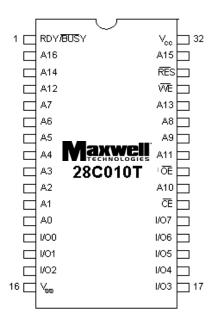
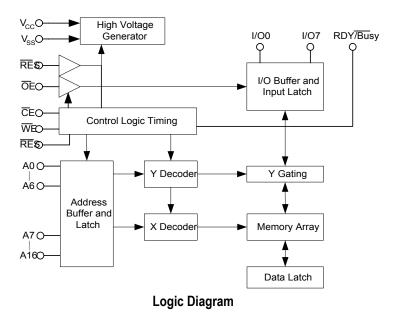


28C010T 1 Megabit (128K x 8-Bit) EEPROM





FEATURES:

- 128k x 8-bit EEPROM
- Rad-Pak® radiation-hardened against natural space radiation
- Total dose hardness:
 - > 100 krad (Si), depending upon space mission
- · Excellent Single Event Effects:
 - No Latchup > 120 MeV/mg/cm²
 - SEU > 90 MeV/mg/cm² read mode
- Package:
 - 32-pin RAD-PAK flat pack/DIP package
 - JEDEC-approved byte-wide pinout
- · High speed:
 - 120, 150, and 200 ns maximum access times available
- · High endurance:
 - 10,000 erase/write (in Page Mode), 10-year data retention
- · Page write mode:
 - 1 to 128 bytes
- Low power dissipation
 - 20 mW/MHz active (typical)
 - 110 µW standby (maximum)
- · Standard JEDEC package width

DESCRIPTION:

Maxwell Technologies' 28C010T high-density 1 Megabit (128K x 8-Bit) EEPROM microcircuit features a greater than 100 krad (Si) total dose tolerance, depending upon space mission. The 28C010T is capable of in-system electrical byte and page programmability. It has a 128-byte page programming function to make its erase and write operations faster. It also features data polling and a Ready/Busy signal to indicate the completion of erase and programming operations. In the 28C010T, hardware data protection is provided with the RES pin, in addition to noise protection on the WE signal and write inhibit on power on and off. Software data protection is implemented using the JEDEC optional standard algorithm.

Maxwell Technologies' patented Rad-Pak® packaging technology incorporates radiation shielding in the microcircuit package. It eliminates the need for box shielding while providing the required radiation shielding for a lifetime in orbit or space mission. In a GEO orbit, Rad-Pak provides greater than 100 krad (Si) radiation dose tolerance. This product is available with screening up to Class S.

TABLE 1. 28C010T PINOUT DESCRIPTION

Pin	Symbol	Description
12-5, 27, 26, 23, 25, 4, 28, 3, 31, 2	A0-A16	Address
24	ŌĒ	Output Enable
22	CE	Chip Enable
29	WE	Write Enable
32	V _{CC}	Power Supply
16	V _{SS}	Ground
1	RDY/BUSY	Ready/Busy
30	RES	Reset

TABLE 2. 28C010T ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	MIN	MAX	UNITS
Supply Voltage (Relative to V _{SS})	V_{CC}	-0.6	+7.0	V
Input Voltage (Relative to V _{SS})	V _{IN}	-0.5 ¹	+7.0	V
Operating Temperature Range	T _{OPR}	-55	+125	°C
Storage Temperature Range	T _{STG}	-65	+150	°C

^{1.} V_{IN} min = -3.0V for pulse width \leq 50ns.

TABLE 3. DELTA LIMITS

PARAMETER	Variation
I _{cc} 1	±10%
I _{CC} 2	±10%
I _{CC} 3A	±10%
I _{CC} 3B	±10%

TABLE 4. 28C010T RECOMMENDED OPERATING CONDITIONS

PARAMETER	Symbol	Min	Max	Units
Supply Voltage	V _{CC}	4.5	5.5	V
Input Voltage	V _{IL}	-0.3 ¹	0.8	V
	V _{IH}	2.2	V _{CC} +0.3	
RES_PIN	V _H	V _{CC} -0.5	V _{CC} +1	
Thermal Impedance — Flat Package	$\Theta_{ extsf{JC}}$		2.17	°C/W

TABLE 4. 28C010T RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Min	Max	Units
Operating Temperature Range	T _{OPR}	-55	+125	°C

