IS82C600 TRAILBLAZER High-Speed SRAM with Address Decoding and Ready Logic



- Zero wait-state performance on the Primary
 Bus
 - Point-to-point interface between the SRAM and the high-speed processor
- Seamless interface to Texas Instruments' TMS320LC54x high-speed processor
- Integrates the single-ported SRAM with a dualported interface and handshake
 - 9 ns access time to the SRAM
 - Can also be used as a standalone, highspeed SRAM
- Integrates the port-to-port bridge function
 - Broadcasts all processor cycles from Primary Bus to the Secondary Bus
 - Programmability to only broadcast non-SRAM cycles to the Secondary Bus
 - Supports older, slower peripheral devices on the Secondary Bus
 - Allows the processor transparent access to the devices on the Secondary Bus through XCVR pin
 - Supports a Boot ROM on the Secondary Bus

- Features Address Decoding and Ready Logic
 - A total of six Chip Selects
 - Supports "Ready" logic signal generation for memory and I/O
 - Eliminates PALs for address decoding and ready logic
 - No "glue logic" interface for local peripherals on the Secondary Bus processor
- Allows dynamic re-allocation of memory spaces for transparent block moves
 - Programmable memory decoding allows memory blocks to be accessed as either Program Space (PS) or Data Space (DS)
 - Programmable registers to map the internal SRAM memory and external secondary port devices into Data Space (DS), Program Space (PS) and I/O Space (IS)
- Can also be used as a standalone, high-speed SRAM
- Allows the shadowing of the ROM on the Secondary Bus into the on-board SRAM

GENERAL DESCRIPTION

The IS82C600 TrailBlazer simplifies high-speed system design and layout, providing an SRAM with zero wait-state performance up to 90 MHz, address coding, and "Ready" logic. In many cases, TrailBlazer allows existing system designs to be easily upgraded, enabling the re-use of already available ASICs and glue logic.

A key benefit of the TrailBlazer device is its ability to relieve high-performance processors from a necessity to drive heavily loaded multidrop buses by providing a point-topoint, low-load interconnect to the high-speed memory and buffering of the slower speed devices. This could allow the processors to operate at a maximum frequency with zero wait-states. Also, it eases PCB timing and layoutrelated considerations, often allowing a reduction in the number of PC board layers and the lowering of noise. Programmable decodes and "Ready" generation logic built into the TrailBlazer eliminates the need for expensive PALs, other glue logic, and additional board space.

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Figure 1. TrailBlazer Functional Block Diagram

PRODUCT OVERVIEW

The IS82C600 TrailBlazer integrates a high-speed 64K x 16 SRAM with a processor port-to-processor port bridge function. This simplifies any high-speed designs by providing a fast access time for the processor on the Primary Port and enabling for a low-cost implementation of a high-frequency system.

TrailBlazer combines a high-performance memory array, programmable decodes, and "Ready" logic to achieve maximum performance and flexibility, while keeping costs at a minimum. In order to simplify system development, TrailBlazer duplicates the Primary Bus signals on its Secondary Bus to permit the use of existing system components and ASICs together with a new generation of high-performance processors. On its Primary Bus, the TrailBlazer provides a high-speed SRAM interface and then broadcasts the Primary Bus cycles to its Secondary Bus, allowing the processor on its Primary Bus to access peripherals on its Secondary Bus. In many cases, since the peripherals are accessed by the same signals, existing ASICs can be re-used.

TrailBlazer provides an optimized, seamless interface to TI TMS320LC54x high-speed processor without the need for any glue logic interfaces for local peripherals on the Secondary Bus. TrailBlazer can also be used as shared Local or Global Memory for a dual processor-based system where the Chip Select logic on each bus allows for the same data to be accessed at different locations in memory, if so desired.





Figure 2. TrailBlazer System Block Diagram with High-Speed DSP on the Primary Bus and the Slower Existing DSP System Components on the Secondary Bus



Complete pin information on the device is organized as follows:

- Overview
- Conventions
- Pin Diagram
- Pin Assignment Table—Arranged by Pin Number
- Pin Assignment Table—Arranged by Ball Location
- Detailed Pin Descriptions

Overview

The R/\overline{W} signal determines the direction of the bus transaction.

Some processors, including TI TMS320LC54X, have three major memory spaces. Program Space (\overline{PS}); Data Space (\overline{DS}); and I/O Space (\overline{IS}). The Memory Space signals (\overline{DS} , \overline{PS} , and \overline{IS}) select the memory address space being accessed (Data, Program, or I/O). No more than one of the Memory Space signals can be asserted at the same time. Data or Program spaces (or any part of these spaces) can be mapped into either internal SRAM of the TrailBlazer or any external devices. I/O space can only be mapped to external devices. The TrailBlazer's internal SRAM has two 32KB regions that are restricted to either \overline{DS} or \overline{PS} space.

Register 0 controls the decoding for the internal SRAM. Registers 1 through 5 control the address decoding for the external devices on the Secondary Bus. For processors that have A15 as the MSB, the three memory spaces are restricted to 64KB each. However, the registers do allow for programmable address ranges in 8KB blocks. For processors with A[21:16] as the MSB, there is a 4MB maximum address space that can be partitioned by programming Registers 1 to 5.

Chip Selects (CSMEMx) are used to select external devices on the Secondary Bus. These signals are generated by combinations of the Memory Space signals and Addresses Ap[13:21]. Strobes ($\overline{\text{MSTRB}}$ and $\overline{\text{IOSTRB}}$) validate Memory Space selections. $\overline{\text{PS}}$ and $\overline{\text{DS}}$ have to be validated by the assertion of $\overline{\text{MSTRB}}$ and $\overline{\text{IS}}$ has to be validated by the assertion of $\overline{\text{IOSTRB}}$.

The following provides detailed technical information related to the pins on the device. For ease of reference, the pin information is presented in a table format arranged both by pin numbers and by pin names. A pin diagram has also been included to be used as a visual point of reference.

