

# MOS INTEGRATED CIRCUIT $\mu PD3778$

# 10600 PIXELS imes 3 COLOR CCD LINEAR IMAGE SENSOR

The  $\mu$ PD3778 is a color CCD (Charge Coupled Device) linear image sensor which changes optical images to electrical signal and has the function of color separation.

The  $\mu$ PD3778 has 3 rows of 10600 pixels, and each row has a double-sided readout type of charge transfer register. And it has reset feed-through level clamp circuits and voltage amplifiers. Therefore, it is suitable for 1200 dpi/A4 color image scanners and so on.

# **FEATURES**

• Valid photocell : 10600 pixels × 3

• Photocell's pitch :  $4 \mu m$ • Photocell size :  $4 \times 4 \mu m^2$ 

• Line spacing : 48  $\mu$ m (12 lines) Red line-Green line, Green line-Blue line

• Color filter : Primary colors (red, green and blue), pigment filter (with light resistance 10<sup>7</sup> lx•hour)

• Resolution : 48 dot/mm A4 (210 × 297 mm) size (shorter side)

1200 dpi US letter (8.5" × 11") size (shorter side)

• Drive clock level : CMOS output under 5 V operation

Data rate : 5 MHz MAX.Power supply : +12 V

• On-chip circuits : Reset feed-through level clamp circuits

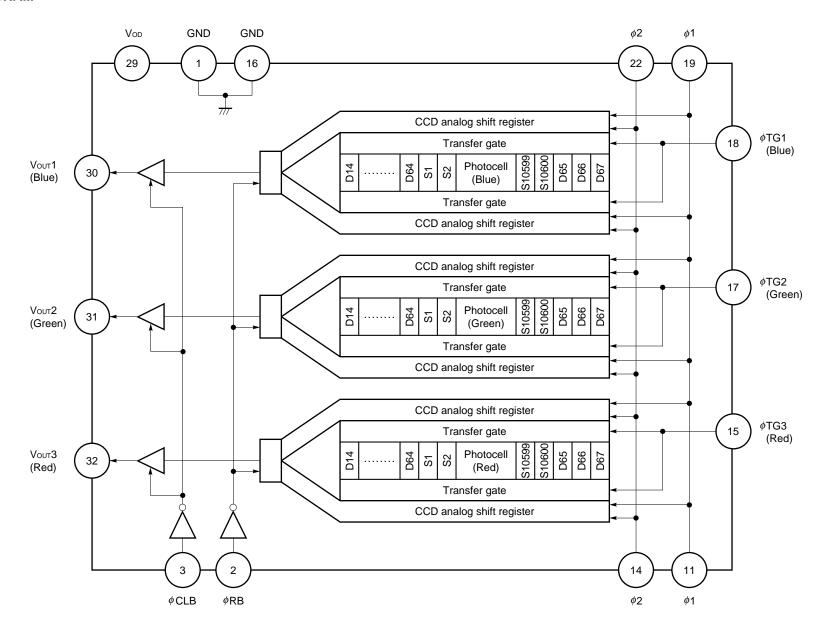
Voltage amplifiers

### ORDERING INFORMATION

Part Number	Package
μPD3778CY	CCD linear image sensor 32-pin plastic DIP (400 mil)

The information in this document is subject to change without notice. Before using this document, please confirm that this is the latest version.

Not all devices/types available in every country. Please check with local NEC representative for availability and additional information.

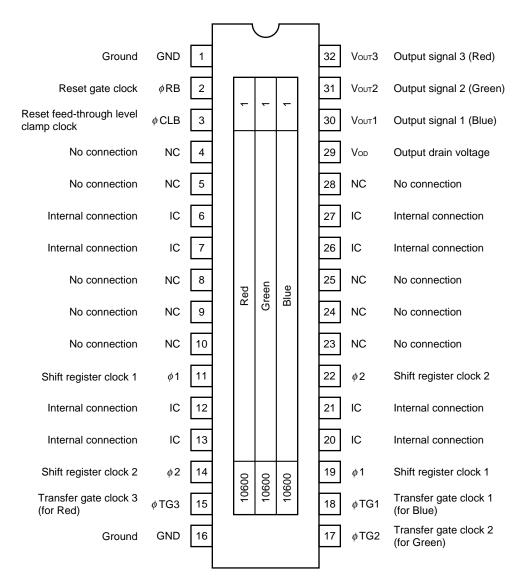




# PIN CONFIGURATION (Top View)

CCD linear image sensor 32-pin plastic DIP (400 mil)