1. V_{II} min = -1.0V for pulse width \leq 50 ns

TABLE 5. 28C010T CAPACITANCE

 $(T_A = 25 \, ^{\circ}C, f = 1 \, MHZ)$

Parameter	Symbol	Min	Max	Units
Input Capacitance: V _{IN} = 0V ¹	C _{IN}		6	pF
Output Capacitance: V _{OUT} = 0V ¹	C _{OUT}		12	pF

1. Guaranteed by design.

Table 6. 28C010T DC Electrical Characteristics

(V_{CC} = 5V \pm 10%, T_A = -55 to +125 °C, unless otherwise specified)

Parameter	TEST CONDITION	Symbol	Min	Max	Units
Input Leakage Current	V _{CC} = 5.5V, V _{IN} = 5.5V			2 1	μA
Output Leakage Current	V _{CC} = 5.5V, V _{OUT} = 5.5V/0.4V	I _{LO}		2	μΑ
Standby V _{CC} Current	CE = V _{CC}	I _{CC1}		20	μΑ
	CE = V _{IH}	I _{CC2}		1	mA
Operating V _{CC} Current	I_{OUT} = 0mA, Duty = 100%, Cycle = 1 μ s at V_{CC} = 5.5 V	I _{CC3}		15	mA
	I _{OUT} = 0mA, Duty = 100%, Cycle = 150ns at V _{CC} = 5.5V			50	
Input Voltage		V _{IL}		0.8	V
		V _{IH}	2.2		
RES_PIN		V _H	V _{CC} -0.5		
Output Voltage	I _{OL} = 2.1 mA	V _{OL}		0.4	V
	I _{OH} = -0.4 mA	V _{OH}	2.4		

1. I_{LI} on RES = 100 uA max.

Table 7. 28C010T AC Electrical Characteristics for Read Operation ¹

 $(V_{CC} = 5V \pm 10\%, T_A = -55 \text{ to } +125 ^{\circ}\text{C})$

PARAMETER	Symbol	Min	Max	Units
$\frac{\text{Address Access Time}}{\text{CE} = \text{OE}} = \text{V}_{\text{IL}}, \overline{\text{WE}} = \text{V}_{\text{IH}}$	t _{ACC}			ns
-120			120	
-150			150	
-200			200	

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Table 7. 28C010T AC Electrical Characteristics for Read Operation 1 (V_{CC} = 5V \pm 10%, T_{A} = -55 to +125 $^{\circ}$ C)

PARAMETER	Symbol	Min	Max	Units
Chip Enable Access Time	t _{CE}			ns
$\overline{OE} = V_{IL}, \overline{WE} = V_{IH}$	- CE			
-120			120	
-150			150	
-200			200	
Output Enable Access Time	t _{OE}			ns
$\overline{CE} = V_{IL}, \overline{WE} = V_{IH}$				
-120		0	75	
-150		0	75	
-200		0	100	
Output Hold to Address Change	t _{OH}			ns
$\overline{CE} = \overline{OE} = V_{IL}, \overline{WE} = V_{IH}$				
-120		0		
-150		0		
-200		0		
Output Disable to High-Z 2				ns
$\overline{CE} = V_{IL}, \overline{WE} = V_{IH}$	t _{DF}			
-120		0	50	
-150		0	50	
		0	60	
$\overline{CE} = \overline{OE} = V_{IL}, \overline{WE} = V_{IH}$				
-120	t _{DFR}	0	300	
-150		0	350	
-200		0	450	
RES to Output Delay ³	t _{RR}			ns
$\overline{CE} = \overline{OE} = V_{IL}, \overline{WE} = V_{IH}$				
-120			400	
-150			450	
-200			650	

^{1.} Test conditions: Input pulse levels - 0.4V to 2.4V; input rise and fall times < 20ns; output load - 1 TTL gate + 100pF (including scope and jig); reference levels for measuring timing - 0.8V/1.8V.

Table 8. 28C010T AC Electrical Characteristics for Page/Byte Erase and Byte Write Operations

 $(V_{CC} = 5V + 10\%, T_A = -55 \text{ to } +125 \text{ °C})$

PARAMETER	Symbol	M _{IN} ¹	Max	Units
Address Setup Time	t _{AS}			ns
-120		0		
-150		0		
-200		0		

^{2.} t_{DF} and t_{DFR} are defined as the time at which the output becomes an open circuit and data is no longer driven.

^{3.} Guaranteed by design.

