

## **Current Mode PWM Controller**

# B3842/43/44/45A&A1

### **Description**

The Bay Linear B3842/43/44/45 are fixed frequency current-mode PWM controller. These devices are designed for Off-Line and DC-to-DC converter applications with minimum external components. The B3842 family Feature a trimmed oscillator for precise duty cycle control, a temperature compensated reference, high gain error amplifier, current sensing comparator, and a high current totempole output. Ideally suited for driving a power N-Channel MOSFET's. It is low when is on off stage. Protection circuitry includes built in under-voltage lockout and current limiting.

Major differences between members of these series are the UVLO thresholds and maximum duty-cycle ranges. Typical UVLO thresholds of 16V (on) and 10V (off) on the B3842 and B3844 devices make them ideally suited to off-line applications. These corresponding typical thresholds for the B3842 and B3845 devices are 8.4V (on) and 7.6V (off). The B3842 and B3843 devices can operate to duty cycles approaching 100%. A duty-Cycle range of 0 to 50% is obtained by the B3844 and B3845 by the addition of an internal toggle flip-flop, which blanks the output off every other clock cycle. It id available in 8 pin DIP and SOIC packages.

### **Features**

- Low Start-Up and Operating Current
- Maximum Duty Cycle
- Operating Frequency Up to 500KHz
- Under voltage Lockout with Hysteresis
- Available in 8 pin SOIC
- Similar to industry Standard UC3842

# **Applications**

- Switching Power Supply
- Monitor

#### **Pin Connection**





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### **Ordering Information**

Devices	Package	Temp.
B384X(Z)M	SO-8	0 °C to 70 °C
B384X(Z)P	8-DIP	0 °C to 70 °C

Z=A ON Semi Z=A1 Fairchild & Samsung

# **Absolute Maximum Rating**

Parameter	Symbol	Value	Unit
Supply Voltage	$V_{CC}$	30	V
Output Current	$I_{O}$	±1	A
Analog Input (pin 2,3)	$V_{(ANA)}$	-0.3 to 6.3	V
Error Amp Output Sink Current	I <sub>SINK (E.A)</sub>	10	mA
Power Dissipation	$P_{\mathrm{D}}$	1	W
Storage Temperature Range	T	-65 to 150	°C
Lead Temperature (Soldering 10 Sec.)	$T_{\rm L}$	260	°C

# **Electrical Characteristics**

 $(V_{CC} = 15V; R_T = 10\Omega, C_T = 3.3nF, T_A = 0 \degree C \text{ to } +70\degree C, \text{ unless otherwise specified})$ 

Parameter	Symbol	Conditions	MIN	TYP	MAX	UNIT
REFERENCE SECTIO	N					
Reference Voltage	$V_{REF}$	$T_J = 25$ °C. $I_{REF} = 1$ mA	4.90	5.00	5.10	V
Line Regulation	REG (line)	12V≤V <sub>CC</sub> ≤25V	-	6	20	mA
Load Regulation	REG (LOAD)	$1 \text{mA} \le I_{\text{REF}} \le 20 \text{mA}$ $T = 25 \text{ °C}$	-	6	25	
Short Circuit Output Current	$I_{SC}$	T= 25 °C	-	-100	-180	mA
OSCILLATOR SECTION	N					
Oscillator Frequency	f	T= 25 °C	47	52	57	KHz
Frequency Change with Voltage	$\Delta f/\Delta V_{CC}$	12V≤V <sub>CC</sub> ≤25V	-	0.05	1	%
Oscillator Amplitude	$V_{OSC}$		-	1.6	-	$V_{P-P}$
ERROR AMPLIFIER SE	CTION					
Input Bias Current	$I_{BIAS}$		-	-0.1	-2	μΑ
Input Voltage	$V_{I(E>A)}$	$V_1 = 2.5V$	2.42	2.50	2.58	V
Open Loop Voltage Gain	$G_{VO}$	2V≤V <sub>O</sub> ≤4V	65	90	-	dB
Power Supply Rejection Ratio	PSRR	12V≤V <sub>CC</sub> ≤25V	60	70	-	dB
Output Sink Current	$I_{SINK}$	$V_2 = 2.7V, V_1 = 1.1V$	2	7	-	mA
Output Source Current	I <sub>SOURCE</sub>	$V_2=2.3, V_1=5V$	-0.6	-1.0	-	mA
High Output Voltage	$V_{OH}$	$V_2 = 2.3$ , $R_L = 15\Omega$ to GND	5	6	-	V
Low Output Voltage	$V_{OL}$	$V_2 = 2.7$ , $R_L = 15\Omega$ to pin 8	-	0.8	1.1	V
OUTPUT SECTION						
Low Output Voltage	$V_{OL}$	$I_{SINK} = 20 \text{mA}$ $I_{SINK} = 200 \text{mA}$	-	0.08 1.4	0.4 2.2	V
High Output Voltage	$V_{\mathrm{OH}}$	$S_{\text{ource}} = 20\text{mA}$ $S_{\text{ource}} = 200\text{mA}$	13 12	13.5 13.0	-	V
Rise Time	$t_{R}$	$T_J = 25 ^{\circ}\text{C},  C_L = 1 \text{nF (note3)}$	-	45	150	ns
Fall Time	$t_{\mathrm{F}}$	$T_J = 25 ^{\circ}\text{C}, C_L = 1 \text{nF (note3)}$	-	35	150	ns

