TC, $V_H$ , or $V_L$ , or $V_{TERM}$		$\pm 0.5$		mV/°C	$V_L$ , $V_H = 0 V$
Output Resistance		20		Ω	DATA = H, $V_H$ = 3 V, $V_L$ = 0 V, $I_{OUT}$ = 45 mA
Output Leakage	-1.0		+1.0	μΑ	$V_{OUT} = -2 V \text{ to } +5 V$
Dynamic Current Limit		130		mA	$C_{BYP} = 39 \text{ nF}, V_H = +5 \text{ V}, V_L = -2 \text{ V}$
Static Current Limit		±85		mA	Output to $-2.5 \text{ V}$ , $V_H = +5.5 \text{ V}$ , $V_L = -2.5 \text{ V}$ ,
					$V_T = 0$ ; DATA = H and Output to 5.5 V,
					$V_H = +5.5 \text{ V}, V_L = -2.5 \text{ V}, V_T = 0$
					$V_L = -3 \text{ V}, \text{ DATA} = L$
PSRR, Drive Mode		35		dB	$V_S = V_S \pm 3\%$
DYNAMIC PERFORMANCE, DRIVE					
$(V_{ m H}$ and $V_{ m L})$					
Propagation Delay Time	0.3		1.1	ns	Measured at 50%, $V_H = 800 \text{ mV}$ , $50 \Omega$ Load,
. P. God and a stary					$V_{L} = -800 \text{ mV}$
Propagation Delay TC		±0.5		ps/°C	Measured at 50%, $V_H = 800 \text{ mV}$ , 50 $\Omega$ Load,
Tropugation Dully 10		_0.5		ps/ c	$V_{\rm L} = -800 \mathrm{mV}$
Delay Matching, Edge to Edge		100		ps	Measured at 50%, $V_H = 800 \text{ mV}$ , $50 \Omega$ Load,
Delay Matching, Eage to Eage		100		Po	$V_{\rm L} = -800 \text{ mV}$
Rise and Fall Time					VL = 000 mV
1 V Swing		300		20	Measured 20%–80%, $V_L = 0 \text{ V}$ , $V_H = 1 \text{ V}$ , $V_T = -2 \text{ V}$
2 V Swing		450		ps	Measured 10%–90%, $V_L = 0 \text{ V}$ , $V_H = 1 \text{ V}$ , $V_T = -2 \text{ V}$ Measured 10%–90%, $V_L = 0 \text{ V}$ , $V_H = 2 \text{ V}$ , $V_T = -2 \text{ V}$
2 V Swing 3 V Swing	1	450 650		ps	Measured 10%–90%, $V_L = 0 \text{ V}$ , $V_H = 2 \text{ V}$ , $V_T = -2 \text{ V}$ Measured 10%–90%, $V_L = 0 \text{ V}$ , $V_H = 3 \text{ V}$ , $V_T = -2 \text{ V}$
Rise and Fall Time TC		050		ps	$v_{\rm H} = 0.000$ , $v_{\rm L} = 0.00$ , $v_{\rm H} = 0.00$ , $v_{\rm H} = 0.00$
		±1		/°C	Manual 200/ 000/ V = 0 V V = 1 V V
1 V Swing	1	±1		ps/°C	Measured 20%–80%, $V_L = 0 \text{ V}$ , $V_H = 1 \text{ V}$ , $V_T = -2 \text{ V}$
2 V Swing		±1		ps/°C	Measured 10%–90%, $V_L = 0 \text{ V}$ , $V_H = 2 \text{ V}$ , $V_T = -2 \text{ V}$
3 V Swing		±1		ps/°C	Measured 10%–90%, $V_L = 0 \text{ V}$ , $V_H = 3 \text{ V}$ , $V_T = -2 \text{ V}$
Overshoot, Undershoot, and Preshoot		$\pm (6\% + 50)$	0 mV)	% of Step + mV	a. $V_L$ , $V_H = 0 V$ , +1 V, $V_T = -2 V$ , 50 $\Omega$
					b. $V_L$ , $V_H = 0 V$ , +3 V, $V_T = -2 V$ , 50 $\Omega$
					c. $V_L$ , $V_H = 0 V$ , +5 V, $V_T = -2 V$ , 50 $\Omega$
Settling Time					
to 15 mV	1	50		ns	$V_L = 0 \text{ V}, V_H = +0.5 \text{ V}, V_T = -2 \text{ V}$
to 4 mV	1	10		μs	$V_L = 0 \text{ V}, V_H = +0.5 \text{ V}, V_T = -2 \text{ V}$
Delay Change vs. Pulsewidth		10		ps	$V_L = 0 V, V_H = +2 V, V_T = -2 V,$
	1				Pulsewidth/Period = 1.0 ns/4.0 ns, 30 ns/120 ns
Minimum Pulsewidth					
2 V Swing	1	700		ps	700 ps Input, $10\%/90\%$ Output, $V_T = -2 V$ ,
-	1				$V_L = 0 \text{ V}, V_H = +2 \text{ V}, 50 \Omega \text{ Terminated}$
Toggle Rate	1	3.2		GHz	$V_L = -1.8 \text{ V}, V_H = -0.8 \text{ V}, V_T = -2 \text{ V},$
				i .	$V_{OUT} > 300 \text{ mV p-p at } 50 \Omega \text{ Terminated}$

