

### FEATURES

- ❑ 50 MHz Maximum Operating Frequency
- ❑ Programmable Buffer Length from 2 to 1281 Clock Cycles
- ❑ 10-bit Data Inputs and Outputs
- ❑ Data Delay and Data Recirculation Modes
- ❑ Supports Positive or Negative Edge System Clocks
- ❑ Expandable Data Word Width or Buffer Length
- ❑ Replaces Harris HSP9501
- ❑ 44-pin PLCC, J-Lead

### DESCRIPTION

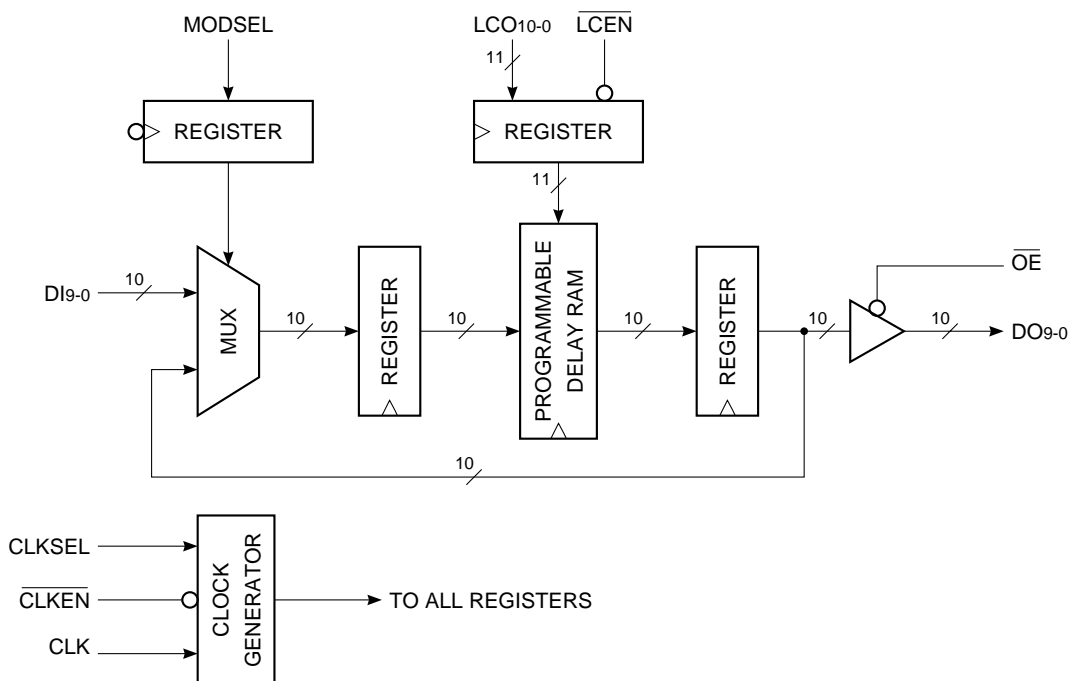
The **LF9501** is a high-speed, 10-bit programmable line buffer. Some applications the LF9501 is useful for include sample rate conversion, data time compression/expansion, software controlled data alignment, and programmable serial data shifting. By using the MODSEL pin, two different modes of operation can be selected: delay mode and data recirculation mode. The delay mode provides a minimum of 2 to a maximum of 1281 clock cycles of delay between the input and output of the device. The data recirculation mode provides a feedback path from the data output to the data input for use as a programmable circular buffer.

By using the length control input (LC10-0) and the length control enable ( $\overline{\text{LCEN}}$ ) the length of the delay buffer or amount of recirculation delay can

be programmed. Providing a delay value on the LC10-0 inputs and driving  $\overline{\text{LCEN}}$  LOW will load the delay value into the length control register on the next selected clock edge. Two registers, one preceding the programmable delay RAM and one following, are included in the delay path. Therefore, the programmed delay value should equal the desired delay minus 2. This consequently means that the value loaded into the length control register must range from 0 to 1279 (to provide an overall range of 2 to 1281).

