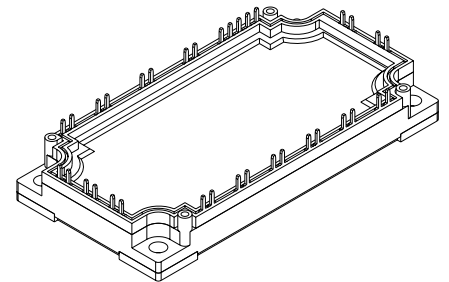
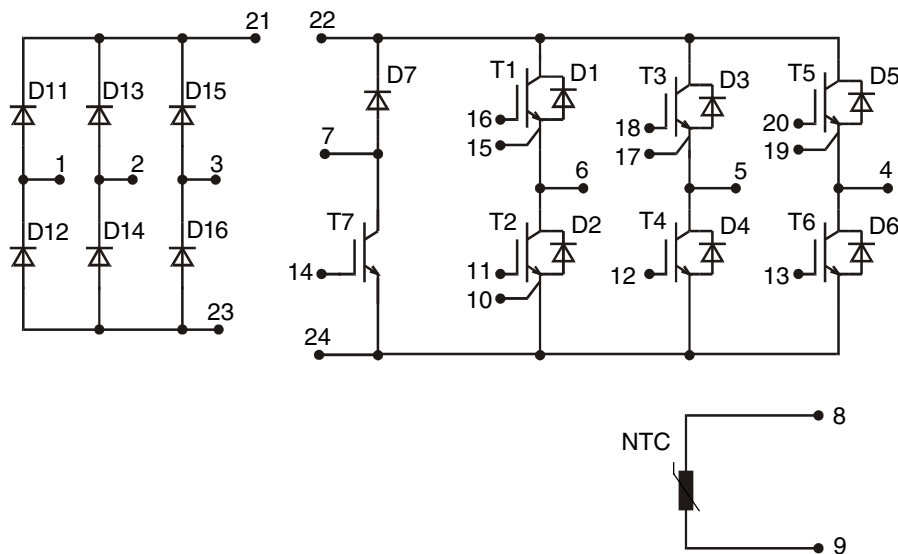


## Converter - Brake - Inverter Module (CBI3)



Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600 \text{ V}$	$V_{CES} = 600 \text{ V}$	$V_{CES} = 600 \text{ V}$
$I_{FAVM} = 60 \text{ A}$	$I_{C25} = 35 \text{ A}$	$I_{C25} = 75 \text{ A}$
$I_{FSM} = 500 \text{ A}$	$V_{CE(sat)} = 2.1 \text{ V}$	$V_{CE(sat)} = 1.9 \text{ V}$

### Input Rectifier D11 - D16

Symbol	Conditions	Maximum Ratings	
$V_{RRM}$		1600	V
$I_{FAV}$	$T_C = 80^\circ\text{C}$ ; sine 180°	42	A
$I_{DAVM}$	$T_C = 80^\circ\text{C}$ ; rectangular; $d = 1/3$ ; bridge	120	A
$I_{FSM}$	$T_{VJ} = 25^\circ\text{C}$ ; $t = 10 \text{ ms}$ ; sine 50 Hz	500	A
$P_{tot}$	$T_C = 25^\circ\text{C}$	120	W

Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_F$	$I_F = 50 \text{ A}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.2 1.2	1.4 V V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.6	0.02 mA mA
$R_{thJC}$	(per diode)			1.06 K/W

### Application: AC motor drives with

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

### Features

- High level of integration - only one power semiconductor module required for the whole drive
- NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

**Output Inverter T1 - T6**

Symbol	Conditions	Maximum Ratings	
$V_{CES}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	600	V
$V_{GES}$	Continuous	$\pm 20$	V
$I_{C25}$	$T_C = 25^{\circ}\text{C}$	75	A
$I_{C80}$	$T_C = 80^{\circ}\text{C}$	50	A
<b>RBSOA</b>	$V_{GE} = \pm 15\text{ V}$ ; $R_G = 22\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$	$I_{CM} = 100$ $V_{CEK} \leq V_{CES}$	A
$t_{SC}$ <b>(SCSOA)</b>	$V_{CE} = V_{CES}$ ; $V_{GE} = \pm 15\text{ V}$ ; $R_G = 22\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	$\mu\text{s}$
$P_{tot}$	$T_C = 25^{\circ}\text{C}$	250	W

Symbol	Conditions	Characteristic Values		
		$(T_{VJ} = 25^{\circ}\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 50\text{ A}$ ; $V_{GE} = 15\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	1.9	2.3	V
		2.1		V
$V_{GE(th)}$	$I_C = 1\text{ mA}$ ; $V_{GE} = V_{CE}$	4.5	6.5	V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	0.7	0.8	mA mA
$I_{GES}$	$V_{CE} = 0\text{ V}$ ; $V_{GE} = \pm 20\text{ V}$		200	nA
$t_{d(on)}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 300\text{ V}$ ; $I_C = 50\text{ A}$ $V_{GE} = \pm 15\text{ V}$ ; $R_G = 22\ \Omega$	50		ns
$t_r$		60		ns
$t_{d(off)}$		300		ns
$t_f$		30		ns
$E_{on}$		2.3		mJ
$E_{off}$		1.7		mJ
$C_{ies}$	$V_{CE} = 25\text{ V}$ ; $V_{GE} = 0\text{ V}$ ; $f = 1\text{ MHz}$	2.8		nF
$Q_{Gon}$	$V_{CE} = 300\text{ V}$ ; $V_{GE} = 15\text{ V}$ ; $I_C = 50\text{ A}$	120		nC
$R_{thJC}$	(per IGBT)		0.5	K/W

