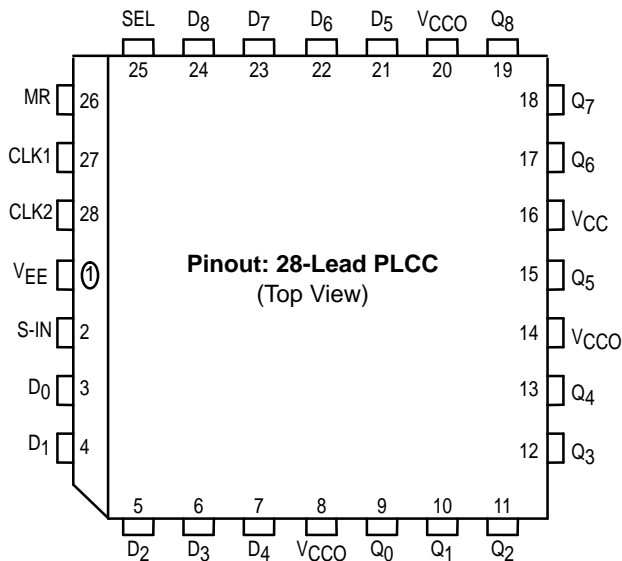


9-Bit Shift Register

The MC10E100E142 is a 9-bit shift register, designed with byte-parity applications in mind. The E142 performs serial/parallel in and serial/parallel out, shifting in one direction. The nine inputs D0 – D8 accept parallel input data, while S-IN accepts serial input data. The Qn outputs do not need to be terminated for the shift operation to function. To minimize noise and power, any Q output not used should be left unterminated.

- 700MHz Min. Shift Frequency
- 9-Bit for Byte-Parity Applications
- Asynchronous Master Reset
- Dual Clocks
- Extended 100E V_{EE} Range of – 4.2V to – 5.46V
- 75kΩ Input Pulldown Resistors

The SEL (Select) input pin is used to switch between the two modes of operation — SHIFT and LOAD. The shift direction is from bit 0 to bit 8. Input data is accepted by the registers a set-up time before the positive going edge of CLK1 or CLK2; shifting is also accomplished on the positive clock edge. A HIGH on the Master Reset pin (MR) asynchronously resets all the registers to zero.



PIN NAMES

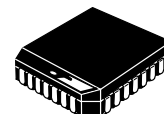
Pin	Function
D ₀ – D ₈	Parallel Data Inputs
S-IN	Serial Data Input
SEL	Mode Select Input
CLK1, CLK2	Clock Inputs
MR	Master Reset
Q ₀ – Q ₈	Data Outputs

FUNCTIONS

SEL	Mode
L	Load
H	Shift

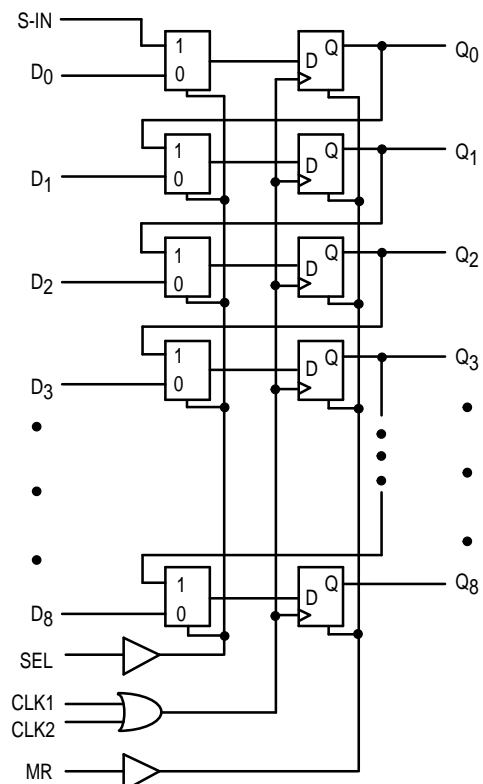
MC10E142
MC100E142

**9-BIT SHIFT
REGISTER**



FN SUFFIX
PLASTIC PACKAGE
CASE 776-02

LOGIC DIAGRAM



MC10E142 MC100E142

DC CHARACTERISTICS ($V_{EE} = V_{EE}(\text{min})$ to $V_{EE}(\text{max})$; $V_{CC} = V_{CCO} = \text{GND}$)

