

93C56A/B

2K 5.0V Automotive Temperature Microwire® **Serial EEPROM**

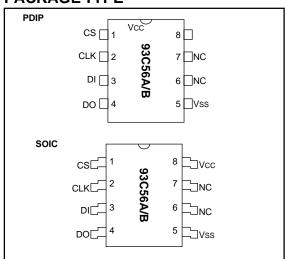
FEATURES

- Single supply 5.0V operation
- · Low power CMOS technology
 - 1 mA active current (typical)
 - 1 μA standby current (maximum)
- 256 x 8 bit organization (93C56A)
- 128 x 16 bit organization (93C56B)
- Self-timed ERASE and WRITE cycles (including auto-erase)
- · Automatic ERAL before WRAL
- Power on/off data protection circuitry
- · Industry standard 3-wire serial interface
- Device status signal during ERASE/WRITE cycles
- Sequential READ function
- 100,000 E/W cycles guaranteed
- Data retention > 200 years
- 8-pin PDIP and SOIC packages
- · Available for the following temperature ranges:
 - Automotive (E): -40°C to +125°C

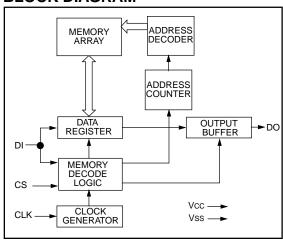
DESCRIPTION

The Microchip Technology Inc. 93C56A/B is a 2K-bit, low-voltage serial Electrically Erasable PROM. The device memory is configured as 256 x 8 bits (93C56A) or 128 x 16 bits (93C56B). Advanced CMOS technology makes this device ideal for low-power, nonvolatile memory applications. The 93C56A/B is available in standard 8-pin DIP and surface mount SOIC packages. This device is only recommeded for 5V automotive temperature applications. For all commercial and industrial applications, the 93LC56A/B is recommended.

PACKAGE TYPE



BLOCK DIAGRAM



Microwire is a registered trademark of National Semiconductor.

1.0 ELECTRICAL CHARACTERISTICS

1.1 <u>Maximum Ratings*</u>

| Vcc | 7.0V |
|--|-------------------|
| All inputs and outputs w.r.t. Vss | 0.6V to Vcc +1.0V |
| Storage temperature | 65°C to +150°C |
| Ambient temp. with power applied | 65°C to +125°C |
| Soldering temperature of leads (10 secon | nds)+300°C |
| ESD protection on all pins | 4 kV |

*Notice: Stresses above those listed under "Maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

TABLE 1-1: PIN FUNCTION TABLE

| Name | Function |
|------|--------------------|
| CS | Chip Select |
| CLK | Serial Data Clock |
| DI | Serial Data Input |
| DO | Serial Data Output |
| Vss | Ground |
| NC | No Connect |
| Vcc | Power Supply |

TABLE 1-2: DC AND AC ELECTRICAL CHARACTERISTICS

| All parameters apply over the specified operating ranges unless otherwise noted | Automotive (E)Vcc = +4.5V to +5.5VTamb = -40°C to +125°C | | | | | | |
|---|--|------|--------|--------|--|--|--|
| Parameter | Symbol | Min. | Max. | Units | Conditions | | |
| High level input voltage | VIH | 2.0 | Vcc +1 | V | (Note 2) | | |
| Low level input voltage | VIL | -0.3 | 0.8 | V | | | |
| Low level output voltage | Vol | _ | 0.4 | V | IOL = 2.1 mA; VCC = 4.5V | | |
| High level output voltage | Voн | 2.4 | _ | V | IOH = -400 μA; VCC = 4.5V | | |
| Input leakage current | ILI | -10 | 10 | μΑ | VIN = VSS to VCC | | |
| Output leakage current | ILO | -10 | 10 | μΑ | Vout = Vss to Vcc | | |
| Pin capacitance (all inputs/outputs) | CIN, COUT | _ | 7 | pF | VIN/VOUT = 0 V (Notes 1 & 2) Tamb = +25°C, FCLK = 1 MHz | | |
| Operating current | Icc write | _ | 1.5 | mA | | | |
| Operating current | Icc read | _ | 1 | mA | | | |
| Standby current | Iccs | _ | 1 | μΑ | CS = Vss | | |
| Clock frequency | FCLK | _ | 2 | MHz | | | |
| Clock high time | Тскн | 250 | _ | ns | | | |
| Clock low time | TCKL | 250 | _ | ns | | | |
| Chip select setup time | Tcss | 50 | _ | ns | Relative to CLK | | |
| Chip select hold time | Тсѕн | 0 | _ | ns | Relative to CLK | | |
| Chip select low time | TCSL | 250 | _ | ns | | | |
| Data input setup time | TDIS | 100 | _ | ns | Relative to CLK | | |
| Data input hold time | TDIH | 100 | _ | ns | Relative to CLK | | |
| Data output delay time | TPD | _ | 400 | ns | CL = 100 pF | | |
| Data output disable time | Tcz | _ | 100 | ns | CL = 100 pF (Note 2) | | |
| Status valid time | Tsv | _ | 500 | ns | CL = 100 pF | | |
| | Twc | | 2 | ms | ERASE/WRITE mode | | |
| Program cycle time | TEC | | 6 | ms | ERAL mode | | |
| | TWL | | 15 | ms | WRAL mode | | |
| Endurance | _ | 100K | _ | cycles | 25°C, Vcc = 5.0V, Block Mode (Note 3) | | |

