19-0297; Rev 1; 9/95



## 300Msps, 12-Bit DAC with Complementary Voltage Outputs

### General Description

The MAX555 is an advanced, monolithic, 12-bit digitalto-analog converter (DAC) with complementary  $50\Omega$ outputs. Fabricated using an oxide-isolated bipolar process, the MAX555 is designed for signal-reconstruction applications at an output update rate of 300Msps. It incorporates an analog multiplying function with 10MHz useable input bandwidth. The voltage-output DAC uses precision laser trimming to achieve 12-bit accuracy with ±1/2LSB integral and differential linearity (±0.012% FS). Absolute gain error is a low 1% of full scale. Full-scale transitions occur in less than 0.5ns. Internal registers and a unique decoder reduce glitching and allow the MAX555 to achieve precise RF performance with over 73dBc of spurious-free dynamic range at 50Msps with foUT = 3.1MHz, or 62dBc at 300Msps with foUT = 18.6MHz.

The MAX555 operates from a single -5.2V supply and dissipates 980mW (nominal). It comes in a 68-pin thermally enhanced PLCC package capable of accepting a heatsink.

### Applications

Direct Digital Synthesis Arbitrary Waveform Generation HDTV/High-Resolution Graphics Instrumentation Communications Local Oscillators Automated Tester Applications ♦ 12-Bit Resolution

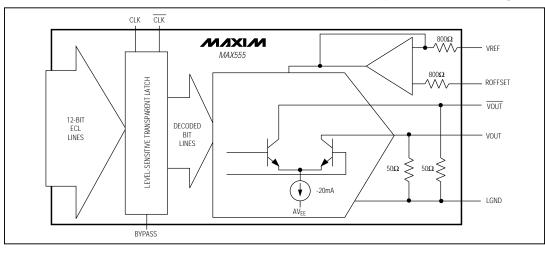
- ±1/2LSB Integral and Differential Nonlinearity
- Capable of 300Msps Min Update Rate
- Complementary 50Ω Outputs
- Multiplying Reference Input
- Low Glitch Energy (5.6pVs)
- Single -5.2V Power Supply
- On-Chip Data Registers
- + ECL-Compatible Inputs with Differential Clock

#### Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE
MAX555CQK	0°C to +70°C	68 Thermally Enhanced PLCC

Pin Configuration appears at end of data sheet.

#### \_Simplified Block Diagram



\_ Maxim Integrated Products 1

Call toll free 1-800-998-8800 for literature.

Features

### ABSOLUTE MAXIMUM RATINGS

**MAX555** 

	Continuous Power Dissipation (T <sub>A</sub> = +70°C)
Digital Supply Voltage (DVEE)	(without additional heatsink)1.3W
Digital Input Voltage (D0–D11)5.5V to 0V	Operating Temperature Range0°C to +70°C
Reference Input Voltage (VIN)OV to +1.25V	Junction Temperature Range (Note 1)0°C to +150°C
Reference Input CurrentOmA to +1.56mA	Storage Temperature Range65°C to +150°C
Output Compliance Voltage (Voc)1.25V to +1.0V	Lead Temperature (soldering, 10sec)+300°C
Output Common-Mode Voltage (V <sub>CM</sub> )0.25V to +1.0V	
Note 1. Typical thermal registrance, junction to case Dave 28°C/M	Soo Backago Information

Note 1: Typical thermal resistance, junction-to-case  $R_{\theta JC} = 28^{\circ}C/W$ . See Package Information.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **ELECTRICAL CHARACTERISTICS**