**Output Inverter D1 - D6**

Symbol	Conditions	Maximum Ratings	
$I_{F25}$	$T_C = 25^{\circ}\text{C}$	72	A
$I_{F80}$	$T_C = 80^{\circ}\text{C}$	45	A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 50\text{ A}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	1.5	1.7	V
		1.3		V
$I_{RM}$	$I_F = 30\text{ A}$ ; $di_F/dt = -500\text{ A}/\mu\text{s}$ ; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 300\text{ V}$ ; $V_{GE} = 0\text{ V}$	25		A
$t_{rr}$		90		ns
$R_{thJC}$	(per diode)		1.19	K/W

**Brake Chopper T7**

Symbol	Conditions	Maximum Ratings	
$V_{CES}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	600	V
$V_{GES}$	Continuous	$\pm 20$	V
$I_{C25}$	$T_C = 25^{\circ}\text{C}$	35	A
$I_{C80}$	$T_C = 80^{\circ}\text{C}$	25	A
<b>RBSOA</b>	$V_{GE} = \pm 15\text{ V}$ ; $R_G = 47\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100\ \mu\text{H}$	$I_{CM} = 40$ $V_{CEK} \leq V_{CES}$	A
$t_{SC}$ <b>(SCSOA)</b>	$V_{CE} = V_{CES}$ ; $V_{GE} = \pm 15\text{ V}$ ; $R_G = 47\ \Omega$ ; $T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	$\mu\text{s}$
$P_{tot}$	$T_C = 25^{\circ}\text{C}$	125	W

Symbol	Conditions	Characteristic Values ( $T_{VJ} = 25^{\circ}\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 25\text{ A}$ ; $V_{GE} = 15\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	2.1	2.6	V
		2.4		V
$V_{GE(th)}$	$I_C = 0.5\text{ mA}$ ; $V_{GE} = V_{CE}$	4.5	6.5	V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	0.3	0.5	mA mA
$I_{GES}$	$V_{CE} = 0\text{ V}$ ; $V_{GE} = \pm 20\text{ V}$		200	nA
$t_{d(on)}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 300\text{ V}$ ; $I_C = 25\text{ A}$ $V_{GE} = \pm 15\text{ V}$ ; $R_G = 47\ \Omega$		50	ns
$t_r$			60	ns
$t_{d(off)}$			300	ns
$t_f$			30	ns
$E_{on}$			1.15	mJ
$E_{off}$			0.85	mJ
$C_{ies}$	$V_{CE} = 25\text{ V}$ ; $V_{GE} = 0\text{ V}$ ; $f = 1\text{ MHz}$	1.1		nF
$Q_{Gon}$	$V_{CE} = 300\text{ V}$ ; $V_{GE} = 15\text{ V}$ ; $I_C = 25\text{ A}$	65		nC
$R_{thJC}$			1	K/W

**Brake Chopper D7**

Symbol	Conditions	Maximum Ratings	
$V_{RRM}$	$T_{VJ} = 25^{\circ}\text{C}$ to $150^{\circ}\text{C}$	600	V
$I_{F25}$	$T_C = 25^{\circ}\text{C}$	22	A
$I_{F80}$	$T_C = 80^{\circ}\text{C}$	15	A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 25\text{ A}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	2.2	2.5	V
		1.7		V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	0.07	0.06	mA mA
$I_{RM}$	$I_F = 10\text{ A}$ ; $di_F/dt = -400\text{ A}/\mu\text{s}$ ; $T_{VJ} = 125^{\circ}\text{C}$ $V_R = 300\text{ V}$		11	A
$t_{rr}$			80	ns
$R_{thJC}$			3.2	K/W

### Temperature Sensor NTC

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$	$T = 25^{\circ}\text{C}$	4.75	5.0	5.25 k $\Omega$
$B_{25/50}$			3375	K

### Module

Symbol	Conditions	Maximum Ratings	
$T_{VJ}$		-40...+150	$^{\circ}\text{C}$
$T_{JM}$		150	$^{\circ}\text{C}$
$T_{stg}$		-40...+125	$^{\circ}\text{C}$
$V_{ISOL}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~
$M_d$	Mounting torque (M5)	3 - 6	Nm

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$			5	m $\Omega$
$d_s$	Creepage distance on surface	6		mm
$d_A$	Strike distance in air	6		mm
$R_{thCH}$	with heatsink compound		0.01	K/W
Weight			300	g

Dimensions in mm (1 mm = 0.0394")

