### **General Description**

The MAX4265–MAX4270 single-supply, voltage-feedback op amps are capable of driving a 100 $\Omega$  load while maintaining ultra-low distortion over a wide bandwidth. They offer superior spurious-free dynamic range (SFDR) performance: -90dBc or better at frequencies below 5MHz and -60dBc at a 100MHz frequency. Additionally, input voltage noise density is 8nV/ $\sqrt{\text{Hz}}$  while operating from a single +4.5V to +8.0V supply or from dual ±2.25V to ±4.0V supplies. These features make the MAX4265–MAX4270 ideal for use in high-performance communications and signal-processing applications that require low distortion and wide bandwidth.

The MAX4265 single and MAX4268 dual unity-gain-stable amplifiers have up to a 300MHz gain-bandwidth product. The MAX4266 single and MAX4269 dual amplifiers have up to a 350MHz bandwidth at a minimum stable gain of  $\pm$ 2V/V. The MAX4267 single and MAX4270 dual amplifiers have a 200MHz bandwidth at a minimum stable gain of  $\pm$ 5V/V.

For additional power savings, these amplifiers feature a low-power disable mode that reduces supply current to 1.6mA and places the outputs in a high-impedance state. The MAX4265/MAX4266/MAX4267 are available in a space-saving 8-pin  $\mu$ MAX package, and the MAX4268/MAX4269/MAX4270 are available in a 16-pin QSOP package.

#### **Applications**

Base-Station Amplifiers

IF Amplifiers

High-Frequency ADC Drivers

High-Speed DAC Buffers

**RF** Telecom Applications

High-Frequency Signal Processing

Pin Configurations appear at end of data sheet.

PART	NO. OF OP AMPS	MIN GAIN (V/V)	BANDWIDTH (MHz)
MAX4265	1	1	300
MAX4266	1	2	350
MAX4267	1	5	200
MAX4268	2	1	300
MAX4269	2	2	350
MAX4270	2	5	200

#### **Selector Guide**

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## For free samples & the latest literature: http://www.maxim-ic.com, or phone 1-800-998-8800. For small orders, phone 1-800-835-8769.

#### Features

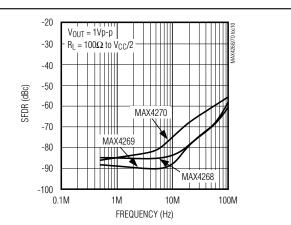
- ♦ +4.5V to +8.0V Single-Supply Operation
- Superior SFDR with 100Ω Load
  -90dBc (fc = 5MHz)
  -60dBc (fc = 100MHz)
- ◆ 35dBm IP3 (f<sub>C</sub> = 20MHz)
- ♦ 8nV/√Hz Voltage Noise Density
- ♦ 100MHz 0.1dB Gain Flatness (MAX4268)
- ♦ 900V/µs Slew Rate
- ♦ ±45mA Output Driving Capability
- Shutdown Mode Places Outputs in High-Impedance State

#### **Ordering Information**

PART	TEMP. RANGE	PIN-PACKAGE
MAX4265EUA*	-40°C to +85°C	8 µMAX
MAX4265ESA*	-40°C to +85°C	8 SO
MAX4266EUA*	-40°C to +85°C	8 µMAX
MAX4266ESA*	-40°C to +85°C	8 SO
MAX4267EUA*	-40°C to +85°C	8 µMAX
MAX4267ESA*	-40°C to +85°C	8 SO
MAX4268EEE	-40°C to +85°C	16 QSOP
MAX4268ESD	-40°C to +85°C	14 SO
MAX4269EEE	-40°C to +85°C	16 QSOP
MAX4269ESD	-40°C to +85°C	14 SO
MAX4270EEE	-40°C to +85°C	16 QSOP
MAX4270ESD	-40°C to +85°C	14 SO

\*Future product—contact factory for availability.

