3D7502

′14□ VDD

13 N/C

12 N/C

11 N/C

10 N/C

9 N/C

DIP (.300)

8 DATB

MONOLITHIC MANCHESTER DECODER (SERIES 3D7502)



RX 🛛 1

N/C \square 2

CLK □4

GND 7

N/C

N/C

N/C

3D7502-xxx

□3

PACKAGES

8 VDD

70 N/C

6 N/C

Gull Wing (.300)

SOIC (.150)

5 DATB

RX \Box_1

CLK 2

GND 4

□3

3D7502M-xxx DIP (.300)

N/C

3D7502H-xxx 3D7502Z-xxx

- All-silicon, low-power CMOS technology
- TTL/CMOS compatible inputs and outputs
- Vapor phase, IR and wave solderable
- Auto-insertable (DIP pkg.)
- Low ground bounce noise
- Maximum data rate: 50 MBaud
- Data rate range: ±15%

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•	-		U	••		•			LC	~				

The 3D7502 product family consists of monolithic CMOS Manchester Decoders. The unit accepts at the RX input a bi-phase-level, embedded-clock signal. In this encoding mode, a logic one is represented by a high-to-low transition within the bit cell, while a logic zero is represented by a low-to-high transition. The recovered clock and data signals are presented on CLK and DATB, respectively, with

PIN DESCRIPTIONS

3D7502D-xxx SOIC (.150)

3D7502G-xxx Gull Wing (.300)

RX CLK	Signal Input Signal Output (Clock)
DATB	Signal Output (Data)
VCC	+5 Volts
GND	Ground

the data signal inverted. The operating baud rate (in MBaud) is specified by the dash number. The input baud rate may vary by as much as $\pm 15\%$ from the nominal device baud rate without compromising the integrity of the information received.

Because the 3D7502 is not PLL-based, it does not require a long preamble in order to lock onto the received signal. Rather, the device requires at most one bit cell before the data presented at the output is valid. This is extremely useful in cases where the information arrives in bursts and the input is otherwise turned off.

The all-CMOS 3D7502 integrated circuit has been designed as a reliable, economic alternative to hybrid TTL Manchester Decoders. It is TTL- and CMOS-compatible, capable of driving ten 74LS-type loads. It is offered in standard 8-pin and 14-pin auto-insertable DIPs and space saving surface mount 8-pin and 14-pin SOICs.

PART	BAUD RATE (MBaud)						
NUMBER	Nominal	Minimum	Maximum				
3D7502-5	5.00	4.25	5.75				
3D7502-10	10.00	8.50	11.50				
3D7502-20	20.00	17.00	23.00				
3D7502-25	25.00	21.25	28.75				
3D7502-30	30.00	25.50	34.50				
3D7502-40	40.00	34.00	46.00				
3D7502-50	50.00	42.50	57.50				

TABLE 1: PART NUMBER SPECIFICATIONS

NOTES: Any baud rate between 5 and 50 MBaud not shown is also available at no extra cost. ©1997 Data Delay Devices

APPLICATION NOTES

The 3D7502 Manchester Decoder samples the input at precise pre-selected intervals to retrieve the data and to recover the clock from the received data stream. Its architecture comprises finely tuned delay elements and proprietary circuitry which, in conjunction with other circuits, implement the data decoding and clock recovery function.

INPUT SIGNAL CHARACTERISTICS

Encoded data transmitted from a source arrives at its destination corrupted. Such corruption of the received data manifests itself as jitter and/or pulse width distortion at the input to the device. The instantaneous deviations from nominal Baud Rate and/or Pulse Width (high or low) adversely impact the data extraction and clock recovery function if their published limits are exceeded. **See Table 4, Allowed Baud Rate/Duty Cycle.**

The 3D7502 Manchester Decoder Data Input **is TTL compatible. The user should assure himself that** the 1.5 volt TTL threshold is used when referring to all timing, especially the input pulse widths.

FREQUENCY (JITTER) ERRORS

The 3D7502 Manchester Decoder, being a selftimed device, is tolerant of frequency modulation (jitter) present in the input data stream, provided that the input data pulse width variations remain within the allowable ranges.

OUTPUT SIGNAL CHARACTERISTICS

The 3D7502 presents at its outputs the decoded data (inverted) and the recovered clock. The decoded data is **valid at the rising edge of the clock.**

The clock recovery function operates in two modes dictated by the input data stream bit sequence. When a data bit is succeeded by its inverse, the clock recovery circuit is engaged and forces the clock output low for a time equal to **one over twice the baud rate**. Otherwise, the input is presented at the clock output unchanged, shifted in time.

When engaged, the clock recovery circuit generates a low-going pulse of fixed width. Therefore, the clock duty cycle is strongly dependent on the baud rate, as this will affect the clock-high duration.

The clock output falling edge is not operated on by the clock recovery circuitry. It, therefore, preserves more accurately the clock frequency information embedded in the transmitted data. Therefore, it can be used, if it is desired, to retrieve clock frequency information.

POWER SUPPLY AND TEMPERATURE CONSIDERATIONS

CMOS integrated circuitry is strongly dependent on power supply and temperature. The monolithic 3D7502 Manchester Decoder utilizes novel and innovative compensation circuitry to minimize timing variations induced by fluctuations in power supply and/or temperature.