TABLE 8. 28C010T AC ELECTRICAL CHARACTERISTICS FOR PAGE/BYTE ERASE AND BYTE WRITE OPERATIONS

 $(V_{CC} = 5V \pm 10\%, T_A = -55 \text{ to } +125 \text{ °C})$

PARAMETER	Symbol	Min ¹	Max	Units
Chip Enable to Write Setup Time (WE controlled) -120 -150 -200	t _{cs}	0 0 0	 	ns
Write Pulse Width CE controlled -120 -150 -200 WE controlled -120 -150 -200	t _{CW}	200 250 350 200 250 350	 	ns
Address Hold Time -120 -150 -200	t _{AH}	150 150 200	 	ns
Data Setup Time -120 -150 -200	t _{DS}	75 100 150	 	ns
Data Hold Time -120 -150 -200	t _{DH}	10 10 20	 	ns
Chip Enable Hold Time (WE controlled) -120 -150 -2000	t _{CH}	0 0 0	 	ns
Write Enable to Write Setup Time (CE controlled) -120 -150 -200	t _{ws}	0 0 0	 	ns
Write Enable Hold Time (CE controlled) -120 -150 -200	t _{WH}	0 0 0	 	ns
Output Enable to Write Setup Time -120 -150 -200	t _{OES}	0 0 0	 	ns

Table 8. 28C010T AC Electrical Characteristics for Page/Byte Erase and Byte Write Operations

 $(V_{CC} = 5V \pm 10\%, T_A = -55 \text{ to } +125 \text{ °C})$

Parameter	SYMBOL	M _{IN} ¹	Max	Units
Output Enable Hold Time -120 -150 -200	t _{OEH}	0 0 0	 	ns
Write Cycle Time ² -120 -150 -200	t _{wc}	 	10 10 20	ms
Data Latch Time -120 -150 -200	t _{DL}	250 300 400	 	ns
Byte Load Window -120 -150 -200	t _{BL}	100 100 200		μs
Byte Load Cycle -120 -150 -200	t _{BLC}	0.55 0.55 0.95	30 30 30	μs
Time to Device Busy -120 -150 -200	t _{DB}	100 120 170	 	ns
Write Start Time ³ -120 -150 -200	t _{DW}	150 150 250	 	ns
RES to Write Setup Time -120 -150 -200	t _{RP}	100 100 200	 	μs
V _{CC} to RES Setup Time ⁴ -120 -150 -200	t _{RES}	1 1 3	 	μs

^{1.} Use this device in a longer cycle than this value.

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^{2.} t_{WC} must be longer than this value unless polling techniques or RDY/BUSY are used. This device automatically completes the internal write operation within this value.

^{3.} Next read or write operation can be initiated after t_{DW} if polling techniques or RDY/BUSY are used.

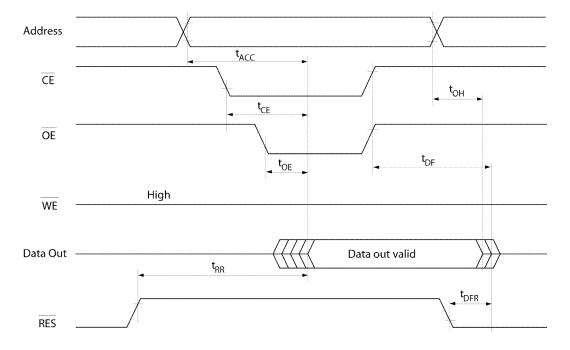
^{4.} Gauranteed by design.

Table 9. 28C010T Mode Selection ¹

PARAMETER	CE	ŌĒ	WE	I/O	RES	RDY/BUSY
Read	V _{IL}	V _{IL}	V _{IH}	D _{OUT}	V _H	High-Z
Standby	V _{IH}	Х	Х	High-Z	Х	High-Z
Write	V _{IL}	V _{IH}	V _{IL}	D _{IN}	V_{H}	High-Z> V _{OL}
Deselect	V _{IL}	V _{IH}	V _{IH}	High-Z	V_{H}	High-Z
Write Inhibit	Х	Х	V _{IH}		Х	
	Х	V _{IL}	Х		Х	
Data Polling	V _{IL}	V _{IL}	V _{IH}	Data Out (I/O7)	V_{H}	V _{OL}
Program	Х	Х	Х	High-Z	V _{IL}	High-Z

