

HA16103PJ/FPJ Voltage Regulator Control IC for Microcomputer Systems



Preliminary
Rev. 1
Mar. 1990

The HA16103PJ/FPJ monolithic voltage control is designed for microcomputer systems. In addition to voltage regulator, it includes watch dog timer function, power on reset function, and output voltage monitor function. It is suitable for battery use microcomputer systems.

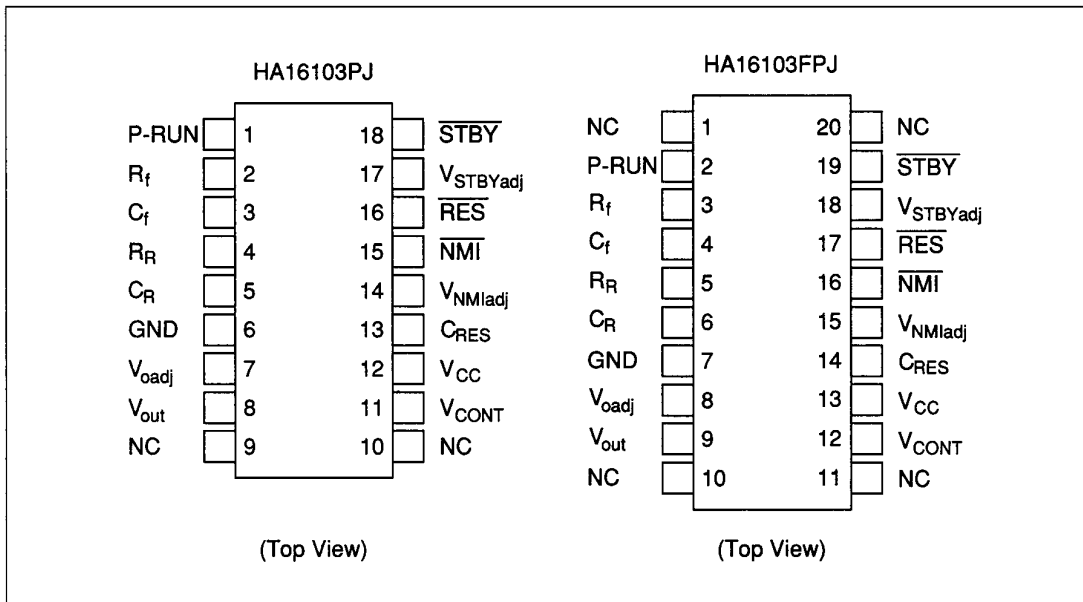
Functions

- 5 V Regulated power supply
- Power on reset pulse generator
- Watch dog timer
- Low voltage inhibit protection

Features

- Wide operational supply voltage range ($V_{CC} = 6$ to 40 V)
- Various control signals are generated when microcomputer system runaway occurs. (\overline{NMI} signal and \overline{STBY} signal are generated by detecting voltage level, and \overline{RES} signal is generated by monitoring the time after \overline{NMI} signal is detected)
- Regulated voltage, \overline{NMI} detecting voltage, \overline{STBY} detecting voltage are adjustable.
- At low voltage and re-start, the delay time of \overline{RES} signal is adjustable
- Watchdog timer filtering uses the minimum clock input pulse width and maximum cycle detection method