Conventions

Table 1 details conventions that are used to present information on the pins.

Table 1. Pin Conventions

| Convention | Meaning |
|------------|--|
| NC | This pin is reserved for ISSI, Inc. and must be left as a 'No Connect' |
| I | Input-only |
| 0 | Output-only |
| I/O | Input or Output (Bi-directional) |
| Power | Power pin |
| Ground | Ground pin |
| SIGNAL | Active (or asserted) state occurs when pin is at a low voltage |
| / | Multiplexed or Dual functionality |

Pin Diagram

Refer to Figure 3 and Table 2 for the pin diagram for the TrailBlazer device. It depicts the pin names and the corresponding ball location. Pins marked as 'NC' are not available and are defined as 'No Connect' pins. For more detailed information on the pins refer to Table 5.

| Tab | Гable 2. Pin Configuration: 119-pin PBGA | | | | | | | |
|-----|--|---------------|--------|------|---------------|--------|---------------|--|
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | |
| Α | Ap18 | Ap16 | Ap4 | Ap5 | Ap11 | XCVR | ISp | |
| В | Ap19 | Ap17 | Ap3 | Ap6 | Ap12 | PSp | DSp | |
| С | Ap21 | Ap20 | Ap2 | Ap7 | Ap13 | Dp0 | Dp1 | |
| D | Ds1 | Ds0 | Ap1 | Ap8 | Ap14 | Dp2 | Dp3 | |
| Е | Ds3 | Ds2 | Ap0 | Ap9 | Ap15 | Dp4 | Dp5 | |
| F | Ds4 | GND | GNDQ | Ap10 | GNDQ | Vcc | Dp6 | |
| G | Ds7 | Ds6 | Ds5 | Dp7 | HOLDAp | CSINTp | R/Wp | |
| Н | CLK | GNDQ | RDY | Vccq | RDp | GNDQ | IOSTRBp | |
| J | Ds8 | OEMEMs | Vccq | Vccq | WEs | WEp | MSTRBp | |
| Κ | Ds9 | GNDQ | WEMEMs | Vccq | IOSTRBs | GNDQ | MSTRBs | |
| L | Ds10 | Ds11 | As1 | As7 | CSINTs | R/Ws | RDs | |
| Μ | Ds12 | Vcc | GNDQ | As8 | GNDQ | GND | HOLDAs | |
| Ν | Ds13 | Ds14 | As2 | As9 | Dp10 | Dp9 | Dp8 | |
| Ρ | Ds15 | CSMEMs0 | As3 | As10 | Dp13 | Dp12 | Dp11 | |
| R | CSMEMs1 | CSMEMs2 | As4 | As11 | PRGM | DSs | Dp14 | |
| Т | CSMEMs3 | CSMEMs5 | As5 | As12 | As15 | ĪSs | Dp15 | |
| U | CSMEMs4 | As0 | As6 | As13 | As14 | PSs | NC | |



Figure 3. TrailBlazer Pin Diagram

Table 3. Pin Assignment Table—Arranged by PinName in Alphabetical Order

| Pin Name | Ball Location | Pin Type |
|----------|---------------|----------|
| Ap0 | E3 | I/O |
| Ap1 | D3 | I/O |
| Ap2 | C3 | I/O |
| АрЗ | B3 | I/O |
| Ap4 | A3 | I/O |
| Ap5 | A4 | I/O |
| Ap6 | B4 | I/O |
| Ap7 | C4 | I/O |
| Ap8 | D4 | I/O |
| Ap9 | E4 | I/O |
| Ap10 | F4 | I/O |
| Ap11 | A5 | I/O |
| Ap12 | B5 | I/O |
| Ap13 | C5 | I/O |
| Ap14 | D5 | I/O |
| Ap15 | E5 | I/O |
| Ap16 | A2 | I |
| Ap17 | B2 | I |
| Ap18 | A1 | <u> </u> |
| Ap19 | B1 | <u> </u> |
| Ap20 | C2 | <u> </u> |
| Ap21 | C1 | <u> </u> |
| As0 | U2 | I/O |
| As1 | L3 | I/O |
| As2 | N3 | I/O |
| As3 | P3 | I/O |
| As4 | R3 | I/O |
| As5 | Т3 | I/O |
| As6 | U3 | I/O |
| As7 | L4 | I/O |
| As8 | M4 | I/O |
| As9 | N4 | I/O |
| As10 | P4 | I/O |
| As11 | R4 | I/O |
| As12 | T4 | I/O |
| As13 | U4 | I/O |
| As14 | U5 | I/O |
| As15 | T5 | I/O |
| CLK | H1 | Ι |
| CSINTp | G6 | <u> </u> |

| Pin Name | Ball Location | Pin Type |
|----------|---------------|----------|
| CSINTs | L5 | I |
| CSMEMs0 | P2 | 0 |
| CSMEMs1 | R1 | 0 |
| CSMEMs2 | R2 | 0 |
| CSMEMs3 | T1 | 0 |
| CSMEMs4 | U1 | 0 |
| CSMEMs5 | T2 | 0 |
| Dp0 | C6 | I/O |
| Dp1 | C7 | I/O |
| Dp2 | D6 | I/O |
| Dp3 | D7 | I/O |
| Dp4 | E6 | I/O |
| Dp5 | E7 | I/O |
| Dp6 | F7 | I/O |
| Dp7 | G4 | I/O |
| Dp8 | N7 | I/O |
| Dp9 | N6 | I/O |
| Dp10 | N5 | I/O |
| Dp11 | P7 | I/O |
| Dp12 | P6 | I/O |
| Dp13 | P5 | I/O |
| Dp14 | R7 | I/O |
| Dp15 | T7 | I/O |
| Ds0 | D2 | I/O |
| Ds1 | D1 | I/O |
| Ds2 | E2 | I/O |
| Ds3 | E1 | I/O |
| Ds4 | F1 | I/O |
| Ds5 | G3 | I/O |
| Ds6 | G2 | I/O |
| Ds7 | G1 | I/O |
| Ds8 | J1 | I/O |
| Ds9 | K1 | I/O |
| Ds10 | L1 | I/O |
| Ds11 | L2 | I/O |
| Ds12 | M1 | I/O |
| Ds13 | N1 | I/O |
| Ds14 | N2 | I/O |
| Ds15 | P1 | I/O |
| DSp | B7 | I/O |