- **Note 1:** This parameter is tested at Tamb = 25°C and FCLK = 1 MHz.
 - 2: This parameter is periodically sampled and not 100% tested.
 - 3: This application is not tested but guaranteed by characterization. For endurance estimates in a specific application, please consult the Total Endurance Model which may be obtained on Microchip's BBS or website.

2.0 PIN DESCRIPTION

2.1 Chip Select (CS)

A high level selects the device. A low level deselects the device and forces it into standby mode. However, a programming cycle which is already in progress will be completed, regardless of the CS input signal. If CS is brought low during a program cycle, the device will go into standby mode as soon as the programming cycle is completed.

CS must be low for 250 ns minimum (TCSL) between consecutive instructions. If CS is low, the internal control logic is held in a RESET status.

2.2 Serial Clock (CLK)

The Serial Clock is used to synchronize the communication between a master device and the 93C56A/B. Opcode, address, and data bits are clocked in on the positive edge of CLK. Data bits are also clocked out on the positive edge of CLK.

CLK can be stopped anywhere in the transmission sequence (at high or low level) and can be continued anytime with respect to clock high time (TCKH) and clock low time (TCKL). This gives the controlling master freedom in preparing opcode, address, and data.

CLK is a "Don't Care" if CS is low (device deselected). If CS is high, but the START condition has not been detected, any number of clock cycles can be received by the device without changing its status (i.e., waiting for a START condition).

CLK cycles are not required during the self-timed WRITE (i.e., auto ERASE/WRITE) cycle.

After detecting a START condition, the specified number of clock cycles (respectively low to high transitions of CLK) must be provided. These clock cycles are required to clock in all required opcode, address, and data bits before an instruction is executed (Table 2-1 and Table 2-2). CLK and DI then become don't care inputs waiting for a new START condition to be detected.

| Note: | CS mus | t go | low | between | consecutive |
|-------|-------------|------|-----|---------|-------------|
| | instruction | ns. | | | |

2.3 <u>Data In (DI)</u>

Data In is used to clock in a START bit, opcode, address, and data synchronously with the CLK input.

2.4 Data Out (DO)

Data Out is used in the READ mode to output data synchronously with the CLK input (TPD after the positive edge of CLK).

This pin also provides READY/BUSY status information during ERASE and WRITE cycles. READY/BUSY status information is available on the DO pin if CS is brought high after being low for minimum chip select low time (TCSL) and an ERASE or WRITE operation has been initiated. The status signal is not available on DO, if CS is held low during the entire ERASE or WRITE cycle. In this case, DO is in the HIGH-Z mode. If status is checked after the ERASE/WRITE cycle, the data line will be high to indicate the device is ready.