Pin Arrangement



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Block Diagram

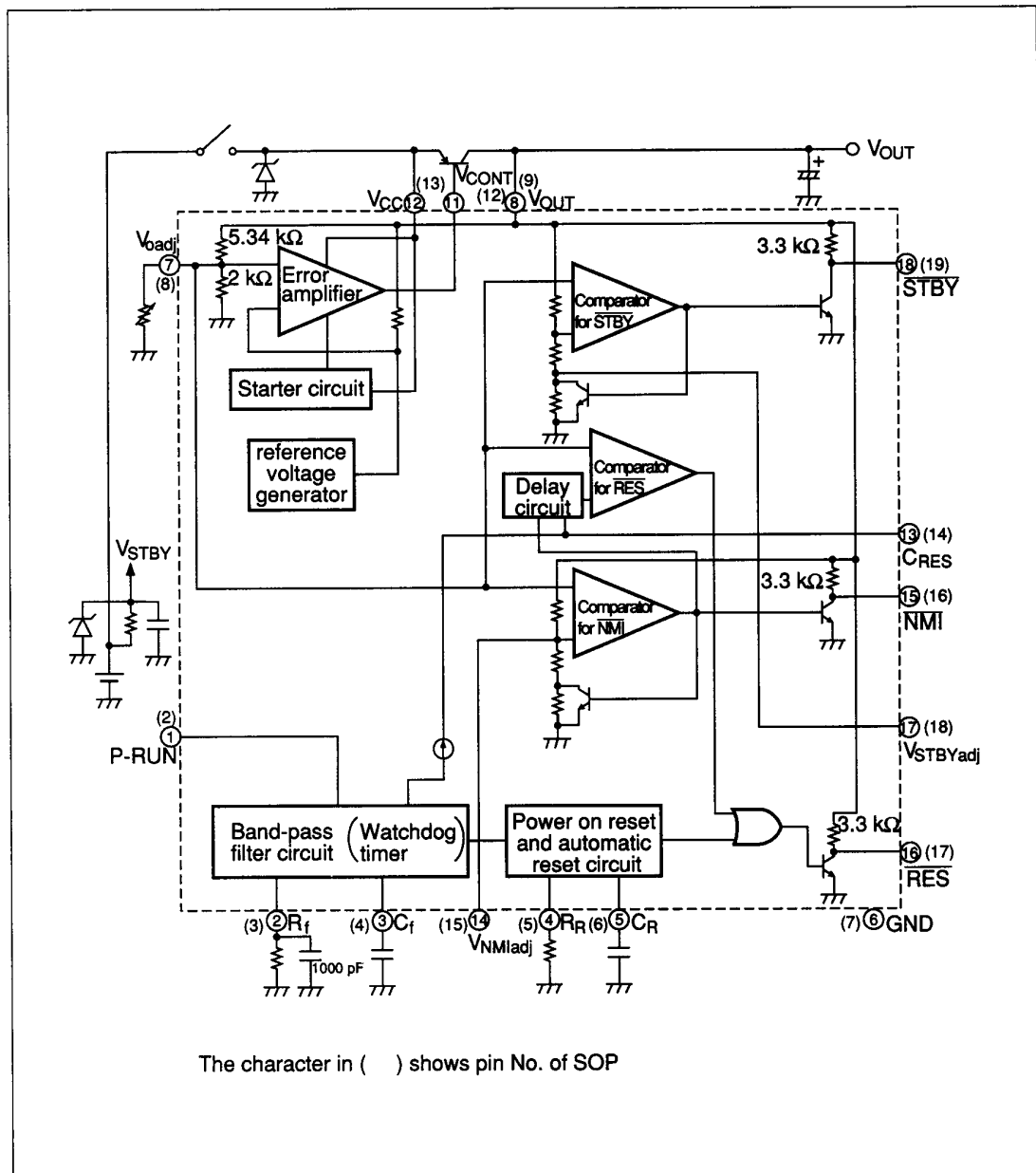


Table 1 Pin Functions

Pin Name No.	Description	
(1)	NC	NC pin
1,(2)	P-RUN	P-RUN signal input pin for watchdog timer
2,(3)	R _f	Connect resistor R _f . Frequency bandwidth of the filter circuit depends on R _f
3,(4)	C _f	Connect resistor C _f . Frequency bandwidth of the filter circuit depends on C _f
4,(5)	R _R	Connect resistor R _R . Reset-signal power-on time depends on R _R
5,(6)	C _R	Connect resistor C _R . Reset-signal power-on time depends on C _R
6,(7)	GND	Ground
7,(8)	V _{oadj}	5-V reference voltage fine-tuning pin. Connect a resistor between this pin and GND. The value of output voltage is given by $V_{out} = \{1 + 5.34 / (R1 // 2.0)\} \times V_{oadj}$ Unit for R1: k Ω
8,(9)	V _{out}	Connect the collector of an external PNP-type transistor. The pin supplies 5-V regulated voltage for internal circuit
9,(10)	NC	NC pin
10,(11)	NC	NC pin
11,(12)	V _{CONT}	The external PNP-type transistor's base control pin
12,(13)	V _{CC}	Supply voltage pin. Operating supply voltage range is 6.0 to 40 V
13,(14)	C _{RES}	If the voltage of V _{out} pin declines to less than Detection voltage(1) (because of an instant power cut or other cause), \overline{NMI} signals are generated. If t _{RES} \cong 0.5•R _f •C _{RES} (sec) has passed since then, \overline{RES} signals are generated. If the voltage of V _{out} pin inclines to more than Detection voltage(1) (in case of re-start from LVI state), \overline{NMI} signals are stop. t _r \cong 0.5•R _f •C _{RES} (sec) has passed since then, \overline{RES} signals are stop. Connect capacitor C _{RES} between this pin and GND to adjust the \overline{RES} signals delay time(t _{RES} , t _r). If delay time is unnecessary, make this pin open (t _{RES} = 2 μ s typ. t _r = 10 μ s typ. at open)
14,(15)	V _{NMIadj}	\overline{NMI} detection voltage fine-tuning pin. Connect a resistor between this pin and V _{out} pin or GND. The value of output voltage is given by $V_{NMI} = \{1 + (R2 / 25.5) / (R3 / 10.6)\} \times V_{NMIadj}$ Unit for R2, R3: k Ω
15,(16)	\overline{NMI}	\overline{NMI} signal output pin. Connect to pin \overline{NMI} of the microcomputer
16,(17)	\overline{RES}	\overline{RES} signal output pin. Connect to pin \overline{RES} of the microcomputer
17,(18)	V _{STBYadj}	\overline{STBY} detection voltage tuning pin. Connect a resistor between this pin and V _{out} or GND. The value of output voltage is given by $V_{STBY} = 1.89 \times \{1 + 21 / (7.9 + 8.85 / R4)\} \times V_{STBYadj}$ Unit for R4: k Ω
18,(19)	\overline{STBY}	\overline{STBY} signal output pin. Connect to pin \overline{STBY} of the microcomputer
(20)	NC	NC pin

The character in () shows pin No. of SOP

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Functional Description

Stabilized Power Supply Function

The stabilized power supply includes the following features:

- Wide range of operating input voltage from 6 V to 40 V to provide stabilized voltages
- Availability of any output current, by simply replacing the external transistor

- Fine adjustment of output voltage

Figure 1 shows the fine adjustment circuit of the output circuit. Select the resistor R1 as shown in equation 1.

Add a resistor between GND and V_{oadj} to increase the output voltage.