#### SFDR vs. Input Frequency



\_ Maxim Integrated Products 1

## ABSOLUTE MAXIMUM RATINGS

 $\label{eq:supply_voltage} \begin{array}{l} \text{Supply Voltage (V_{CC} to V_{EE})} & +8.5 \text{V} \\ \text{Voltage on Any Other Pin} & (V_{EE} - 0.3 \text{V}) \text{ to (V}_{CC} + 0.3 \text{V}) \\ \text{Short-Circuit Duration (V}_{OUT} \text{ to V}_{CC} \text{ or V}_{EE}) & \dots \\ \text{Continuous Power Dissipation (T}_{A} = +70^{\circ}\text{C}) \end{array}$ 

16-Pin QSOP (derate 8.33mW/°C above +70°C).......667mW 8-Pin μMAX (derate 4.10mW/°C above +70°C).......330mW 8-Pin SO (derate 5.9mW/°C above +70°C).......471mW

Operating Temperature Range	40°C to +85°C
Storage Temperature Range	65°C to +150°C
Junction Temperature	+150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## DC ELECTRICAL CHARACTERISTICS

 $(V_{CC} = +5V, V_{EE} = 0, R_L = 100\Omega$  to  $V_{CC}/2, V_{CM} = V_{CC}/2, T_A = T_{MIN}$  to  $T_{MAX}$ , typical values are at  $T_A = +25^{\circ}C$ , unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Operating Supply Voltage Range	V <sub>CC</sub>	Inferred from PSRR test	4.5		8.0	V
Common-Mode Input Voltage	VCM	Inferred from CMRR test	V <sub>EE</sub> + 1.6		V <sub>CC</sub> - 1.6	V
Input Offset Voltage	Vos			1	9	mV
Input Offset Voltage Drift	TCVOS			1.5		µV/°C
Input Offset Voltage Channel Matching		MAX4268/MAX4269/MAX4270		1		mV
Input Bias Current	IB			3.5	40	μΑ
Input Offset Current	I <sub>OS</sub>			0.1	5.5	μΑ
Common-Mode Input Resistance	RINCM	Either input, (V <sub>EE</sub> + 1.6) $\leq$ V <sub>CM</sub> $\leq$ (V <sub>CC</sub> - 1.6)		1		MΩ
Differential Input Resistance	RINDIFF	$-10mV \le V_{IN} \le 10mV$		40		kΩ
Common-Mode Rejection Ratio	CMRR	$(V_{EE} + 1.6V) \le V_{CM} \le (V_{CC} - 1.6V)$ , no load	60	85		dB
Power-Supply Rejection Ratio	PSRR	V <sub>CC</sub> = 4.5V to 8.0V	60	85		dB
Open-Loop Voltage Gain	AOL	$1.75V \le V_{OUT} \le 3.25V$	60	95		dB
Output Voltage Swing	Vout	V <sub>CC</sub> - V <sub>OH</sub> , V <sub>OL</sub> - V <sub>EE</sub>		1.1	1.5	dB
Output Current Drive	IOUT	$R_L = 20\Omega$	±30	±45		mA
Output Short-Circuit Current	ISC	Sinking or sourcing to V <sub>CC</sub> or V <sub>EE</sub>		100		mA
Closed-Loop Output Resistance	Rout			0.035		Ω
Power-Up Time	<b>t</b> PWRUP	$V_{\rm O}$ = 1V step, 0.1% settling time		10		μs
Quiescent Supply Current	la	Normal mode, EN_ = 5V or floating		28	32	mA
Quiescent Supply Current	IS	Disable mode, EN_ = 0	1.6 5		ШA	
Disable Output Leakage Current		$V_{EN_{-}} = 0, V_{EE} \le V_{OUT} \le V_{CC}$		0.2	5	μA
EN_ Logic Low Threshold					V <sub>CC</sub> - 3.5	V
EN_ Logic High Threshold			V <sub>CC</sub> - 1.5			V
EN_ Logic Input Low Current		$V_{EN_{-}} = 0$		5	100	μA
EN_ Logic Input High Current		$V_{EN_{-}} = 5V$		1	30	μΑ

#### **AC ELECTRICAL CHARACTERISTICS**

 $(V_{CC} = +5V, V_{EE} = 0, R_L = 100\Omega \text{ to } V_{CC}/2, V_{CM} = V_{CC}/2, MAX4265/MAX4268 \text{ A}_V = +1V/V, MAX4266/MAX4269 \text{ A}_V = +2V/V, MAX4267/MAX4270 \text{ A}_V = +5V/V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C. )$ 