Figure 1: Timing Diagram

DEVICE SPECIFICATIONS

PARAMETER	SYMBOL	MIN	MAX	UNITS	NOTES
DC Supply Voltage	V _{DD}	-0.3	7.0	V	
Input Pin Voltage	V _{IN}	-0.3	V _{DD} +0.3	V	
Input Pin Current	I _{IN}	-10	10	mA	25C
Storage Temperature	T _{STRG}	-55	150	С	
Lead Temperature	T _{LEAD}		300	С	10 sec

TABLE 2: ABSOLUTE MAXIMUM RATINGS

TABLE 3:	DC ELECTRICAL CHARACTERISTICS
	(0C to 70C, 4.75V to 5.25V)

PARAMETER	SYMBOL	MIN	MAX	UNITS	NOTES
Static Supply Current*	I _{DD}		40	mA	
High Level Input Voltage	V _{IH}	2.0		V	
Low Level Input Voltage	V _{IL}		0.8	V	
High Level Input Current	I _{IH}		1.0	μA	$V_{IH} = V_{DD}$
Low Level Input Current	I _{IL}		1.0	μΑ	$V_{IL} = 0V$
High Level Output Current	I _{он}	-4.0		mA	$V_{DD} = 4.75V$
					$V_{OH} = 2.4V$
Low Level Output Current	I _{OL}	4.0		mA	$V_{DD} = 4.75V$
					$V_{OL} = 0.4V$
Output Rise & Fall Time	T _R & T _F		2	ns	$C_{LD} = 5 \text{ pf}$

 $\label{eq:ldd} \begin{array}{l} {}^{*}I_{\text{DD}}(\text{Dynamic}) = 2 \; {}^{*}C_{\text{LD}} \; {}^{*}V_{\text{DD}} \; {}^{*}F \\ \text{where:} \quad C_{\text{LD}} = \text{Average capacitance load/pin (pf)} \\ F = \text{Input frequency (GHz)} \end{array}$

Input Capacitance = 10 pf typical Output Load Capacitance $(C_{LD}) = 25 \text{ pf max}$

TABLE 4: AC ELECTRICAL CHARACTERISTICS

(0C to 70C, 4.75V to 5.25V, except as noted)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Nominal Input Baud Rate	f _{BN}	5		50	MBaud	
Allowed Input Baud Rate Deviation	f _B	-0.15 f _{BN}		0.15 f _{BN}	MBaud	25C, 5.00V
Allowed Input Baud Rate Deviation	f _B	-0.05 f _{BN}		0.05 f _{BN}	MBaud	-40C to 85C
						4.75V to 5.25V
Allowed Input Baud Rate Deviation	fв	-0.03 f _{BN}		0.03 f _{BN}	MBaud	-55C to 125C
						4.75V to 5.25V
Allowed Input Duty Cycle		42.5	50.0	57.5	%	
Bit Cell Time	tc		1000/f _B		ns	
Input Data Edge to Clock Falling Edge	t _{CL}		0.75 tc		ns	
Clock Width Low	t _{CWL}		500/f _{BN}		ns	±2ns or 5%
Clock Falling Edge to Data Transition	t _{CD}	3.0	4.0	5.0	ns	

SILICON DELAY LINE AUTOMATED TESTING

TEST CONDITIONS

	OUTPUT:	
$25^{\circ}C \pm 3^{\circ}C$	R _{load} :	$10 \mathrm{K}\Omega \pm 10\%$
$5.0V \pm 0.1V$	C _{load} :	5pf ± 10%
High = $3.0V \pm 0.1V$	Threshold:	1.5V (Rising & Falling)
Low = $0.0V \pm 0.1V$		
50Ω Max.	\circ	ΛΛΛΛ
3.0 ns Max. (measured	0—	
between $0.6\dot{V}$ and $2.4V$)	Device	10KO > Digital
$PW_{\rm IN} = 1/(2*BALID)$	Under	Scope
PEP = 1/BAUD	Test	$\leq -$
I ERIN = I/BAOD		$\leq \top_{r}$
		4700 S 501
		47022
		\bigvee
	$\begin{array}{l} 25^{\circ}C\pm3^{\circ}C\\ 5.0V\pm0.1V\\ \text{High}=3.0V\pm0.1V\\ \text{Low}=0.0V\pm0.1V\\ 50\Omega\text{ Max.}\\ 3.0\text{ ns Max. (measured}\\ \text{between }0.6V\text{ and }2.4V\text{)}\\ \text{PW}_{\text{IN}}=1/(2^{*}\text{BAUD})\\ \text{PER}_{\text{IN}}=1/\text{BAUD} \end{array}$	$\begin{array}{lll} & \text{OUTPUT:} \\ 25^{\circ}\text{C} \pm 3^{\circ}\text{C} & & \text{R}_{\text{load}}: \\ 5.0\text{V} \pm 0.1\text{V} & & \text{C}_{\text{load}}: \\ \text{High} = 3.0\text{V} \pm 0.1\text{V} & & \text{Threshold:} \\ \text{Low} = 0.0\text{V} \pm 0.1\text{V} & & \text{Threshold:} \\ \text{Low} = 0.0\text{V} \pm 0.1\text{V} & & \text{SO} \\ 50\Omega \text{ Max.} & & & & & & \\ 3.0 \text{ ns Max. (measured} & & & & & & \\ \text{between } 0.6\text{V} \text{ and } 2.4\text{V} \text{)} & & & & & & \\ \text{PW}_{\text{IN}} = 1/(2^{*}\text{BAUD}) & & & & & & \\ \text{PER}_{\text{IN}} = 1/\text{BAUD} & & & & & & \\ \end{array}$

NOTE: The above conditions are for test only and do not in any way restrict the operation of the device.







Figure 3: Timing Diagram