

# Thyristor Modules

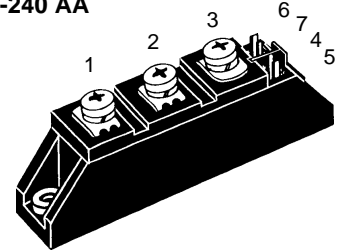
## Thyristor/Diode Modules

$$I_{TRMS} = 2 \times 180 \text{ A}$$

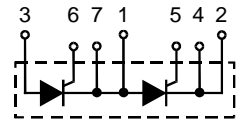
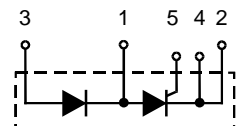
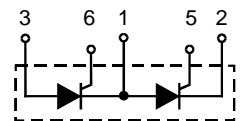
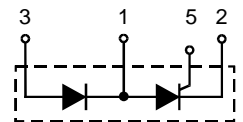
$$I_{TAVM} = 2 \times 116 \text{ A}$$

$$V_{RRM} = 800-1800 \text{ V}$$

| $V_{RSM}$<br>$V_{DSM}$<br>V | $V_{RRM}$<br>$V_{DRM}$<br>V | Type           |                | Version 1      |                | Version 8 |  |
|-----------------------------|-----------------------------|----------------|----------------|----------------|----------------|-----------|--|
| 900                         | 800                         | MCC 95-08io1 B | --             | MCC 95-08io8 B | MCD 95-08io8 B |           |  |
| 1300                        | 1200                        | MCC 95-12io1 B | MCD 95-12io1 B | MCC 95-12io8 B | MCD 95-12io8 B |           |  |
| 1500                        | 1400                        | MCC 95-14io1 B | --             | MCC 95-14io8 B | MCD 95-14io8 B |           |  |
| 1700                        | 1600                        | MCC 95-16io1 B | MCD 95-16io1 B | MCC 95-16io8 B | MCD 95-16io8 B |           |  |
| 1900                        | 1800                        | MCC 95-18io1 B | --             | MCC 95-18io8 B | MCD 95-18io8 B |           |  |
| 1500                        | 1400                        | MCC 95-16io1   |                |                |                |           |  |
| 1700                        | 1600                        | MCC 95-18io1   |                |                |                |           |  |

**TO-240 AA**


| Symbol   | Test Conditions   | Maximum Ratings   |  |  |
|--|---|---|--|--|
| $I_{TRMS}^1, I_{FRMS}$<br>$I_{TAVM}^2, I_{FAVM}$ | $T_{VJ} = T_{VJM}$<br>$T_C = 85^\circ\text{C}; 180^\circ \text{ sine}$  | 180   | A  |  |
| $I_{TSM}^3, I_{FSM}$                             | $T_{VJ} = 45^\circ\text{C};$<br>$V_R = 0$<br>$t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$  | 2250<br>2400  | A<br>A                                       |  |
| $\int i^2 dt$                                    | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0$<br>$t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$   | 25 300<br>23 900  | $\text{A}^2\text{s}$<br>$\text{A}^2\text{s}$ |  |
|  | $T_{VJ} = T_{VJM}$<br>$V_R = 0$<br>$t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$  | 20 000<br>19 100  | $\text{A}^2\text{s}$<br>$\text{A}^2\text{s}$ |  |
| $(di/dt)_{cr}$                                   | $T_{VJ} = T_{VJM}$<br>$f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$<br>$V_D = 2/3 V_{DRM}$<br>$I_G = 0.45 \text{ A}$<br>$di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | repetitive, $I_T = 250 \text{ A}$<br><br>non repetitive, $I_T = I_{TAVM}$ | 150<br>500                                   | $\text{A}/\mu\text{s}$<br>$\text{A}/\mu\text{s}$ |
| $(dv/dt)_{cr}$                                   | $T_{VJ} = T_{VJM}$<br>$R_{GK} = \infty$ ; method 1 (linear voltage rise)  | $V_{DR} = 2/3 V_{DRM}$  | 1000   | $\text{V}/\mu\text{s}$                           |
| $P_{GM}$   | $T_{VJ} = T_{VJM}$<br>$I_T = I_{TAVM}$  | $t_p = 30 \mu\text{s}$<br>$t_p = 300 \mu\text{s}$                         | 10<br>5                                      | W<br>W   |
| $P_{GAV}$  |   |   | 0.5  | W  |
| $V_{RGM}$  |   |   | 10   | V  |
| $T_{VJ}$   |   |   | -40...+125                                   | $^\circ\text{C}$                                 |
| $T_{VJM}$  |   |   | 125  | $^\circ\text{C}$                                 |
| $T_{stg}$  |   |   | -40...+125                                   | $^\circ\text{C}$                                 |
| $V_{ISOL}$                                       | 50/60 Hz, RMS   | $t = 1 \text{ min}$   | 3000   | V~   |
|  | $I_{ISOL} \leq 1 \text{ mA}$  | $t = 1 \text{ s}$   | 3600   | V~   |
| $M_d$  | Mounting torque (M5)  |   | 2.5-4.0/22-35                                | Nm/lb.in.  |
|  | Terminal connection torque (M5)   |   | 2.5-4.0/22-35                                | Nm/lb.in.  |
| Weight   | Typical including screws  |   | 90   | g  |