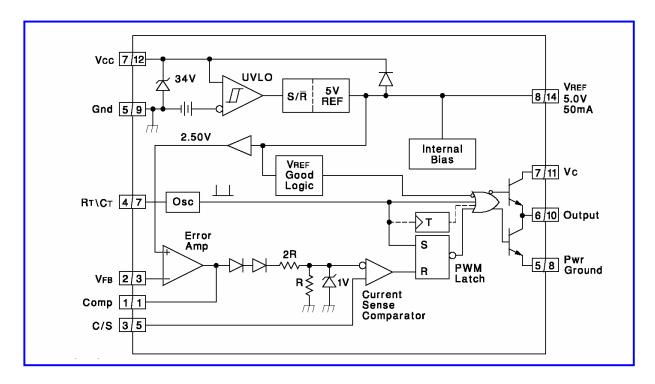
Note: Output Switch tests are performed under pulsed conditions to minimize power dissipation

### **Electrical Characteristics**

 $(V_{CC} = 15V; R_T = 10\Omega, C_T = 3.3nF, T_A = 0 \degree C \text{ to } +70\degree C, \text{ unless otherwise specified})$ 

Parameter	Symbol	Conditions	MIN	TYP	MAX	UNIT
CURRENT SENSE SECT	ION					
Gain	$G_{V}$	(Note 1 & 2)	2.85	3	3.15	V/V
Maximum input Signal	$V_{I(MAX)}$	$V_1 = 5V \text{ (Note 1)}$	0.9	1	1.1	V
Power Supply Rejection Ratio	PSRR	12V≤V <sub>CC</sub> ≤25V		70	-	dB
Input Bias Current	$I_{BIAS}$			-3	-10	μΑ
UNDER-VOLTAGE LOC	KOUT SEC	TION				
Start Threshold	V	B3842/B3844	14.5	16	17.5	V
Start Tilleshold	$V_{TH(ST)}$	B3843/B3845	7.8	8.4	9	
Min-Operating Voltage	M	B3842/B3844	8.5	10	11.5	V
(after Turn On)	V <sub>OPR(MIN)</sub>	B3843/B3845	7.0	7.6	8.2	v
PWM SECTION						
Max Duty Cycle	D(MAX)	B3842/B3843	95	97	100	%
		B3844/B3845	47	48	50	
Min Duty Cycle	D (MIN)		-	-	0	%
TOTAL STANDBY CURI	RENT					
Start-Up Current	$I_{ST}$	B3842A/43A/44A/45A	-	0.17	0.3	mA
		B3842A1/43A1/44A1/45A1		0.45	1	
Operating Supply Current	I <sub>CC(OPR)</sub>	$V_3=V_2=ON$	-	14	17	mA
Zener Voltage	$V_Z$	$I_{CC}$	30	38	-	V