• μPD3778CY

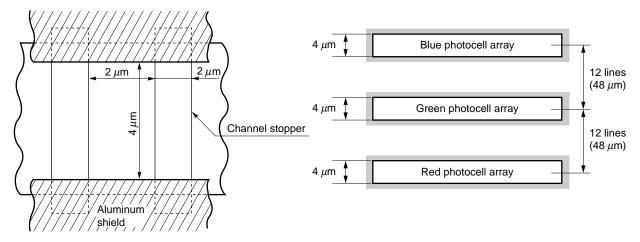


Caution Leave pins 6, 7, 12, 13, 20, 21, 26, 27 (IC) unconnected.



# PHOTOCELL STRUCTURE DIAGRAM

# PHOTOCELL ARRAY STRUCTURE DIAGRAM (Line spacing)





# ABSOLUTE MAXIMUM RATINGS (TA = +25 °C)

Parameter	Symbol	Ratings	Unit
Output drain voltage	Vod	−0.3 to +15	V
Shift register clock voltage	V <sub>\$\phi_1\$</sub> , V <sub>\$\phi_2\$</sub>	-0.3 to +8	V
Reset gate clock voltage	V <sub>Ø</sub> RB	-0.3 to +8	V
Reset feed-through level clamp clock voltage	V <sub>Ø</sub> CLB	-0.3 to +8	V
Transfer gate clock voltage	V <sub>φ</sub> TG1 to V <sub>φ</sub> TG3	-0.3 to +8	V
Operating ambient temperature	TA	-25 to +60	°C
Storage temperature	T <sub>stg</sub>	-40 to +70	°C

Caution Exposure to ABSOLUTE MAXIMUM RATINGS for extended periods may affect device reliability; exceeding the ratings could cause permanent damage. The parameters apply independently.

# RECOMMENDED OPERATING CONDITIONS (TA = +25 °C)

Parameter	Symbol	MIN.	TYP.	MAX.	Unit
Output drain voltage	Vod	11.4	12.0	12.6	٧
Shift register clock high level	V <sub>0</sub> 1H, V <sub>0</sub> 2H	4.5	5.0	5.5	V
Shift register clock low level	V <sub>0</sub> 1L, V <sub>0</sub> 2L	-0.3	0	+0.5	V
Reset gate clock high level	V <sub>Ø</sub> RBH	4.5	5.0	5.5	V
Reset gate clock low level	V <sub>Ø</sub> RBL	-0.3	0	+0.5	V
Reset feed-through level clamp clock high level	V <sub>Ø</sub> CLBH	4.5	5.0	5.5	V
Reset feed-through level clamp clock low level	V <sub>Ø</sub> CLBL	-0.3	0	+0.5	V
Transfer gate clock high level	V <sub>Ø</sub> тG1H <b>to</b> V <sub>Ø</sub> тG3H	4.5	V <sub>ø1H</sub> Note	V <sub>φ1H</sub> Note	V
Transfer gate clock low level	V <sub>Ø</sub> TG1L <b>to</b> V <sub>Ø</sub> TG3L	-0.3	0	+0.5	V
Data rate	føRB	_	1.0	5.0	MHz

**Note** When Transfer gate clock high level ( $V_{\phi TG1H}$  to  $V_{\phi TG3H}$ ) is higher than Shift register clock high level ( $V_{\phi 1H}$ ), Image lag can increase.