The active edge of the clock input, either positive or negative edge, can be selected with the clock select (CLKSEL) input. All timing is based on the active clock edge selected by CLKSEL. Data can be held temporarily by using the clock enable ( $\overline{\text{CLKEN}}$ ) input.

### LF9501 BLOCK DIAGRAM



## Programmable Line Buffer

### SIGNAL DEFINITIONS

#### Power

##### *VCC and GND*

+5 V power supply. All pins must be connected.

#### Clock

##### *CLK — Master Clock*

The active edge of CLK, selected by CLKSEL, strobes all registers. All timing specifications are referenced to the active edge of CLK.

#### Inputs

##### *DI9-0 — Data Input*

10-bit data, from the data input, is latched into the device on the active edge of CLK when MODSEL is LOW.

##### *LC10-0 — Length Control Input*

The 11-bit value is used to specify the length of the delay buffer, between DI9-0 and DO9-0, or the amount of recirculation delay. An integer value ranging from 0 to 1279 is used to select a delay ranging from 2 to 1281 clock cycles. The value placed on the LC10-0 inputs is equal to the desired delay minus 2. The data presented on LC10-0 is loaded into the device on the active edge of CLK, selected by CLKSEL, in conjunction with LCEN being driven LOW.

#### Outputs

##### *DO9-0 — Data Output*

The 10-bit data output appears on DO9-0 on the Nth clock cycle, where N is the overall delay (desired delay).

#### Controls

##### *LCEN — Length Control Enable*

When LCEN is driven LOW, the next active clock edge will cause the loading of the delay value present at the LC10-0 input.

##### *OE — Output Enable*

The Output Enable controls the state of DO9-0. Driving OE LOW enables the output port. When OE is HIGH, DO9-0 is placed in a high-impedance state. The internal transfer of data is not affected by this control.

##### *MODSEL — Mode Select*

The Mode Select pin is used to choose the desired mode of operation: data delay mode or data recirculation mode. Driving MODSEL LOW places the device in the delay mode. The device operates as a programmable pipeline register. New data from the DI9-0 input is loaded on every active edge of CLK. Driving MODSEL HIGH places the device in the data recirculation mode. The device operates as a programmable circular buffer. The output of the device is routed back to the input. MODSEL may be changed during device operation (synchronously), however, the required setup and hold times, with respect to CLK, must be met.

##### *CLKSEL — Clock Select*

The CLKSEL control allows the selection of the active edge of CLK. A LOW on CLKSEL selects negative-edge triggering of the device. Driving CLKSEL HIGH selects positive-edge triggering. All timing specifications are referenced to the selected active edge of CLK.

##### *CLKEN — Clock Enable*

The Clock Enable control enables and disables the CLK input. Driving CLKEN LOW enables CLK and causes the device to operate in a normal fashion. When CLKEN is HIGH, CLK is disabled and the device will hold all internal operations and data. CLKEN may be changed during device operation (synchronously), however, the required setup and hold times, with respect to CLK, must be met. The changing of CLKEN takes effect on the active edge of CLK following the edge in which it was latched.

**Programmable Line Buffer**
**MAXIMUM RATINGS** *Above which useful life may be impaired (Notes 1, 2, 3, 8)*

Storage temperature .....	-65°C to +150°C
Operating ambient temperature .....	-55°C to +125°C
V <sub>CC</sub> supply voltage with respect to ground .....	-0.5 V to +7.0 V
Input signal with respect to ground .....	-0.5 V to V <sub>CC</sub> + 0.5 V
Signal applied to high impedance output .....	-0.5 V to V <sub>CC</sub> + 0.5 V
Output current into low outputs .....	25 mA
Latchup current .....	> 400 mA

