

# ADC08131/ADC08134/ADC08138

## 8-Bit High-Speed Serial I/O A/D Converters with Multiplexer Options, Voltage Reference, and Track/Hold Function

### General Description

The ADC08131/ADC08134/ADC08138 are 8-bit successive approximation A/D converters with serial I/O and configurable input multiplexers with up to 8 channels. The serial I/O is configured to comply with the NSC MICROWIRE™ serial data exchange standard for easy interface to the COPS™ family of controllers, and can easily interface with standard shift registers or microprocessors.

All three devices provide a 2.5V band-gap derived reference with guaranteed performance over temperature.

A track/hold function allows the analog voltage at the positive input to vary during the actual A/D conversion.

The analog inputs can be configured to operate in various combinations of single-ended, differential, or pseudo-differential modes. In addition, input voltage spans as small as 1V can be accommodated.

### Applications

- Digitizing automotive sensors
- Process control/monitoring
- Remote sensing in noisy environments
- Embedded diagnostics

### Features

- Serial digital data link requires few I/O pins
- Analog input track/hold function
- 4- or 8-channel input multiplexer options with address logic
- On-chip 2.5V band-gap reference ( $\pm 2\%$  over temperature guaranteed)
- No zero or full scale adjustment required
- TTL/CMOS input/output compatible
- 0V to 5V analog input range with single 5V power supply

### Key Specifications

- |   |                               |
|---|-------------------------------|
| ■ Resolution                                  | 8 Bits                        |
| ■ Conversion time ( $f_C = 1 \text{ MHz}$ )   | 8 $\mu\text{s}$ (Max)         |
| ■ Power dissipation                           | 20 mW (Max)                   |
| ■ Single supply                               | 5 $V_{DC}$ ( $\pm 5\%$ )      |
| ■ Total unadjusted error                      | $\pm 1/2$ LSB and $\pm 1$ LSB |
| ■ Linearity Error ( $V_{REF} = 2.5\text{V}$ ) | $\pm 1/2$ LSB                 |
| ■ No missing codes (over temperature)         |                               |
| ■ On-board Reference                          | +2.5V $\pm 1.5\%$ (Max)       |

### Ordering Information

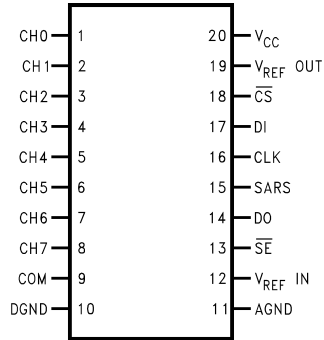
Industrial ( $-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ )	Package
ADC08131CIWM	M14B
ADC08134CIWM	M14B
ADC08138CIWM	M20B

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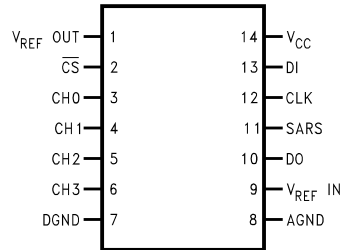
## Connection Diagrams

**ADC08138CIWM**  
Small Outline  
Packages



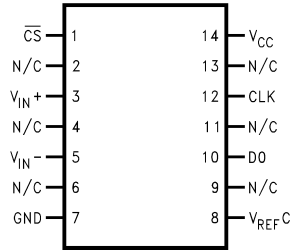
DS010749-2

**ADC08134CIWM**  
Small Outline  
Packages



DS010749-3

**ADC08131CIWM**  
Small Outline Package



DS010749-4

### Absolute Maximum Ratings (Notes 1, 3)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Supply Voltage ( $V_{CC}$ )	6.5V
Voltage at Inputs and Outputs	-0.3V to $V_{CC} + 0.3V$
Input Current at Any Pin (Note 4)	$\pm 5$ mA
Package Input Current (Note 4)	$\pm 20$ mA
Power Dissipation at $T_A = 25^\circ\text{C}$ (Note 5)	800 mW
ESD Susceptibility (Note 6)	1500V

### Soldering Information

N Package (10 sec.)	260°C
SO Package:	215°C
Vapor Phase (60 sec.)	220°C
Infrared (15 sec.) (Note 7)	
Storage Temperature	-65°C to +150°C

### Operating Ratings (Notes 2, 3)

Temperature Range	$T_{MIN} \leq T_A \leq T_{MAX}$ -40°C $\leq T_A \leq$ +85°C
Supply Voltage ( $V_{CC}$ )	4.5 $V_{DC}$ to 6.3 $V_{DC}$

### Electrical Characteristics

The following specifications apply for  $V_{CC} = +5 V_{DC}$ ,  $V_{REF} = +2.5 V_{DC}$  and  $f_{CLK} = 1$  MHz unless otherwise specified. **Boldface limits apply for  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$** ; all other limits  $T_A = T_J = 25^\circ\text{C}$ .