$$R1 = 1 / \{0.187(V_{out} / V_{oadj} - 1) - 0.5\} \quad \text{Equation 1}$$

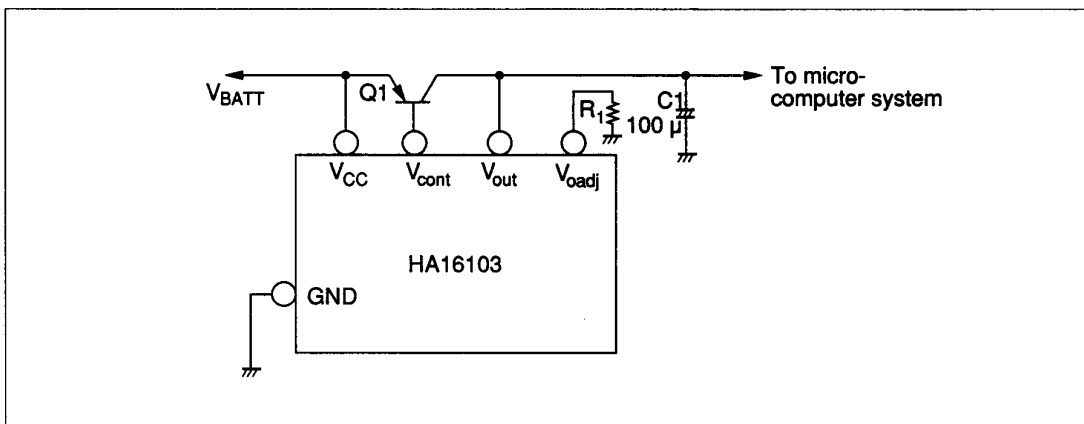


Figure 1 Fine Adjustment Circuit of Output Voltage

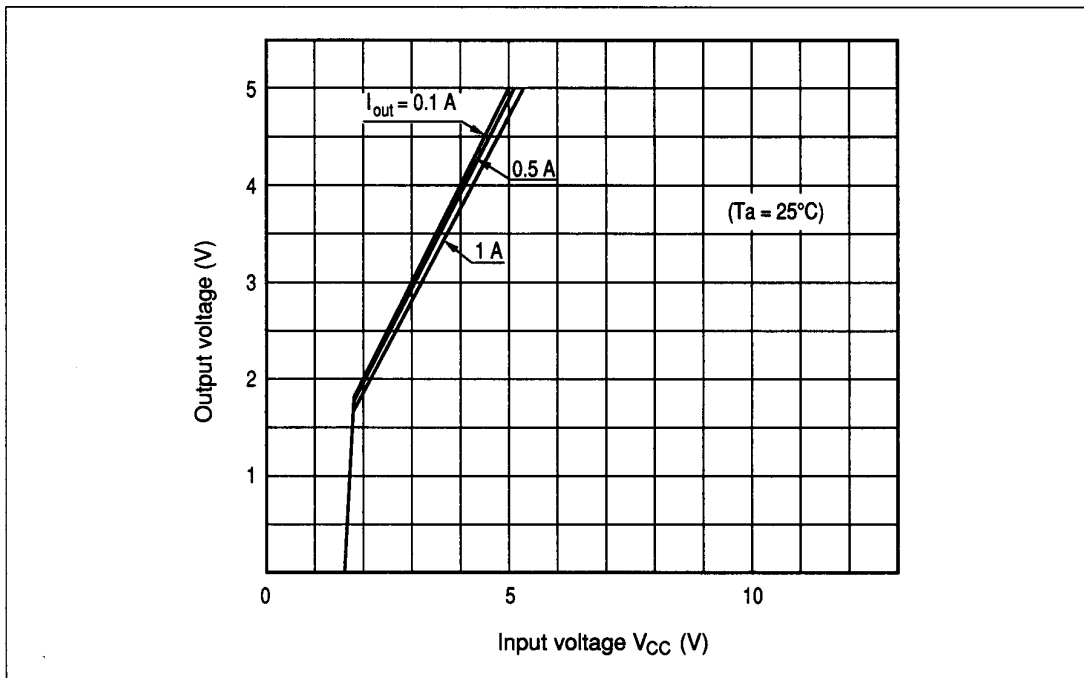


Figure 2 Output Voltage Characteristic

Power-On Reset Function

The system contains the power-on reset function required when a microcomputer is turned on. The

reset period may be set with external components R_R and C_R . Equation 2 specifies how to determine the reset period (t_{on}) and figure 3 shows the characteristic of the circuit.

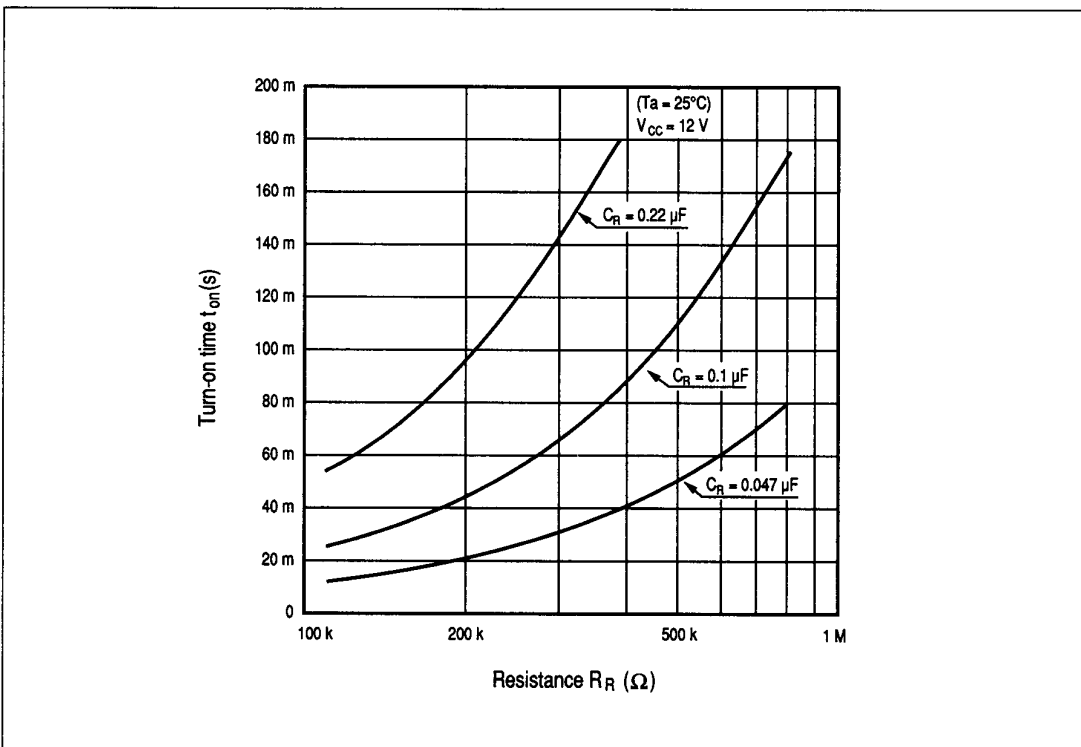
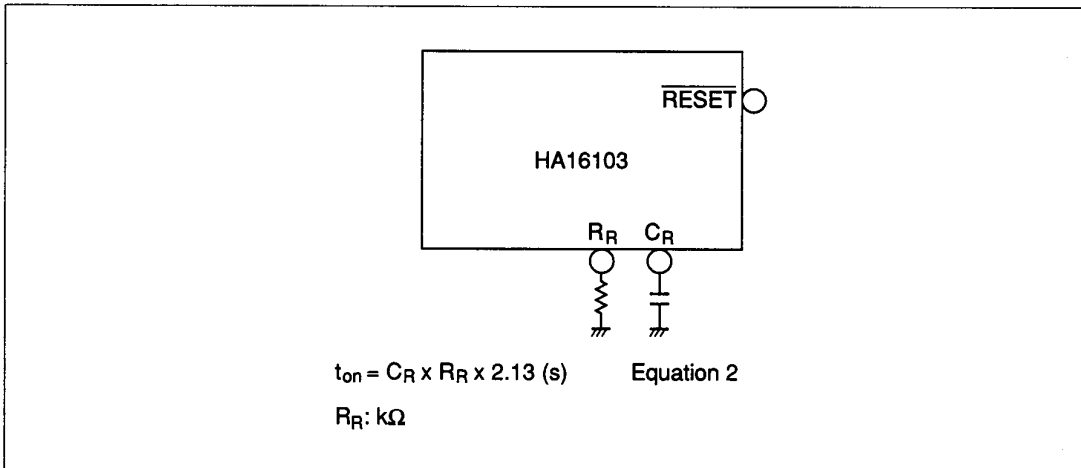


Figure 3 Characteristic of Power-On Reset Circuit

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Watchdog Timer Function

The system contains a bandpass filter for pulse width detection, which outputs a reset pulse when input pulses are not at the preselected frequency (at either a higher or lower frequency).