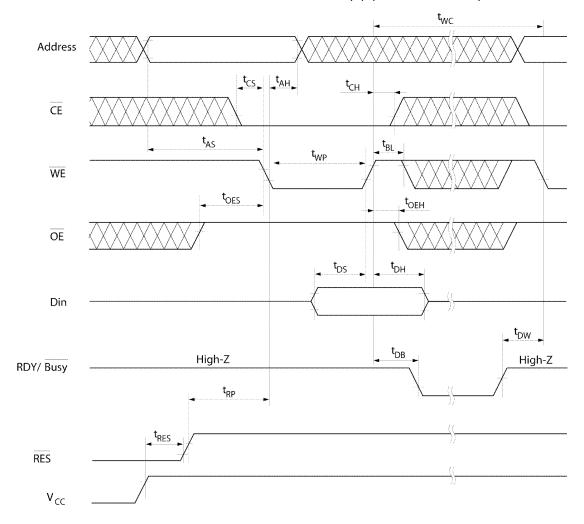
1. X = Don't care.

FIGURE 1. READ TIMING WAVEFORM



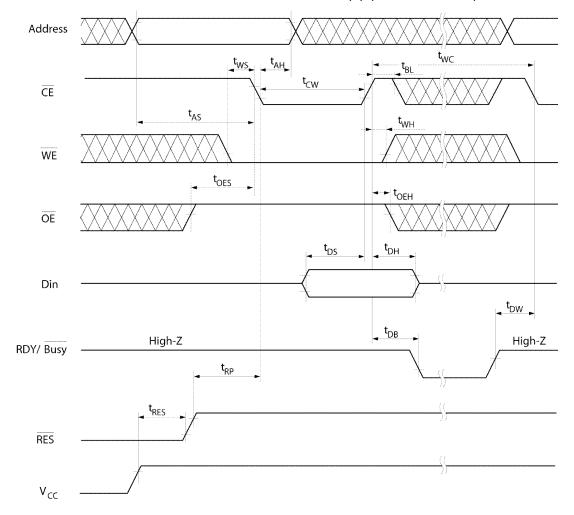
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FIGURE 2. BYTE WRITE TIMING WAVEFORM(1) (WE CONTROLLED)



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FIGURE 3. BYTE WRITE TIMING WAVEFORM (2) (CE CONTROLLED)



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1 Megabit (128K x 8-Bit) EEPROM

FIGURE 4. PAGE WRITE TIMING WAVEFORM(1) (WE CONTROLLED)

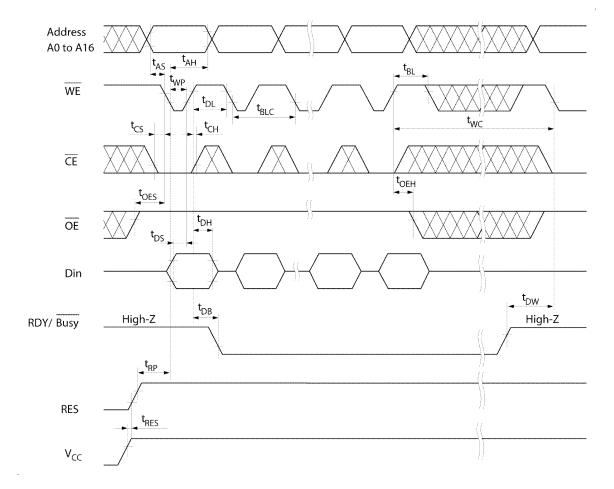


FIGURE 5. PAGE WRITE TIMING WAVEFORM(2) (CE CONTROLLED)

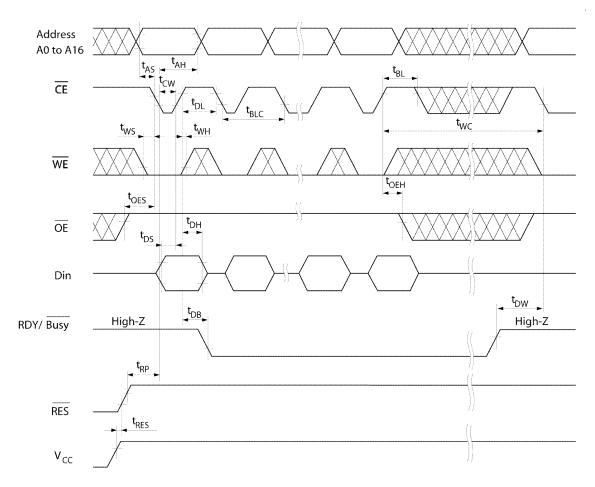
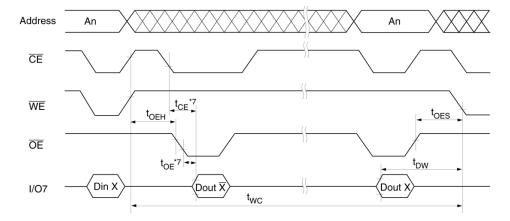