**OPERATING CONDITIONS** *To meet specified electrical and switching characteristics*

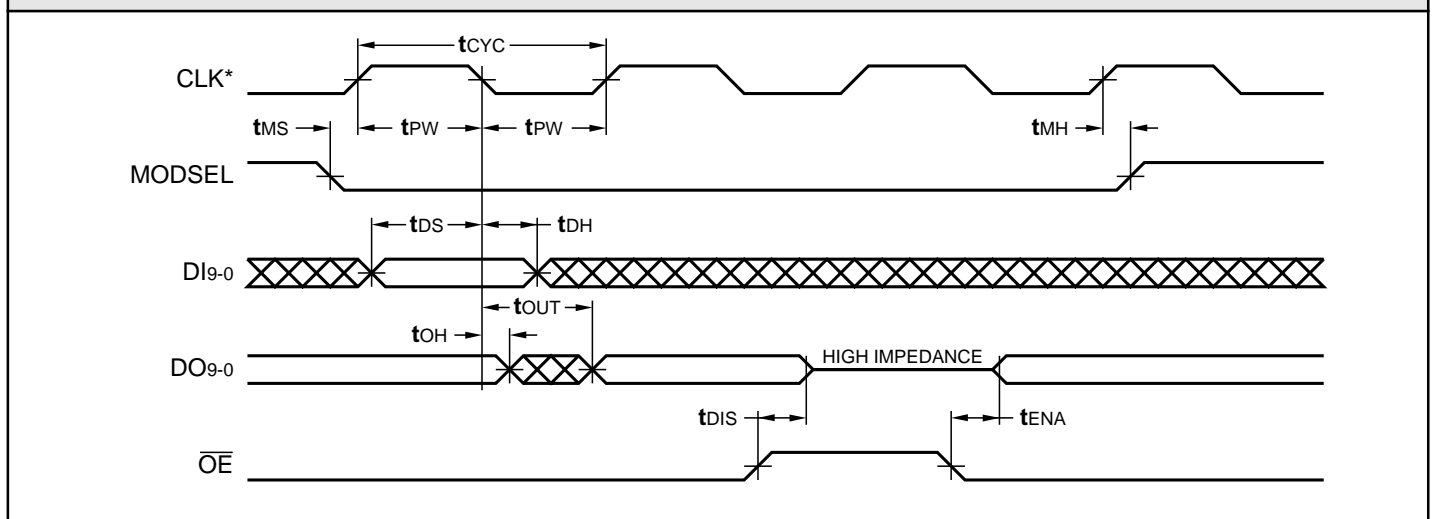
Mode	Temperature Range (Ambient)	Supply Voltage
Active Operation, Commercial	0°C to +70°C	4.75 V ≤ V <sub>CC</sub> ≤ 5.25 V

**ELECTRICAL CHARACTERISTICS** *Over Operating Conditions (Note 4)*

Symbol	Parameter	Test Condition	Min	Typ	Max	Unit
V <sub>OH</sub>	Output High Voltage	V <sub>CC</sub> = Min., I <sub>OH</sub> = -4.0 mA	2.4			V
V <sub>OL</sub>	Output Low Voltage	V <sub>CC</sub> = Min., I <sub>OL</sub> = 4.0 mA			0.4	V
V <sub>IH</sub>	Input High Voltage		2.0		V <sub>CC</sub>	V
V <sub>IL</sub>	Input Low Voltage	(Note 3)	0.0		0.8	V
I <sub>IX</sub>	Input Current	Ground ≤ V <sub>IN</sub> ≤ V <sub>CC</sub> (Note 12)			±10	μA
I <sub>OZ</sub>	Output Leakage Current	Ground ≤ V <sub>OUT</sub> ≤ V <sub>CC</sub> (Note 12)			±10	μA
I <sub>CC1</sub>	V <sub>CC</sub> Current, Dynamic	(Notes 5, 6)			125	mA
I <sub>CC2</sub>	V <sub>CC</sub> Current, Quiescent	(Note 7)			500	μA
C <sub>IN</sub>	Input Capacitance	T <sub>A</sub> = 25°C, f = 1 MHz			10	pF
C <sub>OUT</sub>	Output Capacitance	T <sub>A</sub> = 25°C, f = 1 MHz			10	pF