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| Table 3. | Pin Assignment Table—Arranged by Pin |
|----------|--------------------------------------|
| Name in | Alphabetical Order (continued) |

Table 4. Pin Assignment Table—Arranged by BallLocation in Alphabeltical Order

| Pin Name | Ball Location | Pin Type | | Pin Name | Ball Location | Pin Type |
|----------|---------------|----------|---|----------|---------------|----------|
| DSs | R6 | I/O | _ | Ap18 | A1 | I |
| GND | F2 | Ground | _ | Ap16 | A2 | l |
| GND | M6 | Ground | | Ap4 | A3 | I/O |
| GNDQ | F3 | Ground | | Ap5 | A4 | I/O |
| GNDQ | F5 | Ground | | Ap11 | A5 | I/O |
| GNDQ | H2 | Ground | | XCVR | A6 | I |
| GNDQ | H6 | Ground | | ĪSp | A7 | I/O |
| GNDq | K2 | Ground | | Ap19 | B1 | I |
| GNDq | K6 | Ground | _ | Ap17 | B2 | I |
| GNDq | M3 | Ground | | Ap3 | B3 | I/O |
| GNDq | M5 | Ground | | Ap6 | B4 | I/O |
| HOLDAp | G5 | I | | Ap12 | B5 | I/O |
| HOLDAS | M7 | I | | PSp | B6 | I/O |
| IOSTRBp | H7 | I/O | | DSp | B7 | I/O |
| IOSTRBs | K5 | I/O | | Ap21 | C1 | I |
| ISp | A7 | I/O | | Ap20 | C2 | I |
| ISs | Т6 | I/O | | Ap2 | C3 | I/O |
| MSTRBp | J7 | I/O | | Ap7 | C4 | I/O |
| MSTRBs | K7 | I/O | | Ap13 | C5 | I/O |
| NC | U7 | | | Dp0 | C6 | I/O |
| OEMEMs | J2 | 0 | | Dp1 | C7 | I/O |
| PRGM | R5 | I | _ | Ds1 | D1 | I/O |
| PSp | B6 | I/O | _ | Ds0 | D2 | I/O |
| PSs | U6 | I/O | _ | Ap1 | D3 | I/O |
| RDp | H5 | I/O | | Ap8 | D4 | I/O |
| RDs | L7 | I/O | | Ap14 | D5 | I/O |
| R/Wp | G7 | I/O | | Dp2 | D6 | I/O |
| R/Ws | L6 | I/O | | Dp3 | D7 | I/O |
| RDY | H3 | 0 | | Ds3 | E1 | I/O |
| Vcc | F6 | Power | | Ds2 | E2 | I/O |
| Vcc | M2 | Power | | Ap0 | E3 | I/O |
| Vccq | H4 | Power | | Ap9 | E4 | I/O |
| Vccq | J3 | Power | | Ap15 | E5 | I/O |
| Vccq | J4 | Power | | Dp4 | E6 | I/O |
| Vccq | K4 | Power | | Dp5 | E7 | I/O |
| WEMEMs | K3 | 0 | | Ds4 | F1 | I/O |
| WEp | J6 | I/O | | GND | F2 | Ground |
| WEs | J5 | I/O | | GNDQ | F3 | Ground |
| XCVR | A6 | I | | Ap10 | F4 | I/O |

Table 4. Pin Assignment Table—Arranged by Ball Location in Alphabeltical Order (continued)

| Pin Name | Ball Location | Pin Type |
|---------------|---------------|----------|
| GNDQ | F5 | Ground |
| Vcc | F6 | Power |
| Dp6 | F7 | I/O |
| Ds7 | G1 | I/O |
| Ds6 | G2 | I/O |
| Ds5 | G3 | I/O |
| Dp7 | G4 | I/O |
| HOLDAp | G5 | I |
| CSINTp | G6 | I |
| R/Wp | G7 | I/O |
| CLK | H1 | I |
| GNDQ | H2 | Ground |
| RDY | H3 | 0 |
| Vccq | H4 | Power |
| RDp | H5 | I/O |
| GNDQ | H6 | Ground |
| IOSTRBp | H7 | I/O |
| Ds8 | J1 | I/O |
| OEMEMs | J2 | 0 |
| Vccq | J3 | Power |
| Vccq | J4 | Power |
| WEs | J5 | I/O |
| WEp | J6 | I/O |
| MSTRBp | J7 | I/O |
| Ds9 | K1 | I/O |
| GNDQ | K2 | Ground |
| WEMEMs | K3 | 0 |
| Vccq | K4 | Power |
| IOSTRBs | K5 | I/O |
| GNDa | K6 | Ground |
| MSTRBs | K7 | I/O |
| Ds10 | L1 | I/O |
| Ds11 | L2 | I/O |
| As1 | L3 | I/O |
| As7 | L4 | I/O |
| CSINTs | L5 | I |
| R/Ws | L6 | I/O |
| RDs | L7 | I/O |
| Ds12 | M1 | I/O |
| Vcc | M2 | Power |