The RC characteristic of the bandpass filter may be set with external components R_f and C_f . Equation 3 specifies how to determine the minimum pulse width (t_{min}) for runaway detection of the bandpass filter, (and figure 4 shows the characteristic of the filter.)

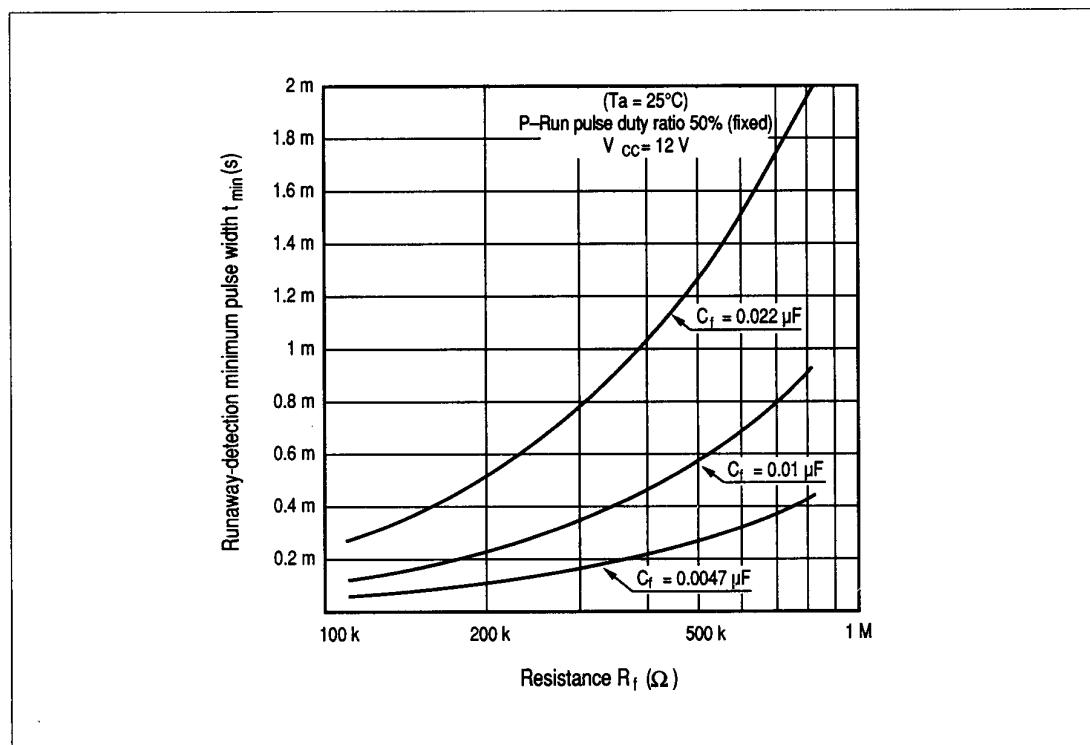
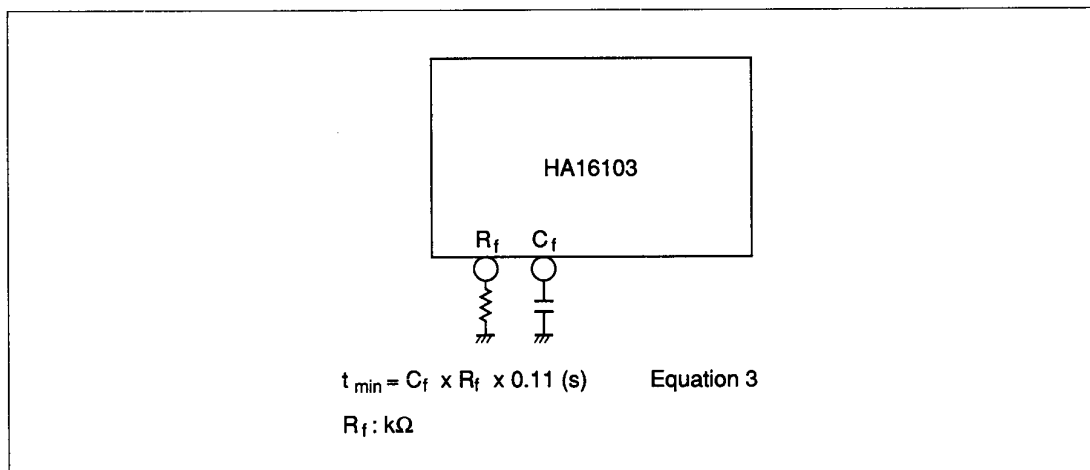


Figure 4 Characteristic of Power-On Reset Circuit

Low Voltage Monitoring Function

The system contains a circuit to send a control signal to the microcomputer when the output voltage drops. The circuit includes the following features.

- Two-point monitoring of output voltage (Vth1 and Vth2)
- Availability of fine adjustment of Vth1 (VNM1) and Vth2 (VSTBY)
- Output of control signal in standby mode of microcomputer

Figure 5 shows the timing chart of control signals when the output voltage drops.

If the output voltage drops below Vth1 (4.60 V), the $\overline{\text{NMI}}$ signal rises to request the microcomputer to issue the $\overline{\text{NMI}}$ interrupt signal. The $\overline{\text{RESET}}$ signal falls t_{RES} seconds after the $\overline{\text{NMI}}$ signal rises. If the output voltage drops further to below Vth2 (3.2 V), the $\overline{\text{STBY}}$ signal rises to enable the microcomputer to enter standby mode.