TABLE 2-1: INSTRUCTION SET FOR 93C56A

| Instruction | SB | Opcode | | Address | | | | | | | | Data In | Data Out | Req. CLK Cycles |
|-------------|----|--------|---|---------|----|----|----|----|----|----|----|---------|-----------|-----------------|
| ERASE | 1 | 11 | Х | A7 | A6 | A5 | A4 | А3 | A2 | A1 | A0 | _ | (RDY/BSY) | 12 |
| ERAL | 1 | 00 | 1 | 0 | Χ | Χ | Χ | Χ | Χ | Χ | Χ | _ | (RDY/BSY) | 12 |
| EWDS | 1 | 00 | 0 | 0 | Χ | Х | Χ | Χ | Х | Χ | Х | _ | HIGH-Z | 12 |
| EWEN | 1 | 00 | 1 | 1 | Χ | Χ | Χ | Χ | Χ | Χ | Χ | _ | HIGH-Z | 12 |
| READ | 1 | 10 | Х | A7 | A6 | A5 | A4 | А3 | A2 | A1 | A0 | _ | D7 - D0 | 20 |
| WRITE | 1 | 01 | Х | A7 | A6 | A5 | A4 | А3 | A2 | A1 | A0 | D7 - D0 | (RDY/BSY) | 20 |
| WRAL | 1 | 00 | 0 | 1 | Χ | Χ | Χ | Χ | Χ | Χ | Χ | D7 - D0 | (RDY/BSY) | 20 |

TABLE 2-2: INSTRUCTION SET FOR 93C56B

| Instruction | SB | Opcode | | Address | | | | | | | Data In | Data Out | Req. CLK Cycles |
|-------------|----|--------|---|---------|----|----|----|----|----|----|----------|-----------|-----------------|
| ERASE | 1 | 11 | Х | A6 | A5 | A4 | А3 | A2 | A1 | A0 | _ | (RDY/BSY) | 11 |
| ERAL | 1 | 00 | 1 | 0 | Χ | Χ | Χ | Χ | Χ | Χ | _ | (RDY/BSY) | 11 |
| EWDS | 1 | 00 | 0 | 0 | Χ | Х | Х | Χ | Χ | Χ | _ | HIGH-Z | 11 |
| EWEN | 1 | 00 | 1 | 1 | Х | Х | Х | Χ | Х | Х | _ | HIGH-Z | 11 |
| READ | 1 | 10 | Χ | A6 | A5 | A4 | АЗ | A2 | A1 | A0 | _ | D15 - D0 | 27 |
| WRITE | 1 | 01 | Х | A6 | A5 | A4 | АЗ | A2 | A1 | A0 | D15 - D0 | (RDY/BSY) | 27 |
| WRAL | 1 | 00 | 0 | 1 | Χ | Х | Х | Χ | Χ | Χ | D15 - D0 | (RDY/BSY) | 27 |

FUNCTIONAL DESCRIPTION 3.0

Instructions, addresses, and write data are clocked into the DI pin on the rising edge of the clock (CLK). The DO pin is normally held in a HIGH-Z state except when reading data from the device, or when checking the READY/BUSY status during a programming operation. The READY/BUSY status can be verified during an ERASE/WRITE operation by polling the DO pin; DO low indicates that programming is still in progress, while DO high indicates the device is ready. The DO will enter the HIGH-Z state on the falling edge of the CS.

3.1 **START Condition**

The START bit is detected by the device if CS and DI are both high with respect to the positive edge of CLK for the first time.

Before a START condition is detected, CS, CLK, and DI may change in any combination (except to that of a START condition), without resulting in any device operation (READ, WRITE, ERASE, EWEN, EWDS, ERAL, and WRAL). As soon as CS is high, the device is no longer in the standby mode.

An instruction following a START condition will only be executed if the required amount of opcode, address and data bits for any particular instruction is clocked in.

After execution of an instruction (i.e., clock in or out of the last required address or data bit) CLK and DI become don't care bits until a new START condition is detected

3.2 Data IN (DI) and Data Out (DO)

It is possible to connect the Data In (DI) and Data Out (DO) pins together. However, with this configuration, if A0 is a logic-high level, it is possible for a "bus conflict" to occur during the "dummy zero" that precedes the READ operation. Under such a condition, the voltage level seen at DO is undefined and will depend upon the relative impedances of DO and the signal source driving A0. The higher the current sourcing capability of A0, the higher the voltage at the DO pin.

3.3 **Data Protection**

During power-up, all programming modes of operation are inhibited until Vcc has reached a level greater than 3.8V. During power-down, the source data protection circuitry acts to inhibit all programming modes when Vcc has fallen below 3.8V at nominal conditions.

The ERASE/WRITE Disable (EWDS) and ERASE WRTE Enable (EWEN) commands give additional protection against accidentally programming during normal operation.

After power-up, the device is automatically in the EWDS mode. Therefore, an EWEN instruction must be performed before any ERASE or WRITE instruction can be executed.