(AV<sub>EE</sub> = DV<sub>EE</sub> = -5.2V, V<sub>REF</sub> = 1.000V, T<sub>MIN</sub> to T<sub>MAX</sub> = 0°C to +70°C, unless otherwise noted.) (Note 2.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
DC ACCURACY	·	•					
	DLE1	V <sub>REF</sub> = 1.000V, current out, into	VOUT	-0.012	±0.003	0.012	% Full
Differential Linearity Error	DLE2	virtual ground, end-point linearity	VOUT	-0.05	±0.01	0.05	Scale
late mediline entry France	ILE1	VREF = 1.000V, current out, into	VOUT	-0.012	±0.006	0.012	% Full
Integral Linearity Error	ILE2	virtual ground, end-point linearity	VOUT	-0.05	±0.01	0.05	Scale
Absolute Gain Error	EG	V <sub>REF</sub> = 1.000V, voltage out, VOUT/VIN (Note 3)		-1.0	±0.2	1.0	% Full Scale
12-Bit Monotonicity				Guaranteed			
Output Offset Current	I <sub>OS</sub>	D0–D11 = logic 1, V <sub>REF</sub> = 1.000V, measured at VOUT			40	100	μΑ
Output Leakage Current	ILEAK	D0–D11 = logic 0, $V_{REF}$ = 0V, measured at $\overline{VOUT}$			3	50	μΑ
TIME-DOMAIN PERFORMANC	CE (Note 4)	1					
Fall Time	tfall	90% to 10%, T <sub>A</sub> = +25°C			510		ps
Rise Time	trise	10% to 90%, T <sub>A</sub> = +25°C		450		ps	
Glitch Energy		Major carry, $T_A = +25^{\circ}C$			5.6		pVs
Settling Time		±0.1% FSR		4		ns	
5		±0.024% FSR, 1LSB change			15		
DYNAMIC PERFORMANCE (N	lotes 4, 5)						1
		$f_{OUT} = 5MHz$ , $f_{CLK} = 50MHz$			70		-
		$f_{OUT} = 10MHz$ , $f_{CLK} = 50MHz$		70			dBc
		$f_{OUT} = 20MHz$ , $f_{CLK} = 100MHz$		65			
		$f_{OUT} = 30MHz$ , $f_{CLK} = 100MHz$		60			
Spurious-Free Dynamic Range		$f_{OUT} = 30MHz$ , $f_{CLK} = 200MHz$		56			
		$f_{OUT} = 40MHz$ , $f_{CLK} = 200MHz$ $f_{OUT} = 40MHz$ , $f_{CLK} = 250MHz$		53			
		$f_{OUT} = 400 \text{MHz}, f_{CLK} = 2500 \text{MHz}$		52			
		$f_{OUT} = 40MHz$ , $f_{CLK} = 300MHz$	52				
		$f_{OUT} = 50MHz$ , $f_{CLK} = 300MHz$			52		
Output Noise		Bits 0–11 high, $T_A = +25^{\circ}C$			10.6		<u>nV</u> √Hz

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### **ELECTRICAL CHARACTERISTICS (continued)**

(AV<sub>EE</sub> = DV<sub>EE</sub> = -5.2V, V<sub>REF</sub> = 1.000V, T<sub>MIN</sub> to T<sub>MAX</sub> = 0°C to +70°C, unless otherwise noted.) (Note 2.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DIGITAL INPUTS						
Input Current, Logic High	lih	V <sub>IH</sub> = -0.75V		10	200	μA
Input Current, Logic Low	Ι <sub>ΙL</sub>	V <sub>IL</sub> = -1.95V		1	2	μA
Logic "1" Voltage	VIH		-1.1	-0.75	0	V
Logic "0" Voltage	VIL		-2.0	-1.95	-1.48	V
DIGITAL TIMING	-					1
Data Update Rate	fD	Minimum data rate = DC (Note 6)	300			MHz
Data-to-Clock Setup Time	tsu	Bypass = 0, clocked mode (Notes 4, 7)		1		ps
Data-to-Clock Hold Time	thold	Bypass = 0, clocked mode (Notes 4, 7)		1.8		ns
Clock-to-VOUT Propagation Delay	t <sub>PD3</sub>	Bypass = 0, clocked mode (Notes 4, 7)		2.0		ns
LSBs Data-to-VOUT Propagation Delay	tPD2	Bypass = 1, transparent mode (Notes 4, 7)		1.5		ns
MSBs Data-to-VOUT Propagation Delay	tPD1	Bypass = 1, transparent mode (Notes 4, 7)		2.1		ns
MSBs Decode Delay	t <sub>DD</sub>	Bypass = 1, transparent mode (Notes 4, 7)		600		ps
CONTROL AMPLIFIER						
Amplifier Input Resistance	RIN	$V_{REF} = 1.000 V$	775	800	825	Ω
Multiplying Input Bandwidth	BW	-3dB		10		MHz
Open-Loop Gain	AVol	$T_A = +25^{\circ}C$	3	20		kV/V
Input Offset Voltage	Vos	$T_A = +25^{\circ}C$	-250	0	250	μV
OUTPUT PERFORMANCE						
Full-Scale Output Current	Ιουτ	$V_{REF} = 1.000V, R_L = 0\Omega$	19.0	20.0	21.0	mA
Output Resistance	Rout	VOUT, VOUT	49.5	50.0	50.5	Ω
Output Capacitance	Cout	VOUT, VOUT		15		pF
POWER SUPPLIES						
Analog Power-Supply Current	AIEE	$AV_{EE} = DV_{EE} = -5.2V$	30	46	60	mA
Digital Power-Supply Current	DIEE	$AV_{EE} = DV_{EE} = -5.2V$	110	150	190	mA
Power Dissipation	PD			0.98	1.3	W
Package Thermal Resistance, Junction to Ambient	ALT			28		°C/W