**SWITCHING CHARACTERISTICS**
**COMMERCIAL OPERATING RANGE (0°C to +70°C) Notes 9, 10 (ns)**

Symbol		Parameter		LF9501-									
				40*		31*		25		20		15*	
				Min	Max	Min	Max	Min	Max	Min	Max	Min	Max
t <sub>CYC</sub>	Cycle Time	40		31		25		20		15			
t <sub>PW</sub>	Clock Pulse Width	15		12		10		8		6			
t <sub>DS</sub>	Data Input Setup Time	12		10		8		6		5			
t <sub>DH</sub>	Data Input Hold Time	2		2		2		2		0			
t <sub>ES</sub>	Clock Enable to Clock Setup Time	12		10		8		6		5			
t <sub>EH</sub>	Clock Enable to Clock Hold Time	2		2		2		2		0			
t <sub>LS</sub>	Length Control Input Setup Time	13		10		8		6		5			
t <sub>LH</sub>	Length Control Input Hold Time	2		2		2		2		0			
t <sub>LES</sub>	Length Control Enable to Clock Setup Time	13		10		8		6		5			
t <sub>LEH</sub>	Length Control Enable to Clock Hold Time	2		2		2		2		0			
t <sub>MS</sub>	Mode Select Setup Time	13		10		8		6		5			
t <sub>MH</sub>	Mode Select Hold Time	2		2		2		2		0			
t <sub>OUT</sub>	Clock to Data Out		22		16		15		14		10		
t <sub>OH</sub>	Output Hold Time (Note 8)	4		4		4		4		4			
t <sub>ENA</sub>	Three-State Output Enable Delay (Note 11)		25		20		15		14		12		
t <sub>DIS</sub>	Three-State Output Disable Delay (Note 11)		25		24		15		14		12		

**FUNCTIONAL TIMING — CLKSEL LOW**


\*When  $\overline{\text{CLKSEL}}$  is HIGH, assume CLK is inverted.

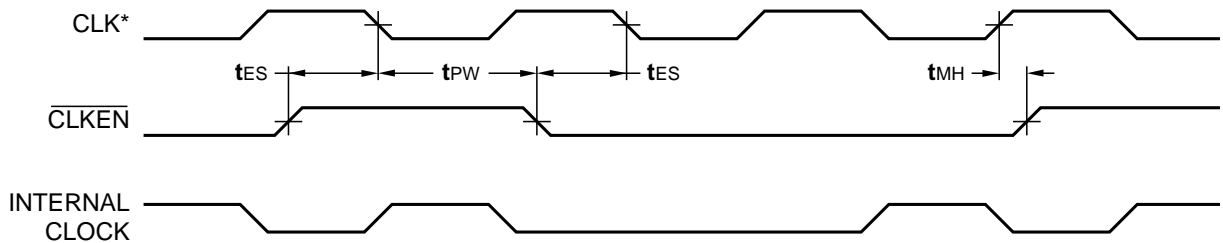
\*DISCONTINUED SPEED GRADE

**SWITCHING CHARACTERISTICS**

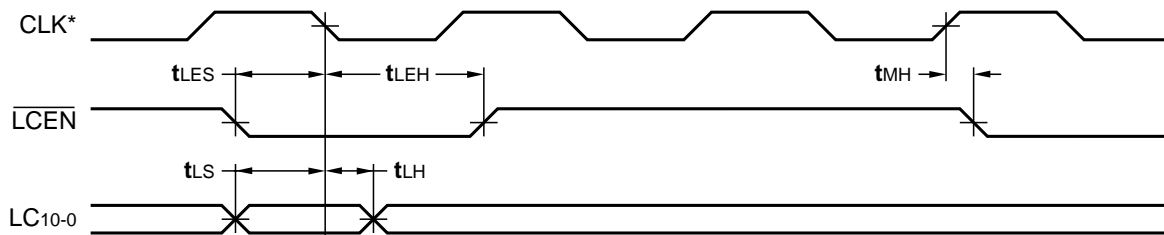
**COMMERCIAL OPERATING RANGE (0°C to +70°C) Notes 9, 10 (ns)**