PARAMETER	SYMBOL	CON	DITIONS	MIN	ТҮР	MAX	UNITS
			MAX4265/MAX4268		300		
Small-Signal -3dB Bandwidth	BW-3dB	V <sub>OUT</sub> = 100mVp-p	MAX4266/MAX4269		350		MHz
			MAX4267/MAX4270		200		-
		V <sub>OUT</sub> = 1Vp-p	MAX4265/MAX4268		175		MHz
Full-Power Bandwidth	FPBW		MAX4266/MAX4269		200		
			MAX4267/MAX4270		200		
			MAX4265/MAX4268		100		
0.1dB Gain Flatness	BW <sub>0.1dB</sub>	V <sub>OUT</sub> = 100mVp-p	MAX4266/MAX4269		35		MHz
			MAX4267/MAX4270		35		
All-Hostile Crosstalk		f = 10MHz	ų.		85		dB
Slew Rate	SR	V <sub>OUT</sub> = 1V step			900		V/µs
Rise/Fall Times	t <sub>R</sub> , t <sub>F</sub>	V <sub>OUT</sub> = 1V step			1		ns
Settling Time (0.1%)	tS,0.1	V <sub>OUT</sub> = 1V step			15		ns
	SFDR	V <sub>OUT</sub> = 1Vp-p (MAX4269)	$f_{\rm C} = 1 \rm MHz$		88		
			$f_{\rm C} = 5 {\rm MHz}$		90		- dBc
Spurious-Free Dynamic			$f_{\rm C} = 10 {\rm MHz}$		87		
Range			$f_{\rm C} = 20 {\rm MHz}$		78		
			$f_{\rm C} = 60 \text{MHz}$		68		
			$f_{\rm C} = 100 \text{MHz}$		60		
			$f_{\rm C} = 1 \rm MHz$		88		
			$f_{\rm C} = 5 {\rm MHz}$		90		
Second Harmonic		V <sub>OUT</sub> = 1Vp-p (MAX4269)	$f_{\rm C} = 10 {\rm MHz}$		87		dBc
Distortion			$f_{\rm C} = 20 {\rm MHz}$		78		
			$f_{\rm C} = 60 \text{MHz}$		68		
			$f_{\rm C} = 100 {\rm MHz}$		60		
		V <sub>OUT</sub> = 1Vp-p (MAX4269)	$f_{\rm C} = 1 \rm MHz$		96		
			$f_{\rm C} = 5 {\rm MHz}$		95		1
Third Harmonic			$f_{\rm C} = 10 {\rm MHz}$		92		
Distortion			$f_{\rm C} = 20 {\rm MHz}$		86		– dBc –
			$f_{\rm C} = 60 \text{MHz}$		72		
			$f_{\rm C} = 100 \text{MHz}$		68		

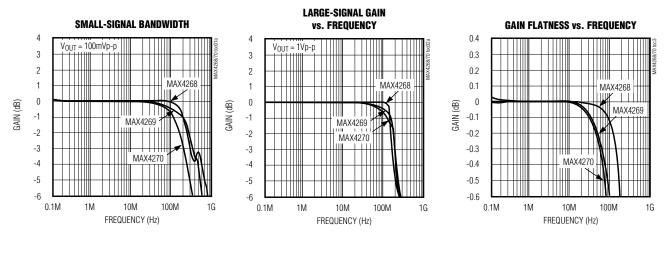
## AC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = +5V, V_{EE} = 0, R_L = 100\Omega \text{ to } V_{CC}/2, V_{CM} = V_{CC}/2, MAX4265/MAX4268 A_V = +1V/V, MAX4266/MAX4269 A_V = +2V/V, MAX4267/MAX4270 A_V = +5V/V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$ 

