

# 2.6GHz Bidirectional I<sup>2</sup>C BUS Controlled Synthesiser

Supersedes version in April 1994 Consumer IC Handbook, HB3120 - 2.0

DS2384 - 4.4 May 1996

The SP5055 is a single chip frequency synthesiser designed for TV tuning systems. Control data is entered in the standard I²C BUS format. The device contains 4 addressable current limited outputs and 4 addressable Bi-Directional open collector ports one of which is a 3 bit ADC. The information on these ports can be read via the I²C BUS. The device has one fixed I²C BUS address and 3 programmable addresses, programmed by applying a specific input voltage to one of the current limited outputs. This enables 2 or more synthesisers to be used in a system.

#### **FEATURES**

- Complete 2.6GHz Single Chip System
- Programmable via I<sup>2</sup>C BUS
- Low power consumption (5V 65mA)
- Low Radiation
- Phase Lock Detector
- Varactor Drive Amp Disable
- 6 Controllable Outputs, 4 Bi-Directional
- 5 Level ADC
- Variable I<sup>2</sup>C BUS Address For Multi Tuner Applications
- Full ESD Protection\*
  - \* Normal ESD handling procedures should be observed.

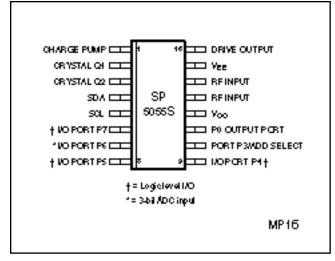


Fig. 1 Pin connections - top view

#### **APPLICATIONS**

- Satellite TV
- High IF Cable Tuning Systems

### **ORDERING INFORMATION**

SP5055S MP - (16 lead Miniature Plastic package)

ELECTRICAL CHARACTERISTICS

T<sub>amb</sub> = -20°C to +80°C, V<sub>CC</sub> = +4.7V to 5.3V.

These Characteristics are guaranteed by either production test or design. They apply within the specified ambient temperature and supply voltage unless otherwise stated. Reference frequency = 4MHz unless otherwise stated.

Characteristic	Dim		Value		lle:te	O a maliti a ma		
Characteristic	Pin	Min.	Тур.	Max.	Units	Conditions		
Supply current Prescaler input voltage Prescaler input voltage	12 13, 14 13, 14	50 100	65	80 300 300	$\begin{array}{c} \text{mA} \\ \text{mV}_{\text{RMS}} \\ \text{mV}_{\text{RMS}} \end{array}$	V <sub>CC</sub> = 5V 500MHz to 2.6GHz Sinewave 120MHz, see Fig. 5		
Prescaler input impedance Prescaler input capacitance	13, 14		50 2		pF			
SDA, SCL Input high voltage Input low voltage Input high current Input low current Leakage current	4, 5 4, 5 4, 5 4, 5 4, 5 4, 5	3 0		5.5 1.5 10 -10	>	Input voltage = $V_{CC}$ Input voltage = $0V$ When $V_{CC} = 0V$		
SDA Output voltage	4			0.4	V	I <sub>sink</sub> = 3mA		
Charge pump current low Charge pump current high Charge pump output leakage current Charge pump drive output current Charge pump amplifier gain	1 1 1 16	500	±50 ±170	±5	μΑ μΑ nA μΑ	Byte 4, bit 2 = 0, pin 1 = 2V Byte 4, bit 2 = 1, pin 1 = 2V Byte 4, bit 4 = 1, pin 1 = 2V V <sub>pin 16</sub> = 0.7V		
Recommended crystal series resistance Crystal oscillator drive level Crystal oscillator negative resistance	2 2	10 750	80	200	mVp-p			
Output Ports P0, P3 sink current P0, P3 leakage current P4-P7 sink current P4-P7 leakage current	10, 11 10, 11 9-6 9-6	0.7	1	1.5 10	mA μA mA μA	$V_{OUT} = 12V$ $V_{OUT} = 13.2V$ $V_{OUT} = 0.7V$ $V_{OUT} = 13.2V$		
Input Ports P3 input current high P3 input current low P4,P5,P7 input voltage low P4,P5,P7 input voltage high P6 input current high P6 input current low	10 10 9,8,6 9,8,6 7 7	2.7		+10 -10 0.8 +10 -10	Д А У Д Д Д Д	$V_{pin 10} = 13.2V$ $V_{pin 10} = 0V$ See Table 3 for ADC Levels		