Symbol	Parameter	Conditions	Typical (Note 8)	Limits (Note 9)	Units (Limits)
<b>CONVERTER AND MULTIPLEXER CHARACTERISTICS</b>					
	Linearity Error	$V_{REF} = +2.5 V_{DC}$		<b><math>\pm 1</math></b>	LSB (max)
	Full Scale Error	$V_{REF} = +2.5 V_{DC}$		<b><math>\pm 1</math></b>	LSB (max)
	Zero Error	$V_{REF} = +2.5 V_{DC}$		<b><math>\pm 1</math></b>	LSB (max)
	Total Unadjusted Error	$V_{REF} = +5 V_{DC}$ (Note 10)		<b><math>\pm 1</math></b>	LSB (max)
	Differential Linearity	$V_{REF} = +2.5 V_{DC}$		<b>8</b>	Bits (min)
$R_{REF}$	Reference Input Resistance	(Note 11)	3.5	<b>1.3</b> <b>6.0</b>	k $\Omega$ k $\Omega$ (min) k $\Omega$ (max)
$V_{IN}$	Analog Input Voltage	(Note 12)		<b>(<math>V_{CC} + 0.05</math>)</b> <b>(<math>GND - 0.05</math>)</b>	V (max) V (min)
	DC Common-Mode Error	$V_{REF} = 2.5 V_{DC}$		$\pm 1/2$	LSB (max)
	Power Supply Sensitivity	$V_{CC} = +5V \pm 5\%$ , $V_{REF} = +2.5 V_{DC}$		$\pm 1/4$	LSB (max)
	On Channel Leakage Current (Note 13)	On Channel = 5V, Off Channel = 0V		0.2 <b>1</b>	$\mu\text{A}$ (max)
		On Channel = 0V, Off Channel = 5V		-0.2 <b>-1</b>	$\mu\text{A}$ (max)
	Off Channel Leakage Current (Note 13)	On Channel = 5V, Off Channel = 0V		-0.2 <b>-1</b>	$\mu\text{A}$ (max)
		On Channel = 0V, Off Channel = 5V		0.2 <b>1</b>	$\mu\text{A}$ (max)
<b>DIGITAL AND DC CHARACTERISTICS</b>					
$V_{IN(1)}$	Logical "1" Input Voltage	$V_{CC} = 5.25V$		<b>2.0</b>	V (min)
$V_{IN(0)}$	Logical "0" Input Voltage	$V_{CC} = 4.75V$		<b>0.8</b>	V (max)
$I_{IN(1)}$	Logical "1" Input Current	$V_{IN} = 5.0V$		<b>1</b>	$\mu\text{A}$ (max)
$I_{IN(0)}$	Logical "0" Input Current	$V_{IN} = 0V$		<b>-1</b>	$\mu\text{A}$ (max)
$V_{OUT(1)}$	Logical "1" Output Voltage	$V_{CC} = 4.75V$ : $I_{OUT} = -360 \mu\text{A}$ $I_{OUT} = -10 \mu\text{A}$		<b>2.4</b> <b>4.5</b>	V (min) V (min)
$V_{OUT(0)}$			Logical "0" Output Voltage	$V_{CC} = 4.75V$ $I_{OUT} = 1.6 \text{ mA}$	
$I_{OUT}$	TRI-STATE® Output Current	$V_{OUT} = 0V$		<b>-3.0</b>	$\mu\text{A}$ (max)
		$V_{OUT} = 5V$		<b>3.0</b>	$\mu\text{A}$ (max)
$I_{SOURCE}$	Output Source Current	$V_{OUT} = 0V$		<b>-6.5</b>	mA (min)

## Electrical Characteristics (Continued)

The following specifications apply for  $V_{CC} = +5 V_{DC}$ ,  $V_{REF} = +2.5 V_{DC}$  and  $f_{CLK} = 1 \text{ MHz}$  unless otherwise specified. **Boldface limits apply for  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$** ; all other limits  $T_A = T_J = 25^\circ\text{C}$ .

Symbol	Parameter	Conditions	Typical (Note 8)	Limits (Note 9)	Units (Limits)
<b>DIGITAL AND DC CHARACTERISTICS</b>					
$I_{SINK}$	Output Sink Current	$V_{OUT} = V_{CC}$		<b>8.0</b>	mA (min)
$I_{CC}$	Supply Current			<b>3.0</b>	mA (max)
	ADC08134, ADC08138 ADC08131 (Note 16)	$\overline{CS} = \text{HIGH}$		<b>6.0</b>	mA (max)

## Electrical Characteristics

The following specifications apply for  $V_{CC} = +5 V_{DC}$ , and  $f_{CLK} = 1 \text{ MHz}$  unless otherwise specified. **Boldface limits apply for  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$** ; all other limits  $T_A = T_J = 25^\circ\text{C}$ .

Symbol	Parameter	Conditions	Typical (Note 8)	Limits (Note 9)	Units (Limits)
<b>REFERENCE CHARACTERISTICS</b>					
$V_{REF-OUT}$	Output Voltage	DC08134, ADC08138	<b>2.5 ±2%</b>	$2.5 \pm 1.5\%$	V
$\Delta V_{REF}/\Delta T$	Temperature Coefficient		40		ppm/°C
$\Delta V_{REF}/\Delta I_L$	Load Regulation (Note 17)	Sourcing ( $0 \leq I_L \leq +4 \text{ mA}$ ) ADC08134, ADC08138	0.003	<b>0.1</b>	%mA (max)
		Sourcing ( $0 \leq I_L \leq +2 \text{ mA}$ ) ADC08131	0.003	<b>0.1</b>	
		Sinking ( $-1 \leq I_L \leq 0 \text{ mA}$ ) ADC08134, ADC08138	0.2	<b>0.5</b>	
		Sinking ( $-1 \leq I_L \leq 0 \text{ mA}$ ) ADC08131	0.2	<b>0.5</b>	
	Line Regulation	$4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$	0.5	<b>6</b>	mV (max)
$I_{SC}$	Short Circuit Current	$V_{REF} = 0\text{V}$ ADC08134, ADC08138	8	<b>25</b>	mA (max)
		$V_{REF} = 0\text{V}$ ADC08131	8	<b>25</b>	
$T_{SU}$	Start-Up Time	$V_{CC}: 0\text{V} \rightarrow 5\text{V}$ $C_L = 100 \mu\text{F}$	20		ms
$\Delta V_{REF}/\Delta t$	Long Term Stability		200		ppm/1 kHr

## Electrical Characteristics

The following specifications apply for  $V_{CC} = +5 V_{DC}$ ,  $V_{REF} = +2.5 V_{DC}$  and  $t_r = t_f = 20 \text{ ns}$  unless otherwise specified. **Boldface limits apply for  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$** ; all other limits  $T_A = T_J = 25^\circ\text{C}$ .

Symbol	Parameter	Conditions	Typical (Note 8)	Limits (Note 9)	Units (Limits)
$f_{CLK}$	Clock Frequency		10	<b>1</b>	kHz (min) MHz (max)
	Clock Duty Cycle (Note 14)			<b>40</b> <b>60</b>	% (min) % (max)

## Electrical Characteristics (Continued)

The following specifications apply for  $V_{CC} = +5 V_{DC}$ ,  $V_{REF} = +2.5 V_{DC}$  and  $t_r = t_f = 20$  ns unless otherwise specified. **Boldface limits apply for  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$** ; all other limits  $T_A = T_J = 25^\circ C$ .