FIGURE 6. DATA POLLING TIMING WAVEFORM



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FIGURE 7. SOFTWARE DATA PROTECTION TIMING WAVEFORM(1) (IN PROTECTION MODE)

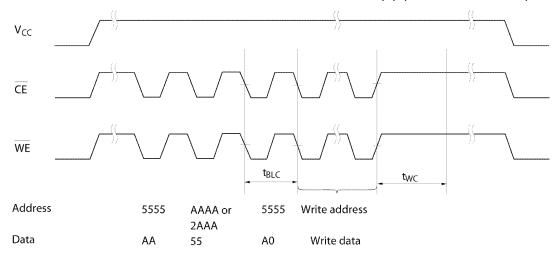
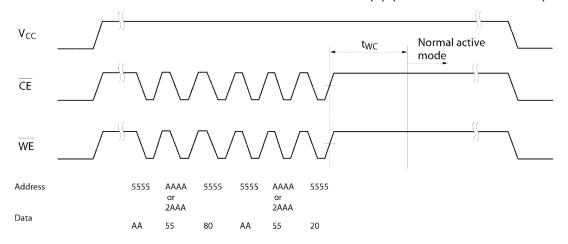


FIGURE 8. SOFTWARE DATA PROTECTION TIMING WAVEFORM(2) (IN NON-PROTECTION MODE)



EEPROM APPLICATION NOTES

This application note describes the programming procedures for the EEPROM modules and with details of various techniques to preserve data protection.

Automatic Page Write

Page-mode write feature allows 1 to 128 bytes of data to be written into the EEPROM in a single write cycle, and allows the undefined data within 128 bytes to be written corresponding to the undefined address (A0 to A6). Loading the first byte of data, the data load window opens 30µs for the second byte. In the same manner each additional byte of data can be loaded within 30µs. In case $\overline{\text{CE}}$ and $\overline{\text{WE}}$ are kept high for 100 µs after data input, EEPROM enters erase and write mode automatically and only the input data are written into the EEPROM.

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WE, CE Pin Operation

<u>During a write cycle</u>, addresses are latched by the falling edge of $\overline{\text{WE}}$ or $\overline{\text{CE}}$, and data is latched by the rising edge of $\overline{\text{WE}}$ or $\overline{\text{CE}}$.

Data Polling

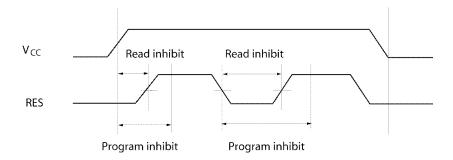
Data Polling function allows the status of the EEPROM to be determined. If EEPROM is set to read mode during a write cycle, an inversion of the last byte of data to be loaded outputs from I/O 7 to indicate that the EEPROM is performing a write operation.

RDY/Busy Signal

RDY/Busy signal also allows a comparison operation to determine the status of the EEPROM. The RDY/Busy signal has high <u>impe</u>dance except in write cycle and is lowered to V_{OL} after the first write signal. At the-end of a write cycle, the RDY/Busy signal changes state to high impedance.

RES Signal

When $\overline{\text{RES}}$ is LOW, the EEPROM cannot be read and programmed. Therefore, data can be protected by keeping RES low when V_{CC} is switched. RES should be high during read and programming because it doesn't provide a latch function.



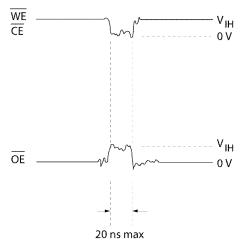
Data Protection

To protect the data during operation and power on/off, the EEPROM has the internal functions described below.

1. Data Protection against Noise of Control Pins (\overline{CE} , \overline{OE} , \overline{WE}) during Operation.

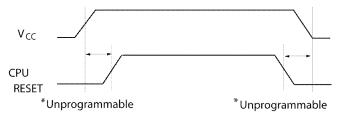
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During readout or standby, noise on the control pins may act as a trigger and turn the EEPROM to programming mode by mistake. To prevent this phenomenon, the EEPROM has a noise cancellation function that cuts noise if its width is 20ns or less in programming mode. Be careful not to allow noise of a width of more than 20ns on the control pins.