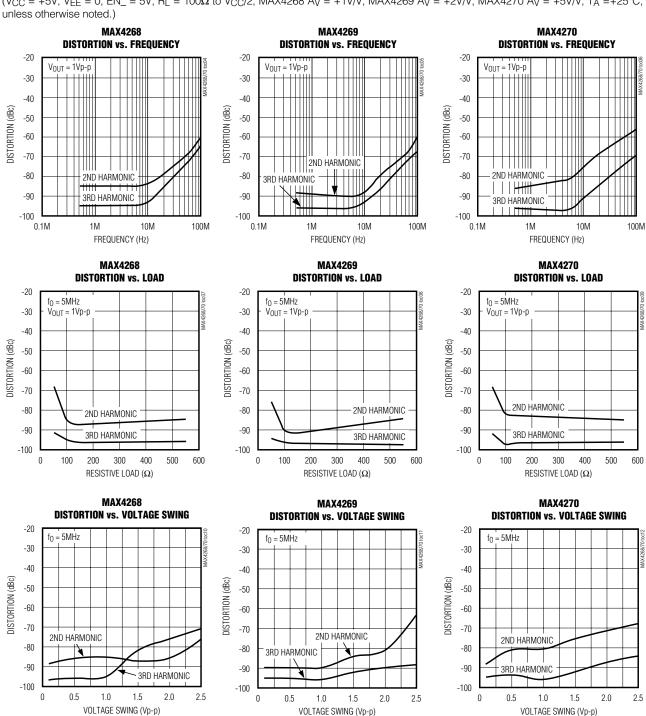
PARAMETER	SYMBOL	CONE	MIN	TYP	MAX	UNITS			
Two-Tone, Third-Order Intercept Distortion	IP3	$V_{OUT} = 1V_{P-P}, f_{CA} = 2$ $f_{CB} = 21.25MHz$ (MAX		35		dBm			
Input -1dB Compression Point		$f_{\rm C} = 20 \rm MHz$			12		dBm		
Differential Gain	D <sub>G</sub>	NTSC, f = 3.58MHz, R	$L = 150\Omega$ to $V_{CC}/2$	0.015		%			
Differential Phase	Dp	NTSC, f = 3.58MHz, R	$L = 150\Omega$ to V <sub>CC</sub> /2	0.03			degrees		
Input Capacitance	CIN		2		рF				
Output Impedance	Rout	f = 10MHz	1			Ω			
Disabled Output Capacitance		$V_{EN_{-}} = 0$			5		pF		
Enable Time	t <sub>EN</sub>	V <sub>IN</sub> = 1V			100		ns		
Disable Time	tDIS	V <sub>IN</sub> = 1V		750			μs		
		N	MAX4265/MAX4268		15				
Capacitive Load Stability		No sustained oscillation	MAX4266/MAX4269		15		рF		
			MAX4267/MAX4270		22				
Input Voltage Noise Density	en	f = 1kHz		f = 1kHz			8		nV/√Hz
Input Current Noise Density	in	f = 1kHz			1		pA/√Hz		

### **Typical Operating Characteristics**

 $(V_{CC} = +5V, V_{EE} = 0, EN_{-} = 5V, R_{L} = 100\Omega$  to  $V_{CC}/2$ , MAX4268 A<sub>V</sub> = +1V/V, MAX4269 A<sub>V</sub> = +2V/V, MAX4270 A<sub>V</sub> = +5V/V, T<sub>A</sub> =+25°C, unless otherwise noted.)