Symbol	Parameter	Conditions	Typical (Note 8)	Limits (Note 9)	Units (Limits)
$T_C$	Conversion Time (Not Including MUX Addressing Time)	$f_{CLK} = 1$ MHz		<b>8</b> <b>8</b>	$1/f_{CLK}$ (max) $\mu s$ (max)
$t_{CA}$	Acquisition Time			1/2	$1/f_{CLK}$ (max)
$t_{SELECT}$	CLK High while $\overline{CS}$ is High		50		ns
$t_{SET-UP}$	$\overline{CS}$ Falling Edge or Data Input Valid to CLK Rising Edge			<b>25</b>	ns (min)
$t_{HOLD}$	Data Input Valid after CLK Rising Edge			<b>20</b>	ns (min)
$t_{pd1}, t_{pd0}$	CLK Falling Edge to Output Data Valid (Note 15)	$C_L = 100$ pF: Data MSB First Data LSB First		<b>250</b> <b>200</b>	ns (max) ns (max)
$t_{1H}, t_{0H}$	TRI-STATE Delay from Rising Edge of $\overline{CS}$ to Data Output and SARS Hi-Z	$C_L = 10$ pF, $R_L = 10$ k $\Omega$ (see TRI-STATE Test Circuits) $C_L = 100$ pF, $R_L = 2$ k $\Omega$	50		ns ns (max)
$C_{IN}$	Capacitance of Logic Inputs		5		pF
$C_{OUT}$	Capacitance of Logic Outputs		5		pF

**Note 1:** Absolute Maximum Ratings indicate limits beyond which damage to the device may occur.

**Note 2:** Operating Ratings indicate conditions for which the device is functional. These ratings do not guarantee specific performance limits. For guaranteed specifications and test conditions, see the Electrical Characteristics. The guaranteed specifications apply only for the test conditions listed. Some performance characteristics may degrade when the device is not operated under the listed test conditions.

**Note 3:** All voltages are measured with respect to AGND = DGND =  $0 V_{DC}$ , unless otherwise specified.

**Note 4:** When the input voltage ( $V_{IN}$ ) at any pin exceeds the power supplies ( $V_{IN} < (AGND \text{ or } DGND)$  or  $V_{IN} > AV_{CC}$ ) the current at that pin should be limited to 5 mA. The 20 mA maximum package input current rating limits the number of pins that can safely exceed the power supplies with an input current of 5 mA to four pins.

**Note 5:** The maximum power dissipation must be derated at elevated temperatures and is dictated by  $T_{JMAX}$ ,  $\theta_{JA}$  and the ambient temperature,  $T_A$ . The maximum allowable power dissipation at any temperature is  $P_D = (T_{JMAX} - T_A)/\theta_{JA}$  or the number given in the Absolute Maximum Ratings, whichever is lower. For these devices  $T_{JMAX} = 125^\circ C$ . The typical thermal resistances ( $\theta_{JA}$ ) of these parts when board mounted for the ADC 08131 and the ADC08134 is 140  $^\circ C/W$  and 91  $^\circ C/W$  for the ADC08138.

**Note 6:** Human body model, 100 pF capacitor discharged through a 1.5 k $\Omega$  resistor.

**Note 7:** See AN450 "Surface Mounting Methods and Their Effect on Product Reliability" or Linear Data Book section "Surface Mount" for other methods of soldering surface mount devices.

**Note 8:** Typical values are at  $T_J = 25^\circ C$  and represent the most likely parametric norm.

**Note 9:** Guaranteed to National's AOQL (Average Outgoing Quality Level).

**Note 10:** Total unadjusted error includes zero, full-scale, linearity, and multiplexer error. Total unadjusted error with  $V_{REF} = +5V$  only applies to the ADC08134 and ADC08138. See (Note 16).

**Note 11:** Cannot be tested for the ADC08131.

**Note 12:** For  $V_{IN(-)} \geq V_{IN(+)}$  the digital code will be 0000 0000. Two on-chip diodes are tied to each analog input (see Block Diagram) which will forward-conduct for analog input voltages one diode drop below ground or one diode drop greater than  $V_{CC}$  supply. During testing at low  $V_{CC}$  levels (e.g., 4.5V), high level analog inputs (e.g., 5V) can cause an input diode to conduct, especially at elevated temperatures. This will cause errors for analog inputs near full-scale. The specification allows 50 mV forward bias of either diode; this means that as long as the analog  $V_{IN}$  does not exceed the supply voltage by more than 50 mV, the output code will be correct. Exceeding this range on an unselected channel will corrupt the reading of a selected channel. Achievement of an absolute  $0 V_{DC}$  to  $5 V_{DC}$  input voltage range will therefore require a minimum supply voltage of 4.950  $V_{DC}$  over temperature variations, initial tolerance and loading.

**Note 13:** Channel leakage current is measured after a single-ended channel is selected and the clock is turned off. For off channel leakage current the following two cases are considered: one, with the selected channel tied high ( $5 V_{DC}$ ) and the remaining seven off channels tied low ( $0 V_{DC}$ ), total current flow through the off channels is measured; two, with the selected channel tied low and the off channels tied high, total current flow through the off channels is again measured. The two cases considered for determining on channel leakage current are the same except total current flow through the selected channel is measured.

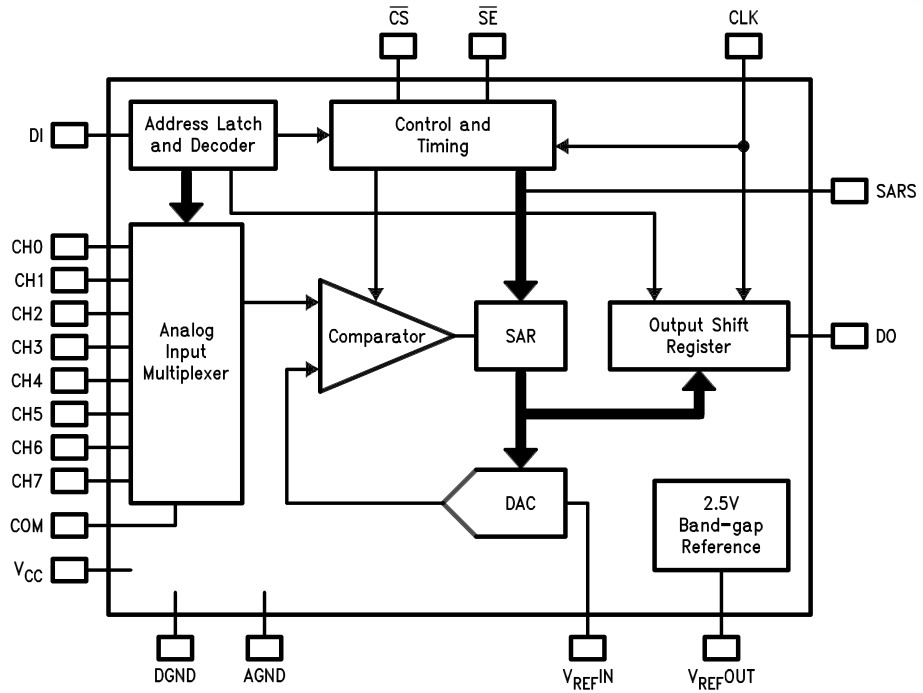
**Note 14:** A 40% to 60% duty cycle range insures proper operation at all clock frequencies. In the case that an available clock has a duty cycle outside of these limits the minimum time the clock is high or low must be at least 450 ns. The maximum time the clock can be high or low is 100  $\mu s$ .