Note 2: All devices are 100% production tested at +25°C and are guaranteed by design for  $T_A = T_{MIN}$  to  $T_{MAX}$  as specified. Note 3: The gain-error method of calculation is shown below:

Definition: [VMEASURE(FS) - VIDEAL(FS)] x 100 FG(%) =	EG Method: EG = [(4096	
VIDEAL(FS)		

 $EG = [(4096 / 4095) V_{MEASURE} - 16(V_{REF} / R_{IN}) (R_{OUT})] \times 100$ 

16(V<sub>REF</sub> / R<sub>IN</sub>) (R<sub>OUT</sub>)

where FS indicates full-scale measurements.

= [(4096 / 4095) V<sub>MEASURE</sub> - 1] x 100 . %

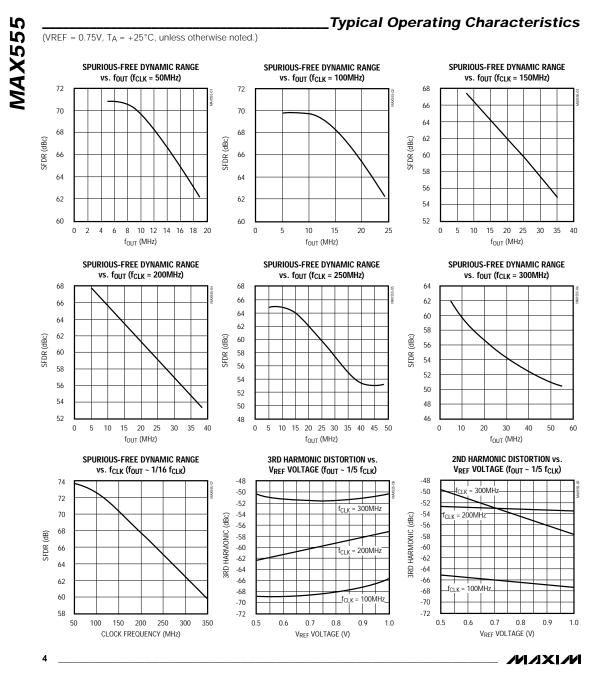
where:  $V_{REF} = 1.000V$ ,  $R_{IN} = 800\Omega$ ,  $R_{OUT} = 50\Omega$ ,  $V_{MEASURE} = \overline{VOUT}$  (FS).

Note 4: Dynamic and timing specifications are obtained from device characterization and simulation testing and are not production tested.
Note 5: Spurious-free dynamic range is measured from the fundamental frequency to any harmonic or non-harmonic spurs within the bandwidth f<sub>CLK</sub>/2, unless otherwise specified.
Note 6: Guaranteed by design.
Note 7: Timing definitions are detailed in Figure 2.

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### Pin Description

### Detailed Description

PIN	NAME	FUNCTION		
1	BYPASS	Disables latching of data when high (ECL input)		
2 CLK		Data Clock (ECL input)		
3 CLK		Data Clock Not (ECL input)		
4, 56, 57, 63, 66 DGND		Digital Signal Grounds		
5, 55	DVEE	-5.2V Digital Power Supplies		
10, 11, 12, 21–25, 27, 31, 36, 37, 40, 41, 43, 45, 46, 61	N.C.	No Connection		
13, 14	VOUT	DAC Outputs		
15, 16	LGND	Ladder Grounds		
17, 18	VOUT	DAC Output Complements		
19, 49, 51, 52, 53, 68	TN	Test Node—internal test point, do not connect		
20, 29, 30, 48	AGND	Analog Signal Grounds		
26, 44	HS	Heatspreader Connections— bypass with 0.1µF to AV <sub>EE</sub>		
28 ALTCOMPIB		PTAT-IB Reference Compensation Output (con- nect bypass capacitor to AV <sub>EE</sub> )		
32 LOOPCRNT		Test node—must connect to AGND		
33, 34	AVEE	-5.2V Analog Power Supplies		
35	VREF/2	Analog Reference Voltage Center-Tap Input		
38, 39	VREF	Analog Reference Voltage Inputs (Kelvin connection)		
42	ROFFSET	Offset Compensation Input		
47 ALTCOMPC		Control-Amplifier PTAT Reference Compensation Input (connect bypass capaci- tor to AVEE)		
50 LBIAS		Ladder-Bias Alternate Compensation Output (con- nect bypass capacitor to AV <sub>EE</sub> )		
54, 58, 59, 60, 62, 64, 65, 67, 6, 7, 8, 9	D11(MSB)- D0(LSB)	Data Words (ECL inputs)		

