DS90CR285/DS90CR286 +3.3V Rising Edge

# National Semiconductor

# DS90CR285/DS90CR286 +3.3V Rising Edge Data Strobe LVDS 28-Bit Channel Link-66 MHz

## **General Description**

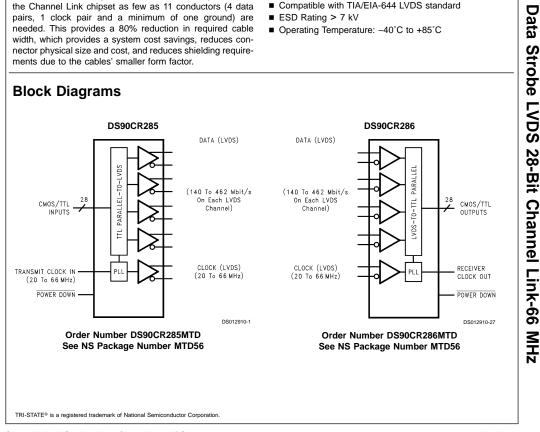
The DS90CR285 transmitter converts 28 bits of CMOS/TTL data into four LVDS (Low Voltage Differential Signaling) data streams. A phase-locked transmit clock is transmitted in parallel with the data streams over a fifth LVDS link. Every cycle of the transmit clock 28 bits of input data are sampled and transmitted. The DS90CR286 receiver converts the LVDS data streams back into 28 bits of CMOS/TTL data. At a transmit clock frequency of 66 MHz, 28 bits of TTL data are transmitted at a rate of 462 Mbps per LVDS data channel. Using a 66 MHz clock, the data throughput is 1.848 Gbit/s (231 Mbytes/s).

The multiplexing of the data lines provides a substantial cable reduction. Long distance parallel single-ended buses typically require a ground wire per active signal (and have very limited noise rejection capability). Thus, for a 28-bit wide data and one clock, up to 58 conductors are required. With the Channel Link chipset as few as 11 conductors (4 data pairs, 1 clock pair and a minimum of one ground) are needed. This provides a 80% reduction in required cable width, which provides a system cost savings, reduces connector physical size and cost, and reduces shielding requirements due to the cables' smaller form factor.

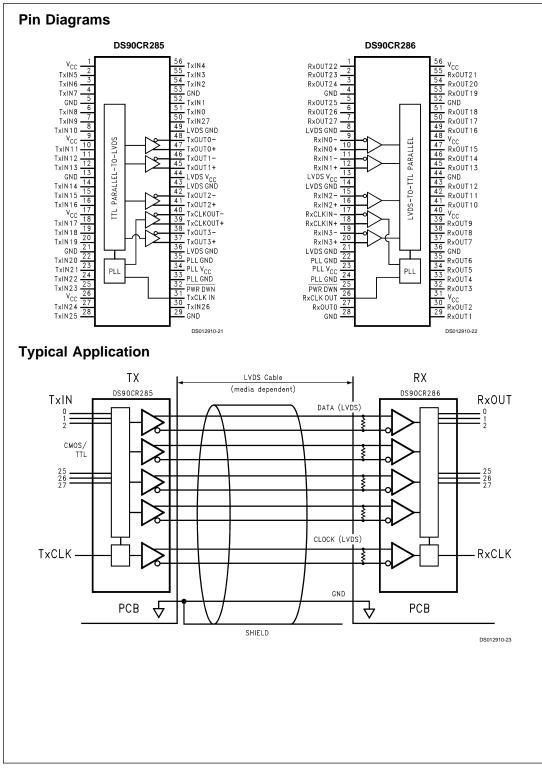
The 28 CMOS/TTL inputs can support a variety of signal combinations. For example, seven 4-bit nibbles or three 9-bit (byte + parity) and 1 control.

#### Features

- Single +3.3V supply
- Chipset (Tx + Rx) power consumption <250 mW (typ)
- Power-down mode (<0.5 mW total)</li>
- Up to 231 Megabytes/sec bandwidth
- Up to 1.848 Gbps data throughput
- Narrow bus reduces cable size
- 290 mV swing LVDS devices for low EMI
- +1V common mode range (around +1.2V)
- PLL requires no external components
- Low profile 56-lead TSSOP package
- Rising edge data strobe
- Compatible with TIA/EIA-644 LVDS standard
- ESD Rating > 7 kV ■ Operating Temperature: -40°C to +85°C