| Pin Name | Ball Location | Pin Type |
|----------|---------------|----------|
| GNDQ | M3 | Ground |
| As8 | M4 | I/O |
| GNDQ | M5 | Ground |
| GND | M6 | Ground |
| HOLDAs | M7 | Ι |
| Ds13 | N1 | I/O |
| Ds14 | N2 | I/O |
| As2 | N3 | I/O |
| As9 | N4 | I/O |
| Dp10 | N5 | I/O |
| Dp9 | N6 | I/O |
| Dp8 | N7 | I/O |
| Ds15 | P1 | I/O |
| CSMEMs0 | P2 | 0 |
| As3 | P3 | I/O |
| As10 | P4 | I/O |
| Dp13 | P5 | I/O |
| Dp12 | P6 | I/O |
| Dp11 | P7 | I/O |
| CSMEMs1 | R1 | 0 |
| CSMEMs2 | R2 | 0 |
| As4 | R3 | I/O |
| As11 | R4 | I/O |
| PRGM | R5 | I |
| DSs | R6 | I/O |
| Dp14 | R7 | I/O |
| CSMEMs3 | T1 | 0 |
| CSMEMs5 | T2 | 0 |
| As5 | Т3 | I/O |
| As12 | T4 | I/O |
| As15 | T5 | I/O |
| ISs | Т6 | I/O |
| Dp15 | T7 | I/O |
| CSMEMs4 | U1 | 0 |
| As0 | U2 | I/O |
| As6 | U3 | I/O |
| As13 | U4 | I/O |
| As14 | U5 | I/O |
| PSs | U6 | I/O |
| NC | U7 | |



Table 5. Primary Bus Pins

| Pin Name | Pin Type | Pin Description |
|-----------|----------|---|
| Ap[15:0] | I/O | ADDRESS: Primary Bus address pins. The Ap[21] is the MSB and Ap[0] is the LSB. |
| Ap[21:16] | I | |
| CLK | Ι | CLOCK SIGNAL (Primary): This is the high-speed clock from the processor. Used for generation of RDY signal. |
| CSINTp | I | INTERNAL SRAM CHIP SELECT SIGNAL (Primary): When asserted, the SRAM access is guaranteed from the Primary Bus, irrespective of the configuration mode. |
| Dp[15:0] | I/O | DATA: Data pins Dp[15] (MSB) through Dp[0] (LSB) connected to the processor on the Primary Bus. |
| DSp | I/O | DATA SPACE SIGNAL (Primary): When asserted, indicates processor is accessing the Data Space (\overline{DS}) memory. It also validates address information on Ap[21:0]. |
| HOLDAp | Ι | HOLD ACKNOWLEDGE SIGNAL (Primary): HOLDAp, when asserted, indicates that the processor or MPU on the Primary Bus is in a Hold state. This also indicates that Ap[21:0] and Dp[15:0] are tri-stated. Typically, this signal is used in dual-processor configurations where access to the internal SRAM is guaranteed for the processor on the Secondary Bus. |
| IOSTRBp | I/O | I/O STROBE (Primary): When asserted, indicates a Primary Bus access to I/O devices. |
| ISp | I/O | I/O SPACE SIGNAL (Primary): When asserted, indicates that processor is accessing the I/O Space (\overline{IS}). It also validates the address. |
| MSTRBp | I/O | MEMORY STROBE (Primary): When asserted, indicates bus access to data or program memory. |
| PSp | I/O | PROGRAM SPACE SIGNAL (Primary): When asserted, indicates processor is communicating with Program Space (PS) memory. It also validates the address. |
| RDp | I/O | This pin should be pulled HIGH. |
| R/Wp | I/O | READ/WRITE SIGNAL (Primary): R/\overline{W} indicates transfer direction during access from Primary Bus. Set HIGH for a Read and LOW for a Write access. |
| WEp | I/O | This pin should be pulled HIGH. |



Table 6. Secondary Bus Pins

| Pin Name | Pin Type | Pin Description |
|-------------|----------|---|
| As[15:0] | I/O | ADDRESS: Secondary Bus address pins. As[15] is the MSB and As[0] is the LSB. |
| CSINTs | I | INTERNAL SRAM CHIP SELECT SIGNAL (Secondary): When asserted, the SRAM access is guaranteed from the Secondary Bus (if $HOLDAp = 0$), irrespective of the configuration mode. |
| CSMEMs[5:0] | Ο | EXTERNAL MEMORY CHIP SELECTS (Secondary): Selects devices on the Secondary Bus. Refer to the Register Definition Section for more details. |
| DSs | I/O | DATA SPACE SIGNAL (Secondary): When asserted, indicates processor is accessing the Data Space (DS) memory. It also validates address information on As[15:0]. |
| HOLDAs | Ι | HOLD ACKNOWLEDGE SIGNAL (Secondary): HOLDAs, when asserted, indicates that the processor or MPU on the Secondary Bus is in a Hold state. This also indicates that As[15:0] and Ds[15:0] are tri-stated. Typically, this signal is used in dual-processor configurations where access to the internal SRAM is guaranteed for the processor on the Secondary Bus. |
| IOSTRBs | I/O | I/O STROBE (Secondary): When asserted, indicates a Secondary Bus access to I/O devices. |
| ISs | I/O | I/O SPACE SIGNAL (Secondary): When asserted, indicates that processor is accessing the I/O space (IS). It also validates the address. |
| MSTRBs | I/O | MEMORY STROBE (Secondary): When asserted, indicates bus access to data or program memory. |
| PSs | I/O | PROGRAM SPACE SIGNAL (Secondary): When asserted, indicates processor is communicating with Program Space (PS) memory. It also validates the address. |
| RDs | I/O | This pin should be pulled HIGH. |
| R/Ws | I/O | READ/WRITE SIGNAL (Secondary): R/W indicates transfer direction during access from Secondary Bus. Set HIGH for a Read access and LOW for a Write access. |
| WEs | I/O | This should be pulled HIGH. |
| WEMEMs | 0 | EXTERNAL MEMORY WRITE ENABLE: This is the memory Write Enable signal for external memory or peripherals on the Secondary Bus. |