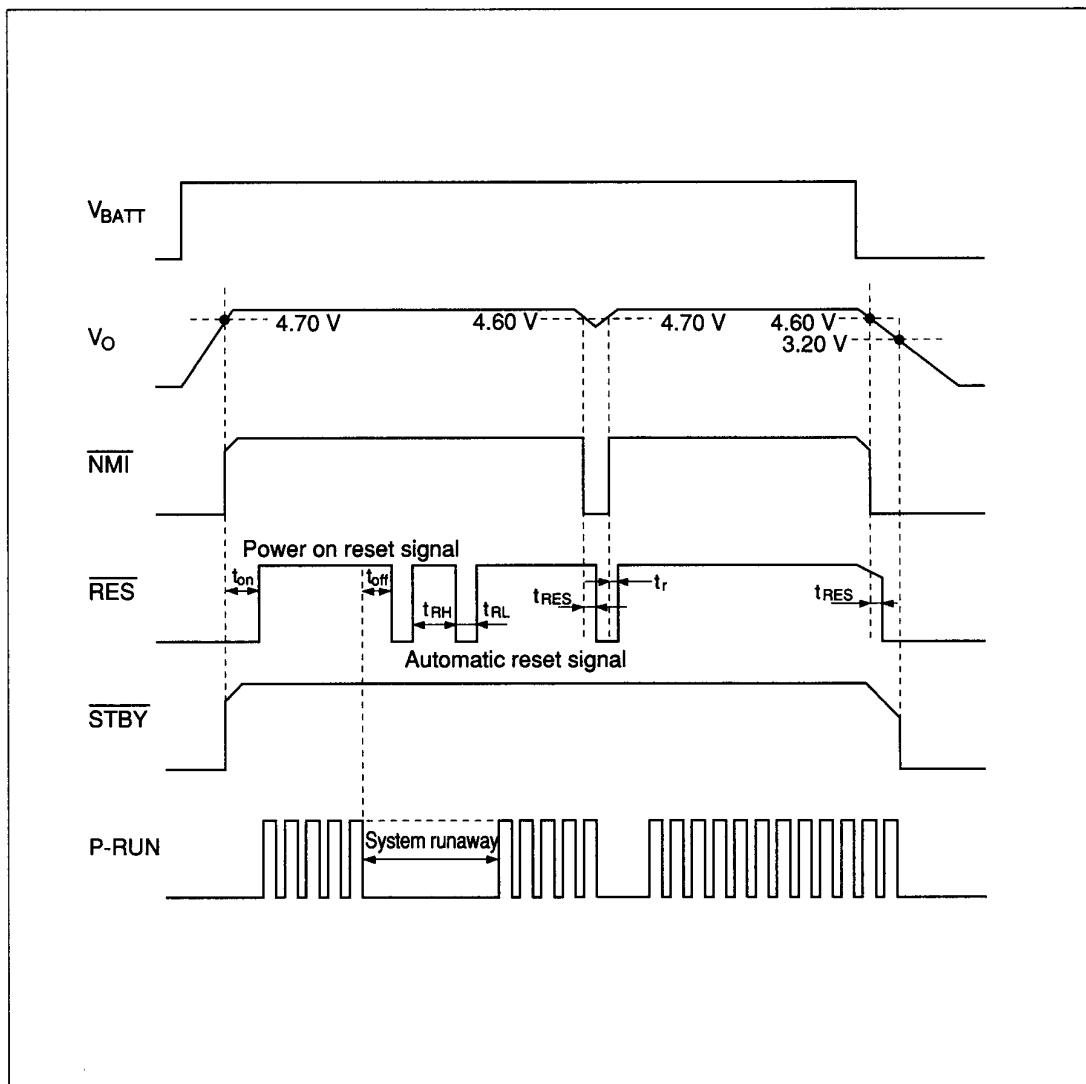


Figure 5 Timing Chart for Low Voltage Monitoring

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Table 2 Absolute Maximum Ratings (Ta = 25°C)

Item	Symbol	Ratings		Units
		HA16103PJ	HA16103FPJ	
V _{CC} supply voltage	V _{CC}	40	40	V
Control pin voltage	V _{CONT}	40	40	V
Control pin current	I _{CONT}	20	20	mA
V _{OUT} pin voltage	V _{OUT}	12	12	V
Power dissipation	P _T	400*	400**	mW
Operating ambient temperature range	Topr	-40 to +85	-40 to +85	°C
Storage temperature range	Tstg	-50 to +125	-50 to +125	°C

* Value under Ta ≤ 77°C. If Ta is greater, 8.3 mW/°C derating occurs.

** Allowable temperature of IC junction part, Tj (max.), is as shown below.

$$T_j (\text{max.}) = \theta_{j-a} \cdot P_c (\text{max.}) + T_a$$

(θ_{j-a} is thermal resistance value during mounting, and P_c (max.) is the maximum value of IC power dissipation.)

Therefore, to keep Tj (max.) ≤ 125°C, wiring density and board material must be selected according to the board thermal conductivity ratio shown below.

Be careful that the value of P_c (max.) does not exceed that P_T.