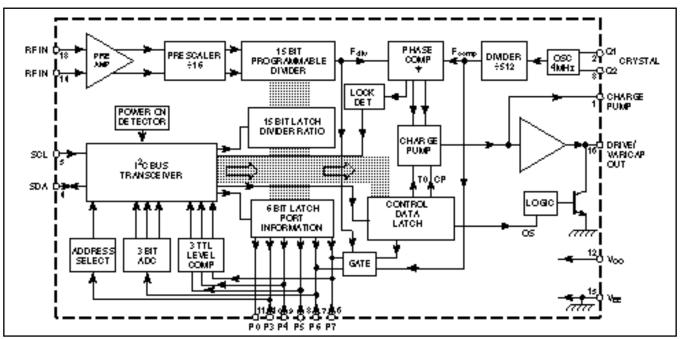


Fig. 2 Block diagram

#### **FUNCTIONAL DESCRIPTION**

The SP5055 is programmed from an I<sup>2</sup>C BUS. Data and Clock are fed in on the SDA and SCL lines respectively as defined by the I<sup>2</sup>C BUS format. The synthesiser can either accept new data (write mode) or send data (read mode). The Tables in Fig. 3 illustrate the format of the data. The device can be programmed to respond to several addresses, which enables the use of more than one synthesiser in an I2C Bus system. Table 4 shows how the address is selected by applying a voltage to P3. The last bit of the address byte (R/W) sets the device into read mode if it is high and write mode if it is low. When the SP5055 receives a correct address byte it pulls the SDA line low during the acknowledge period and during following acknowledge periods after further data bytes are programmed. When the SP5055 is programmed into the read mode the controlling device accepting the data must pull down the SDA line during the following acknowledge period to read another status byte.

#### WRITE MODE (FREQUENCY SYNTHESIS)

When the device is in the write mode Bytes 2 + 3 select the synthesised frequency while bytes 4 + 5 select the output port states and charge pump information.

Once the correct address is received and acknowledged, the first Bit of the next Byte determines whether that byte is interpreted as byte 2 or 4, a logic 0 for frequency information and a logic 1 for charge pump and output port information. Additional data bytes can be entered without the need to re-address the device until an I<sup>2</sup>C stop condition is recognised. This allows a smooth frequency sweep for fine tuning or AFC purposes.

If the transmission of data is stopped mid-byte (i.e., by another device on the bus) then the previously programmed byte is maintained.

Frequency data from bytes 2 and 3 is stored in a 15-bit shift register and is used to control the division ratio of the 15-bit programmable divider which is preceded by a divide-by-16 prescaler and amplifier to give excellent sensitivity at the local oscillator input; see Fig 5. The input impedance is shown in Fig 7.

The programmed frequency can be calculated by multiplying the programmed division ratio by 16 times the comparison frequency  $F_{\text{comp}}$ .

When frequency data is entered, the phase comparator, via the charge pump and varactor drive amplifier, adjusts the local oscillator control voltage until the output of the programmable divider is frequency and phase locked to the comparison frequency.

The reference frequency may be generated by an external source capacitively coupled into pin 2 or provided by an onboard 4MHz crystal controlled oscillator.

Note that the comparison frequency is 7.8125 kHz when a 4MHz reference is used.

Bit 2 of byte 4 of the programming data (CP) controls the current in the charge pump circuit, a logic 1 for  $\pm 170\mu A$  and a logic 0 for  $\pm 50\mu A$ , allowing compensation for the variable tuning slope of the tuner and also to enable fast channel changes over the full band. Bit 4 of byte 4 (T0) disables the charge pump if set to a logic 1. Bit 8 of byte 4 (OS) switches the charge pump drive amplifier's output off when it is set to a logic 1. Bit 3 of Byte 4 (T1) selects a test mode where the phase comparator inputs are available on P6 and P7, a logic 1 connects  $F_{comp}$  to P6 and  $F_{div}$  to P7.

Byte 5 programs the output ports P0 to P7; on a logic 0 for a high impedance output, logic 1 for low impedance (on).