**Note 15:** Since data, MSB first, is the output of the comparator used in the successive approximation loop, an additional delay is built in (see Block Diagram) to allow for comparator response time.

**Note 16:** For the ADC08131  $V_{REFIN}$  is internally tied to the on chip 2.5V band-gap reference output; therefore, the supply current is larger because it includes the reference current (700  $\mu A$  typical, 2 mA maximum).

**Note 17:** Load regulation test conditions and specifications for the ADC08131 differ from those of the ADC08134 and ADC08138 because the ADC08131 has the on-board reference as a permanent load.

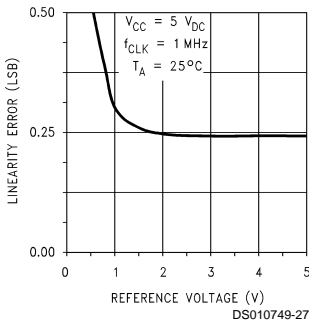
### ADC08138 Simplified Block Diagram



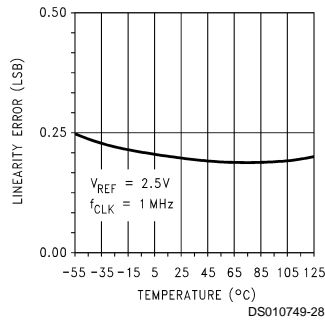
DS010749-1

## Typical Converter Performance Characteristics

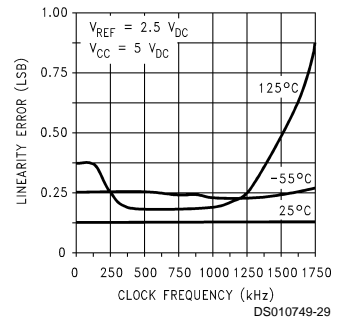
**Linearity Error vs Reference Voltage**



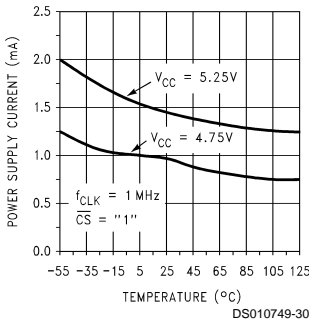
**Linearity Error vs Temperature**



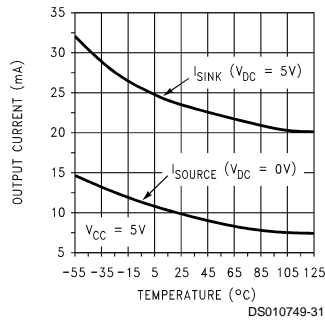
**Linearity Error vs Clock Frequency**



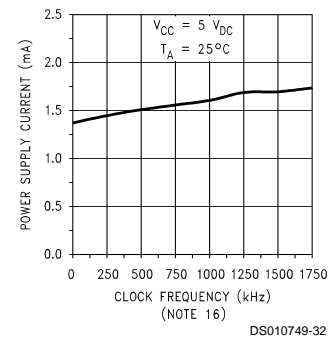
**Power Supply Current vs Temperature (ADC08138, ADC08134)**



**Output Current vs Temperature**



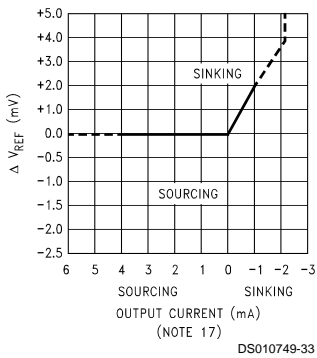
**Power Supply Current vs Clock Frequency**



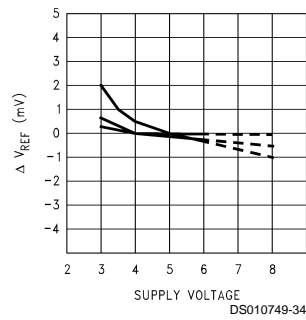
Note: For ADC08131 add  $I_{REF}$

## Typical Reference Performance Characteristics

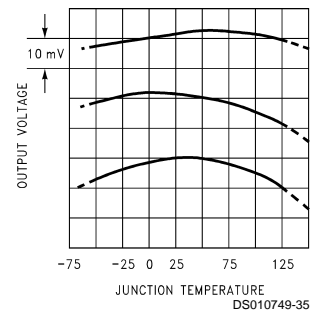
**Load Regulation**



**Line Regulation (3 Typical Parts)**

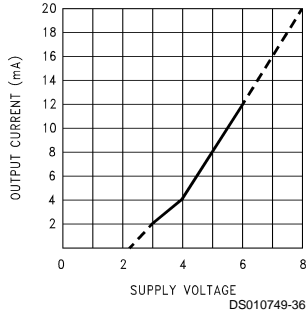


**Output Drift vs Temperature (3 Typical Parts)**

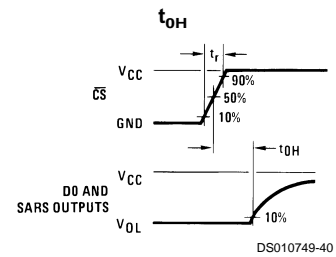
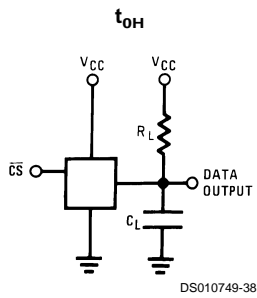
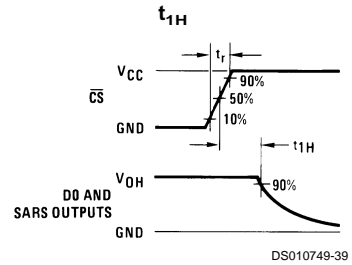
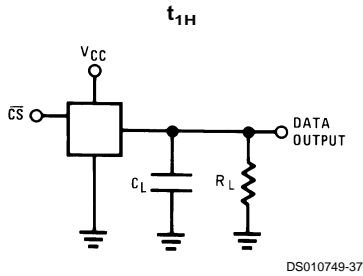