**MCC**  
**Version 1**

**MCD**  
**Version 1**

**MCC**  
**Version 8**

**MCD**  
**Version 8**

**Features**

- International standard package, JEDEC TO-240 AA
- Direct copper bonded  $\text{Al}_2\text{O}_3$  -ceramic base plate
- Planar passivated chips
- Isolation voltage 3600 V~
- UL registered, E 72873
- Gate-cathode twin pins for version 1

**Applications**

- DC motor control
- Softstart AC motor controller
- Light, heat and temperature control

**Advantages**

- Space and weight savings
- Simple mounting with two screws
- Improved temperature and power cycling
- Reduced protection circuits

Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated. IXYS reserves the right to change limits, test conditions and dimensions

| Symbol             | Test Conditions  | Characteristic Values            |
|--------------------|--|----------------------------------|
| $I_{RRM}, I_{DRM}$ | $T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$   | 5 mA                             |
| $V_T, V_F$         | $I_T, I_F = 300 \text{ A}; T_{VJ} = 25^\circ\text{C}$  | 1.5 V                            |
| $V_{T0}$           | For power-loss calculations only ( $T_{VJ} = 125^\circ\text{C}$ )  | 0.8 V                            |
| $r_T$              |  | 2.4 mΩ                           |
| $V_{GT}$           | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$   | 2.5 V                            |
|                    | $T_{VJ} = -40^\circ\text{C}$   | 2.6 V                            |
| $I_{GT}$           | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$   | 150 mA                           |
|                    | $T_{VJ} = -40^\circ\text{C}$   | 200 mA                           |
| $V_{GD}$           | $T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$  | 0.2 V                            |
| $I_{GD}$           |  | 10 mA                            |
| $I_L$              | $T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}; V_D = 6 \text{ V}$<br>$I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$   | 450 mA                           |
| $I_H$              | $T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$  | 200 mA                           |
| $t_{gd}$           | $T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$<br>$I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$   | 2 μs                             |
| $t_q$              | $T_{VJ} = T_{VJM}; I_T = 150 \text{ A}; t_p = 200 \mu\text{s}; -di/dt = 10 \text{ A}/\mu\text{s}$ typ.<br>$V_R = 100 \text{ V}; dv/dt = 20 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$ | 185 μs                           |
| $Q_S$              | $T_{VJ} = T_{VJM}; I_T, I_F = 50 \text{ A}; -di/dt = 6 \text{ A}/\mu\text{s}$  | 170 μC                           |
| $I_{RM}$           |  | 45 A                             |
| $R_{thJC}$         | per thyristor/diode; DC current per module   | 0.22 K/W                         |
| $R_{thJK}$         | per thyristor/diode; DC current per module   | 0.11 K/W<br>0.42 K/W<br>0.21 K/W |
|                    | other values see Fig. 8/9  |                                  |
| $d_s$              | Creepage distance on surface   | 12.7 mm                          |
| $d_A$              | Strike distance through air  | 9.6 mm                           |
| $a$                | Maximum allowable acceleration   | 50 m/s <sup>2</sup>              |