# **Block Diagram**



**Figure 1: Error Amp Configuration** 

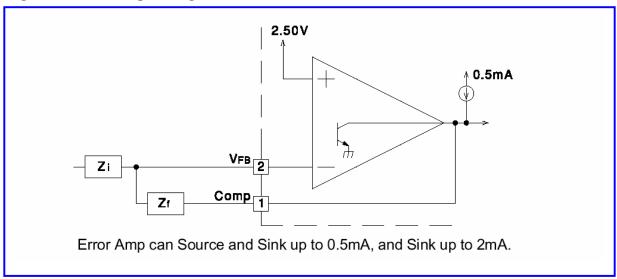


Figure 2: Under-Voltage Lockout

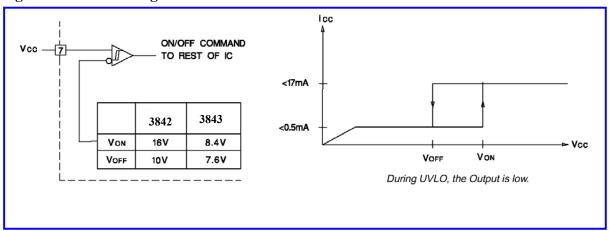
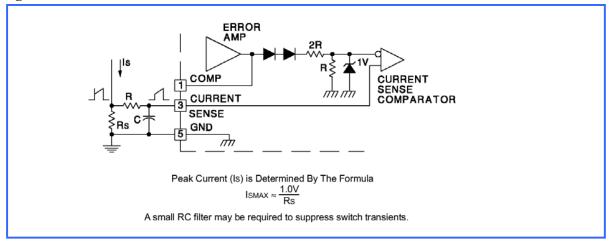
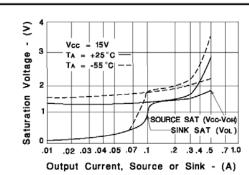


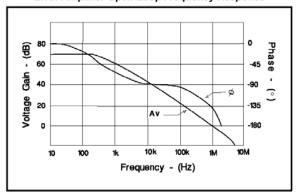
Figure 3: Current Sense Circuit



### **Output Saturation Characteristics**

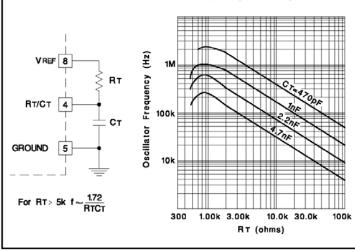


### Error Amplifier Open-Loop Frequency Response

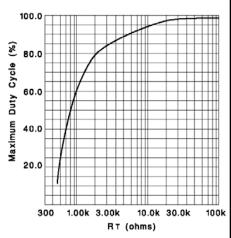


### **Oscillator Section**

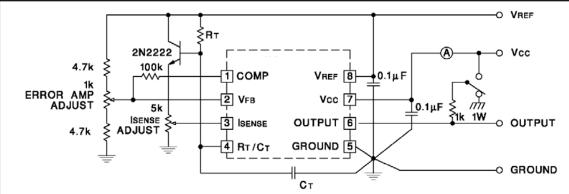
### Oscillator Frequency vs Timing Resistance



### Maximum Duty Cycle vs Timing Resistor



### **Open-Loop Laboratory Test Fixture**



High peak currents associated with capacitive loads necessitate careful grounding techniques. Timing and bypass capacitors should be connected close to pin 5 in a single point

ground. The transistor and 5k potentiometer are used to sample the oscillator waveform and apply an adjustable ramp to  $\sin 3$ .



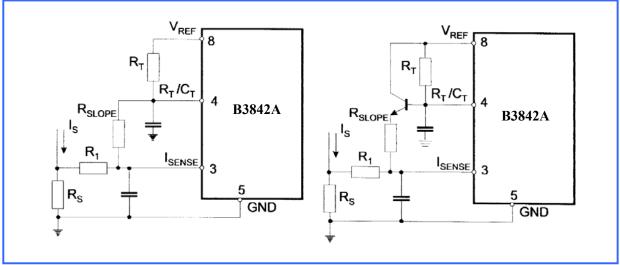
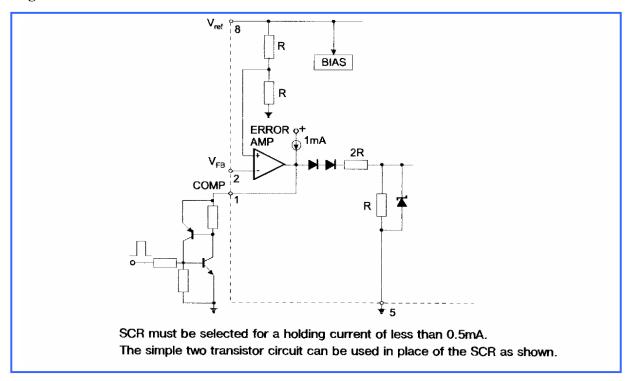
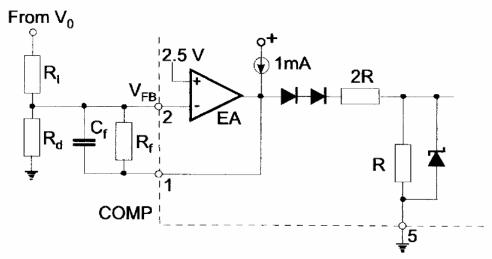
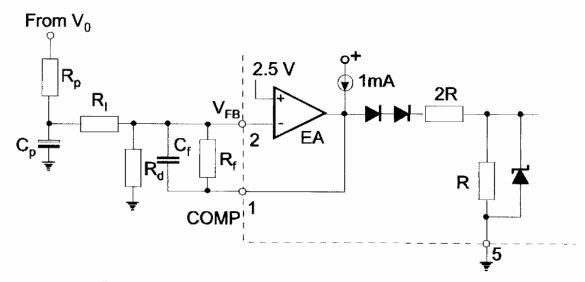