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If Milita	Iute Maximum Ra ry/Aerospace specified d	-		DS90CR285 DS90CR286				1.63 V 1.61 V
	contact the National Semico			Package Derating:				
Distribu	tors for availability and sp	ecifications	S.	DS90CR285		12.5 mV	//°C abo	ve +25°0
Supply \	/oltage (V <sub>CC</sub> )	-	0.3V to +4V	DS90CR286		12.4 mV	N/°C abo	ve +25°
CMOS/T	TL Input Voltage	–0.3V to (	V <sub>CC</sub> + 0.3V)	ESD Rating				
CMOS/T	TL Output Voltage	–0.3V to (	V <sub>CC</sub> + 0.3V)	(HBM, 1.5 kΩ, 100 p	oF)			> 7 k
LVDS Re Voltage	eceiver Input	0 2\/ to /	V <sub>CC</sub> + 0.3V)	Recommende	d One	rating		
•	river Output Voltage		v <sub>cc</sub> + 0.3v) V <sub>cc</sub> + 0.3V)	Conditions		ating	,	
	utput Short Circuit	0.07 10 (	166 1 0.01)	Conditions				
Durati	•		Continuous		Min	Nom	Max	Units
Junction	Temperature		+150°C	Supply Voltage (V <sub>CC</sub> )	3.0	3.3	3.6	V
Storage	Temperature	-65°	C to +150°C	Operating Free Air	10	. 05	. 05	•
Lead Ter	mperature			Temperature (T <sub>A</sub> ) Receiver Input Range	-40	+25 0	+85 2.4	°C V
	ering, 4 sec.)		+260°C	Supply Noise Voltage	()/)	0		v 00 mV <sub>PF</sub>
	m Package Power Dissipatio 6 (TSSOP) Package:	on @ +25°C		Supply Noise Voltage	V CC)			0 III PF
Over re	rical Characterist		0	•				1
ymbol	Parameter			Conditions	Min	Тур	Max	Units
	TL DC SPECIFICATIONS							
VIH	High Level Input Voltage				2.0		V <sub>cc</sub>	
VIL	Low Level Input Voltage			•	GND		0.8	
V <sub>OH</sub>	High Level Output Voltag	•	I <sub>OH</sub> = -0.4 n	nA	2.7	3.3		
Vol	Low Level Output Voltag	je	$I_{OL} = 2 \text{ mA}$	•		0.06	0.3	
V <sub>CL</sub>	Input Clamp Voltage		I <sub>CL</sub> = -18 m			-0.79	-1.5	V
			$V_{m} = V_{m}$	GND, 2.5V or 0.4V		±5.1	±10	μ/
	Input Current			,			100	
l <sub>os</sub>	Output Short Circuit Cur		$V_{OUT} = 0V$	,		-60	-120	m/
I <sub>os</sub> LVDS D	Output Short Circuit Cur RIVER DC SPECIFICATION	IS	V <sub>OUT</sub> = 0V		050			
I <sub>os</sub> LVDS D V <sub>od</sub>	Output Short Circuit Cur RIVER DC SPECIFICATION Differential Output Volta	IS ge			250	-60 290	450	m\
I <sub>OS</sub> LVDS D V <sub>OD</sub> ΔV <sub>OD</sub>	Output Short Circuit Cur RIVER DC SPECIFICATION Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S	IS ge	V <sub>OUT</sub> = 0V	·		290	450 35	m\ 
I <sub>OS</sub> LVDS D V <sub>OD</sub> ΔV <sub>OD</sub>	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4)	IS ge States	V <sub>OUT</sub> = 0V		250 1.125		450 35 1.375	m\ m\ V
I <sub>OS</sub> LVDS D V <sub>OD</sub> ΔV <sub>OD</sub>	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4) Change in V <sub>OS</sub> between	IS ge States	V <sub>OUT</sub> = 0V			290	450 35	m\ m\ V
I <sub>OS</sub> LVDS D ΔV <sub>OD</sub> ΔV <sub>OD</sub> ΔV <sub>OS</sub>	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4) Change in V <sub>OS</sub> between Complimentary Output S	IS ge States States	V <sub>OUT</sub> = 0V R <sub>L</sub> = 100Ω			290 1.25	450 35 1.375 35	m\ m\ V
$\frac{I_{OS}}{V_{OD}}$ $\frac{V_{OD}}{\Delta V_{OD}}$ $\frac{V_{OS}}{\Delta V_{OS}}$ $I_{OS}$	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4) Change in V <sub>OS</sub> between Complimentary Output S Output Short Circuit Cur	IS ge States States rent	$V_{OUT} = 0V$ $R_L = 100\Omega$ $V_{OUT} = 0V,$	R <sub>L</sub> = 100Ω		290 1.25 -3.5	450 35 1.375 35 -5	m\ m\ V m\
$\frac{I_{OS}}{V_{OD}}$ $\frac{V_{OD}}{\Delta V_{OD}}$ $\frac{V_{OS}}{\Delta V_{OS}}$ $I_{OS}$	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4) Change in V <sub>OS</sub> between Complimentary Output S	IS ge States States rent	$V_{OUT} = 0V$ $R_L = 100\Omega$ $V_{OUT} = 0V,$ $\overline{PWR DWN}$	R <sub>L</sub> = 100Ω = 0V,		290 1.25	450 35 1.375 35	m\ m\ V m\
I <sub>OS</sub> LVDS DI ΔV <sub>OD</sub> ΔV <sub>OS</sub> ΔV <sub>OS</sub> I <sub>OS</sub> I <sub>OZ</sub>	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltag Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4) Change in V <sub>OS</sub> between Complimentary Output S Output Short Circuit Cur Output TRI-STATE® Cur	IS ge States States rent rrent	$V_{OUT} = 0V$ $R_L = 100\Omega$ $V_{OUT} = 0V,$	R <sub>L</sub> = 100Ω = 0V,		290 1.25 -3.5	450 35 1.375 35 -5	m\ m\ V m\
I <sub>OS</sub> LVDS D ΔV <sub>OD</sub> ΔV <sub>OS</sub> ΔV <sub>OS</sub> I <sub>OS</sub> I <sub>OZ</sub> LVDS R	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4) Change in V <sub>OS</sub> between Complimentary Output S Output Short Circuit Cur Output TRI-STATE® Cur ECEIVER DC SPECIFICATI	IS ge States States rent rrent ONS	$V_{OUT} = 0V$ $R_{L} = 100\Omega$ $V_{OUT} = 0V,$ $PWR DWN$ $V_{OUT} = 0V c$	$R_L = 100Ω$ = 0V, or V <sub>CC</sub>		290 1.25 -3.5	450 35 1.375 35 -5 ±10	/m / /m / //m / /m / /u /
I <sub>OS</sub> LVDS D           V <sub>OD</sub> ΔV <sub>OD</sub> ΔV <sub>OS</sub> I <sub>OS</sub> I <sub>OS</sub> I <sub>OZ</sub> LVDS R           V <sub>TH</sub>	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4) Change in V <sub>OS</sub> between Complimentary Output S Output Short Circuit Cur Output TRI-STATE® Cur <b>ECEIVER DC SPECIFICATI</b> Differential Input High Th	IS ge States States rent rrent ONS nreshold	$V_{OUT} = 0V$ $R_L = 100\Omega$ $V_{OUT} = 0V,$ $\overline{PWR DWN}$	$R_L = 100Ω$ = 0V, or V <sub>CC</sub>	1.125	290 1.25 -3.5	450 35 1.375 35 -5	/m / /m / /m / /m / /m / /m /
I <sub>OS</sub> LVDS D           V <sub>OD</sub> ΔV <sub>OD</sub> V <sub>OS</sub> ΔV <sub>OS</sub> I <sub>OS</sub> I <sub>OS</sub> V <sub>OTH</sub> V <sub>TL</sub>	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4) Change in V <sub>OS</sub> between Complimentary Output S Output Short Circuit Cur Output Short Circuit Cur Output TRI-STATE® Cur <b>ECEIVER DC SPECIFICATI</b> Differential Input High Th Differential Input Low Th	IS ge States States rent rrent ONS nreshold	$V_{OUT} = 0V$ $R_{L} = 100\Omega$ $V_{OUT} = 0V,$ $PWR DWN$ $V_{OUT} = 0V c$ $V_{CM} = +1.2V$	$R_L = 100\Omega$ = 0V, pr V <sub>CC</sub>		290 1.25 -3.5	450 35 1.375 35 −5 ±10 +100	/m \ m\ V m\ m\ µ4 m\ m\
V <sub>OD</sub> ΔV <sub>OD</sub> V <sub>OS</sub> ΔV <sub>OS</sub> I <sub>OS</sub> I <sub>OZ</sub>	Output Short Circuit Cur <b>RIVER DC SPECIFICATION</b> Differential Output Voltage Change in V <sub>OD</sub> between Complimentary Output S Offset Voltage (Note 4) Change in V <sub>OS</sub> between Complimentary Output S Output Short Circuit Cur Output TRI-STATE® Cur <b>ECEIVER DC SPECIFICATI</b> Differential Input High Th	IS ge States States rent rrent ONS nreshold	$V_{OUT} = 0V$ $R_{L} = 100\Omega$ $V_{OUT} = 0V,$ $PWR DWN$ $V_{OUT} = 0V c$ $V_{CM} = +1.2V$	$R_{L} = 100\Omega$ = 0V, or V <sub>CC</sub> /	1.125	290 1.25 -3.5	450 35 1.375 35 -5 ±10	Am // // // // // // // // // // // // //