Figure 1's functional diagram shows the MAX555's three major divisions: a digital section, a control-amplifier section, and a resistor-divider network. The digital section consists of a master/slave register, decoding logic, and current switches. The control-amplifier section includes a control amplifier and an array of 23 current sources divided into three groups. The resistor divider scales the currents from these groups to achieve the correct binary weighting at the output. The output of the resistor-divider network is laser trimmed to  $50\Omega$ , a key feature for driving into controlled impedance transmission lines.

The first group of current sources comprises the six MSBs, D11–D6 (resulting in 15 identical, plus two binary weighted currents), which are applied directly to the output of the resistor-divider network. The second group, bits D5–D3 (three binary weighted currents), is applied to the middle of the divider network. The middle of the network divides the current seen at the output by 8. The third group, bits D2–D0 (three additional binary weighted current sources), is applied to the input of the resistive network, dividing the current seen at the output by 64.

Glitching is reduced by decoding the four MSBs into 15 identical current sources and synchronizing data with a master/slave register at every current switch. Data bits are transferred to the output on the positive-going edge of the clock, with the BYPASS input asserted low. In the asynchronous mode with the BYPASS input asserted high, the latches are transparent and data is transferred to the output regardless of the clock state. All digital inputs are ECL compatible. The clock input is differential.

The control amplifier forces a reference current, which is replicated in the current sources. This reference current is nominally 1.25mA. It can be supplied by an external current source, or by an external voltage source of 1.000V applied to the VREF input.

A reference input of  $V_{REF}$  = 1.000V will produce a full-scale output voltage of  $V_{FS}$  = -1.000V, where:

VFS = 4096 / 4095 x VOUT (code 0)

for the  $\overline{\text{VOUT}}$  output. The output coding is summarized in Table 1.

The DAC's control amplifier has a typical open-loop voltage gain of 85dB, and its gain-magnitude bandwidth is flat up to 10MHz. When the control amplifier is not being used for high-speed multiplying applications, it is recommended that a 0.4 $\mu$ F capacitor be connected from LBIAS to AV<sub>EE</sub> to increase control-amplifier stability and reduce current-source noise.

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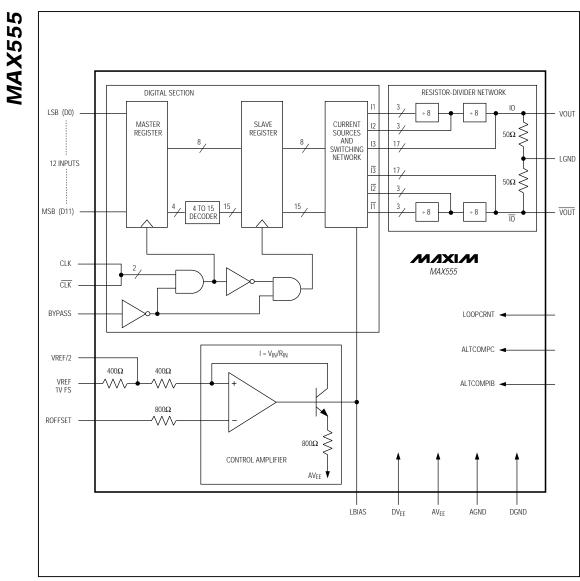


Figure 1. Functional Diagram

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#### Table 1. Output Coding

DIGITAL CODE (D11–D0)	VOUT (V)	VOUT (V)
000000000000	-0.999756	0
00000000001	-0.999512	-0.000244
011111111111	-0.500000	-0.499756
10000000000	-0.499756	-0.500000
111111111111	0	-0.999756

#### **Timing Information**

The MAX555 features a differential ECL clock input with selective transparent operation (BYPASS = 1). It is possible to drive the MAX555 clock single-ended if desired by tying the  $\overline{\text{CLK}}$  input to an external voltage of -1.3V (ECL VBB). However, using a differential clock provides greater noise immunity and improved dynamic performance.