M/X/M

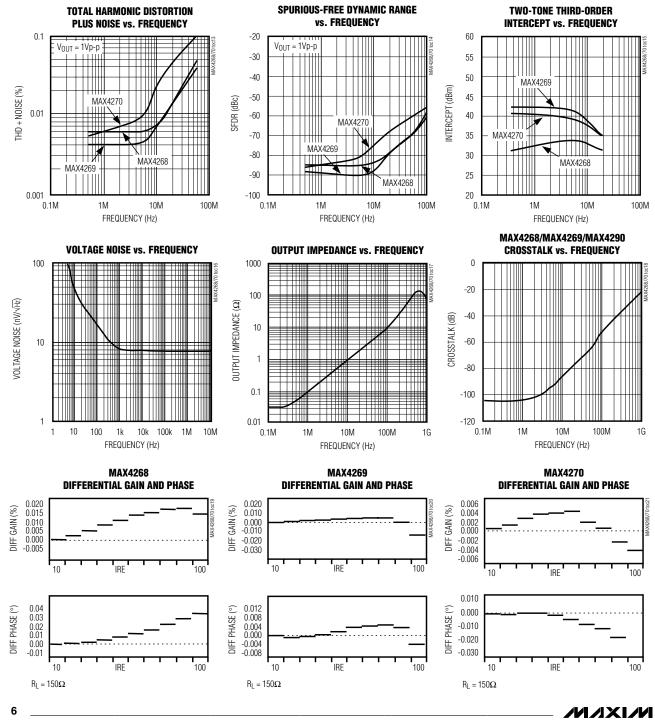


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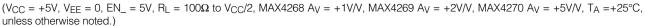
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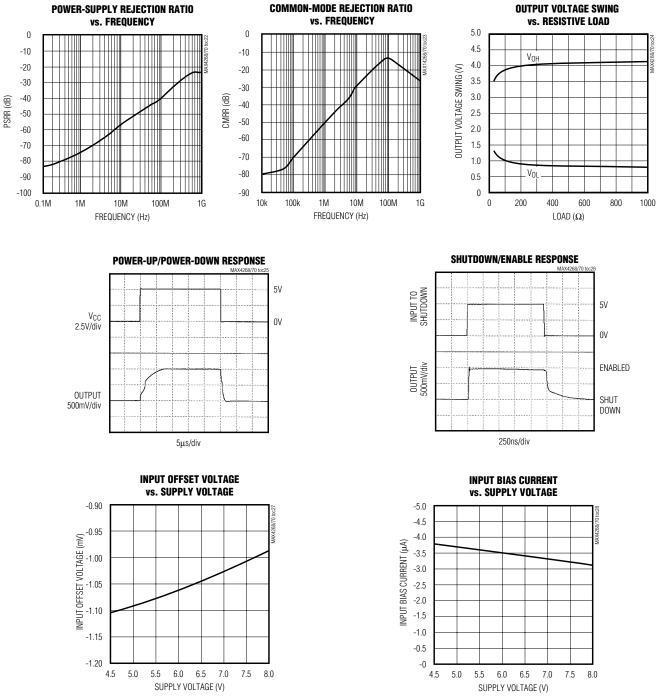
MAX4265-MAX4270



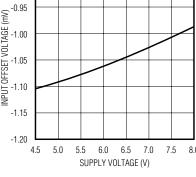


## **Typical Operating Characteristics (continued)**



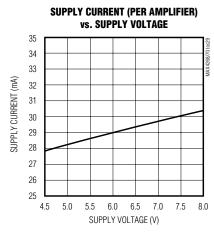


MAX4265-MAX4270

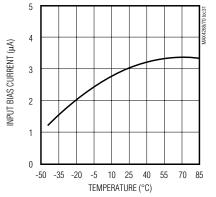




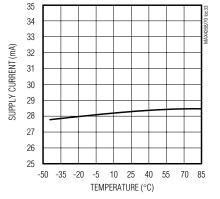
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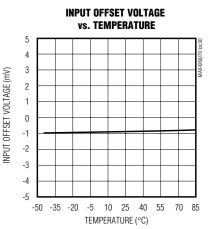


**INPUT BIAS CURRENT vs. TEMPERATURE** 

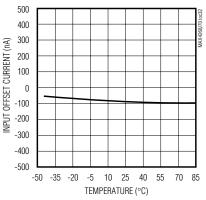




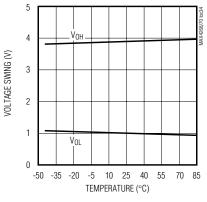




INPUT OFFSET CURRENT vs. TEMPERATURE



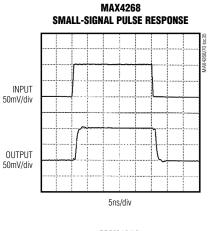
**VOLTAGE SWING vs. TEMPERATURE** 

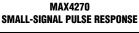


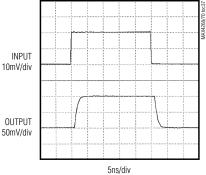
MAX4265-MAX4270

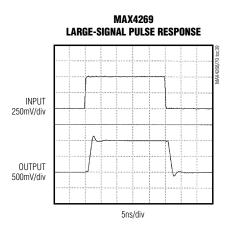
### **Typical Operating Characteristics (continued)**

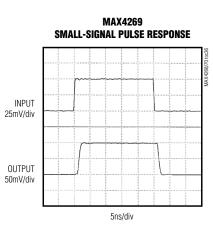
 $(V_{CC} = +5V, V_{EE} = 0, EN_{=} = 5V, R_{L} = 100\Omega$  to  $V_{CC}/2$ , MAX4268 A<sub>V</sub> = +1V/V, MAX4269 A<sub>V</sub> = +2V/V, MAX4270 A<sub>V</sub> = +5V/V, T<sub>A</sub> =+25°C, unless otherwise noted.)