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Symbol	Parameter	Condi	tions	Min	Тур	Max	Units
•					- 76		
I <sub>CCTW</sub>	Transmitter Supply Current Worst Case (with Loads)	$R_{L} = 100\Omega,$ $C_{L} = 5 \text{ pF},$	f = 32.5 MHz		31	45	mA
		Worst Case Pattern ( <i>Figures 1, 2</i> ),	f = 37.5 MHz		32	50	mA
		$T_A = -10^{\circ}C$ to +70°C	f = 66 MHz		37	55	mA
		$R_{L} = 100\Omega,$ $C_{L} = 5 \text{ pF},$ Worst Case Pattern	f = 40 MHz		38	51	mA
		(Figures 1, 2), $T_A = -40^{\circ}C to$ +85°C	f = 66 MHz		42	55	mA
I <sub>CCTZ</sub>	Transmitter Supply Current Power Down	PWR DWN = Low           Driver Outputs in           under Powerdown	TRI-STATE		10	55	μA
RECEIVE	ER SUPPLY CURRENT						
I <sub>CCRW</sub>	Receiver Supply Current Worst Case	C <sub>L</sub> = 8 pF, Worst Case	f = 32.5 MHz		49	65	mA
		Pattern ( <i>Figures 1, 3</i> ),	f = 37.5 MHz		53	70	mA
		T <sub>A</sub> = −10°C to +70°C	f = 66 MHz		78	105	mA
		C <sub>L</sub> = 8 pF, Worst Case Pattern	f = 40 MHz		55	82	mA
		( <i>Figures 1, 3</i> ), T <sub>A</sub> = −40°C to +85°C	f = 66 MHz		78	105	mA
I <sub>CCRZ</sub>	Receiver Supply Current Power Down	PWR DWN = Low Receiver Outputs Powerdown Mode			10	55	μA

should be operated at these limits. The tables of "Electrical Characteristics" specify conditions for device operation.

Note 2: Typical values are given for V<sub>CC</sub> = 3.3V and T<sub>A</sub> = +25  $^\circ\text{C}.$ 

Note 3: Current into device pins is defined as positive. Current out of device pins is defined as negative. Voltages are referenced to ground unless otherwise specified (except  $V_{OD}$  and  $\Delta V_{OD}$ ).

Note 4:  $V_{OS}$  previously referred as  $V_{CM}$ .

Transmitter Switching Characteristics Over recommended operating supply and -40°C to +85°C ranges unless otherwise specified

Symbol	Parameter		Min	Тур	Max	Units
LLHT	LVDS Low-to-High Transition Time (Figure	? <i>2</i> )		0.5	1.5	ns
LHLT	LVDS High-to-Low Transition Time (Figure	? <i>2</i> )		0.5	1.5	ns
TCIT	TxCLK IN Transition Time (Figure 4)				5	ns
TCCS	TxOUT Channel-to-Channel Skew (Figure	5)		250		ps
TPPos0	Transmitter Output Pulse Position for Bit0 (Note 7) ( <i>Figure 16</i> )	f = 40 MHz	-0.4	0	0.4	ns
TPPos1	Transmitter Output Pulse Position for Bit1		3.1	3.3	4.0	ns
TPPos2	Transmitter Output Pulse Position for Bit2		6.5	6.8	7.6	ns