Symbol		Parameter		LF9501-									
				40*		31*		25		20		15*	
				Min	Max	Min	Max	Min	Max	Min	Max	Min	Max
t <sub>CYC</sub>	Cycle Time	40		31		25		20		15			
t <sub>PW</sub>	Clock Pulse Width	15		12		10		8		6			
t <sub>DS</sub>	Data Input Setup Time	12		10		8		6		5			
t <sub>DH</sub>	Data Input Hold Time	2		2		2		2		0			
t <sub>ES</sub>	Clock Enable to Clock Setup Time	12		10		8		6		5			
t <sub>EH</sub>	Clock Enable to Clock Hold Time	2		2		2		2		0			
t <sub>LS</sub>	Length Control Input Setup Time	13		10		8		6		5			
t <sub>LH</sub>	Length Control Input Hold Time	2		2		2		2		0			
t <sub>LES</sub>	Length Control Enable to Clock Setup Time	13		10		8		6		5			
t <sub>LEH</sub>	Length Control Enable to Clock Hold Time	2		2		2		2		0			
t <sub>MS</sub>	Mode Select Setup Time	13		10		8		6		5			
t <sub>MH</sub>	Mode Select Hold Time	2		2		2		2		0			
t <sub>OUT</sub>	Clock to Data Out		22		16		15		14		10		
t <sub>OH</sub>	Output Hold Time (Note 8)	4		4		4		4		4			
t <sub>ENA</sub>	Three-State Output Enable Delay (Note 11)		25		20		15		14		12		
t <sub>DIS</sub>	Three-State Output Disable Delay (Note 11)		25		24		15		14		12		

**CLOCK ENABLE TIMING — CLKSEL LOW**



**LENGTH CONTROL TIMING — CLKSEL LOW**



\*When  $\overline{\text{CLKSEL}}$  is HIGH, assume CLK is inverted.

**\*DISCONTINUED SPEED GRADE**

**NOTES**

1. Maximum Ratings indicate stress specifications only. Functional operation of these products at values beyond those indicated in the Operating Conditions table is not implied. Exposure to maximum rating conditions for extended periods may affect reliability.

2. The products described by this specification include internal circuitry designed to protect the chip from damaging substrate injection currents and accumulations of static charge. Nevertheless, conventional precautions should be observed during storage, handling, and use of these circuits in order to avoid exposure to excessive electrical stress values.

3. This device provides hard clamping of transient undershoot and overshoot. Input levels below ground or above VCC will be clamped beginning at -0.6 V and VCC + 0.6 V. The device can withstand indefinite operation with inputs in the range of -0.5 V to +7.0 V. Device operation will not be adversely affected, however, input current levels will be well in excess of 100 mA.

4. Actual test conditions may vary from those designated but operation is guaranteed as specified.

5. Supply current for a given application can be accurately approximated by:

$$\frac{NCV^2F}{4}$$

where

4

- N = total number of device outputs
- C = capacitive load per output
- V = supply voltage
- F = clock frequency

6. Tested with all outputs changing every cycle and no load, at a 25 MHz clock rate.

7. Tested with all inputs within 0.1 V of VCC or Ground, no load.

8. These parameters are guaranteed but not 100% tested.

9. AC specifications are tested with input transition times less than 3 ns, output reference levels of 1.5 V (except tDIS test), and input levels of nominally 0 to 3.0 V. Output loading may be a resistive divider which provides for specified IOH and IOL at an output voltage of VOH min and VOL max respectively. Alternatively, a diode bridge with upper and lower current sources of IOH and IOL respectively, and a balancing voltage of 1.5 V may be used. Parasitic capacitance is 30 pF minimum, and may be distributed.