## Typical Reference Performance Characteristics (Continued)

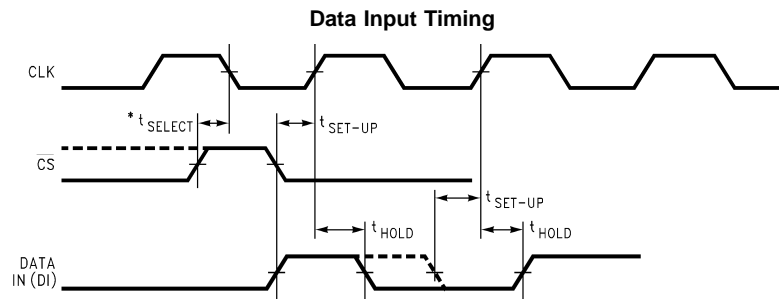
Available  
Output Current  
vs Supply Voltage



## TRI-STATE Test Circuits and Waveforms



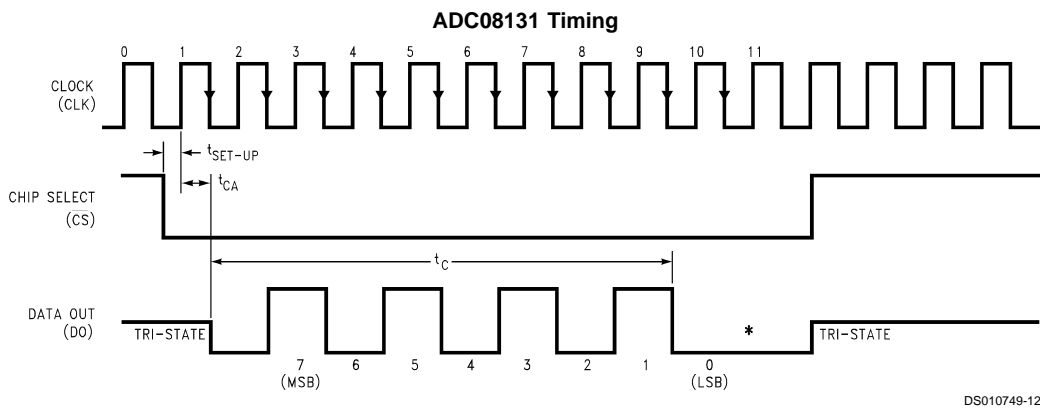
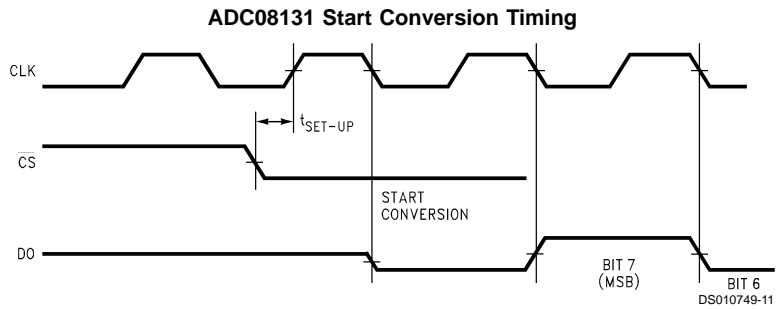
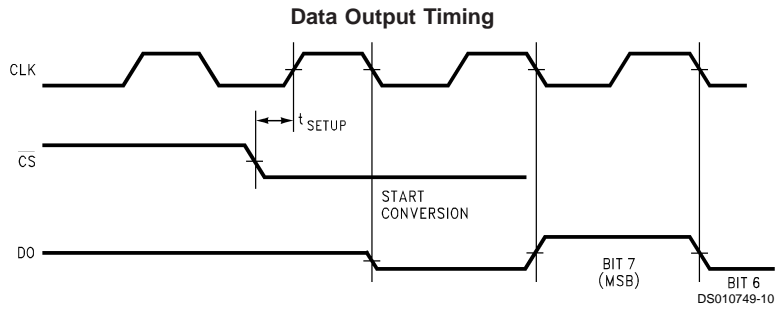
## Timing Diagrams



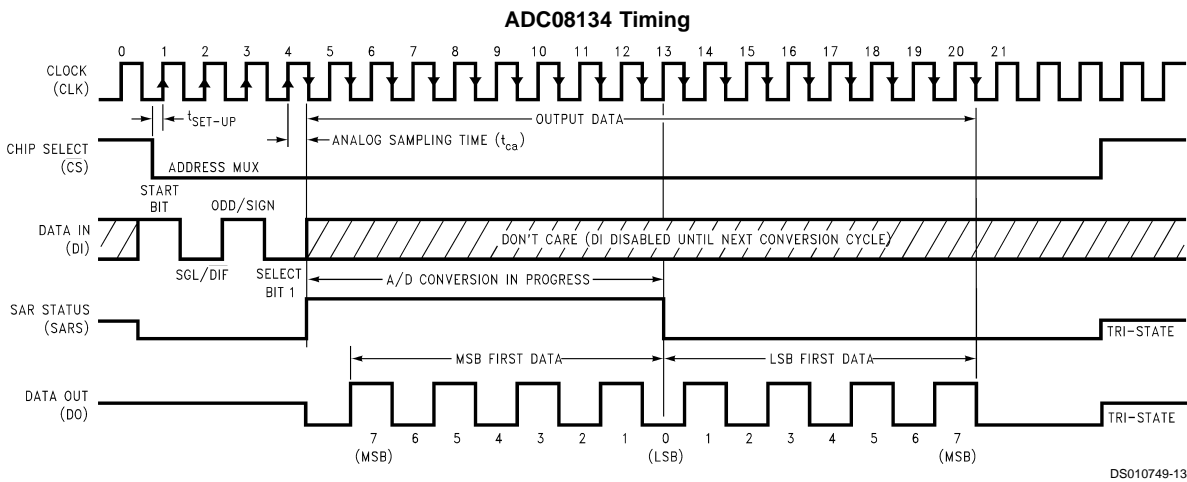
\*To reset these devices, CLK and  $\overline{CS}$  must be simultaneously high for a period of  $t_{SELECT}$  or greater. Otherwise these devices are compatible with industry standards ADC0831/4/8.