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Parameter	Min	Typ*	Max	Unit	Test Conditions
DYNAMIC PERFORMANCE, INHIBIT					
Delay Time, Active to Inhibit	1.5		2.5	ns	Measured at 50%, $V_H = +2 \text{ V}$ , $V_L = -2 \text{ V}$ , $V_T = -2 \text{ V}$
Delay Time, Inhibit to Active	0.7		1.7	ns	Measured at 50%, $V_H = +2 \text{ V}$ , $V_L = -2 \text{ V}$ , $V_T = -2 \text{ V}$
I/O Spike		<200		mV p-p	$V_{\rm H} = 0 \text{ V}, V_{\rm L} = 0 \text{ V}, V_{\rm T} = -2 \text{ V}$
Output Capacitance		6		pF	Driver Inhibited
DYNAMIC PERFORMANCE, V <sub>TERM</sub>					
Delay Time, Active to V <sub>TERM</sub>	0.50		1.30	ns	Measured at 50%, $V_H = +0.8 \text{ V}$ , $V_L = -0.8 \text{ V}$ , $V_T = 0 \text{ V}$
Delay Time, V <sub>TERM</sub> to Active	0.45		1.25	ns	50 Ω Terminated
Overshoot, Undershoot, and Preshoot					$V_{L} = -2 V, V_{H} = +2 V, V_{T} = 0 V$
$ m V_{TERM}$ to $ m V_L$ or $ m V_H$		±6%/±75		mV	$V_L = -0.8 \text{ V}, V_H = +0.8 \text{ V}, V_T = 0 \text{ V}$
					Output Terminated 50 Ω
POWER SUPPLIES					
Total Supply Range		15		V	
Positive Supply		9		V	
Negative Supply		-6		V	
Positive Supply Current			570	mA	
Negative Supply Current			570	mA	
Total Power Dissipation			8.6	W	
Temperature Sensor Gain Factor		1.0		μA/K	$R_{LOAD} = 4.2 \text{ k}\Omega, V_{SOURCE} = 9 \text{ V}$

#### NOTES

Connecting or shorting the decoupling capacitors to ground will result in the destruction of the device.

Specifications subject to change without notice.

### ABSOLUTE MAXIMUM RATINGS1

Power Supply Voltage
$+V_S$ to GND
$-V_S$ to GND
$+V_S$ to $-V_S$
Inputs
DATA, $\overline{DATA}$ , INH, $\overline{INH}$ , RLD, VBB +5 V, -3 V
DATA to $\overline{DATA}$ , INH to $\overline{INH}$ , RLD, VBB $\pm 3$ V
$V_H$ , $V_L$ , $V_T$ to GND
$V_H$ to $V_L  (V_H - V_T)$ and $(V_T - V_L)  \ldots  \pm 9 \; V$
Outputs
V <sub>OUT</sub> Short Circuit Duration Indefinite <sup>2</sup>
V <sub>OUT</sub> Range in Inhibit Mode
$V_{\text{HDCPL}}$ Do Not Connect Except for Capacitor to $V_{\text{CC}}$
$V_{LDCPL}$ Do Not Connect Except for Capacitor to $V_{EE}$
THERM 11 V, 0 V

#### Environmental

Operating Temperature (Junction)	175°C
Storage Temperature65°C to +1	150°C
Lead Temperature (Soldering, 10 sec) <sup>3</sup>	260°C

#### NOTES

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Absolute maximum limits apply individually, not in combination. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

<sup>2</sup>Output short circuit protection is guaranteed as long as proper heat sinking is employed to ensure compliance with the operating temperature limits.

#### ORDERING GUIDE

Model	Package Description	Shipment Method, Quantity Per Shipping Container	Package Option
AD53513JSQ	100-Lead LQFP-CDQUAD	Tray, 90 Pieces	SQ-100

#### CAUTION\_

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD53513 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high-energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

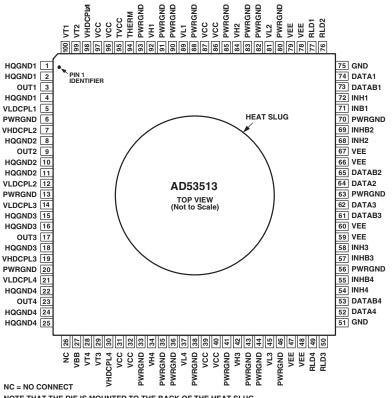


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<sup>\*</sup>Typical parameters are not production tested but guaranteed through characterization.

 $<sup>^3</sup>$ To ensure lead coplanarity ( $\pm 0.002$  inches) and solderability, handling with bare hands should be avoided and the device should be stored in environments at 24°C  $\pm 5$ °C (75°F  $\pm 10$ °F) with relative humidity not to exceed 65%.

#### PIN CONFIGURATION



NOTE THAT THE DIE IS MOUNTED TO THE BACK OF THE HEAT SLUG. THE PACKAGE IS MOUNTED TO THE BOARD HEAT SLUG UP.

Table I. Driver Truth Table

DATA	DATA	INH	ĪNĦ	RLD	VBB	Output State
0	1	0	1	X	VBB	$V_{\rm L}$
1	0	0	1	X	VBB	$V_{H}$
X	X	1	0	0	VBB	INH
X	X	1	0	1	VBB	$V_{TERM}$

### **OUTLINE DIMENSIONS**

Dimensions shown in inches and (mm).

## 100-Lead LQFP\_ED Package (SQ-100)