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Symbol	mmended operating supply and -40°C to + Parameter		Min	Тур	N	lax	Units	
TPPos3	Transmitter Output Pulse Position for Bit3		10.2	10.4	1	1.0	ns	
TPPos4	Transmitter Output Pulse Position for Bit4		13.7	13.9	1	4.6	ns	
TPPos5	Transmitter Output Pulse Position for Bit5		17.3	17.6	1	8.2	ns	
TPPos6	Transmitter Output Pulse Position for Bit6		21.0	21.2	2 21.8			
TPPos0	Transmitter Output Pulse Position for Bit0 (Note 6) ( <i>Figure 16</i> )	f = 66 MHz	-0.4	0	(	).3	ns	
TPPos1	Transmitter Output Pulse Position for Bit1		1.8	2.2	2	2.5	ns	
TPPos2	Transmitter Output Pulse Position for Bit2		4.0	4.4	4	1.7	ns	
TPPos3	Transmitter Output Pulse Position for Bit3		6.2	6.6	6	6.9	ns	
TPPos4	Transmitter Output Pulse Position for Bit4		8.4	8.8	ę	9.1	ns	
TPPos5	Transmitter Output Pulse Position for Bit5		10.6	11.0	11.3		ns	
TPPos6	Transmitter Output Pulse Position for Bit6		12.8	13.2	13.5		ns	
TCIP	TxCLK IN Period (Figure 6)		15	Т		50	ns	
TCIH	TxCLK IN High Time (Figure 6)		0.35T	0.5T	0.	65T	ns	
TCIL	TxCLK IN Low Time (Figure 6)		0.35T	0.5T	0.65T		ns	
TSTC	TxIN Setup to TxCLK IN (Figure 6)		2.5				ns	
тнтс	TxIN Hold to TxCLK IN (Figure 6)		0				ns	
TCCD	TxCLK IN to TxCLK OUT Delay @ 25°C, ( <i>Figure 8</i> )	V <sub>CC</sub> =3.3V	3	3.7	5	5.5	ns	
TPLLS	Transmitter Phase Lock Loop Set (Figure	ə 10)				10	ms	
TPDD	Transmitter Powerdown Delay (Figure 14	A)			1	00	ns	
	ver Switching Characteris mmended operating supply and -40°C to +		otherwise specifie	ed				
Symbol	Parame	eter		Min	Тур	Max	Unit	
CLHT	CMOS/TTL Low-to-High Transition Time	(Figure 3)			2.2	5.0	ns	
CHLT	CMOS/TTL High-to-Low Transition Time	(Figure 3)			2.2	5.0	ns	
RSPos0	Receiver Input Strobe Position for Bit 0 (	Note 7)(Figure 17)	f = 40 MHz	1.0	1.4	2.15	ns	
RSPos1	Receiver Input Strobe Position for Bit 1			4.5	5.0	5.8	ns	
RSPos2	Receiver Input Strobe Position for Bit 2		_	8.1	8.5	9.15	ns	
RSPos3	Receiver Input Strobe Position for Bit 3		_	11.6	11.9	12.6	ns	
RSPos4	Receiver Input Strobe Position for Bit 4		_	15.1	15.6	16.3	ns	
RSPos5	Receiver Input Strobe Position for Bit 5	_	18.8	19.2	19.9	ns		
RSPos6	Receiver Input Strobe Position for Bit 6			22.5	22.9	23.6	ns	

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# Receiver Switching Characteristics (Continued)

Over recommended operating supply and -40°C to +85°C ranges unless otherwise specified

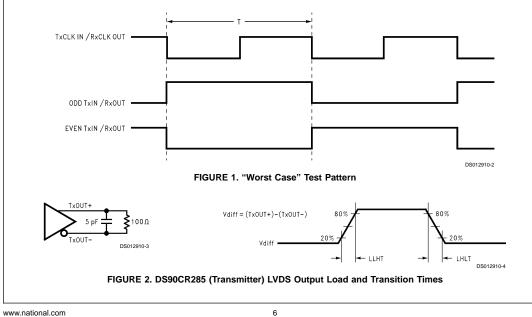
Symbol	Parameter		Min	Тур	Max	Units
RSPos0	Receiver Input Strobe Position for Bit 0 (Note 6)(Figure 17)	f = 66 MHz	0.7	1.1	1.4	ns
RSPos1	Receiver Input Strobe Position for Bit 1	1	2.9	3.3	3.6	ns
RSPos2	Receiver Input Strobe Position for Bit 2	]	5.1	5.5	5.8	ns
RSPos3	Receiver Input Strobe Position for Bit 3	1	7.3	7.7	8.0	ns
RSPos4	Receiver Input Strobe Position for Bit 4	]	9.5	9.9	10.2	ns
RSPos5	Receiver Input Strobe Position for Bit 5	1	11.7	12.1	12.4	ns
RSPos6	Receiver Input Strobe Position for Bit 6	]	13.9	14.3	14.6	ns
RSKM	RxIN Skew Margin (Note 5) (Figure 18)	f = 40 MHz	490			ps
		f = 66 MHz	400			ps
RCOP	RxCLK OUT Period (Figure 7)		15	Т	50	ns
RCOH	RxCLK OUT High Time (Figure 7)	f = 40 MHz	6.0	10.0		ns
		f = 66 MHz	4.0	6.1		ns
RCOL	RxCLK OUT Low Time (Figure 7)	f = 40 MHz	10.0	13.0		ns
		f = 66 MHz	6.0	7.8		ns
RSRC	RxOUT Setup to RxCLK OUT (Figure 7)	f = 40 MHz	6.5	14.0		ns
		f = 66 MHz	2.5	8.0		ns
RHRC	RxOUT Hold to RxCLK OUT (Figure 7)	f = 40 MHz	6.0	8.0		ns
		f = 66 MHz	2.5	4.0		ns
RCCD	RxCLK IN to RxCLK OUT Delay (Figure 9)	f = 40 MHz	4.0	6.7	8.0	ns
		f = 66 MHz	5.0	6.6	9.0	ns
RPLLS	Receiver Phase Lock Loop Set (Figure 11)				10	ms
RPDD	Receiver Powerdown Delay (Figure 15)				1	μs