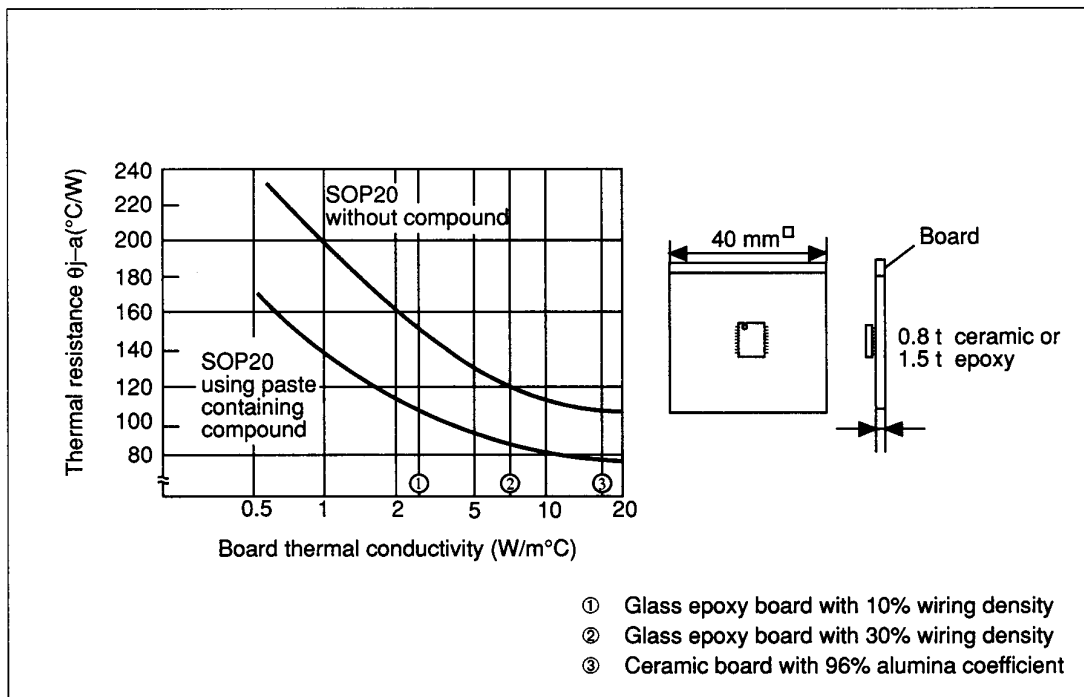


Figure 6 Thermal Resistance of SOP

Table 3 Electrical Characteristics ($T_a = 25^\circ\text{C}$, $V_{DD} = 12\text{ V}$, $V_{out} = 5\text{ V}$)

Items	Symbols	Min	Typ	Max	Units	Test Conditions	
Supply current	I_{CCL}	—	8	12	mA	$V_{CC} = 12\text{ V}$	
Regulator Output voltage	V_{O1}	4.80	5.00	5.20	V	$V_{CC} = 6\text{ to }17.5\text{ V}$ $I_{OUT} = 0.5\text{ A}$, $R_1 = 30\text{ k}\Omega$	
	V_{O2}	4.70	5.00	5.30	V	$V_{CC} = 6\text{ to }17.5\text{ V}$ $I_{OUT} = 1\text{ A}$, $R_1 = 30\text{ k}\Omega$	
Line regulation	V_{oline}	-50	—	50	mV	$V_{CC} = 6\text{ to }17.5\text{ V}$ $I_{out} = 1\text{ A}$, $R_1 = 30\text{ k}\Omega$	
Load regulation	V_{oload}	-100	—	100	mV	$I_{out} = 10\text{ mA to }1.5\text{ A}$, $R_1 = 30\text{ k}\Omega$	
Ripple rejection	R_{REJ}	45	75	—	dB	$V_i = 0.5\text{ Vrms}$, $f_i = 1\text{ kHz}$, $R_1 = 30\text{ k}\Omega$	
Output voltage Temperature coefficient	$\delta V_o/\delta T$	—	0.6	—	mV/°C	$V_{CC} = 12\text{ V}$, $R_1 = 30\text{ k}\Omega$	
Clock input	"L"-input voltage	V_{IL}	—	—	0.8	V	
	"H"-input voltage	V_{IH}	2.0	—	—	V	
	"L"-input current	I_{IL}	-120	-60	—	μA	$V_{IL} = 0\text{ V}$
	"H"-input current	I_{IH}	—	0.3	0.5	mA	$V_{IH} = 5\text{ V}$
NMI output	NMI pin "L"-level voltage	V_{OL1}	—	—	0.4	V	$I_{OL1} = 2\text{ mA}$
	NMI pin "H"-level voltage	V_{OH1}	—	V_{O1} (V_{O2})	—	V	
	NMI function start V_{out} voltage	V_{NMI}	—	0.7	1.4	V	
STBY output	STBY pin "L"-level voltage	V_{OL2}	—	—	0.4	V	$I_{OL2} = 2\text{ mA}$
	STBY pin "H"-level voltage	V_{OH2}	—	V_{O1} (V_{O2})	—	V	
	STBY function start V_{out} voltage	V_{STBY}	—	0.7	1.4	V	

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Table 3 Electrical Characteristics ($T_a = 25^\circ\text{C}$, $V_{DD} = 12\text{ V}$, $V_{out} = 5\text{ V}$) (Cont)

Items		Symbols	Min	Typ	Max	Units	Test Conditions
RES output	RES pin "L"-level voltage	V_{OL3}	—	—	0.4	V	$I_{OL3} = 2\text{ mA}$
	RES pin "H"-level voltage	V_{OH3}	—	V_{O1} (V_{O2})	—	V	
	RES function start V_{out} voltage	V_{RES}	—	0.7	1.4	V	
	Power on time	t_{ON}	25	40	60	ms	$R_f = 180\text{ k}\Omega$, $R_R = 180\text{ k}\Omega$
	Clock off reset time	t_{OFF}	80	130	190	ms	$C_f = 0.01\text{ }\mu\text{F}$, $C_R = 0.1\text{ }\mu\text{F}$
	Reset pulse "L"-level time	t_{RL}	15	20	30	ms	$R_f = 180\text{ k}\Omega$, $R_R = 180\text{ k}\Omega$ $C_f = 0.01\text{ }\mu\text{F}$, $C_R = 0.1\text{ }\mu\text{F}$
	Reset pulse "H"-level time	t_{RH}	37	60	90	ms	$R_f = 180\text{ k}\Omega$, $R_R = 180\text{ k}\Omega$ $C_f = 0.01\text{ }\mu\text{F}$, $C_R = 0.1\text{ }\mu\text{F}$
Low Voltage Protection	Detection voltage(1)	V_{H1}	4.40	4.60	4.80	V	
	Detection voltage(1) Hysteresis width	V_{HYS1}	50	100	150	mV	
	Detection voltage(2)	V_{H2}	2.9	3.2	3.5	V	
	Detection voltage(2) Hysteresis width	V_{HYS2}	1.35	1.5	1.65	V	
	Reset pulse inhibit Delay time	t_{RES}	—	200	—	μs	$C_{RES} = 2200\text{ pF}$
	restart	t_r	—	200	—	μs	$C_{RES} = 2200\text{ pF}$