Data Sheet S14374EJ1V0DS00



# **ELECTRICAL CHARACTERISTICS**

 $T_A = +25 \, ^{\circ}\text{C}$ ,  $V_{OD} = 12 \, \text{V}$ , data rate (f<sub>\text{PRB}</sub>) = 2 MHz, storage time = 5.5 ms, input signal clock = 5  $V_{P-P}$ , light source: 3200 K halogen lamp +C-500S (infrared cut filter, t = 1mm) + HA-50 (heat absorbing filter, t = 3 mm)

Parameter		Symbol	Test Conditions	MIN.	TYP.	MAX.	Unit
Saturation voltage		V <sub>sat</sub>		2.0	2.5	_	V
Saturation exposure Red		SER			0.694		lx∙s
	Green	SEG			0.757		lx•s
	Blue	SEB			1.250		lx•s
Photo response non-unit	formity	PRNU	Vout = 1.0 V		6	20	%
Average dark signal		ADS	Light shielding		0.2	4.0	mV
Dark signal non-uniformi	ty	DSNU	Light shielding		1.5	4.0	mV
Power consumption		Pw			400	600	mW
Output impedance		Zo			0.5	1	kΩ
Response	Red	Rr		2.52	3.60	4.68	V/Ix•s
	Green	Rg		2.31	3.30	4.29	V/Ix•s
	Blue	Rв		1.40	2.00	2.60	V/Ix•s
Image lag		IL	Vout = 1.0 V		2.0	10.0	%
Offset level Note1	Offset level Note1			4.0	6.0	7.0	V
Output fall delay time No	te2	<b>t</b> d	Vout = 1.0 V		50		ns
Total transfer efficiency		TTE	Vout = 1.0 V,	92	98		%
			data rate = 5 MHz				
Register imbalance		RI	Vout = 1.0 V	0	1.0	4.0	%
Response peak	Red				630		nm
	Green				540		nm
	Blue				460		nm
Dynamic range		DR1	V <sub>sat</sub> /DSNU		1666		times
		DR2	V <sub>sat</sub> /σ CDS		2500		times
Reset feed-through nois	e Note1	RFTN	Light shielding	-1000	-300	+500	mV
Random noise (CDS)		σ CDS	Light shielding	-	1.0	-	mV

# Notes 1. Refer to TIMING CHART 2.

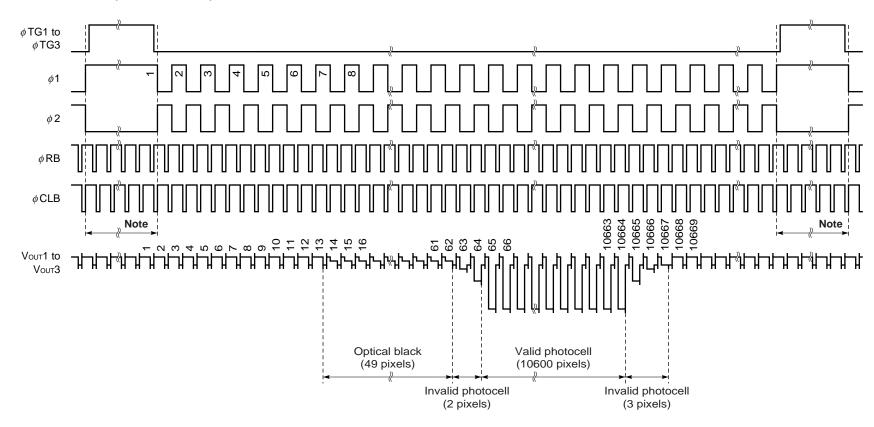
**2.** When each fall time of  $\phi$ 1 and  $\phi$ 2 (t2, t1) is the TYP. value (refer to **TIMING CHART 2**).