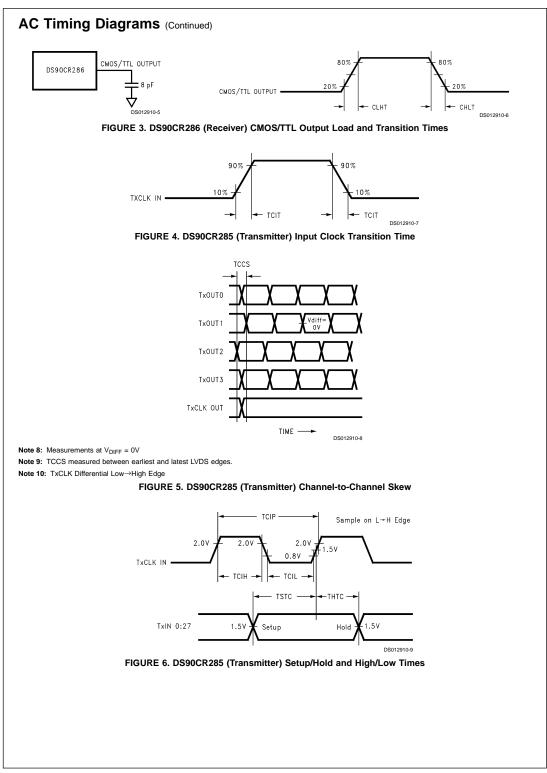
Note 5: Receiver Skew Margin is defined as the valid data sampling region at the receiver inputs. This margin takes into account the transmitter pulse positions (min and max) and the receiver input setup and hold time (internal data sampling window). This margin allows LVDS interconnect skew, inter-symbol interference (both dependent on type/length of cable), and clock jitter less than 250 ps).

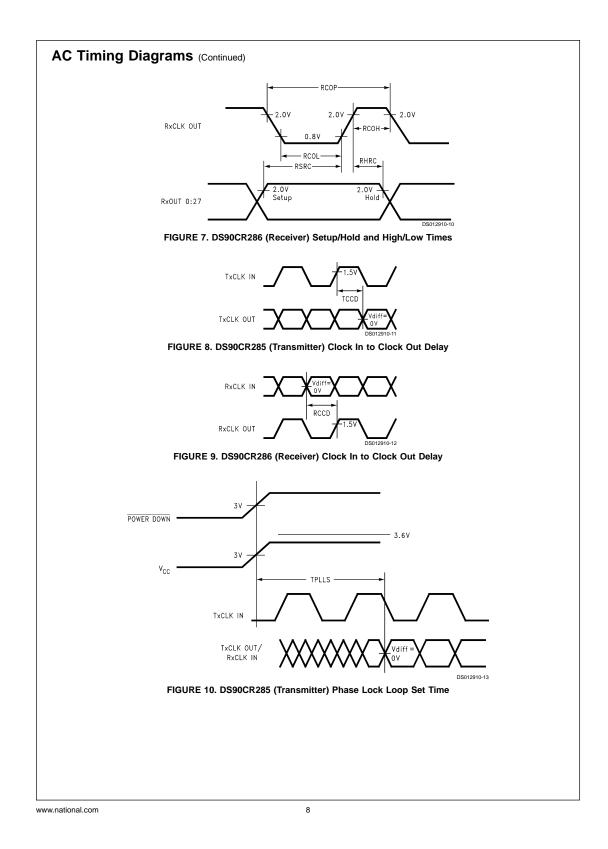
Note 6: The min. and max. limits are based on the worst bit by applying a -400ps/+300ps shift from ideal position.

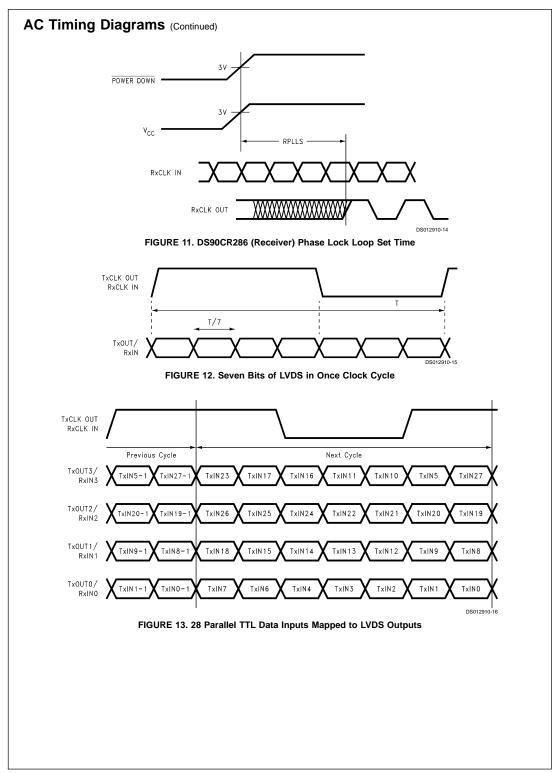
Note 7: The min. and max. are based on the actual bit position of each of the 7 bits within the LVDS data stream across PVT.