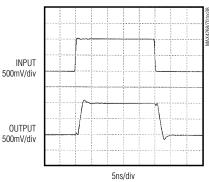


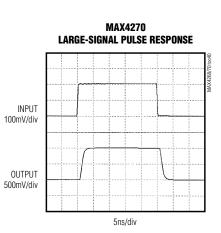






MAX4268 LARGE-SIGNAL PULSE RESPONSE





MAX4265-MAX4270

#### **Pin Description**

	266 MAX4269		PIN					
MAX4265 MAX4266 MAX4267			NAME	FUNCTION				
8 µMAX/SO	14 SO	16 QSOP						
1	_		EN	Enable Input. Active high. Connect to $V_{CC}$ for normal operation.				
_	4, 5	4, 5	ENA, ENB	Enable Input. Active high. Connect to $V_{CC}$ for normal operation.				
2	_	_	IN-	Inverting Input				
_	2, 9	2, 11	INA-, INB-	Inverting Input				
3	_	_	IN+	Noninverting Input				
—	3, 10	3, 12	INA+, INB+	Noninverting Input				
4, 5	6, 7	6, 7	V <sub>EE</sub>	Negative Power Supply				
6	_	_	OUT	Amplifier Output				
_	1, 8	1, 10	OUTA, OUTB	Amplifier Output				
7, 8	13, 14	15, 16	Vcc	Positive Power Supply. Connect to a +4.5V to +8.0V supply and bypass with a $0.1\mu$ F capacitor for single-supply operation.				
_	11, 12	8, 9, 13, 14	N.C.	No Connection. Not internally connected.				

### **Detailed Description**

The MAX4265–MAX4270 single-supply operational amplifiers feature ultra-low distortion and wide bandwidth. Their low distortion and low noise make them ideal for driving high-speed analog-to-digital converters (ADCs) up to 16 bits in telecommunications applications and high-performance signal processing.

These devices can drive loads as low as 100 $\Omega$  and deliver 45mA while maintaining DC accuracy and AC performance. The input common-mode voltage ranges from (V<sub>EE</sub> + 1.6V) to (V<sub>CC</sub> - 1.6V), while the output swings to within 1.1V of the rails.

#### Low Distortion

The MAX4265–MAX4270 use proprietary bipolar technology to achieve minimum distortion in single-supply systems—a feature typically available only in dual-supply op amps.

Several factors can affect the noise and distortion that a device contributes to the input signal. The following guidelines explain how various design choices impact the total harmonic distortion (THD).

- Choose the proper feedback-resistor and gain-resistor values for the application. In general, the smaller the closed-loop gain, the smaller the THD generated—especially when driving heavy resistive loads. Large-value feedback resistors can significantly improve distortion. The MAX4265–MAX4270's THD normally increases at approximately 20dB per decade at frequencies above 1MHz; this is a lower rate than that of comparable dual-supply op amps.
- Operating the device near or above the full-power bandwidth significantly degrades distortion (see the Total Harmonic Distortion vs. Frequency graph in the *Typical Operating Characteristics*).
- The decompensated devices (MAX4266/MAX4267/ MAX4269/MAX4270) deliver the best distortion performance since they have a slightly higher slew rate and provide a higher amount of loop gain for a given closed-loop gain setting.

M/XI/M

#### **Choosing Resistor Values** Unity-Gain Configurations

The MAX4265 and MAX4268 are internally compensated for unity gain. When configured for unity gain, they require a small resistor ( $R_F$ ) in series with the feedback path (Figure 1). This resistor improves AC response by reducing the Q of the tank circuit, which is formed by parasitic feedback inductance and capacitance.

#### Inverting and Noninverting Configurations

The values of the gain-setting feedback and input resistors are important design considerations. Large resistor values will increase voltage noise and interact with the amplifier's input and PC board capacitance to generate undesirable poles and zeros, which can decrease bandwidth or cause oscillations. For example, a noninverting gain of +2V/V (Figure 1) using  $R_F = R_G = 1k\Omega$ combined with 2pF of input capacitance and 0.5pF of board capacitance will cause a feedback pole at 128MHz. If this pole is within the anticipated amplifier bandwidth, it will jeopardize stability. Reducing the  $1k\Omega$ resistors to  $100\Omega$  extends the pole frequency to 1.28GHz, but could limit output swing by adding  $200\Omega$ in parallel with the amplifier's load. Clearly, the selection of resistor values must be tailored to the specific application.

#### **Distortion Considerations**

The MAX4265–MAX4270 are ultra-low-distortion, highbandwidth op amps. Output distortion will degrade as the total load resistance seen by the amplifier decreases. To minimize distortion, keep the input and gain-setting resistor values relatively large. A 500 $\Omega$  feedback resistor combined with an appropriate input resistor to set the gain will provide excellent AC performance without significantly increasing distortion.

#### Noise Considerations

The amplifier's input-referred noise-voltage density is dominated by flicker noise at lower frequencies and by thermal noise at higher frequencies. Because the thermal noise contribution is affected by the parallel combination of the feedback resistive network, those resistor values should be reduced in cases where the system bandwidth is large and thermal noise is dominant. This noise-contribution factor decreases, however, with increasing gain settings. For example, the input noise voltage density at the op amp input with a gain of +10V/V using RF = 100k $\Omega$  and RG = 11k $\Omega$  is en = 18nV/NHz. The input noise can be reduced to 8nV/NHz by choosing RF = 1k $\Omega$ , RG = 110 $\Omega$ .