Optional accessories for module-type MCC 95 version 1 B

Keyed gate/cathode twin plugs with wire length = 350 mm, gate = yellow, cathode = red

Type ZY 200L (L = Left for pin pair 4/5) } UL 758, style 1385,  
 Type ZY 200R (R = right for pin pair 6/7) } CSA class 5851, guide 460-1-1

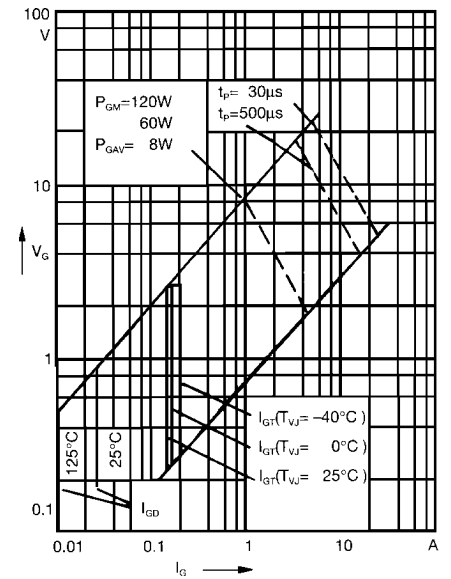


Fig. 1 Gate trigger characteristics

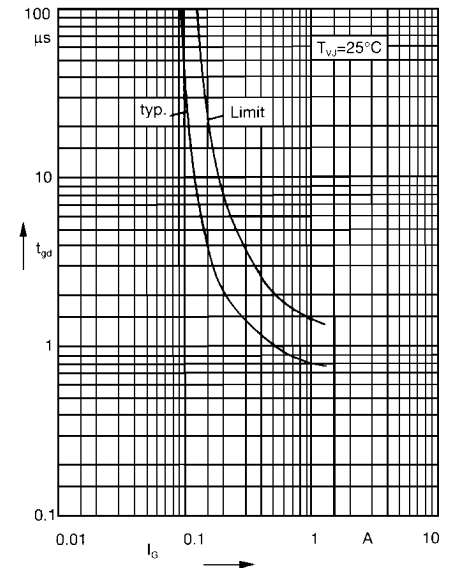
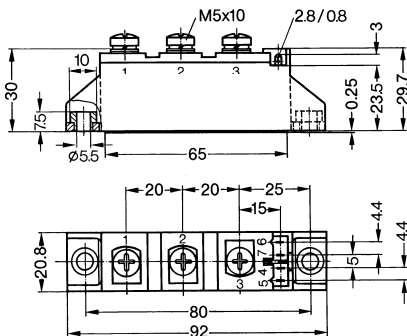