# INPUT PIN CAPACITANCE (TA = +25 $^{\circ}$ C, Vod = 12 V)

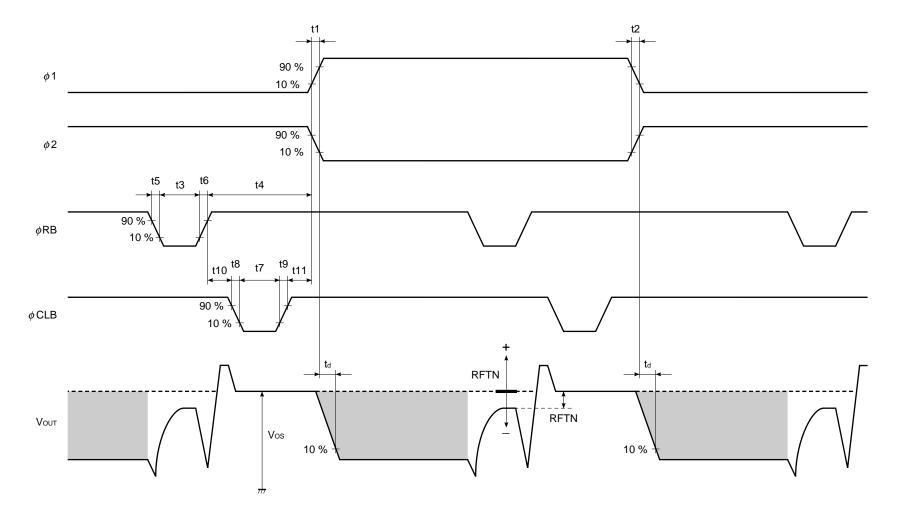
Parameter	Symbol	Pin name	Pin No.	MIN.	TYP.	MAX.	Unit
Shift register clock pin capacitance 1	C <sub>Ø</sub> 1	φ1	11		400		pF
			19		400		pF
Shift register clock pin capacitance 2	C <sub>\$\phi\2</sub>	φ2	14		400		pF
			22		400		pF
Reset gate clock pin capacitance	CøRB	φRB	2		15		pF
Reset feed-through level clamp clock pin capacitance	C <sub>Ø</sub> CLB	φCLB	3		15		pF
Transfer gate clock pin capacitance	С <sub>Ø</sub> тG	φTG1	18		120		pF
		φTG2	17		120		pF
		φTG3	15		120		pF

**Remark** Pins 11 and 19 ( $\phi$ 1), 14 and 22 ( $\phi$ 2) are each connected inside of the device.



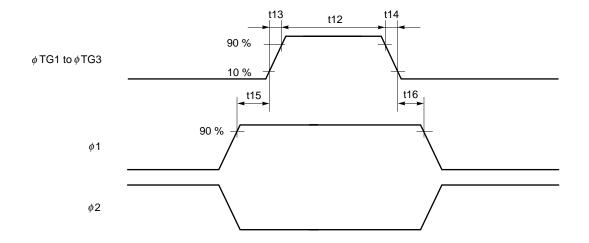
Note Input the  $\phi RB$  and  $\phi CLB$  pulses continuously during this period, too.

# TIMING CHART 2 (for each color)



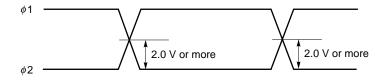
Data Sheet S14374EJ1V0DS00

# $\phi$ TG1 to $\phi$ TG3, $\phi$ 1, $\phi$ 2 TIMING CHART



Symbol	MIN.	TYP.	MAX.	Unit
t1, t2	0	25	_	ns
t3	20	50	_	ns
t4	70	250	_	ns
t5, t6	0	25	_	ns
t7	30	50	_	ns
t8, t9	0	25	_	ns
t10	30	50	_	ns
t11	5	15	_	ns
t12	5000	10000	-	ns
t13, t14	0	50	_	ns
t15, t16	900	1000	_	ns

# $\phi$ 1, $\phi$ 2 cross points



**Remark** Adjust cross points of  $\phi 1$  and  $\phi 2$  with input resistance of each pin.



### **DEFINITIONS OF CHARACTERISTIC ITEMS**

1. Saturation voltage: Vsat

Output signal voltage at which the response linearity is lost.

2. Saturation exposure: SE

Product of intensity of illumination (Ix) and storage time (s) when saturation of output voltage occurs.

3. Photo response non-uniformity: PRNU

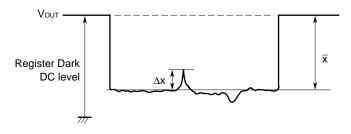
The output signal non-uniformity of all the valid pixels when the photosensitive surface is applied with the light of uniform illumination. This is calculated by the following formula.