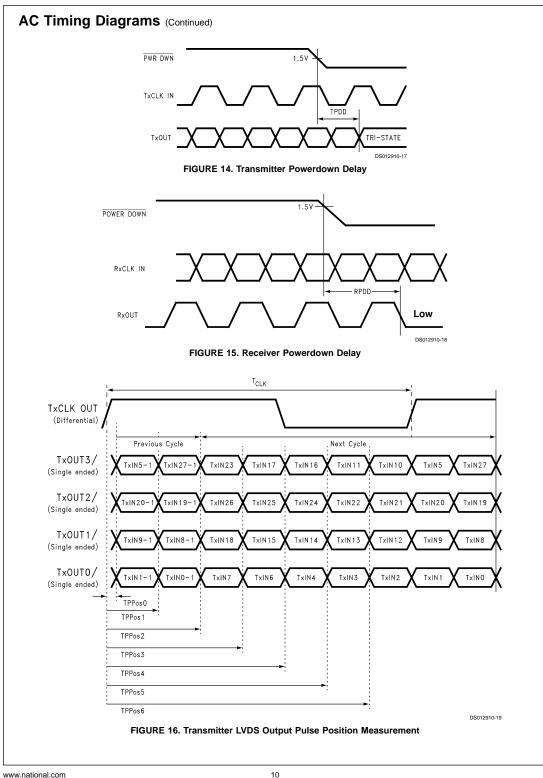
# **AC Timing Diagrams**

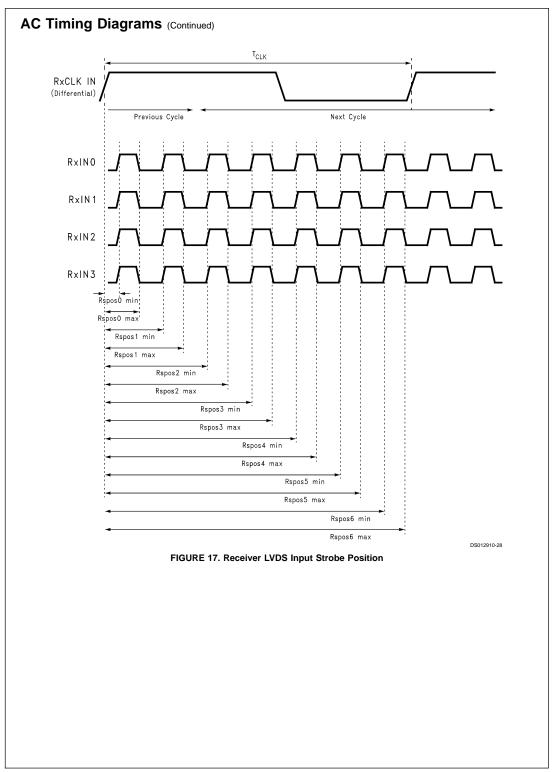


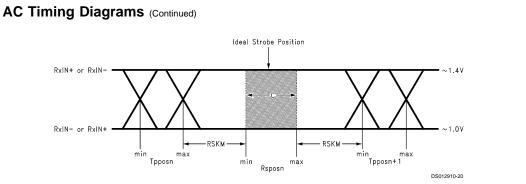












C — Setup and Hold Time (Internal data sampling window) defined by Rspos (receiver input strobe position) min and max Tppos — Transmitter output pulse position (min and max) RSKM ≥ Cable Skew (type, length) + Source Clock Jitter (cycle to cycle)(Note 11) + ISI (Inter-symbol interference)(Note 12)

 $\mathsf{RSKM} \geq \mathsf{Cable Skew} \ (\mathsf{type}, \, \mathsf{length}) + \mathsf{Source Clock Jitter} \ (\mathsf{cycle to cycle}) (\mathsf{Note 11}) + \mathsf{ISI} \ (\mathsf{Inter-symbol interference}) \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps-40 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typically 10 ps per foot, media dependent} \\ \mathsf{Cable Skew} \ - \mathsf{typical skew} \ - \mathsf{typi$ 

Note 11: Cycle-to-cycle jitter is less than 250 ps

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Note 11: Cycle-to-cycle jitter is less than 250 ps Note 12: ISI is dependent on interconnect length; may be zero

#### FIGURE 18. Receiver LVDS Input Skew Margin

Applications Information

The DS90CR285 and DS90CR286 are backward compatible with the existing 5V Channel Link transmitter/receiver pair (DS90CR283, DS90CR284). To upgrade from a 5V to a 3.3V system the following must be addressed:

- 1. Change 5V power supply to 3.3V. Provide this supply to the V\_{CC}, LVDS V\_{CC} and PLL V\_{CC}.
- Transmitter input and control inputs except 3.3V TTL/ CMOS levels. They are not 5V tolerant.
- The receiver powerdown feature when enabled will lock receiver output to a logic low. However, the 5V/66 MHz receiver maintain the outputs in the previous state when powerdown occurred.

# DS90CR285 Pin Description—Channel Link Transmitter

Pin Name	I/O	No.	Description
TxIN	1	28	TTL level input.
TxOUT+	0	4	Positive LVDS differential data output.
TxOUT-	0	4	Negative LVDS differential data output.
TxCLK IN	1	1	TTL level clock input. The rising edge acts as data strobe. Pin name TxCLK IN.
TxCLK OUT+	0	1	Positive LVDS differential clock output.
TxCLK OUT-	0	1	Negative LVDS differential clock output.
PWR DWN	I	1	TTL level input. Assertion (low input) TRI-STATES the outputs, ensuring low current at power down.
V <sub>cc</sub>	I	4	Power supply pins for TTL inputs.
GND	1	5	Ground pins for TTL inputs.
PLL V <sub>CC</sub>	I	1	Power supply pin for PLL.
PLL GND	1	2	Ground pins for PLL.
LVDS V <sub>CC</sub>	1	1	Power supply pin for LVDS outputs.
LVDS GND	1	3	Ground pins for LVDS outputs.

# DS90CR286 Pin Description—Channel Link Receiver

Pin Name	I/O	No.	Description
RxIN+	1	4	Positive LVDS differential data inputs.
RxIN-	1	4	Negative LVDS differential data inputs.
RxOUT	0	28	TTL level data outputs.
RxCLK IN+	1	1	Positive LVDS differential clock input.
RxCLK IN-	1	1	Negative LVDS differential clock input.
RxCLK OUT	0	1	TTL level clock output. The rising edge acts as data strobe. Pin name RxCLK OUT.