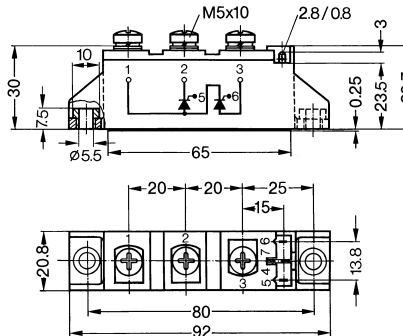
Fig. 2 Gate trigger delay time

**Dimensions in mm (1 mm = 0.0394")**

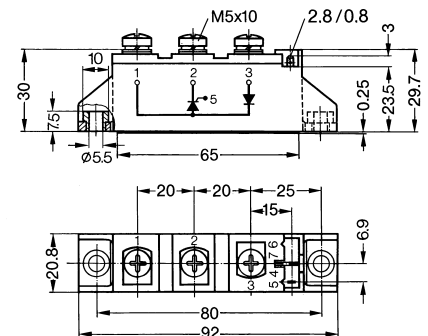
**MCC / MCD Version 1 B**



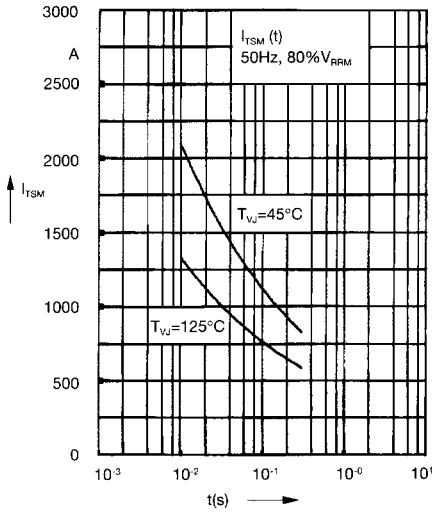
**MCC Version 8 B**



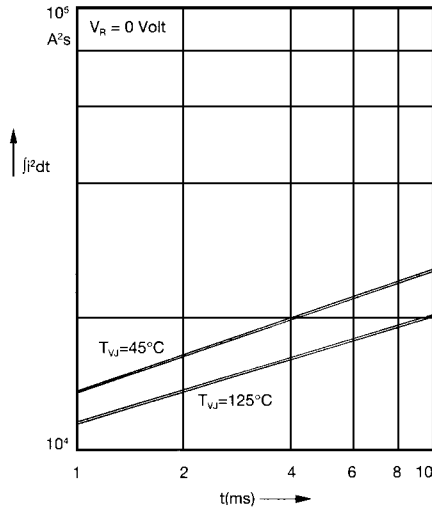
**MCD Version 8 B**



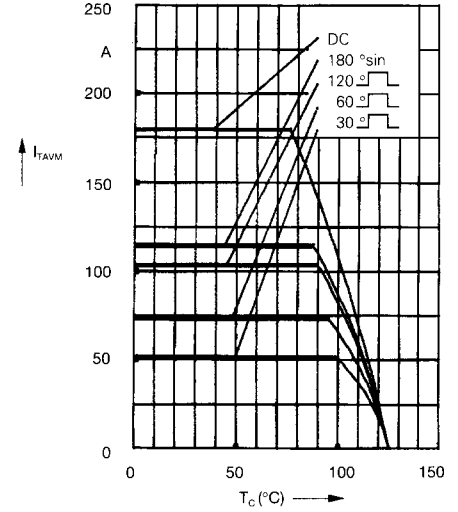
Version 1 or 8 without B in typ designation = without insert in mountig holes



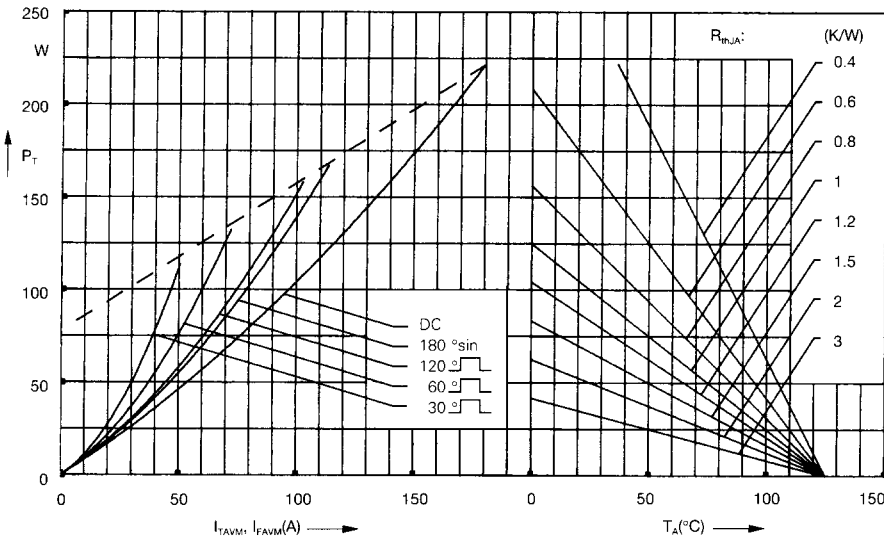
**Fig. 3 Surge overload current**  
 $I_{TSM}$ ,  $I_{FSM}$ : Crest value,  $t$ : duration