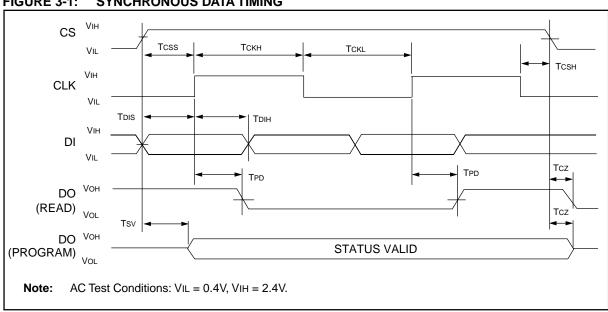


FIGURE 3-1: SYNCHRONOUS DATA TIMING

3.4 ERASE

The ERASE instruction forces all data bits of the specified address to the logical "1" state. This cycle begins on the rising clock edge of the last address bit.

The DO pin indicates the READY/BUSY status of the device if CS is brought high after a minimum of 250 ns low (Tcsl). DO at logical "0" indicates that programming is still in progress. DO at logical "1" indicates that the register at the specified address has been erased and the device is ready for another instruction.

3.5 Erase All (ERAL)

The ERAL instruction will erase the entire memory array to the logical "1" state. The ERAL cycle is identical to the ERASE cycle, except for the different opcode. The ERAL cycle is completely self-timed and commences at the rising clock edge of the last address bit. Clocking of the CLK pin is not necessary after the device has entered the ERAL cycle.

The DO pin indicates the READY/BUSY status of the device, if CS is brought high after a minimum of 250 ns low (TCSL) and before the entire ERAL cycle is complete.

FIGURE 3-2: ERASE TIMING

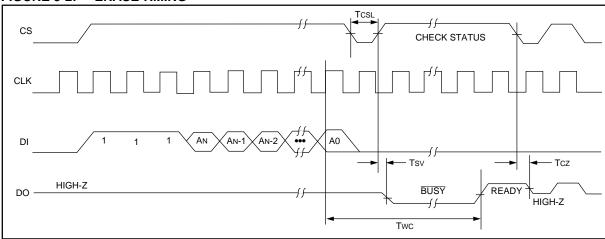
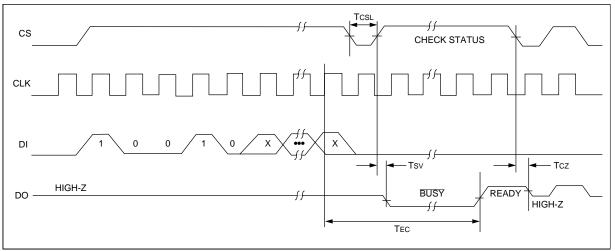


FIGURE 3-3: ERAL TIMING



3.6 <u>ERASE/WRITE Disable and Enable</u> (EWDS/EWEN)

The device powers up in the ERASE/WRITE Disable (EWDS) state. All programming modes must be preceded by an ERASE/WRITE Enable (EWEN) instruction. Once the EWEN instruction is executed, programming remains enabled until an EWDS instruction is executed or Vcc is removed from the device. To protect against accidental data disturbance, the EWDS instruction can be used to disable all ERASE/WRITE functions and should follow all programming operations. Execution of a READ instruction is independent of both the EWEN and EWDS instructions.

3.7 READ

The READ instruction outputs the serial data of the addressed memory location on the DO pin. A dummy zero bit precedes the 8-bit (93C56A) or 16-bit (93C56B) output string. The output data bits will toggle on the rising edge of the CLK and are stable after the specified time delay (TPD). Sequential read is possible when CS is held high. The memory data will automatically cycle to the next register and output sequentially.