#### **Driving Capacitive Loads**

The MAX4265–MAX4270 are not designed to drive highly reactive loads; stability is maintained with loads up to 15pF with less than 2dB peaking in the frequency response. To drive higher capacitive loads, place a small isolation resistor in series between the amplifier's output and the capacitive load (Figure 1). This resistor improves the amplifier's phase margin by isolating the capacitor from the op amp's output.

To ensure a load capacitance that limits peaking to less than 2dB, select a resistance value from Figure 2. For example, if the capacitive load is 100pF, the corresponding isolation resistor is  $6\Omega$  (MAX4269). Figures 3 and 4 show the peaking that occurs in the frequency response with and without an isolation resistor.

Coaxial cable and other transmission lines are easily driven when terminated at both ends with their characteristic impedance. When driving back-terminated transmission lines, the capacitive load of the transmission line is essentially eliminated.

#### **ADC Input Buffer**

Input buffer amplifiers can be a source of significant errors in high-speed ADC applications. The input buffer is usually required to rapidly charge and discharge the ADC's input, which is often capacitive (see *Driving Capacitive Loads*). In addition, since a high-speed ADC's input impedance often changes very rapidly during the conversion cycle, measurement accuracy must

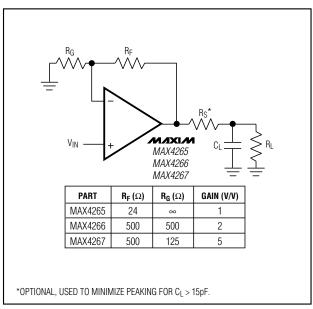


Figure 1. Noninverting Configuration

///XI//

be maintained using an amplifier with very low output impedance at high frequencies. The combination of high speed, fast slew rate, low noise, and a low and stable distortion over load makes the MAX4265– MAX4270 ideally suited for use as buffer amplifiers in high-speed ADC applications.

#### Low-Power Disable Mode

The MAX4265–MAX4270 feature an active-high enable pin that can be used to save power and place the outputs in a high-impedance state. Drive EN\_ with logic levels or connect EN\_ to V<sub>CC</sub> for normal operation. In the dual versions (MAX4268/MAX4269/MAX4270), each individual op amp is enabled separately, allowing the devices to be used in a multiplex configuration. The supply current in low-power mode is reduced to 1.6mA per device. Enable time is typically 100ns, and disable time is typically 750µs.

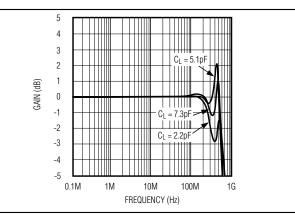


Figure 3a. MAX4268 Small-Signal Gain vs. Frequency Without Isolation Resistor

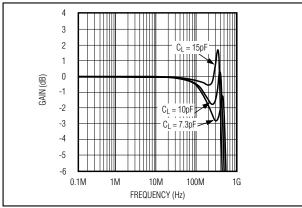


Figure 3c. MAX4270 Small-Signal Gain vs. Frequency Without Isolation Resistor

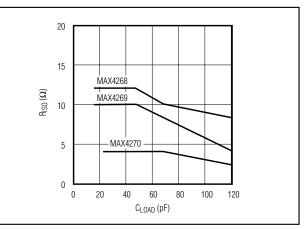


Figure 2. MAX4268/MAX4269/MAX4270 Isolation Resistance vs. Capacitive Load

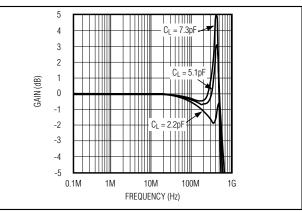
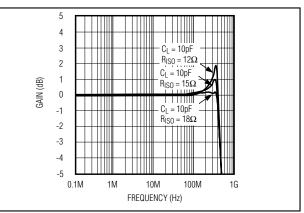