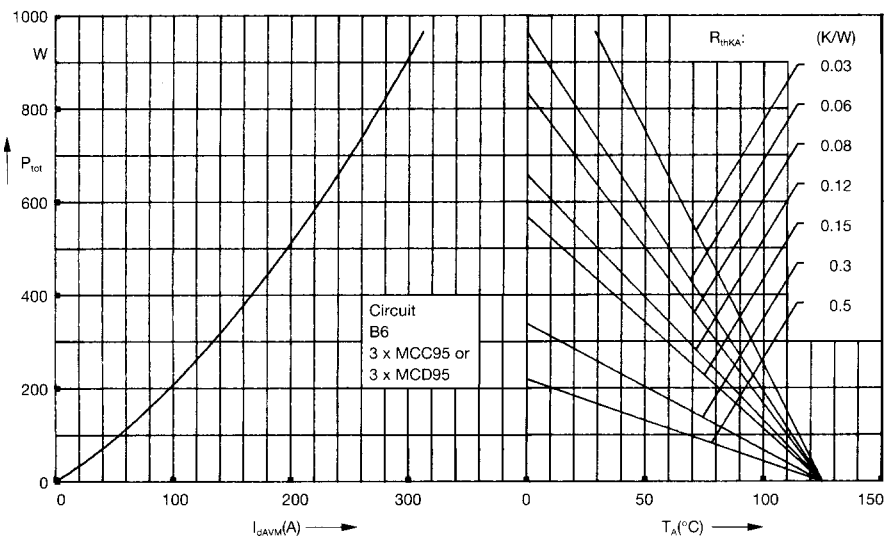
**Fig. 4  $\int i^2 dt$  versus time (1-10 ms)**



**Fig. 4a Maximum forward current at case temperature**



**Fig. 5 Power dissipation versus on-state current and ambient temperature (per thyristor or diode)**



**Fig. 6 Three phase rectifier bridge: Power dissipation versus direct output current and ambient temperature**

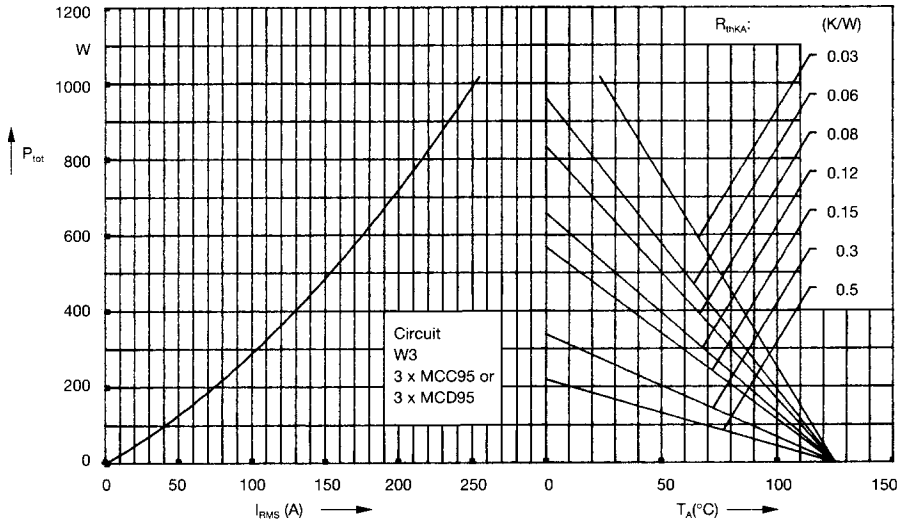


Fig. 7 Three phase AC-controller: Power dissipation versus RMS output current and ambient temperature