#### **READ MODE**

When the device is in the read mode the status data read from the device on the SDA line takes the form shown in Table 2.

Bit 1 (POR) is the power-on reset indicator and is set to a logic 1 if the power supply to the device has dropped below 3V and the programmed information lost (e.g., when the device is initially turned on). The POR is set to 0 when the read sequence is terminated by a stop command. The outputs are all set to high impedance when the device is initially powered up. Bit 2 (FL) indicates whether the device is phase locked, a logic 1 is present if the device is locked and a logic 0 if the device is unlocked.

Bits 3, 4 and 5 (I2,I1,I0) show the status of the I/O Ports P7, P5 and P4 respectively. A logic 0 indicates a low level and a logic 1 a high level. If the ports are to be used as inputs they should be programmed to a high impedance state (logic 1). These inputs will then respond to data complying with TTL type voltage levels. Bits 6, 7 and 8 (A2,A1,A0) combine to give the output of the 5 level ADC.

The 5 level ADC can be used to feed AFC information to the microprocessor from the IF section of the receiver, as illustrated in the typical application circuit.

#### **APPLICATION**

A typical Application is shown in Fig. 4. All input/output interface circuits are shown in Fig. 6.

MSB						LSB					
Address	1	1	0	0	0	MA1	MA0	0	Α	Byte 1	
Programmable divider	0	2 <sup>14</sup>	2 <sup>13</sup>	2 <sup>12</sup>	2 <sup>11</sup>	2 <sup>10</sup>	2 <sup>9</sup>	2 <sup>8</sup>	Α	Byte 2	
Programmable divider	<b>2</b> <sup>7</sup>	2 <sup>6</sup>	2 <sup>5</sup>	2 <sup>4</sup>	2 <sup>3</sup>	<b>2</b> <sup>2</sup>	2 <sup>1</sup>	2 <sup>0</sup>	Α	Byte 3	
Charge pump and test bits	1	СР	T1	T0	1	1	1	os	Α	Byte 4	
I/O port control bits	P7	P6	P5	P4	P3	Х	Х	P0	Α	Byte 5	

Table 1 Write data format (MSB transmitted first)

Address	1	1	0	0	0	MA1	MA0	1	Α	Byte 1
Status byte	POR	FL	12	11	10	A2	A1	Α0	Α	Byte 2

Table 2 Read data format (MSB is transmitted first)

A : Acknowledge bit

MA1, MA0 : Variable address bits (see Table 4)
CP : Charge Pump current select

T1 : Test mode selection
T0 : Charge pump disable

OS : Varactor drive Output disable Switch

P7, P6, P5, P4, : Control output states

P3, P0

POR : Power On Reset indicator FL : Phase lock detect flag

**12, 11, 10** : Digital information from Ports P7, P5 and P4, respectively

A2, A1, A0 : 5 Level ADC data from P6 (see Table 3)

X : Don't care

A2	<b>A</b> 1	Α0	Voltage input to P6
1	0	0	0.6V <sub>CC</sub> to 13.2V
0	1	1	0.45V <sub>CC</sub> to 0.6V <sub>CC</sub>
0	1	0	0.3V <sub>CC</sub> to 0.45V <sub>CC</sub>
0	0	1	0·15V <sub>CC</sub> to 0·3V <sub>CC</sub>
0	0	0	0 to 0.15V <sub>CC</sub>

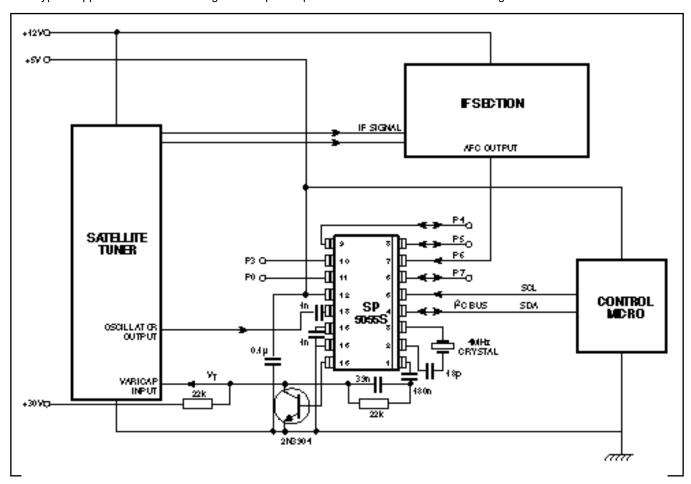
Table 3 ADC levels

MA1	MAO	Voltage input to Page 1					
0	0	0V to 0·2V <sub>CC</sub>					
0	1	Always valid					
1	0	0.3V <sub>CC</sub> to 0.7V <sub>CC</sub>					
1	1	0.8V <sub>CC</sub> -13.2V					