Figure 3b. MAX4269 Small-Signal Gain vs. Frequency Without Isolation Resistor



M/XI/M

Figure 4a. MAX4268 Small-Signal Gain vs. Frequency With Isolation Resistor

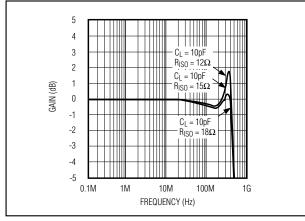
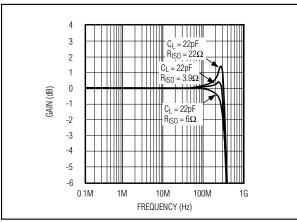


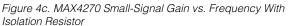
Figure 4b. MAX4269 Small-Signal Gain vs. Frequency With Isolation Resistor

#### **Power Supplies and Layout**

The MAX4265–MAX4270 operate from a single +4.5V to +8.0V power supply or from dual  $\pm 2.25V$  to  $\pm 4.0V$  supplies. For single-supply operation, bypass each power-supply input with a 0.1µF ceramic capacitor placed close to the V<sub>CC</sub> pins, and an additional 10µF to V<sub>EE</sub>. When operating from dual supplies, bypass each supply to ground.

Good layout improves performance by decreasing the amount of stray capacitance and noise at the op amp's inputs and output. To decrease stray capacitance, minimize PC board trace lengths and resistor leads, and place external components close to the op amp's pins.

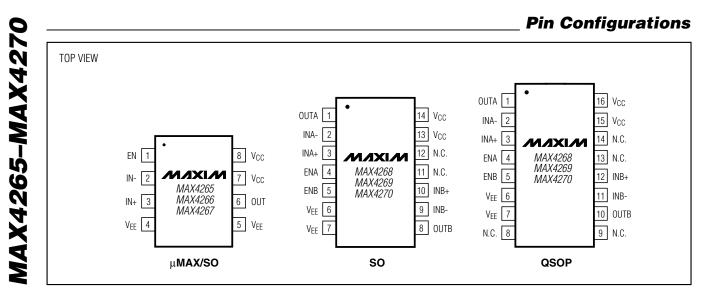




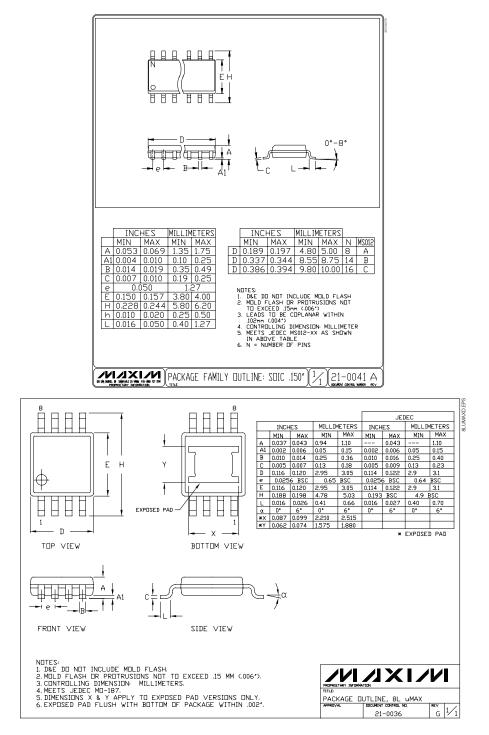
#### Chip Information

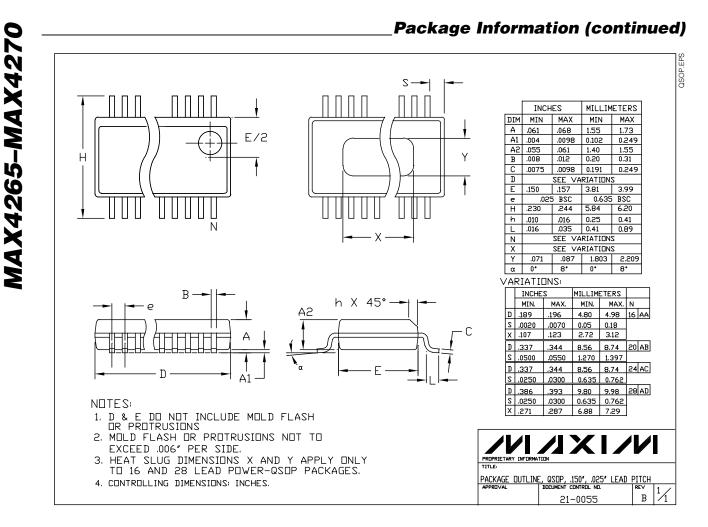
TRANSISTOR COUNT: MAX4265/66/67: 132 MAX4268/69/70: 285

M/IXI/N









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