Table 7. Miscellaneous Pins

| Pin Name | Pin Type | Pin Description |
|----------|----------|---|
| PRGM | Ι | PROGRAM ENABLE: This signal latches the Secondary Address Bus, As[15:0], on its rising edge. Typically, the PRGM is derived from RESET so that upon power-up, the state of As[15:0] is latched. As[15:8] determine the mode of internal SRAM decode and external memory decoding for the Secondary Bus. (See Register Descriptions for more detail.) |
| RDY | 0 | RDY is asserted whenever a Secondary Bus device is able to communicate with the TrailBlazer. RDY is programmed in Register 6 for various DS, IS, and PS memory address spaces. |
| XCVR | Ι | TRANSCEIVER MODE: This pin puts the TrailBlazer into a transceiver-like mode to support the processor's DMA through the TrailBlazer, e.g., when a Primary Bus wants to read the data on the Secondary Bus. In this mode, the XCVR is asserted, and the HOLDAs pin must be LOW, indicating no processors are on the Secondary Bus and the Primary Bus processor can read from the peripheral (or memory) from the Secondary Bus. (See Table 8, Bus Logic Truth Table for every possible combination.) |
| Vccq | Power | Power pins for I/O buffers of TrailBlazer. |
| GNDQ | Ground | Ground pins for I/O buffers of TrailBlazer. |
| Vcc | Power | Power pins for core of TrailBlazer. |
| GND | Ground | Ground pins for core of TrailBlazer |
| | | |

Note: 1. Typically, Vcc and Vccq are at 3.3 Volts.



Table 8. Bus Logic Truth Table

| XCVR | HOLDAp | HOLDAs | CSINT p | CSINT s | Action | CSMEMs[5:0] |
|------|--------|--------|----------------|----------------|--|---|
| 0 | 0 | Х | Х | Х | Transceiver R/W of Primary Bus by Secondary Bus (DMA). | CSMEMs[5:0] are not asserted. |
| 0 | 1 | Х | Х | Х | Transceiver R/W of Secondary Bus by Primary Bus (DMA). | CSMEMs[5:0] are not asserted. |
| 1 | 0 | Х | Х | 0 | R/\overline{W} of Internal SRAM by the Secondary Bus only. | CSMEMs[5:0] are not asserted |
| 1 | 1 | 0 | 0 | Х | R/\overline{W} of Internal SRAM by the Primary Bus only. | CSMEMs[5:0] are not asserted |
| 1 | 1 | 0 | 1 | Х | Primary Bus is in control. R/W from external or internal memory by Primary Bus. Control signals are forward to the Secondary Bus. | One of CSMEMs[5:0] asserted, depending on Ap[21:13] and PSp, DSp and ISp. |
| 1 | 1 | 1 | 0 | Х | R/W of Internal SRAM by the Primary Bus only. Control signals are not forwarded to the Secondary Bus. Secondary Bus access to internal memory denied. | CSMEMs[5:0] are not asserted |
| 1 | 1 | 1 | 1 | Х | R/W of internal SRAM by Primary Bus. Control signals are not forwarded to the Secondary Bus. Secondary Bus access to internal memory denied. | CSMEMs[5:0] are not asserted Internal SRAM selection is based on Ap[21:13], PSp and DSp |



Figure 4. TrailBlazer Interface with TMS320LC54x DSP.

REGISTER DEFINITIONS

A set of I/O addresses is reserved in the system and is used for TrailBlazer registers. As[15:8], when sampled by the rising edge of PRGM, determine the displacement of the starting address for the registers from location 00. A block of 256 addresses from the starting address is not available for the system. For example, if As[15:8] are sampled as 80 (i.e., As[15] pulled HIGH and As[14:8] pulled LOW) the starting I/O address is 8000h and I/O address 8000h to(80+255)h are reserved. Register 0 of TrailBlazer maps to 80 and Register 1 maps to 81, and so on. Currently, eight registers are defined and the remaining registers are reserved. All these registers will come up in their predetermined default states during power-up.

Upon power-up, the mode registers are loaded by sampling the As[15:0] (Secondary Address Bus). These bits are sampled on the rising edge of the PRGM. The PRGM pin can be controlled in several different ways. The simpliest method is to tie the pin to the RESET pulse of the processor. When PRGM is asserted, the entire chip will be tri-stated and, therefore, normal functionality cannot be maintained while this pin is active. If the system requires a "dynamic" decoding of the address bits, the XF pin from the processor can be used as a gate to the decoding latch.

Register 0

TrailBlazer SRAM Decode Register (default FFFF)

This register is used to set the base address for each of the two 32K x 16 blocks of TrailBlazer SRAM. Register 0 bits 6:0 are used for setting the starting address of a 32K block of SRAM and bit 7 determines if this block corresponds for

 \overline{PS} or \overline{DS} . When the $\overline{DS}/\overline{PS}$ bit is 0, the block is in \overline{DS} space and if 1, the block is in \overline{PS} space. Similarly, bits 15:8 programs the other 32K block.

| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
|-------|-----|-----|-----|-----|-----|-----|-----|-------|-----|-----|-----|-----|-----|-----|-----|
| DS/PS | A21 | A20 | A19 | A18 | A17 | A16 | A15 | DS/PS | A21 | A20 | A19 | A18 | A17 | A16 | A15 |

Register 1

CSMEMs0 Pin Select Register (default 0008)

This register is used to select the decoding for $\overline{\text{CSMEMs0}}$. The decoding is on an 8K boundary and can be programmed to respond to $\overline{\text{PS}}$, $\overline{\text{DS}}$, or $\overline{\text{IS}}$ address space or a combination thereof. The $\overline{\text{CSMEMs0}}$ can be used as a chip select pin for external memory or I/O device. Register 1 bits D[14:6] are used to set the base address for which the decode occurs, bits 5:3 determine the space, \overline{PS} , \overline{DS} , or \overline{IS} , and bits 2:0 determine the size of the decode. Bit 15 is a reserved bit. On power-up, the register will reset at the default state of 0008.

| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|-----|-----|-----|
| RSVD | A21 | A20 | A19 | A18 | A17 | A16 | A15 | A14 | A13 | PS | DS | ĪS | SZ2 | SZ1 | SZ0 |

Bits 14 to 6 correspond to address bits A21 to A13 and sets the starting address for which CSMEMs0 is active.