### Applications Information (Continued)

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## DS90CR286 Pin Description—Channel Link Receiver (Continued)

I/O	No.	Description
I	1	TTL level input.When asserted (low input) the receiver outputs are low.
Ι	4	Power supply pins for TTL outputs.
I	5	Ground pins for TTL outputs.
Ι	1	Power supply for PLL.
I	2	Ground pin for PLL.
Ι	1	Power supply pin for LVDS inputs.
I	3	Ground pins for LVDS inputs.
	I/O 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	I         1           I         4           I         5           I         1           I         2           I         1

The Channel Link devices are intended to be used in a wide variety of data transmission applications. Depending upon the application the interconnecting media may vary. For example, for lower data rate (clock rate) and shorter cable lengths (< 2m), the media electrical performance is less critical. For higher speed/long distance applications the media's performance becomes more critical. Certain cable constructions provide tighter skew (matched electrical length between the conductors and pairs). Twin-coax for example, has been demonstrated at distances as great as 5 meters and with the maximum data transfer of 1.848 Gbit/s. Additional applications information can be found in the following National Interface Application Notes:

AN = ####	Торіс
AN-1041	Introduction to Channel Link
AN-1035	PCB Design Guidelines for LVDS and Link Devices
AN-806	Transmission Line Theory
AN-905	Transmission Line Calculations and Differential Impedance
AN-916	Cable Information

**CABLES:** A cable interface between the transmitter and receiver needs to support the differential LVDS pairs. The 21bit CHANNEL LINK chipset (DS90CR215/216) requires four pairs of signal wires and the 28-bit CHANNEL LINK chipset (DS90CR285/286) requires five pairs of signal wires. The ideal cable/connector interface would have a constant 100Ω differential impedance throughout the path. It is also recommended that cable skew remain below 150 ps ( 66 MHz clock rate) to maintain a sufficient data sampling window at the receiver.

In addition to the four or five cable pairs that carry data and clock, it is recommended to provide at least one additional conductor (or pair) which connects ground between the transmitter and receiver. This low impedance ground provides a common mode return path for the two devices. Some of the more commonly used cable types for point-to-point applications include flat ribbon, flex, twisted pair and Twin-Coax. All are available in a variety of configurations and options. Flat ribbon cable, flex and twisted pair generally perform well in short point-to-point applications while Twin-Coax is good for short and long applications. When using ribbon cable, it is recommended to place a ground line between each differential pair to act as a barrier to noise coupling between adjacent pairs. For Twin-Coax cable applications, it is recommended to utilize a shield on each cable pair. All extended point-to-point applications should also employ an overall shield surrounding all cable pairs regardless of the

cable type. This overall shield results in improved transmission parameters such as faster attainable speeds, longer distances between transmitter and receiver and reduced problems associated with EMS or EMI.

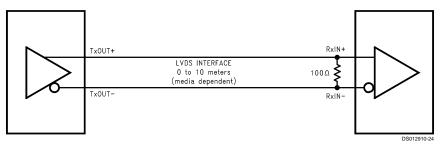
The high-speed transport of LVDS signals has been demonstrated on several types of cables with excellent results. However, the best overall performance has been seen when using Twin-Coax cable. Twin-Coax has very low cable skew and EMI due to its construction and double shielding. All of the design considerations discussed here and listed in the supplemental application notes provide the subsystem communications designer with many useful guidelines. It is recommended that the designer assess the tradeoffs of each application thoroughly to arrive at a reliable and economical cable solution.

BOARD LAYOUT: To obtain the maximum benefit from the noise and EMI reductions of LVDS, attention should be paid to the layout of differential lines. Lines of a differential pair should always be adjacent to eliminate noise interference from other signals and take full advantage of the noise canceling of the differential signals. The board designer should also try to maintain equal length on signal traces for a given differential pair. As with any high speed design, the impedance discontinuities should be limited (reduce the numbers of vias and no 90 degree angles on traces). Any discontinuities which do occur on one signal line should be mirrored in the other line of the differential pair. Care should be taken to ensure that the differential trace impedance match the differential impedance of the selected physical media (this impedance should also match the value of the termination resistor that is connected across the differential pair at the receiver's input). Finally, the location of the CHANNEL LINK TxOUT/ RxIN pins should be as close as possible to the board edge so as to eliminate excessive pcb runs. All of these considerations will limit reflections and crosstalk which adversely effect high frequency performance and EMI.

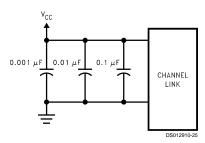
**UNUSED INPUTS:** All unused inputs at the TxIN inputs of the transmitter must be tied to ground. All unused outputs at the RxOUT outputs of the receiver must then be left floating. **TERMINATION:** Use of current mode drivers requires a terminating resistor across the receiver inputs. The CHANNEL LINK chipset will normally require a single 100 $\Omega$  resistor between the true and complement lines on each differential pair of the receiver input. The actual value of the termination resistor should be selected to match the differential mode characteristic impedance (90 $\Omega$  to 120 $\Omega$  typical) of the cable. *Figure 19* shows an example. No additional pull-up or pulldown resistors are necessary as with some other differential technologies such as PECL. Surface mount resistors are

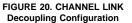
#### Applications Information (Continued)

companies leaded resistors. These resistors should be placed as close as possible to the receiver input pins to reduce stubs and effectively terminate the differential lines. **DECOUPLING CAPACITORS:** Bypassing capacitors are needed to reduce the impact of switching noise which could limit performance. For a conservative approach three parallel-connected decoupling capacitors (Multi-Layered Ce ramic type in surface mount form factor) between each V<sub>CC</sub> and the ground plane(s) are recommended. The three capacitor values are 0.1  $\mu$ F, 0.01 $\mu$ F and 0.001  $\mu$ F. An example is shown in *Figure 20*. The designer should employ wide traces for power and ground and ensure each capacitor has its own via to the ground plane. If board space is limiting the number of bypass capacitors, the PLL V<sub>CC</sub> should receive the most filtering/bypassing. Next would be the LVDS V<sub>CC</sub> pins and finally the logic V<sub>CC</sub> pins.