Timing Diagrams (Continued)

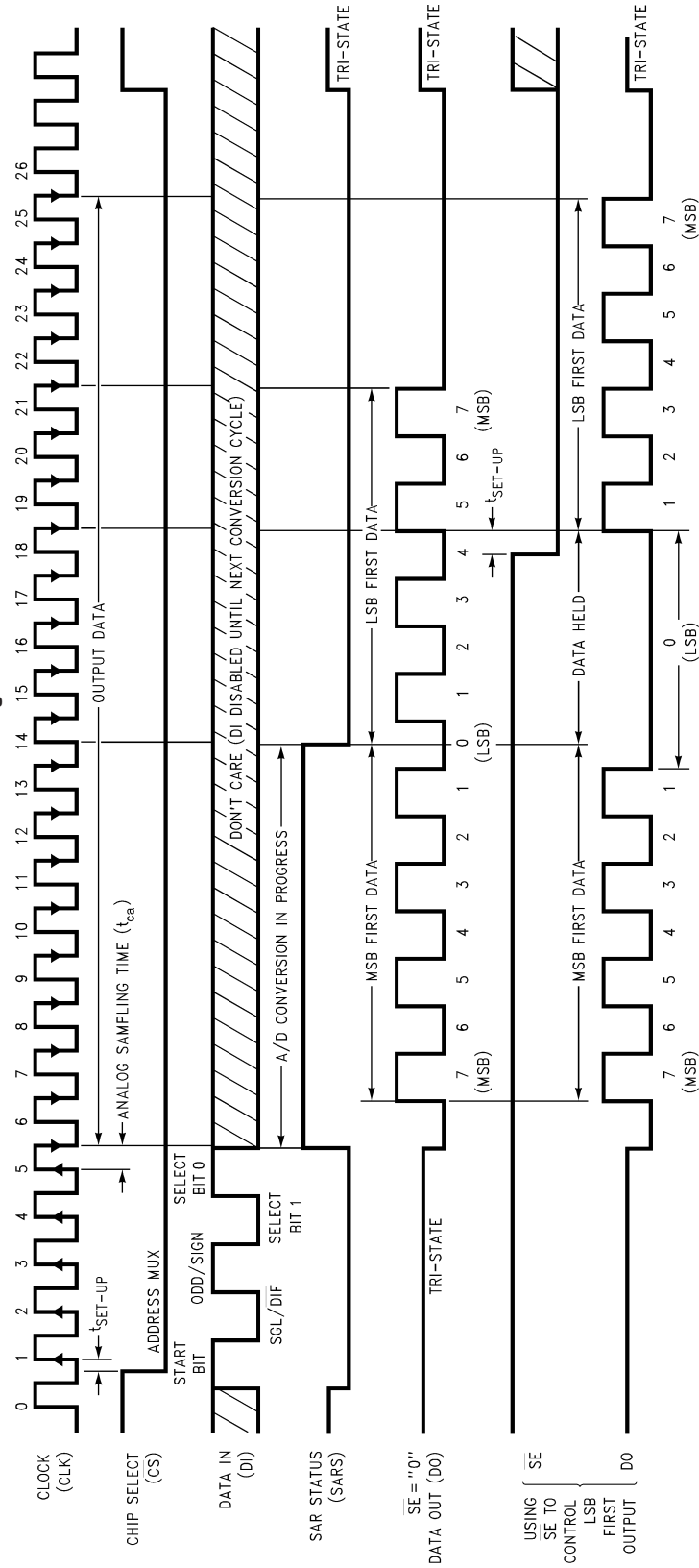


\*LSB first output not available on ADC08131.  
LSB information is maintained for remainder of clock periods until CS goes high.



Timing Diagrams (Continued)