In the clocked mode (BYPASS = 0), when the clock line is low, the slave register is locked out and information on the digital inputs is permitted to enter the master register. The clock transition from low to high locks the master register in its present state and ignores further changes on the digital inputs. This transition simultaneously transfers the contents of the master register to the slave register, causing the DAC output to change.

Figure 2's timing diagram illustrates the importance of operating the MAX555 in the clocked mode. In the transparent mode (BYPASS = 1), both the master and slave registers are transparent, and changes in input data rip-

ple directly to the output. Because the four MSBs are decoded into 15 identical currents, there is a decode delay for these bits that is longer than for the eight LSBs. For the full-scale transition case shown, an intermediate output of 1/16 full-scale occurs until the four MSBs are properly decoded. This decode delay seriously degrades the device's spurious performance. In addition, skew in the timing of the input data also directly appears at the DAC output, further degrading high-speed performance.

**MAX555** 

MAX555 operation in the clocked mode (BYPASS = 0) with a differential clock precludes both of these potential problems and is required for high-speed operation. Since input data can only enter the master register when the clock is low (while the slave register is locked out), data-bus timing skew and the internal MSB decode delay will not appear at the DAC output. The DAC currents are switched only when the clock transitions from low to high, after the internal data stabilizes.

#### Layout and Power Supplies

The MAX555 has separate pins for analog and digital supplies. AVEE and DVEE are connected to each other through the substrate of the IC. These potentials should be derived from the same supply to minimize voltage mismatch, which would cause substrate current flow and possible latchup. Appropriate decoupling is needed to prevent digital-section current spikes from affecting the analog section (Figure 4).

It is recommended that a multilayer PC board be used, containing a solid ground and power planes. All analog

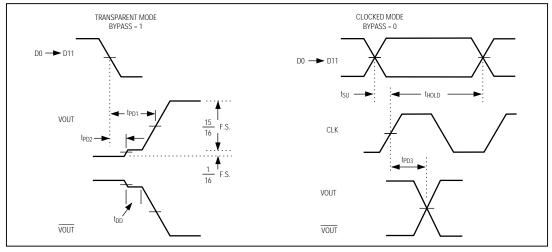


Figure 2. Timing Diagram

M/X/W

and digital ground pins must be connected directly to the analog ground plane at the MAX555, preferably with a "star connection" at the LGND pins (15 and 16).

High-speed ECL inputs, as well as the output from the MAX555, should employ good transmission-line techniques, with terminations close to the device pins. Separate power-supply buses for analog and digital power supplies are recommended as good general practice. Best results will be achieved by bypassing the device pins with high-quality ceramic chip capacitors connected physically close to the pins.

#### Applications Information

#### Reference Input

The MAX555 uses an internal op-amp circuit to buffer the reference current. The input to the op amp may be driven with a 1.25mA external current source or a 1V external voltage reference. The reference input is the VREF pin. The input impedance to the op amp is 800 $\Omega$ . As shown in Figure 1, VREF/2 is brought out externally with 400 $\Omega$  of impedance to the op amp. These reference inputs can be used to vary the full-scale output for high-speed multiplying applications. RoFFSET must be connected to analog ground. In addition, a 0.1µF capacitor should be connected from VREF/2 to analog ground to reduce reference current noise.

#### Outputs

The analog outputs are laser trimmed to  $5\Omega\Omega$ . They can be used either as a voltage drive with  $5\Omega\Omega$  impedance, or to drive into a virtual null using a transimpedance amplifier. Greater speed is achieved driving into  $5\Omega\Omega$  loads. The differential outputs of the MAX555 may be used to drive a balun for conversion to a single-ended output, while at the same time greatly reducing the second-harmonic content of the output.

#### Dynamic Performance

The *Typical Operating Characteristics* graphs show the MAX555's performance when used in direct digital synthesis (DDS) applications for generating RF sine waves. The first six graphs show the MAX555's spurious-free dynamic range (SFDR) for clock frequencies of 50MHz to 300MHz at various output frequencies. The seventh graph shows the SFDR for clock frequencies from 50MHz to 350MHz while producing an output frequency of about 1/16 the clock frequency.

The last two graphs show the MAX555's third and second harmonic distortion while producing an output frequency of about 1/5  $f_{CLK}$  for clock frequencies from 100MHz to 300MHz as a function of the reference voltage. The third harmonic content of the output can be reduced at clock frequencies below about 200MHz by

reducing the reference voltage from its 1.000V nominal value. At clock frequencies above about 200MHz, the output's third harmonic content is dominated by coupling from the high-speed digital inputs to the output. Reducing the reference voltage at these high clock rates actually increases the third harmonic distortion in the output, since the carrier amplitude drops but the third harmonic level remains relatively constant.