PRNU (%) = 
$$\frac{\Delta x}{\overline{x}} \times 100$$

 $\Delta x$ : maximum of  $|x_j - \overline{x}|$ 

$$\overline{x} = \frac{\sum_{j=1}^{10600} x_j}{10600}$$

x<sub>j</sub>: Output voltage of valid pixel number j



4. Average dark signal: ADS

Average output signal voltage of all the valid pixels at light shielding. This is calculated by the following formula.

ADS (mV) = 
$$\frac{\sum_{j=1}^{10600} d_j}{10600}$$

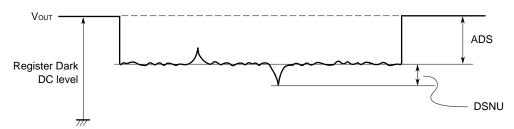
dj: Dark signal of valid pixel number j

5. Dark signal non-uniformity: DSNU

Absolute maximum of the difference between ADS and voltage of the highest or lowest output pixel of all the valid pixels at light shielding. This is calculated by the following formula.

DSNU (mV) : maximum of 
$$|d_j - ADS|_{j=1 \text{ to } 10600}$$

dj : Dark signal of valid pixel number j



6. Output impedance: Zo

Impedance of the output pins viewed from outside.

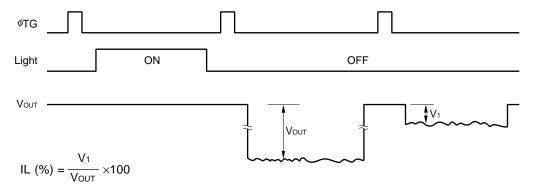
7. Response: R

Output voltage divided by exposure (Ix•s).

Note that the response varies with a light source (spectral characteristic).

8. Image Lag: IL

The rate between the last output voltage and the next one after read out the data of a line.



9. Register imbalance: RI

The rate of the difference between the averages of the output voltage of Odd and Even pixels, against the average output voltage of all the valid pixels.

RI (%) = 
$$\frac{\frac{2}{n} \left| \sum_{j=1}^{\frac{n}{2}} (V_{2j-1} - V_{2j}) \right|}{\frac{1}{n} \sum_{j=1}^{n} V_{j}} \times 100$$

n: Number of valid pixels

V<sub>j</sub>: Output voltage of each pixel

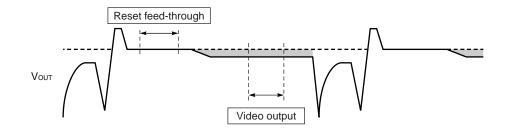


### 10. Random noise (CDS): σCDS

Random noise (CDS)  $\sigma$ CDS is defined as the standard deviation of a valid pixel output signal with 100 times (= 100 lines) data sampling at dark (light shielding). This is measured by the following procedure.

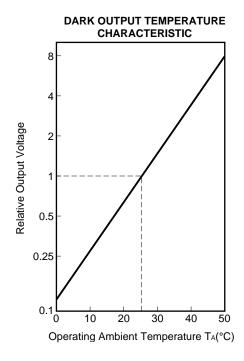
- 1. One valid photocell in one reading is fixed as measurement point.
- 2. The output level is measured during the Reset feed-through period which is averaged over 100 ns to get "VDi".
- 3. The output level is measured during the Video output time averaged over 100 ns to get "VOi".
- 4. The correlated double sampling output is defined by "VCDSi = VDi VOi".
- 5. Repeat the above procedure (1 to 4) for 100 times (= 100 lines).
- 6. Calculate the standard deviation  $\sigma$ CDS using the following formula.