Table 4 Address selection

### **APPLICATION**

A typical application is shown in Fig. 4. All input/output interface circuits are shown in Fig. 6.



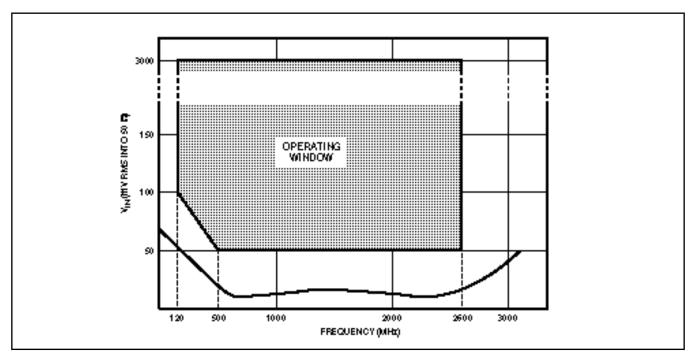


Fig. 5 Typical input sensitivity

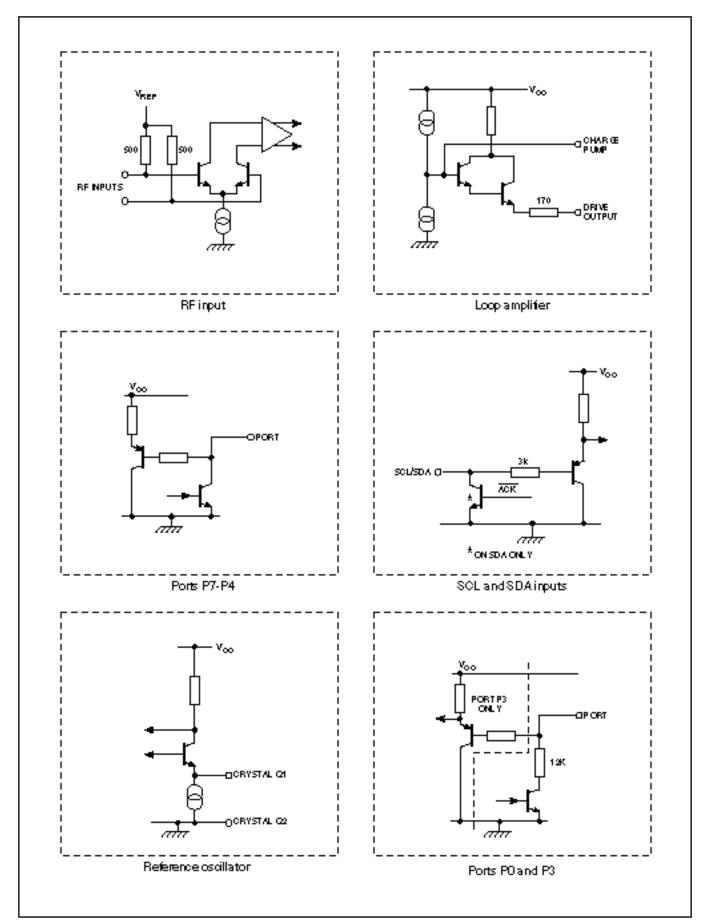


Fig. 6 SP5055 Input/output interface circuits

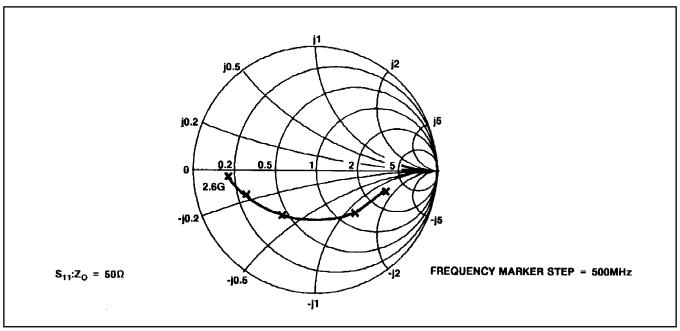
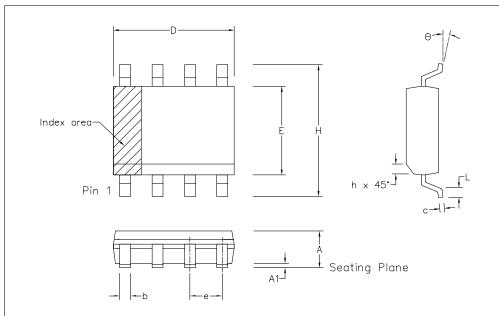


Fig. 7 Typical input impedance

## **ABSOLUTE MAXIMUM RATINGS**

All voltages are referred to  $V_{\text{EE}}$  and pin 3 at 0V

Davamatav	Pin	Val	ue	l lesite	O a maliki a ma		
Parameter	PIII	Min.	Max.	Units	Conditions		
Supply voltage	12	-0.3	7	V			
RF input voltage	13, 14		2.5	Vp-p			
Port voltage	6-11 6-9 10, 11	-0.3 -0.3 -0.3	14 6 14	V V V	Port in off state Port in on state Port in on state		
Total port output current	6-11		50	mA			
RF input DC offset	13, 14	-0.3	V <sub>CC</sub> +0.3	V			
Charge pump DC offset	1	-0.3	V <sub>CC</sub> +0.3	٧			
Drive DC offset	16	-0.3	V <sub>CC</sub> +0.3	٧			
Crystal oscillator DC offset	2	-0.3	V <sub>CC</sub> +0.3	٧			
SDA, SCL input voltage	4, 5	-0.3 -0.3	V <sub>CC</sub> +0.3 5.5	V V	With $V_{CC}$ applied $V_{CC}$ not applied		
Storage temperature		-55	+125	°C	00		
Junction temperature			+150	°C			
MP 16 Thermal resistance, chip-to-ambient MP 16 Thermal resistance, chip-to-case			111 41	°C/W °C/W			
Power consumption at 5.5V			440	mW	All ports off		



	Min mm	Max mm	Min inch	Max inch				
A	1.35	1.75	0.053	0.069				
A1	0.10	0.25	0.004	0.010				
D	9.80	10.00	0.386	0.394				
Н	5.80	6.20	0.228	0.244				