Symbol	Characteristic	0°C			25°C			85°C			Unit	Condition
		min	typ	max	min	typ	max	min	typ	max		
I_{IH}	Input HIGH Current			150			150			150	μA	
I_{EE}	Power Supply Current										mA	
	10E		120	145		120	145		120	145		
	100E		120	145		120	145		138	165		

AC CHARACTERISTICS ($V_{EE} = V_{EE}(\text{min})$ to $V_{EE}(\text{max})$; $V_{CC} = V_{CCO} = \text{GND}$)

Symbol	Characteristic	0°C			25°C			85°C			Unit	Condition
		min	typ	max	min	typ	max	min	typ	max		
f_{SHIFT}	Max. Shift Frequency	700	900		700	900		700	900		MHz	
t_{PLH} t_{PHL}	Propagation Delay to Output										ps	
	Clk MR	600 600	800 800	1000 1000	600 600	800 800	1000 1000	600 600	800 800	1000 1000		
t_s	Setup Time										ps	
	D SEL	50 300	-100 150		50 300	-100 150		50 300	-100 150			
t_h	Hold Time										ps	
	D SEL	300 75	100 -150		300 75	100 -150		300 75	100 -150			
t_{RR}	Reset Recovery Time	900	700		900	700		900	700		ps	
t_{PW}	Minimum Pulse Width Clk, MR	400			400			400			ps	
t_{SKEW}	Within-Device Skew		75			75			75		ps	Note 1
t_r t_f	Rise/Fall Times 20 - 80%	300	525	800	300	525	800	300	525	800	ps	

1. Within-device skew is defined as identical transitions on similar paths through a device.

OUTLINE DIMENSIONS

FN SUFFIX
 PLASTIC PLCC PACKAGE
 CASE 776-02
 ISSUE D



NOTES:

- DATUMS -L-, -M-, AND -N- DETERMINED WHERE TOP OF LEAD SHOULDER EXITS PLASTIC BODY AT MOLD PARTING LINE.
- DIM G1, TRUE POSITION TO BE MEASURED AT DATUM -T-, SEATING PLANE.
- DIM R AND U DO NOT INCLUDE MOLD FLASH. ALLOWABLE MOLD FLASH IS 0.010 (0.250) PER SIDE.
- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: INCH.
- THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOTTOM BY UP TO 0.012 (0.300). DIMENSIONS R AND U ARE DETERMINED AT THE OUTERMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.
- DIMENSION H DOES NOT INCLUDE DAMBAR PROTRUSION OR INTRUSION. THE DAMBAR PROTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE GREATER THAN 0.037 (0.940). THE DAMBAR INTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE SMALLER THAN 0.025 (0.635).

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.485	0.495	12.32	12.57
B	0.485	0.495	12.32	12.57
C	0.165	0.180	4.20	4.57
E	0.090	0.110	2.29	2.79
F	0.013	0.019	0.33	0.48
G	0.050 BSC		1.27 BSC	
H	0.026	0.032	0.66	0.81
J	0.020	—	0.51	—
K	0.025	—	0.64	—
R	0.450	0.456	11.43	11.58
U	0.450	0.456	11.43	11.58
V	0.042	0.048	1.07	1.21
W	0.042	0.048	1.07	1.21
X	0.042	0.056	1.07	1.42
Y	—	0.020	—	0.50
Z	2°		10°	
G1	0.410	0.430	10.42	10.92
K1	0.040	—	1.02	—

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