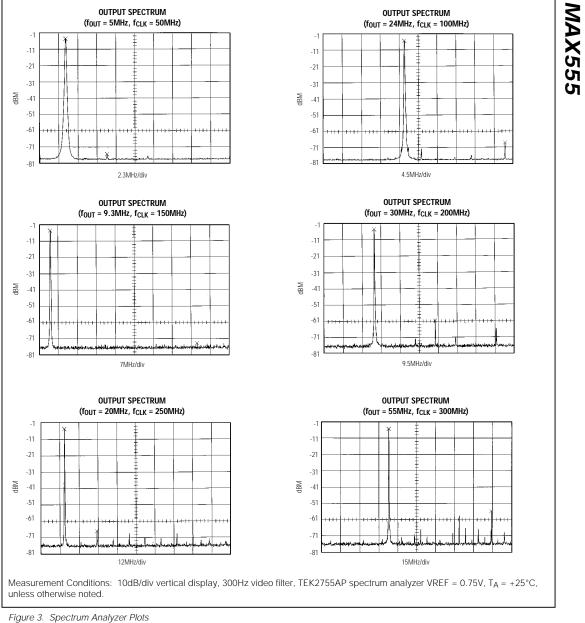
The second harmonic distortion of the outputs is shown as a function of clock frequency and reference voltage. It is relatively constant for clock frequencies below about 200MHz at different VREF values. As with the third harmonic distortion, however, the second harmonic distortion also increases at clock frequencies over 200MHz for lower VREF values. Minimize these effects by bypassing the MAX555 heatspreader (pins 26 and 44) to VEE with a good-quality RF chip capacitor. Reducing the swing of the input logic levels and/or decreasing the rise time of the digital signals can also improve the output's harmonic content. Combining these techniques achieves the best results. Some experimentation may be required to optimize the MAX555's performance for a particular application

Figure 3 shows the spectrum analyzer plots of the MAX555 when used in DDS applications. These plots show the MAX555's output spectrum at clock frequencies from 50MHz to 300MHz while producing various output frequencies. Observing the output spectrum while adjusting the reference voltage or varying the logic levels is a sensitive method of optimizing MAX555 performance. The plots shown were obtained with a +0.75V reference voltage with 500mV ECL logic swings.

### **Typical Application**

Figure 4 shows a typical connection. With VOUT used to drive a 50 $\Omega$  line, the unused complementary output, VOUT, should also be terminated to 50 $\Omega$ . A 1V reference voltage at VREF gives a -0.5V full-scale voltage at VOUT (when doubly terminated with 50 $\Omega$  on the output). Because some loads may represent a complex impedance, be sure to match the output impedance with the load. Mismatching the impedances can cause reflections that will affect AC-performance parameters.

In all applications, the LOOPCRNT pin is always connected to AGND, and compensation capacitors are connected to pins ALTCOMPC, ALTCOMPIB, and LBIAS. The LBIAS compensation is recommended for non-multiplying applications. AC grounding the heat spreader on the package (with pins 26 and 44) reduces digital noise feedthrough and improves the MAX555's spurious performance at high data rates.



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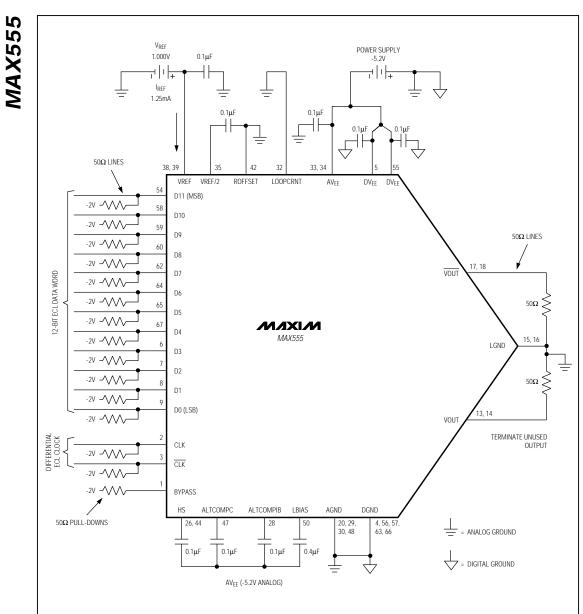


Figure 4. Typical Application

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