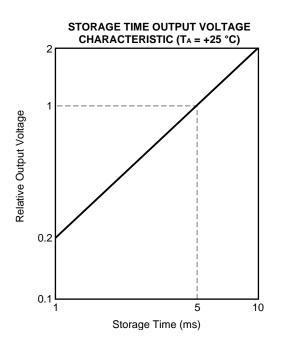
$$\sigma CDS (mV) = \sqrt{\frac{\displaystyle \sum_{i=1}^{100} (VCDS_i - \overline{V})^2}{100}} \quad , \ \overline{V} = \frac{1}{100} \sum_{i=1}^{100} VCDS_i$$



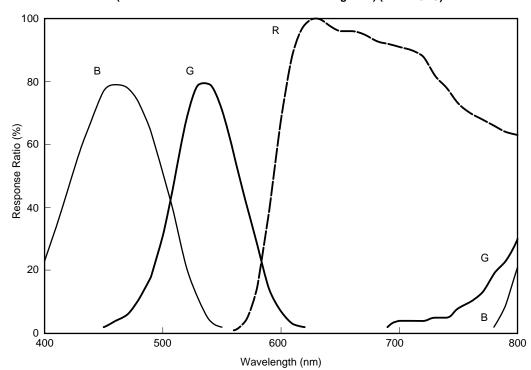


# STANDARD CHARACTERISTIC CURVES (Nominal)

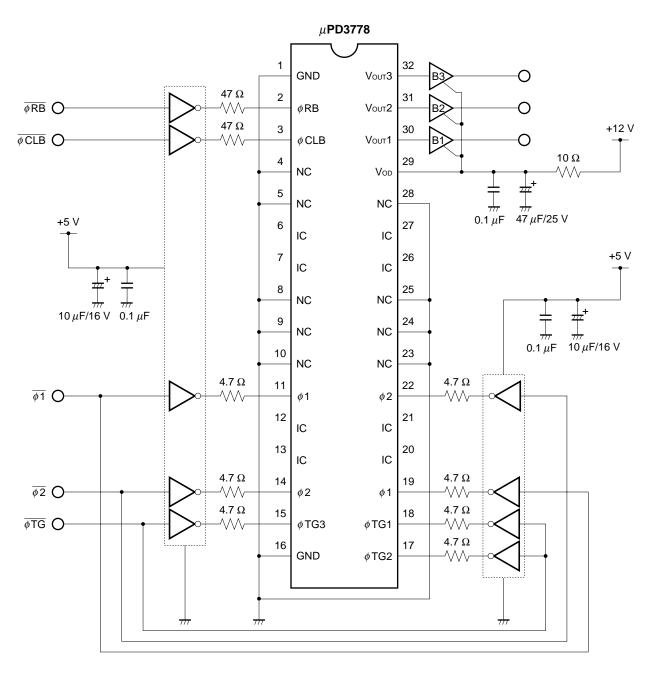




TOTAL SPECTRAL RESPONSE CHARACTERISTICS (without infrared cut filter and heat absorbing filter) (TA = +25  $^{\circ}$ C)



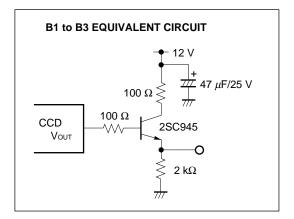
# **APPLICATION CIRCUIT EXAMPLE**



Caution Leave pins 6, 7, 12, 13, 20, 21, 26, 27 (IC) unconnected.

**Remark** The inverters shown in the above application circuit example are the 74HC04 or 74AC04.

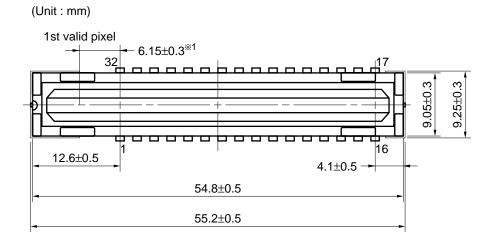
Data Sheet S14374EJ1V0DS00 **15** 

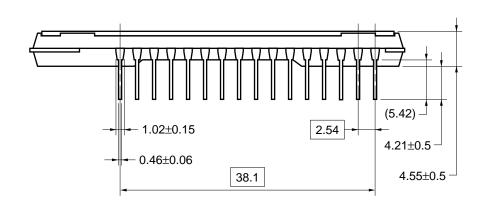


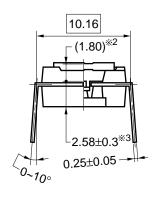


### **PACKAGE DRAWING**

# **CCD LINEAR IMAGE SENSOR 32-PIN PLASTIC DIP (400 mil)**







Name	Dimensions	Refractive index	
Plastic cap	52.2×6.4×0.7 <sup>**4</sup>	1.5	

- 2 The surface of the chip  $\longrightarrow$  The top of the cap
- ★ 3 The bottom of the package 
   ★ The surface of the chip
- \*4 Thickness of plastic cap over CCD chip

32C-1CCD-PKG3

### RECOMMENDED SOLDERING CONDITIONS

When soldering this product, it is highly recommended to observe the conditions as shown below.