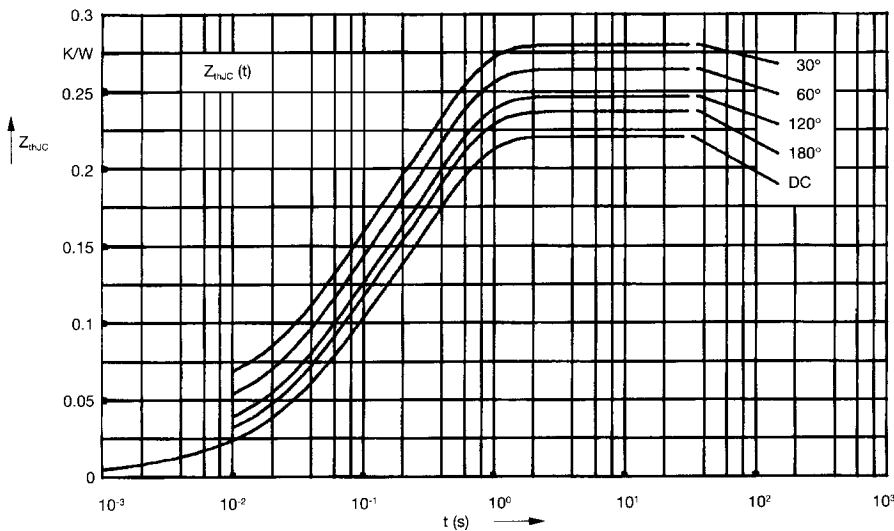


Fig. 8 Transient thermal impedance junction to case (per thyristor or diode)

$R_{thJC}$  for various conduction angles d:

| d    | $R_{thJC}$ (K/W) |
|------|------------------|
| DC   | 0.22             |
| 180° | 0.23             |
| 120° | 0.25             |
| 60°  | 0.27             |
| 30°  | 0.28             |

Constants for  $Z_{thJC}$  calculation:

| i | $R_{thi}$ (K/W) | $t_i$ (s) |
|---|-----------------|-----------|
| 1 | 0.0066          | 0.0019    |
| 2 | 0.0678          | 0.0477    |
| 3 | 0.1456          | 0.344     |

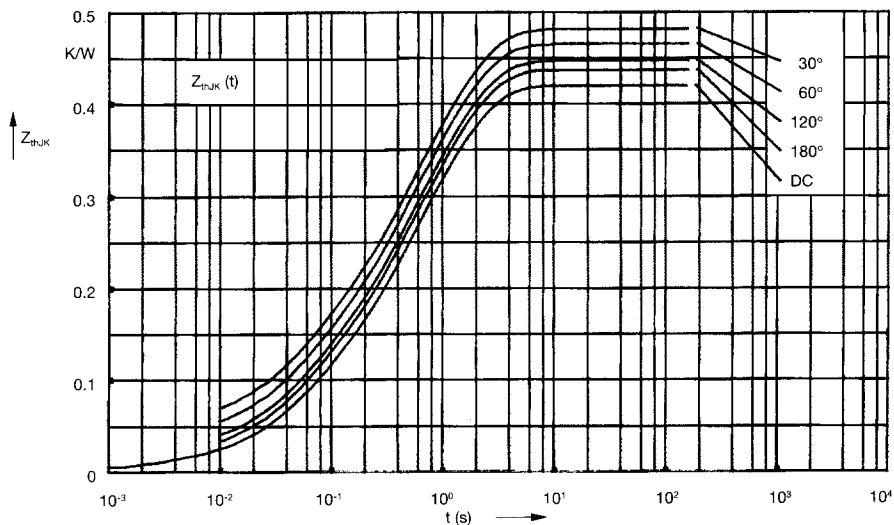


Fig. 9 Transient thermal impedance junction to heatsink (per thyristor or diode)

$R_{thJK}$  for various conduction angles d:

| d    | $R_{thJK}$ (K/W) |
|------|------------------|
| DC   | 0.42             |
| 180° | 0.43             |
| 120° | 0.45             |
| 60°  | 0.47             |
| 30°  | 0.48             |

Constants for  $Z_{thJK}$  calculation:

| i | $R_{thi}$ (K/W) | $t_i$ (s) |
|---|-----------------|-----------|
| 1 | 0.0066          | 0.0019    |
| 2 | 0.0678          | 0.0477    |
| 3 | 0.1456          | 0.344     |
| 4 | 0.2             | 1.32      |