FIGURE 3-4: READ TIMING

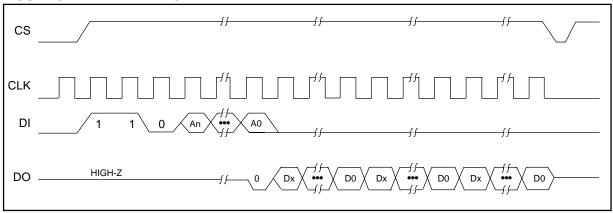


FIGURE 3-5: EWDS TIMING

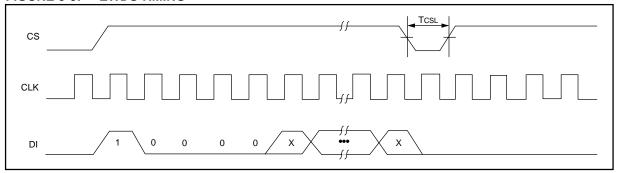
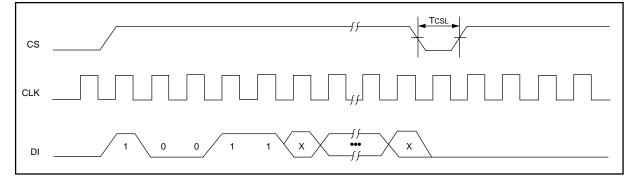


FIGURE 3-6: EWEN TIMING



3.8 WRITE

The WRITE instruction is followed by 8-bits (93C56A) 16-bits (93C56B) of data which are written into the specified address. After the last data bit is clocked into the DI pin, the self-timed auto-erase and programming cycle begins.

The DO pin indicates the READY/BUSY status of the device, if CS is brought high after a minimum of 250 ns low (TCSL) and before the entire write cycle is complete. DO at logical "0" indicates that programming is still in progress. DO at logical "1" indicates that the register at the specified address has been written with the data specified and the device is ready for another instruction.

3.9 Write All (WRAL)

The Write All (WRAL) instruction will write the entire memory array with the data specified in the command. The WRAL cycle is completely self-timed and commences at the rising clock edge of the last data bit. Clocking of the CLK pin is not necessary after the device has entered the WRAL cycle. The WRAL command does include an automatic ERAL cycle for the device. Therefore, the WRAL instruction does not require an ERAL instruction but the chip must be in the EWEN status.

The DO pin indicates the READY/BUSY status of the device if CS is brought high after a minimum of 250 ns low (TCSL).

FIGURE 3-7: WRITE TIMING

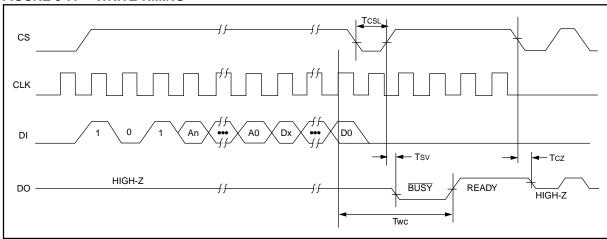
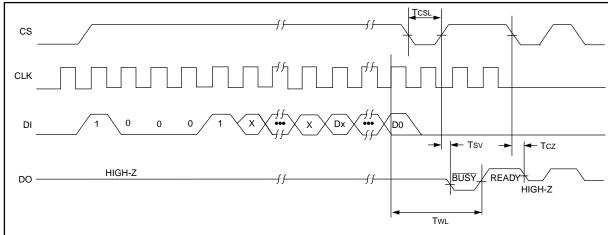


FIGURE 3-8: WRAL TIMING



| 03 | C5 | 64 | /R |
|----|----|--------------|-----|
| JJ | | \mathbf{U} | V D |

NOTES:

| Q | 3 | C | 5 | 6 | Δ | / | R |
|---|---|---|---|----|---------------|-----|---|
| • | • | • | • | u. | $\overline{}$ | , , | |

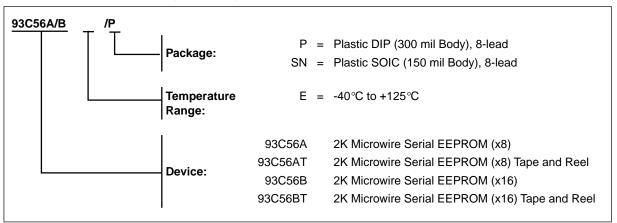
NOTES:

| Q | 3 | C5 | 6 | Δ | /R |
|---|---|-----------|---|--------|----|
| J | J | UU | v | \neg | |

NOTES:

93C56A/B PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.



Sales and Support

Data Sheets

Products supported by a preliminary Data Sheet may have an errata sheet describing minor operational differences and recommended workarounds. To determine if an errata sheet exists for a particular device, please contact one of the following:

- 1. Your local Microchip sales office.
- 2. The Microchip Corporate Literature Center U.S. FAX: (602) 786-7277.
- 3. The Microchip's Bulletin Board, via your local CompuServe number (CompuServe membership NOT required).