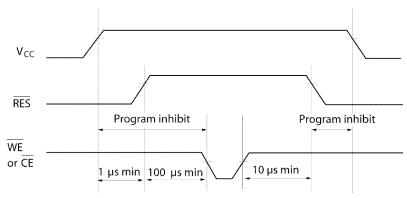


2. Data Protection at V_{CC} on/off

When V_{CC} is turned on or off, noise on the control pins generated by external circuits, such as CPUs, may turn the EEPROM to programming mode by mistake. To prevent this unintentional programming, the EEPROM must be kept in unprogrammable state during V_{CC} on/off by using a CPU reset signal to \overline{RES} pin.



 $\overline{\text{RES}}$ should be kept at V_{SS} level when V_{CC} is turned on or off. The EEPROM breaks off programming operation when $\overline{\text{RES}}$ become low, programming operation doesn't finish correctly in case that $\overline{\text{RES}}$ falls low during programming operation. $\overline{\text{RES}}$ should be kept high for 10 ms after the last data input.



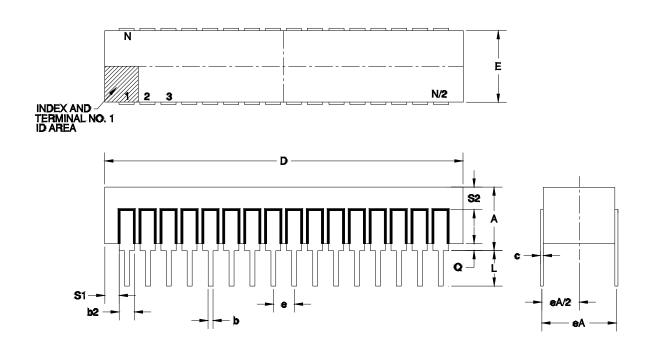
3. Software Data Protection

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The software data protection function is to prevent unintentional programming caused by noise generated by external circuits. In software data protection mode, 3 bytes of data must be input before write data as follows. These bytes can switch the nonprotection mode to the protection mode.

Software data protection mode can be canceled by inputting the following 6 bytes. Then, the EEPROM turns to the non-protection mode and can write data normally. However, when the data is input in the canceling cycle, the data cannot be written.

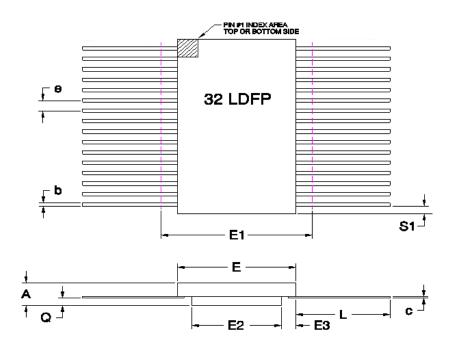
Address	Data
5555	AA
AAAA or 2AAA	5 5 5
↓ 5555	80 80
↓ 5555	↓ AA
AAAA or 2AAA	55
\downarrow	J,
5555	20



32 PIN DUAL IN-LINE PACKAGE

Symbol	DIMENSION				
	Min	Nом	Max		
А		0.152	0.225		
b	0.014	0.018	0.026		
b2	0.045	0.050	0.065		
С	0.008	0.010	0.018		
D		1.600	1.680		
Е	0.510	0.590	0.620		
eA	0.600 BSC				
eA/2	0.300 BSC				
е	0.100 BSC				
L	0.135	0.145	0.155		
Q	0.015	0.037	0.070		
S1	0.005	0.025			
S2	0.005				
N	32				

D32-02 Note: All dimensions in inches



28C010T 32-PIN RAD-PAK® FLAT PACKAGE

Sүмвоl —	DIMENSION				
	Min	Nом	Max		
A	0.121	0.134	0.147		
b	0.015	0.017	0.022		
С	0.004	0.005	0.009		
D		0.820	0.830		
E	0.472	0.480	0.488		
E1			0.498		
E2	0.304	0.31			
E3	0.030	0.085			
е	0.050BSC				
L	0.355	0.365	0.375		
Q	0.020	0.035	0.045		
S1	0.005	0.027			
N	32				

F32-10
Note: All dimensions in inches.

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Important Notice:

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These data sheets are created using the chip manufacturers published specifications. Maxwell Technologies verifies functionality by testing key parameters either by 100% testing, sample testing or characterization.

The specifications presented within these data sheets represent the latest and most accurate information available to date. However, these specifications are subject to change without notice and Maxwell Technologies assumes no responsibility for the use of this information.

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Product Ordering Options