E	3.80	4.00	0.150	0.157				
L	0.40	1.27	0.016	0.050				
е	1.27	BSC	0.050_BSC					
b	0.33	0.51	0.013	0.020				
С	0.19	0.25	0.008	0.010				
0	0°	8°	0°	8 <b>°</b>				
h	0.25	0.50	0.010	0.020				
	Pin Features							
N	16 16							
Confor	Conforms to JEDEC MS-012AC Iss. C							

#### Notes:

- The chamfer on the body is optional. If it not present, a visual index feature, e.g. a dot, must be located within the cross—hatched area.
   Controlling dimension are in inches.
   Dimension D do not include mould flash, protusion or gate burrs. These shall not exceed 0.006" per side.
   Dimension E1 do not include inter—lead flash or protusion. These shall not exceed 0.010" per side.
   Dimension b does not include dambar protusion/intrusion. Allowable dambar protusion shall be 0.004" total in excess of b dimension.

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ISSUE	1	2	3	4			Title: Package Outline Drawing for 16 Ids SOIC(N)—0.150" Body Width (MP)
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DATE	7APR95	27FEB97	12JUN97	9DEC97		SLIVICONDOCTOR	Drawing Number
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http://www.mitelsemi.com

World Headquarters - Canada

Tel: +1 (613) 592 2122 Fax: +1 (613) 592 6909

Asia/Pacific

Tel: +65 333 6193 Fax: +65 333 6192 Europe, Middle East, and Africa (EMEA)

Tel: +44 (0) 1793 518528 Fax: +44 (0) 1793 518581

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**North America** 

Tel: +1 (770) 486 0194

Fax: +1 (770) 631 8213

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