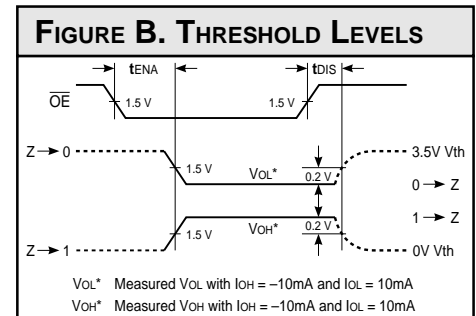
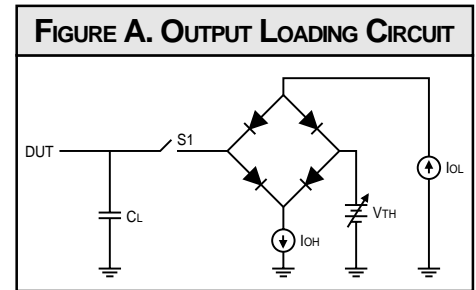
This device has high-speed outputs capable of large instantaneous current pulses and fast turn-on/turn-off times. As a result, care must be exercised in the testing of this device. The following measures are recommended:

- a. A 0.1 μF ceramic capacitor should be installed between VCC and Ground leads as close to the Device Under Test (DUT) as possible. Similar capacitors should be installed between device VCC and the tester common, and device ground and tester common.
- b. Ground and VCC supply planes must be brought directly to the DUT socket or contactor fingers.
- c. Input voltages should be adjusted to compensate for inductive ground and VCC noise to maintain required DUT input levels relative to the DUT ground pin.

10. Each parameter is shown as a minimum or maximum value. Input requirements are specified from the point of view of the external system driving the chip. Setup time, for example, is specified as a minimum since the external system must supply at least that much time to meet the worst-case requirements of all parts. Responses from the internal circuitry are specified from the point of view of the device. Output delay, for example, is specified as a maximum since worst-case operation of any device always provides data within that time.

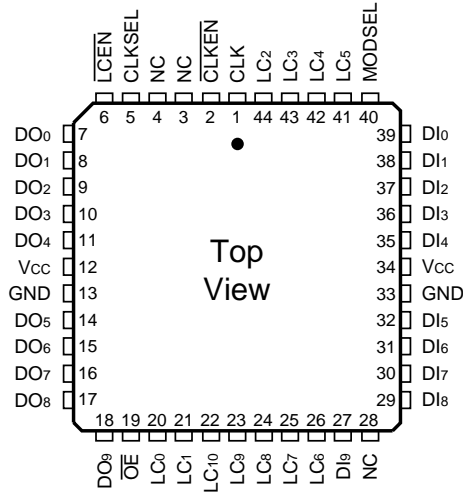
11. For the tENA test, the transition is measured to the 1.5 V crossing point with datasheet loads. For the tDIS test, the transition is measured to the ±200mV level from the measured steady-state output voltage with ±10mA loads. The balancing voltage, VTH, is set at 3.5 V for Z-to-0 and 0-to-Z tests, and set at 0 V for Z-to-1 and 1-to-Z tests.

12. These parameters are only tested at the high temperature extreme, which is the worst case for leakage current.



**ORDERING INFORMATION**

**44-pin**



<b>Speed</b>	<b>Plastic J-Lead Chip Carrier (J1)</b>
	<b>0°C to +70°C — COMMERCIAL SCREENING</b>
25 ns	LF9501JC25
20 ns	LF9501JC20
	<b>-40°C to +85°C — COMMERCIAL SCREENING</b>