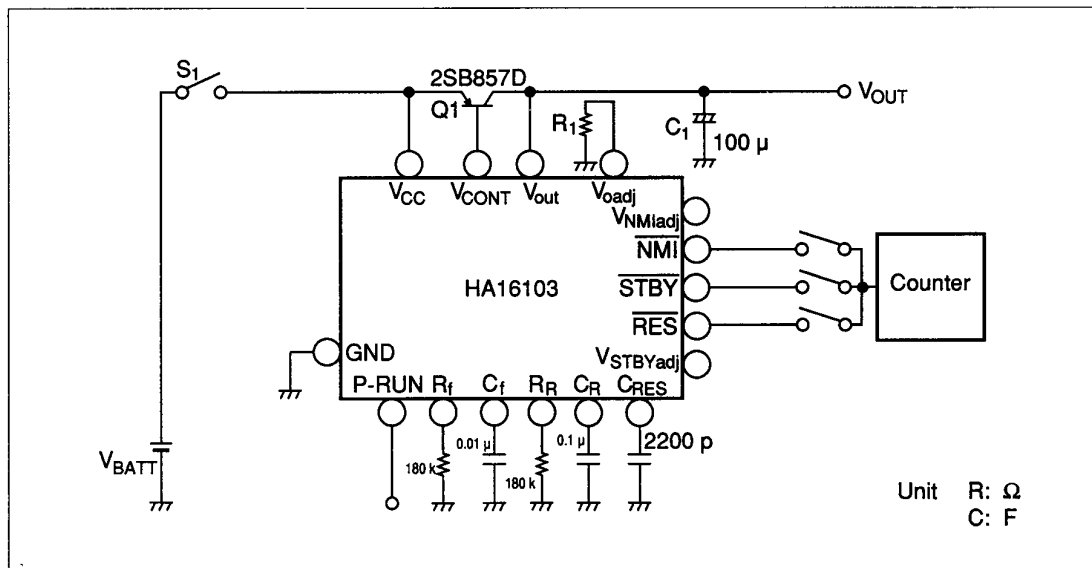


Figure 7 Test Circuit

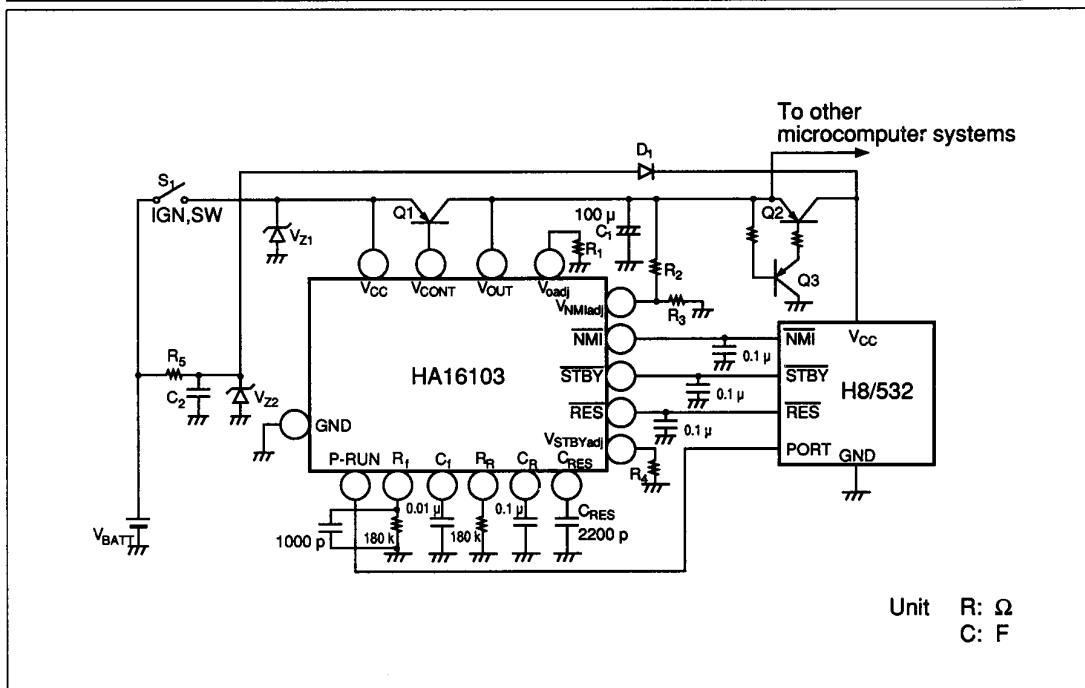


Figure 8 Sample Connection Circuit between HA16103 and H8/532 (1)