#### FIGURE 19. LVDS Serialized Link Termination





**CLOCK JITTER:** The CHANNEL LINK devices employ a PLL to generate and recover the clock transmitted across the LVDS interface. The width of each bit in the serialized LVDS data stream is one-seventh the clock period. For example, a 66 MHz clock has a period of 15 ns which results in a data bit width of 2.16 ns. Differential skew ( $\Delta t$  within one differential pair), interconnect skew ( $\Delta t$  of one differential pair to another) and clock jitter will all reduce the available window for sampling the LVDS serial data streams. Care must be taken to ensure that the clock input to the transmitter be a clean low noise signal. Individual bypassing of each V<sub>CC</sub> to ground will minimize the noise passed on to the PLL, thus creating a

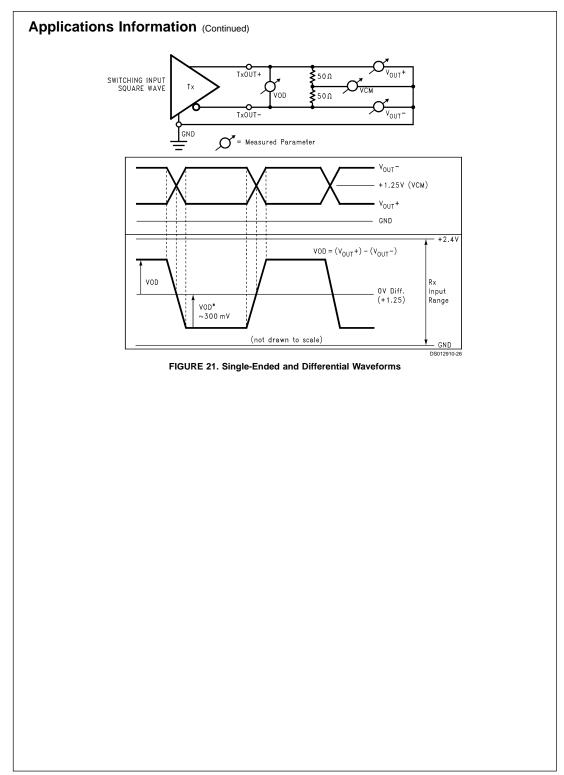
low jitter LVDS clock. These measures provide more margin for channel-to-channel skew and interconnect skew as a part of the overall jitter/skew budget.

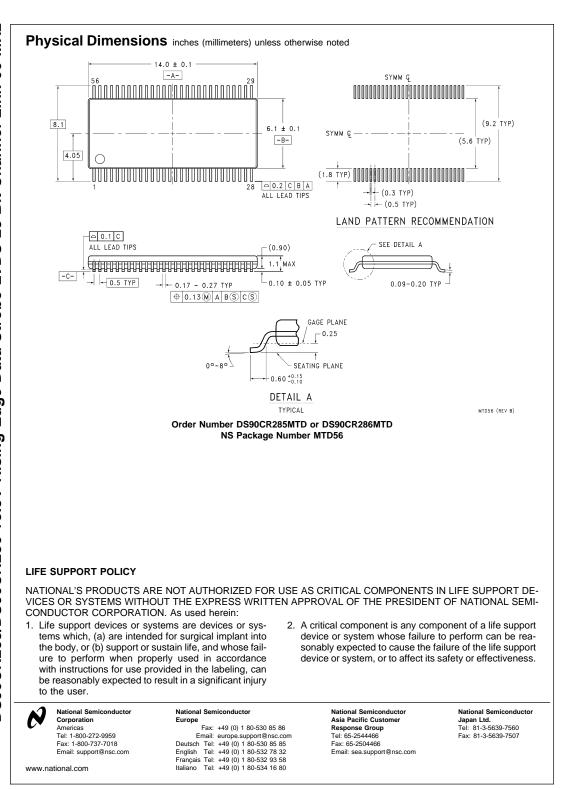
**COMMON MODE vs. DIFFERENTIAL MODE NOISE MAR-GIN:** The typical signal swing for LVDS is 300 mV centered at +1.2V. The CHANNEL LINK receiver supports a 100 mV threshold therefore providing approximately 200 mV of differential noise margin. Common mode protection is of more importance to the system's operation due to the differential data transmission. LVDS supports an input voltage range of Ground to +2.4V. This allows for a ±1.0V shifting of the center point due to ground potential differences and common mode noise.

**POWER SEQUENCING AND POWERDOWN MODE:** Outputs of the CNANNEL LINK transmitter remain in TRI-STATE® until the power supply reaches 2V. Clock and data outputs will begin to toggle 10 ms after  $V_{CC}$  has reached 3V and the Powerdown pin is above 1.5V. Either device may be placed into a powerdown mode at any time by asserting the Powerdown pin (active low). Total power dissipation for each device will decrease to 5  $\mu$ W (typical).

The CHANNEL LINK chipset is designed to protect itself from accidental loss of power to either the transmitter or receiver. If power to the transmit board is lost, the receiver clocks (input and output) stop. The data outputs (RxOUT) retain the states they were in when the clocks stopped. When the receiver board loses power, the receiver inputs are shorted to V $_{\rm CC}$  through an internal diode. Current is limited (5 mA per input) by the fixed current mode drivers, thus avoiding the potential for latchup when powering the device.

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