If other soldering processes are used, or if the soldering is performed under different conditions, please make sure to consult with our sales offices.

For more details, refer to our document "Semiconductor Device Mounting Technology Manual" (C10535E).

### Type of Through-hole Device

 $\mu$ PD3778CY : CCD linear image sensor 32-pin plastic DIP (400 mil)

Process	Conditions
Partial heating method	Pin temperature: 300 °C or below, Heat time: 3 seconds or less (per pin)

Caution During assembly care should be taken to prevent solder or flux from contacting the plastic cap.

The optical characteristics could be degraded by such contact.



# NOTES ON CLEANING THE PLASTIC CAP-

# (1) CLEANING THE PLASTIC CAP

Care should be taken when cleaning the surface to prevent scratches.

The optical characteristics of the CCD will be degraded if the cap is scratched during cleaning.

We recommend cleaning the cap with a soft cloth moistened with one of the recommended solvents below. Excessive pressure should not be applied to the cap during cleaning. If the cap requires multiple cleanings it is recommended that a clean surface or cloth be used.

# (2) RECOMMENDED SOLVENTS

The following are the recommended solvents for cleaning the CCD plastic cap. Use of solvents other than these could result in optical or physical degradation in the plastic cap. Please consult your sales office when considering an alternative solvent.

Solvents	Symbol
Ethyl Alcohol	EtOH
Methyl Alcohol	MeOH
Isopropyl Alcohol	IPA
N-methyl Pyrrolidone	NMP

### **NOTES FOR CMOS DEVICES -**

### 1 PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

### (2) HANDLING OF UNUSED INPUT PINS FOR CMOS

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

### (3) STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

- The information in this document is subject to change without notice. Before using this document, please confirm that this is the latest version.
- No part of this document may be copied or reproduced in any form or by any means without the prior written
  consent of NEC Corporation. NEC Corporation assumes no responsibility for any errors which may appear in
  this document.
- NEC Corporation does not assume any liability for infringement of patents, copyrights or other intellectual
  property rights of third parties by or arising from use of a device described herein or any other liability arising
  from use of such device. No license, either express, implied or otherwise, is granted under any patents, copyrights
  or other intellectual property rights of NEC Corporation or others.
- Descriptions of circuits, software, and other related information in this document are provided for illustrative
  purposes in semiconductor product operation and application examples. The incorporation of these circuits,
  software, and information in the design of the customer's equipment shall be done under the full responsibility
  of the customer. NEC Corporation assumes no responsibility for any losses incurred by the customer or third
  parties arising from the use of these circuits, software, and information.
- While NEC Corporation has been making continuous effort to enhance the reliability of its semiconductor devices, the possibility of defects cannot be eliminated entirely. To minimize risks of damage or injury to persons or property arising from a defect in an NEC semiconductor device, customers must incorporate sufficient safety measures in its design, such as redundancy, fire-containment, and anti-failure features.
- NEC devices are classified into the following three quality grades:
  - "Standard", "Special", and "Specific". The Specific quality grade applies only to devices developed based on a customer designated "quality assurance program" for a specific application. The recommended applications of a device depend on its quality grade, as indicated below. Customers must check the quality grade of each device before using it in a particular application.
    - Standard: Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots
    - Special: Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support)
    - Specific: Aircraft, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems or medical equipment for life support, etc.

The quality grade of NEC devices is "Standard" unless otherwise specified in NEC's Data Sheets or Data Books. If customers intend to use NEC devices for applications other than those specified for Standard quality grade, they should contact an NEC sales representative in advance.

M7 98.8