Figure 5:Latched Shutdown



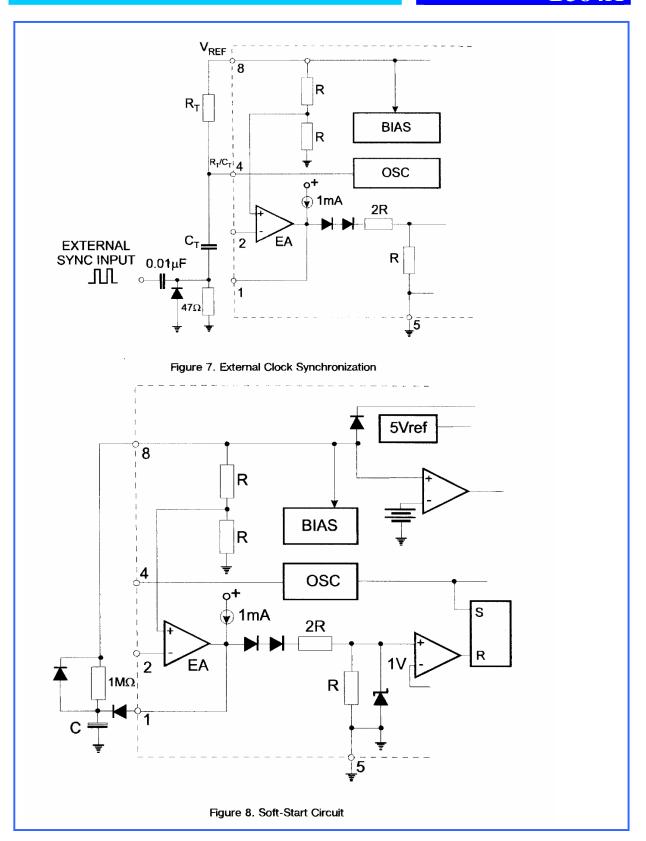


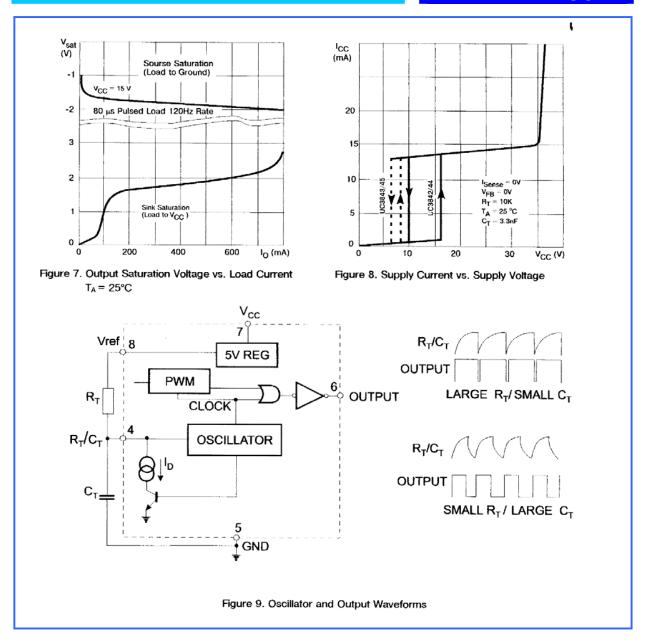
Error Amp compensation circuit for stabilizing any current-mode topology except for boost and flyback converters operating with continuous inductor current.



Error Amp compensation circuit for stabilizing current-mode boost and flyback topologies operating with continuous inductor current.

Figure 6. Error Amplifier Compensation





<b>Advance Information</b> - These data sheets contain descriptions of products that are in development. The specifications are based on the engineering calculations, computer simulations and/ or initial prototype evaluation.
<b>Preliminary Information</b> - These data sheets contain minimum and maximum specifications that are based on the initial device characterizations. These limits are subject to change upon the completion of the full characterization over the specified temperature and supply voltage ranges.
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