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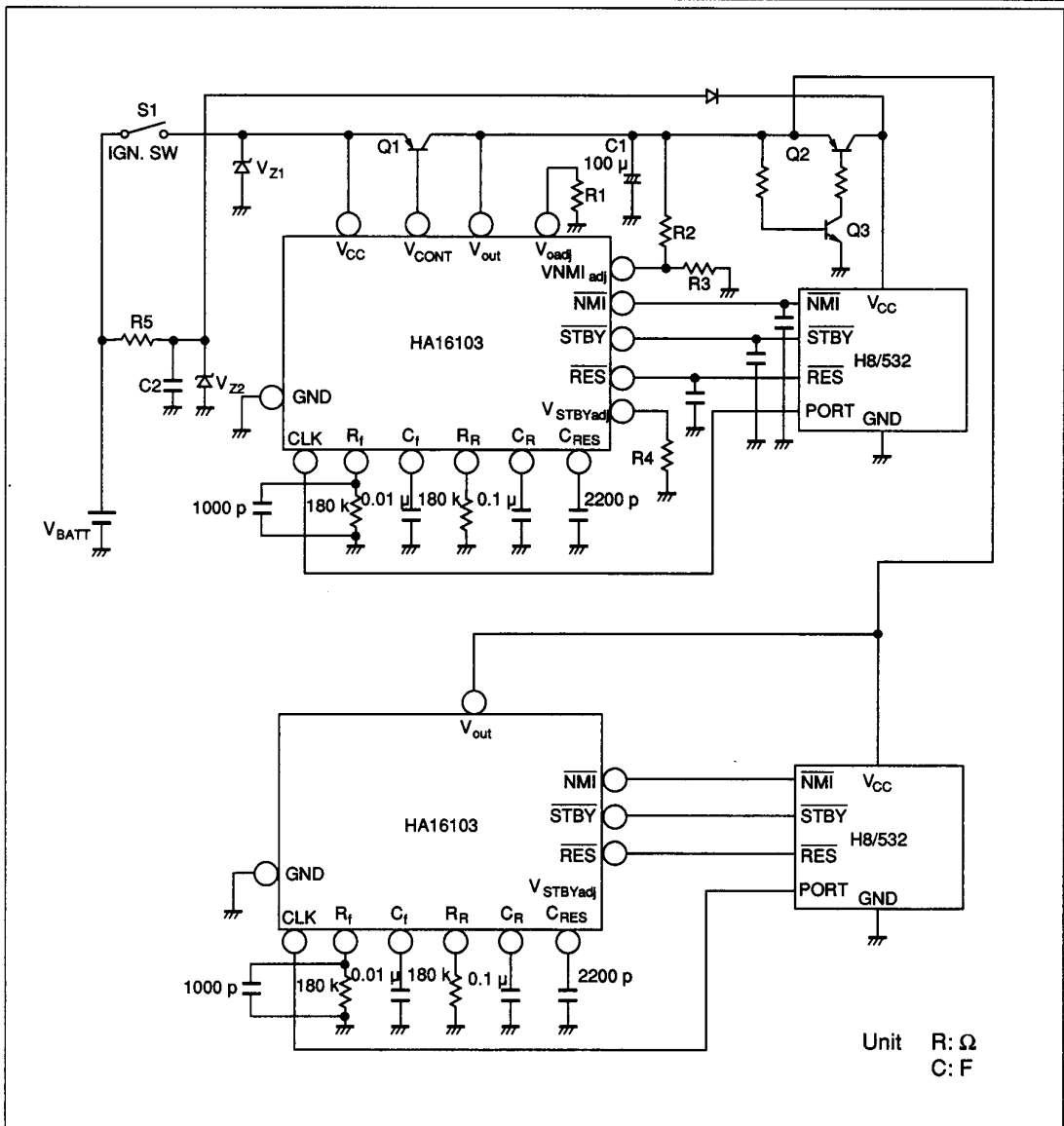
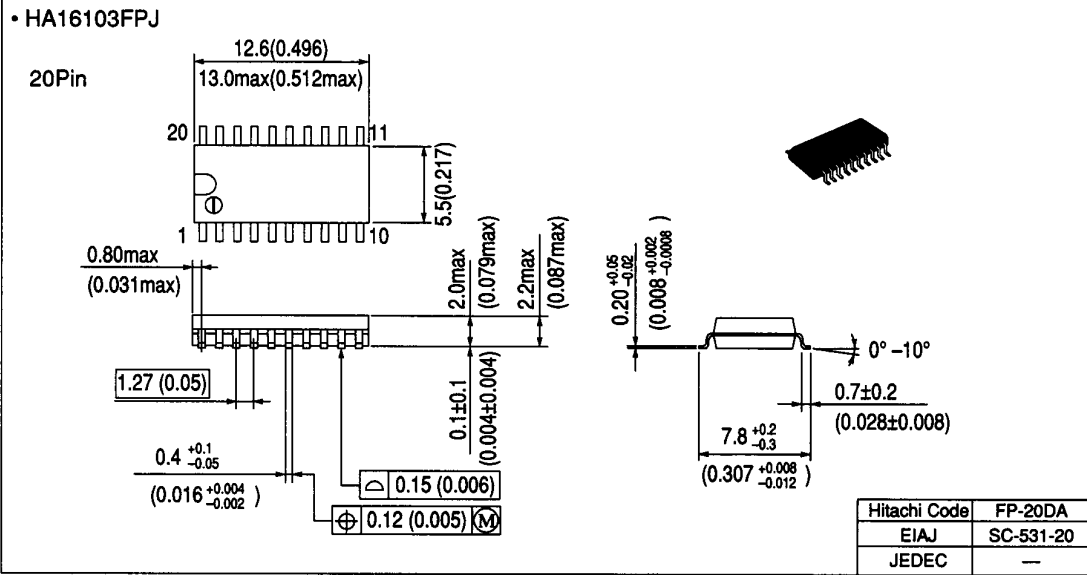
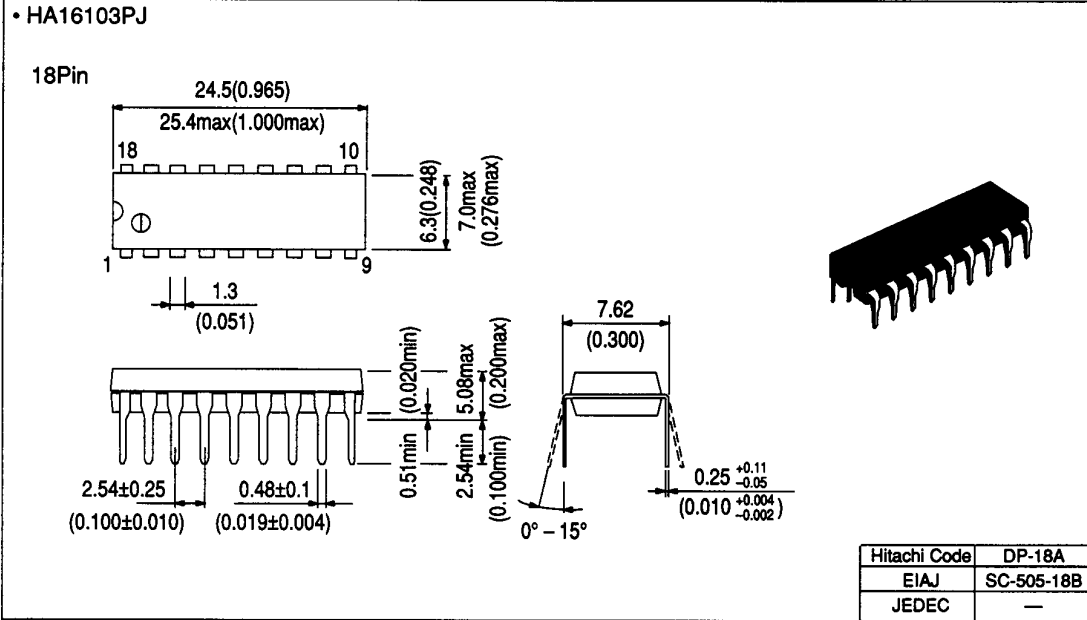


Figure 9 Sample Connection Circuit between HA16103 and H8/532 (2)

Package Dimensions

Unit: mm (inch)



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