Bits 5 to 3 determine the space for which the pin will be active which are encoded as follows:

Bits 2 to 0 determine the size for which CSMEMs0 will be active starting from address as determined by bits 14 to 6. RSRVD bit should always be programmed to ZERO.

| PS | DS | ĪS | Space for which CSMEMs0 will be active |
|----|----|----|--|
| 0 | 0 | 0 | CSMEMs0 will not respond to any space, i.e., disabled. |
| 0 | 0 | 1 | $\overline{\text{CSMEMs0}}$ will be asserted for I/O space (when $\overline{\text{IS}}$ asserted) as determined by the starting address and size bits. |
| 0 | 1 | 0 | $\overline{\text{CSMEMs0}}$ will be asserted for DATA space (when $\overline{\text{DS}}$ asserted) as determined by the starting address and size bits. |
| 0 | 1 | 1 | $\overline{\text{CSMEMs0}}$ will be asserted for I/O or DATA space (when $\overline{\text{IS}}$ or $\overline{\text{DS}}$ asserted) as determined by the starting address and size bits. |
| 1 | 0 | 0 | $\overline{\text{CSMEMs0}}$ will be asserted for PROGRAM space (when $\overline{\text{PS}}$ asserted) as determined by the starting address and size bits. |
| 1 | 0 | 1 | $\overline{\text{CSMEMs0}}$ will be asserted for PROGRAM or I/O space (when $\overline{\text{PS}}$ or $\overline{\text{IS}}$ asserted) as determined by the starting address and size bits. |
| 1 | 1 | 0 | $\overline{\text{CSMEMs0}}$ will be asserted for PROGRAM or DATA space (when $\overline{\text{PS}}$ or $\overline{\text{DS}}$ asserted) as determined by the starting address and size bits. |
| 1 | 1 | 1 | CSMEMs0 will be asserted for any space as determined by the starting address and size bits. |

| SZ2 | SZ1 | SZ0 | Size for which CSMEMs0 will be active starting from the programmed starting address. The sizes are in the increments of 8K Words. |
|-----|-----|-----|---|
| 0 | 0 | 0 | CSMEMs0 will be asserted for starting address to starting address + 8K |
| 0 | 0 | 1 | CSMEMs0 will be asserted for starting address to starting address + 16K |
| 0 | 1 | 0 | CSMEMs0 will be asserted for starting address to starting address + 32K |
| 0 | 1 | 1 | CSMEMs0 will be asserted for starting address to starting address + 64K |
| 1 | 0 | 0 | CSMEMs0 will be asserted for starting address to starting address + 128K |
| 1 | 0 | 1 | CSMEMs0 will be asserted for starting address to starting address + 256K |
| 1 | 1 | 0 | CSMEMs0 will be asserted for starting address to starting address + 512K |
| 1 | 1 | 1 | CSMEMs0 will be asserted for starting address to starting address + 1024K |

CSMEMs1 Pin Select Register (default 0048):

This register is used to select the decoding for $\overline{\text{CSMEMs1}}$. The decoding is on an 8K boundary and can be programmed to respond to $\overline{\text{PS}}$, $\overline{\text{DS}}$, or $\overline{\text{IS}}$ address space or a combination thereof. The $\overline{\text{CSMEMs0}}$ can be used as chip select pin for external memory or I/O device. The bit descriptions and programmability are identical to Register 1, except that the default is 0048. Refer to $\overline{\text{CSMEMs0}}$ bit descriptions.

| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
|----------|-----|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|-----|-----|-----|
| RSVD | A21 | A20 | A19 | A18 | A17 | A16 | A15 | A14 | A13 | PS | DS | ĪS | SZ2 | SZ1 | SZ0 |

CSMEMs2 Pin Select Register (default 0088):

This register is used to select the decoding for $\overline{\text{CSMEMs2}}$. The decoding is on an 8K boundary and can be programmed to respond to $\overline{\text{PS}}$, $\overline{\text{DS}}$, or $\overline{\text{IS}}$ address space or a combination thereof. The $\overline{\text{CSMEMs2}}$ can be used as a chip select pin for external memory or I/O device. The bit descriptions and programmability are identical to Register 1, except that the default is 0088. Refer to CSMEMs0 bit descriptions.

| 15 | 1 | 4 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
|-----|------|----|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|-----|-----|-----|
| RSV | D A2 | 21 | A20 | A19 | A18 | A17 | A16 | A15 | A14 | A13 | PS | DS | ĪS | SZ2 | SZ1 | SZ0 |

Register 4

CSMEMs3 Pin Select Register (default 00C8):

This register is used to select the decoding for $\overline{\text{CSMEMs3}}$. The decoding is on an 8K boundary and can be programmed to respond to $\overline{\text{PS}}$, $\overline{\text{DS}}$, or $\overline{\text{IS}}$ address space or a combination thereof. The $\overline{\text{CSMEMs3}}$ can be used as a chip select pin for external memory or I/O device The bit descriptions and programmability are identical to Register 1, except that the default is 00C8. Refer to CSMEMs0 bit descriptions.

| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|----|----|----|-----|-----|-----|
| RSVD | A21 | A20 | A19 | A18 | A17 | A16 | A15 | A14 | A13 | PS | DS | ĪS | SZ2 | SZ1 | SZ0 |

CSMEMs4 Pin Select Register (default 0112):

This register is used to select the decoding for $\overline{\text{CSMEMs4}}$. The decoding is on an 8K boundary and can be programmed to respond to $\overline{\text{DS}}$ or $\overline{\text{IS}}$ address space or a combination thereof. The $\overline{\text{CSMEMs4}}$ can be used as a chip

select pin for external memory or I/O device. The bit descriptions and programmability are identical to Register 1, except that the default is 0112. Refer to CSMEMs0 bit descriptions.

| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
|------|------|------|------|------|------|------|-----|-----|-----|------|----|----|------|-----|-----|
| RSVD | A15 | A14 | A13 | RSVD | DS | ĪS | RSVD | SZ1 | SZ0 |

| DS | ĪS | Space for which CSMEMs4 will be active |
|-----|-----|---|
| 0 | 0 | CSMEMs0 will not respond to any space, i.e., disabled. |
| 0 | 1 | $\overline{\text{CSMEMs0}}$ will go active for I/O space (when $\overline{\text{IS}}$ is active) as determined by the starting address and size bits. |
| 1 | 0 | $\overline{\text{CSMEMs0}}$ will go active for DATA space (when $\overline{\text{DS}}$ is active) as determined by the starting address and size bits. |
| 1 | 1 | $\overline{\text{CSMEMs0}}$ will go active for I/O or DATA space (when $\overline{\text{IS}}$ or $\overline{\text{DS}}$ is active) as determined by the starting address and size bits. |
| | | |
| | | Size for which CSMEMs4 will be active starting from the programmed starting |
| SZ1 | SZ0 | address. The sizes are in the increments of 8K Words. |
| 0 | 0 | CSMEMs0 will be active for starting address to starting address + 8K |
| 0 | 1 | CSMEMs0 will be active for starting address to starting address + 16K |
| 1 | 0 | CSMEMs0 will be active for starting address to starting address + 32K |
| 1 | 1 | CSMEMs0 will be active for starting address to starting address + 64K |

CSMEMs5 Pin Select Register

This is a negative decode of the other chip selects, i.e., it is active when $\overline{\text{CSMEMs}}[4{:}0]$ are HIGH.

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RDY Generation Logic and Write Control Register (default FFFF):

Register 6 is the signal RDY generation register for \overline{PS} , \overline{DS} , and \overline{IS} space. \overline{PS} [4:0] (bits 4:0) determine the number of clocks after which the RDY is generated whenever \overline{PS} goes active. Similarly, \overline{DS} [4:0] are used to program the RDY generation in number of clocks when \overline{DS} is active and

IS[4:0] are used to generate the RDY for I/O cycles. The RDY signal could be used to delay an access to an external device on the Secondary Bus. Please note that if an external RDY has to be sampled by the processor, the processor's access should be programmed for at least two wait states.

| 15 | 14 | 13 | 12 | 11 | 10 | 09 | 08 | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
|----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| WE | IS4 | IS3 | IS2 | IS1 | IS0 | DS4 | DS3 | DS2 | DS1 | DS0 | PS4 | PS3 | PS2 | PS1 | PS0 |

Notes:

1. The above registers are read/writable.

2. No CSMEMs will be active if the I/O address of the registers matches with any CSMEMs decodes.

Table 9. Register Accessibility

| Register Number | Register Address | Register Compare Data | Chip Select |
|-----------------|------------------|--------------------------|---------------|
| 0 | Ap[15:8] = SA | Ap[21:15]; DSp; PSp | Internal SRAM |
| 1 | Ap[15:8] = SA+1 | Ap[21:13]; DSp; PSp; Isp | CSMEMs0 |
| 2 | Ap[15:8] = SA+2 | Ap[21:13]; DSp; PSp; ISp | CSMEMs1 |
| 3 | Ap[15:8] = SA+3 | Ap[21:13]; DSp; PSp; ISp | CSMEMs2 |
| 4 | Ap[15:8] = SA+4 | Ap[21:13]; DSp; PSp; ISp | CSMEMs3 |
| 5 | Ap[15:8] = SA+5 | Ap[15:13]; | CSMEMs4 |
| 6 | Ap[15:8] = SA+6 | DSp; PSp; ISp | CSMEMs5 |

Notes:

- 1. SA = Starting address as defined by As[15:8] on the rising edge of \overline{PRGM} .
- 2. Register write data: Dp[15:0].
- 3. Register write control: IOSTRBp (R/Wp) ISp. Some processors, including TI TMS320LC54X, have three major memory spaces. Program Space (PS signal); Data space (DS signal); and I/O space (IS signal). The TrailBlazer's internal SRAM has two 32KB regions that are restricted to either DS or PS space. Register 0 controls the decoding for the internal SRAM. Registers 1 through 5 control the address decoding for the external devices on the Secondary Bus. For processors that have A15 as the MSB, the three memory spaces are restricted to 64MB each. However, the registers do allow for programmable address ranges in 8KB blocks. For processors with A[21:16] as the MSB, there is a 4MB maximum address space that can be partitioned by programming Registers 1 to 5.

ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings

| Symbol | Parameters | Ratings | Units |
|--------|-------------------------|-------------|-------|
| Vcc | Supply Voltage | -0.4 to 4.1 | V |
| Tstg | Storage Temperature | -65 to +150 | °C |
| Рт | Power Dissipation | 1.5 | W |
| Ιουτ | DC Output Current (Low) | 20 | mA |

Note:

1. Stresses above the absolute maximum ratings can cause permanent damage to the device.

Operating Range

| Range | Ambient Temperature | Vcc |
|------------|---------------------|--------------|
| Commercial | 0°C to +70°C | 3.0V to 3.6V |
| Industrial | –40°C to +85°C | 3.0V to 3.6V |

DC Electrical Characteristics (Over Operating Range)

| Symbol | Parameter | Test Conditona | Min | Max | Units |
|--------|----------------------------------|---|-----|-----------|-------|
| Vон | Output High Voltage | Vcc = Min., Iон = -4.0 mA | 2.4 | — | V |
| Vol | Output Low Voltage | Vcc = Min., IoL = 8.0 mA | — | 0.4 | V |
| Vін | Input High Voltage | | 2.2 | Vcc + 0.3 | V |
| VIL | Input Low Voltage ⁽¹⁾ | | 0.3 | 0.8 | V |
| lu | Input Leakage | $GND \le VIN \le Vcc$ | -2 | 2 | μΑ |
| Ilo | Output Leakage | $GND \le V_{OUT} \le V_{CC}$, Outputs Disabled | -2 | 2 | μA |