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Corporate Office

Microchip Technology Inc. 2355 West Chandler Blvd. Chandler, AZ 85224-6199 Tel: 602-786-7200 Fax: 602-786-7277 Technical Support: 602 786-7627 Web: http://www.microchip.com

Atlanta

Microchip Technology Inc. 500 Sugar Mill Road, Suite 200B Atlanta, GA 30350 Tel: 770-640-0034 Fax: 770-640-0307

Microchip Technology Inc. 5 Mount Royal Avenue Marlborough, MA 01752 Tel: 508-480-9990 Fax: 508-480-8575

Chicago

Microchip Technology Inc. 333 Pierce Road, Suite 180 Itasca, IL 60143 Tel: 630-285-0071 Fax: 630-285-0075

Dallas

Microchip Technology Inc. 14651 Dallas Parkway, Suite 816 Dallas, TX 75240-8809 Tel: 972-991-7177 Fax: 972-991-8588

Dayton

Microchip Technology Inc. Two Prestige Place, Suite 150 Miamisburg, OH 45342 Tel: 937-291-1654 Fax: 937-291-9175

Los Angeles

Microchip Technology Inc. 18201 Von Karman, Suite 1090 Irvine, CA 92612 Tel: 714-263-1888 Fax: 714-263-1338

New York

Microchip Technology Inc. 150 Motor Parkway, Suite 202 Hauppauge, NY 11788 Tel: 516-273-5305 Fax: 516-273-5335

San Jose

Microchip Technology Inc. 2107 North First Street, Suite 590 San Jose, CA 95131 Tel: 408-436-7950 Fax: 408-436-7955

Toronto

Microchip Technology Inc. 5925 Airport Road, Suite 200 Mississauga, Ontario L4V 1W1, Canada Tel: 905-405-6279 Fax: 905-405-6253

ASIA/PACIFIC

Hong Kong

Microchip Asia Pacific RM 3801B, Tower Two Metroplaza 223 Hing Fong Road Kwai Fong, N.T., Hong Kong Tel: 852-2-401-1200 Fax: 852-2-401-3431

Microchip Technology Inc. India Liaison Office No. 6, Legacy, Convent Road Bangalore 560 025, India Tel: 91-80-229-0061 Fax: 91-80-229-0062

Korea

Microchip Technology Korea 168-1, Youngbo Bldg. 3 Floor Samsung-Dong, Kangnam-Ku Seoul, Korea Tel: 82-2-554-7200 Fax: 82-2-558-5934

Shanghai

Microchip Technology RM 406 Shanghai Golden Bridge Bldg. 2077 Yan'an Road West, Hong Qiao District Shanghai, PRC 200335 Tel: 86-21-6275-5700 Fax: 86 21-6275-5060

Singapore

Microchip Technology Taiwan Singapore Branch 200 Middle Road #07-02 Prime Centre Singapore 188980 Tel: 65-334-8870 Fax: 65-334-8850

Taiwan, R.O.C

Microchip Technology Taiwan 10F-1C 207 Tung Hua North Road Taipei, Taiwan, ROC Tel: 886-2-2717-7175 Fax: 886-2-2545-0139

EUROPE

United Kingdom

Arizona Microchip Technology Ltd. 505 Eskdale Road Winnersh Triangle Wokingham Berkshire, England RG41 5TU Tel: 44-1189-21-5858 Fax: 44-1189-21-5835

Arizona Microchip Technology SARL Zone Industrielle de la Bonde 2 Rue du Buisson aux Fraises 91300 Massy, France Tel: 33-1-69-53-63-20 Fax: 33-1-69-30-90-79

Germany

Arizona Microchip Technology GmbH Gustav-Heinemann-Ring 125 D-81739 Müchen, Germany Tel: 49-89-627-144 0 Fax: 49-89-627-144-44

Arizona Microchip Technology SRL Centro Direzionale Colleoni Palazzo Taurus 1 V. Le Colleoni 1 20041 Agrate Brianza Milan, Italy Tel: 39-39-6899939 Fax: 39-39-6899883

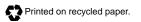
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Microchip Technology Intl. Inc. Benex S-1 6F 3-18-20, Shinyokohama Kohoku-Ku, Yokohama-shi Kanagawa 222 Japan Tel: 81-45-471- 6166 Fax: 81-45-471-6122

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