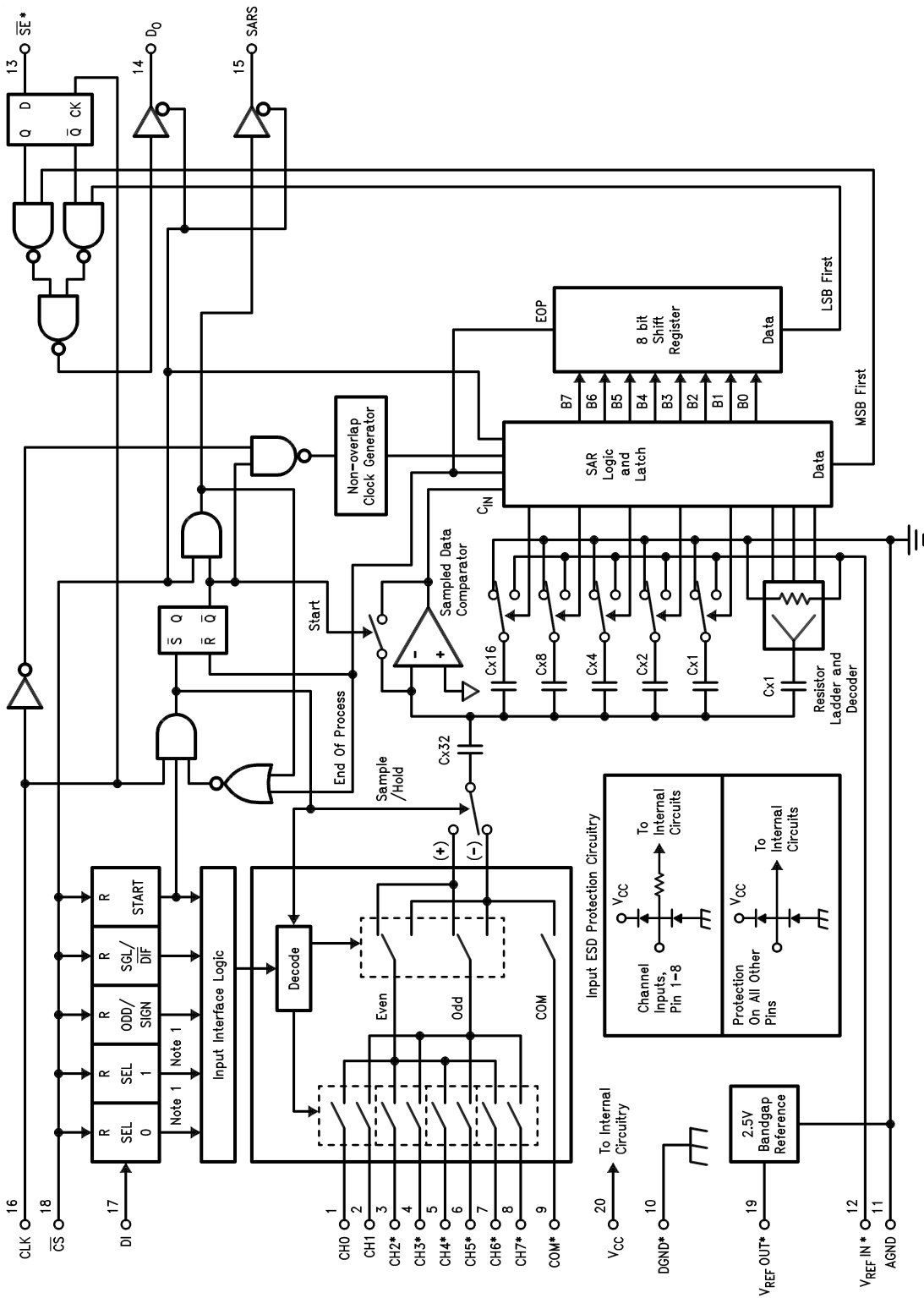
ADC08138 Timing



DS010749-14

\*Make sure clock edge #18 clocks in the LSB before  $\overline{SE}$  is taken low

# ADC08138 Functional Block Diagram



DS010749-15

\*Some of these functions/pins are not available with other options.  
**Note 18:** For the ADC08134, the "SEL 1" Flip-Flop is bypassed. For the ADC08131,  $V_{REFOUT}$  and  $V_{REFIN}$  are internally tied together.

ADC08131/ADC08134/ADC08138

## Functional Description

### MULTIPLEXER ADDRESSING

The design of these converters utilizes a comparator structure with built-in sample-and-hold which provides for a differential analog input to be converted by a successive approximation routine.

The actual voltage converted is always the difference between an assigned “+” input terminal and a “-” input terminal. The polarity of each input terminal of the pair indicates which line the converter expects to be the most positive. If the assigned “+” input voltage is less than the “-” input voltage the converter responds with an all zeros output code.

A unique input multiplexing scheme has been utilized to provide multiple analog channels with software-configurable single-ended, differential, or pseudo-differential (which will convert the difference between the voltage at any analog input and a common terminal) operation. The analog signal conditioning required in transducer-based data acquisition systems is significantly simplified with this type of input flexibility. One converter package can now handle ground referenced inputs and true differential inputs as well as signals with some arbitrary reference voltage.

A particular input configuration is assigned during the MUX addressing sequence, prior to the start of a conversion. The MUX address selects which of the analog inputs are to be enabled and whether this input is single-ended or differential. Differential inputs are restricted to adjacent channel pairs. For example, channel 0 and channel 1 may be selected as a differential pair but channel 0 or 1 cannot act differentially with any other channel. In addition to selecting differential

mode the polarity may also be selected. Channel 0 may be selected as the positive input and channel 1 as the negative input or vice versa. This programmability is best illustrated by the MUX addressing codes shown in the following tables for the various product options.

The MUX address is shifted into the converter via the DI line. Because the ADC08131 contains only one differential input channel with a fixed polarity assignment, it does not require addressing.

The common input line (COM) on the ADC08138 can be used as a pseudo-differential input. In this mode the voltage on this pin is treated as the “-” input for any of the other input channels. This voltage does not have to be analog ground; it can be any reference potential which is common to all of the inputs. This feature is most useful in single-supply applications where the analog circuitry may be biased up to a potential other than ground and the output signals are all referred to this potential.

**TABLE 1. Multiplexer/Package Options**

Part Number	Number of Analog Channels		Number of Package Pins
	Single-Ended	Differential	
ADC08131	1	1	8
ADC08134	4	2	14
ADC08138	8	4	20

**TABLE 2. MUX Addressing: ADC08138**

#### Single-Ended MUX Mode

MUX Address					Analog Single-Ended Channel #								
START	SGL/ DIF	ODD/ SIGN	SELECT		0	1	2	3	4	5	6	7	COM
			1	0									
1	1	0	0	0	+								-
1	1	0	0	1			+						-
1	1	0	1	0					+				-
1	1	0	1	1							+		-
1	1	1	0	0		+							-
1	1	1	0	1				+					-
1	1	1	1	0						+			-
1	1	1	1	1								+	-

**TABLE 3. MUX Addressing: ADC08138**

#### Differential MUX Mode

MUX Address					Analog Differential Channel-Pair #							
START	SGL/ DIF	ODD/ SIGN	SELECT		0		1		2		3	
			1	0	0	1	2	3	4	5	6	7
1	0	0	0	0	+	-						
1	0	0	0	1			+	-				
1	0	0	1	0					+	-		
1	0	0	1	1							+	-
1	0	1	0	0	-	+						
1	0	1	0	1			-	+				
1	0	1	1	0					-	+		

## Functional Description (Continued)

**TABLE 3. MUX Addressing: ADC08138 (Continued)**

Differential MUX Mode														
MUX Address				Analog Differential Channel-Pair #										
START	SGL/ DIF	ODD/ SIGN	SELECT		0		1		2		3			
			1	0	0	1	2	3	4	5	6	7		
1	0	1	1	1									-	+

**TABLE 4. MUX Addressing: ADC08134**

Single-Ended MUX Mode							
MUX Address				Channel #			
START	SGL/ DIF	ODD/ SIGN	SELECT	0	1	2	3
			1				
1	1	0	0	+			
1	1	0	1			+	
1	1	1	0		+		
1	1	1	1				+

COM is internally tied to AGND

Differential MUX Mode							
MUX Address				Channel #			
START	SGL/ DIF	ODD/ SIGN	SELECT	0	1	2	3
			1				
1	0	0	0	+	-		
1	0	0	1			+	-
1	0	1	0	-	+		
1	0	1	1			-	+

Since the input configuration is under software control, it can be modified as required before each conversion. A channel can be treated as a single-ended, ground referenced input for one conversion; then it can be reconfigured as part of a differential channel for another conversion. *Figure 1* illustrates the input flexibility which can be achieved.

The analog input voltages for each channel can range from 50 mV below ground to 50 mV above  $V_{CC}$  (typically 5V) without degrading conversion accuracy.

### THE DIGITAL INTERFACE

A most important characteristic of these converters is their serial data link with the controlling processor. Using a serial communication format offers two very significant system improvements; it allows many functions to be included in a small package and it can eliminate the transmission of low level analog signals by locating the converter right at the analog sensor; transmitting highly noise immune digital data back to the host processor.

To understand the operation of these converters it is best to refer to the Timing Diagrams and Functional Block Diagram and to follow a complete conversion sequence. For clarity a separate timing diagram is shown for each device.