Note:

1. VIL(min) = -2.0V for pulse width less than 10 μ s.

AC Specification: 25 pF Load Internal SRAM Cycles Primary Bus Master

| | | -8 | -9 | -10 | |
|-----|--|---------|---------|---------|-------|
| T# | Parameter | Min Max | Min Max | Min Max | Units |
| T1 | Data Access Time from RDp LOW | — 5 | — 5.5 | — 6 | ns |
| T2 | Data Access Time from Address Valid (5X CPU) | — 8 | — 9 | — 10 | ns |
| Т3 | Data Access Time from Address (54X CPU) | — 8 | — 9 | — 10 | ns |
| T4 | Data Access Time from PS/DS/IS | — 8 | — 9 | — 10 | ns |
| T5 | Data Access Time from MSTRBp | — 5 | — 5.5 | — 6 | ns |
| T6 | Data Access Time from CSINTp | — 6 | — 6.5 | — 7 | ns |
| T7 | Address to WEp Valid | 1 — | 1 — | 1 — | ns |
| Т8 | Write Data Setup Time before WEP HIGH | 4 — | 4 — | 4 — | ns |
| Т9 | Write Data Hold Time after WEP HIGH | 0 — | 0 — | 0 — | ns |
| T10 | Write Data Setup Time before MSTRB HIGH | 4 — | 4 — | 4 — | ns |
| T11 | Write Data Hold Time after MSTRB HIGH | 0 — | 0 — | 0 — | ns |



Primary Bus Master Local Mode

| T# | Parameter | Min | Max | Min | Max | Min | Max | Units |
|-----|---|-----|-----|-----|-----|-----|-----|-------|
| T12 | MSTRBp / IOSTRBp Active to OEMEMp Active Delay | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| T13 | WEp Active to WMEMp Active Delay | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| T14 | MSTRBp / IOSTRBp Active to WEMEMp Delay | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| T15 | PSp / DSp / ISp Active to CSMEMp[5:0] Delay | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |

Primary Bus Master Remote Mode (Non-XCVR Mode)

| T# | Parameter | Min | Max | Min | Max | Min | Max | Units |
|-----|--|-----|-----|-----|-----|-----|-----|-------|
| T16 | $\underline{R}/\overline{W}_p, \overline{PSp}, \overline{DSp}, \overline{ISp}, \overline{MSTRBp}, \overline{IOSTRBp}, \overline{RDp},$ | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| | WEp Delay to corresponding control signals on | | | | | | | |
| | Secondary Bus | | | | | | | |
| T17 | Dp to Ds Write Mode (R/W=0) | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| T18 | Ds to Dp Read Mode (R/W=1) | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| T19 | MSTRBp / IOSTRBp Active to OEMEMs Active Delay | / 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| T20 | WEP Active to WEMEMs Active Delay | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| T21 | MSTRB / IOSTRBP Active to WEMEMs Delay | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| T22 | PSp / DSp / ISp Active to CSMEMs[5:0] Delay | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |

Primary Bus Master XCVR Mode

| T# | Parameter | Min | Max | Min | Max | Min | Max | Units |
|-----|--|-----|-----|-----|-----|-----|-----|-------|
| T23 | R/Wp, PSp, DSp, ISp, MSTRBp, IOSTRBp, RDp, WEp Delay to corresponding control signals on Secondary Bus | 0 | 3 | 0 | 3 | 0 | 3 | ns |
| T24 | Ds to Dp Delay (R/W=HIGH) Read from Secondary Bus | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |
| T25 | Dp to Ds Delay ($R/\overline{W}=0$) Write to Secondary Bus | 0 | 5 | 0 | 5.5 | 0 | 6 | ns |

Note:

1. In the above list, the timing parameters are specified with the Primary Bus Master as the basis.

READ CYCLE 1: Primary Bus Internal SRAM READ Cycle Timing (TI TMS320LC5x/C5x DSP)



READ CYCLE 2: Primary Bus Internal SRAM READ Cycle Timing (TI TMS320LC54x/C54x DSP)





WRITE CYCLE 1: Primary Bus Internal SRAM WRITE Cycle Timing (TI TMS320LC5x/C5x DSP)



Note:

1. All timings are at zero wait state. However, external Writes require two cycles to prevent external bus conflicts. (Refer to the TI TMS320LC54x/C54x Databook.)

WRITE CYCLE 2: Primary Bus Internal SRAM WRITE Cycle Timing (TI TMS320LC54x/C54x DSP)



Note:

1. All timings are at zero wait state. However, external Writes require two cycles to prevent external bus conflicts. (Refer to the TI TMS320LC54x/C54x Databook.)

Primary Bus Control Signals for OEMEMp, WEMEMp, and CSMEMp[5:0]



MSTRBp, IOSTRBp, R/Wp, RDp, PSp, DSp, ISp WEp, Dp OEMEMp, WEMEMp, WEMEMs, CSMEMp, Ds

Note:

1. Tx2 = Timings from T16 through T25.

ORDERING INFORMATION

Commercial Range: 0°C to +70°C

| Speed (ns) | Order Part Number | Package |
|------------|-------------------|---------|
| 8 | IS82C600-8B | PBGA |
| 9 | IS82C600-9B | PBGA |
| 10 | IS82C600-10B | PBGA |

ORDERING INFORMATION

Industrial Range: –40°C to +85°C

| Speed (ns) | Order Part Number | Package |
|------------|-------------------|---------|
| 8 | IS82C600-8BI | PBGA |
| 9 | IS82C600-9BI | PBGA |
| 10 | IS82C600-10BI | PBGA |

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