1. A conversion is initiated by pulling the  $\overline{CS}$  (chip select) line low. This line must be held low for the entire conversion. The converter is now waiting for a start bit and its MUX assignment word.
2. On each rising edge of the clock the status of the data in (DI) line is clocked into the MUX address shift register. The start bit is the first logic "1" that appears on this line (all leading zeros are ignored). Following the start bit the

converter expects the next 2 to 4 bits to be the MUX assignment word.

3. When the start bit has been shifted into the start location of the MUX register, the input channel has been assigned and a conversion is about to begin. An interval of  $\frac{1}{2}$  clock period is automatically inserted to allow for sampling the analog input. The SARS line goes high at the end of this time to signal that a conversion is now in progress and the DI line is disabled (it no longer accepts data).
4. The data out (DO) line now comes out of TRI-STATE and provides a leading zero.
5. During the conversion the output of the SAR comparator indicates whether the analog input is greater than (high) or less than (low) a series of successive voltages generated internally from a ratioed capacitor array (first 5 bits) and a resistor ladder (last 3 bits). After each comparison the comparator's output is shipped to the DO line on the falling edge of CLK. This data is the result of the conversion being shifted out (with the MSB first) and can be read by the processor immediately.
6. After 8 clock periods the conversion is completed. The SARS line returns low to indicate this  $\frac{1}{2}$  clock cycle later.

## Functional Description (Continued)

7. The stored data in the successive approximation register is loaded into an internal shift register. If the programmer prefers the data can be provided in an LSB first format [this makes use of the shift enable ( $\overline{SE}$ ) control line]. On the ADC08138 the  $\overline{SE}$  line is brought out and if held high the value of the LSB remains valid on the DO line. When  $\overline{SE}$  is forced low the data is clocked out LSB first. On devices which do not include the  $\overline{SE}$  control line, the data, LSB first, is automatically shifted out the DO line after the MSB first data stream. The DO line then goes low and stays low until  $\overline{CS}$  is returned high. The

ADC08131 is an exception in that its data is only output in MSB first format.

8. All internal registers are cleared when the  $\overline{CS}$  line is high and the  $t_{SELECT}$  requirement is met. See Data Input Timing under Timing Diagrams. If another conversion is desired  $\overline{CS}$  must make a high to low transition followed by address information.

The DI and DO lines can be tied together and controlled through a bidirectional processor I/O bit with one wire. This is possible because the DI input is only "looked-at" during the MUX addressing interval while the DO line is still in a high impedance state.

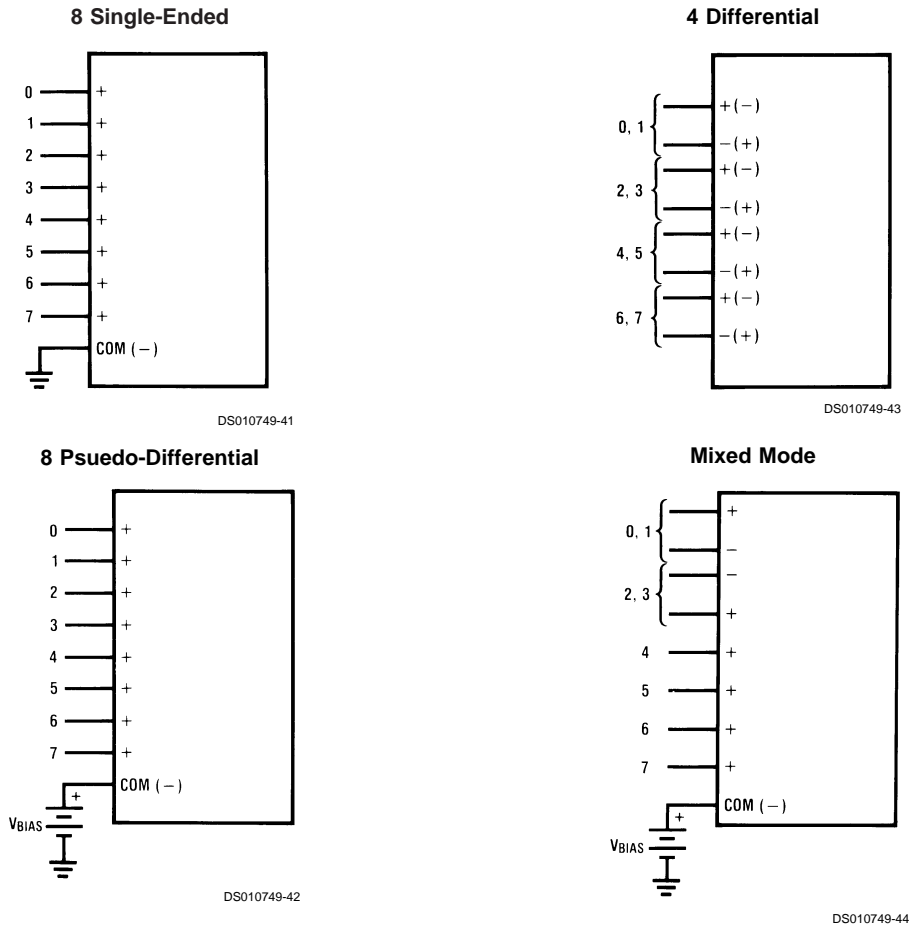


FIGURE 1. Analog Input Multiplexer Options for the ADC08138

### REFERENCE CONSIDERATIONS

The  $V_{REFIN}$  pin on these converters is the top of a resistor divider string and capacitor array used for the successive approximation conversion. The voltage applied to this reference input defines the voltage span of the analog input (the difference between  $V_{IN(MAX)}$  and  $V_{IN(MIN)}$  over which the 256 possible output codes apply). The reference source must be capable of driving the reference input resistance, which can be as low as 1.3 k $\Omega$ .

For absolute accuracy, where the analog input varies between specific voltage limits, the reference input must be biased with a stable voltage source. The ADC08134 and the ADC08138 provide the output of a 2.5V band-gap reference at  $V_{REFOUT}$ . This voltage does not vary appreciably with

temperature, supply voltage, or load current (see Reference Characteristics in the Electrical Characteristics tables) and can be tied directly to  $V_{REFIN}$  for an analog input span of 0V to 2.5V. This output can also be used to bias external circuits and can therefore be used as the reference in ratiometric applications. Bypassing  $V_{REFOUT}$  with a 100  $\mu F$  capacitor is recommended.

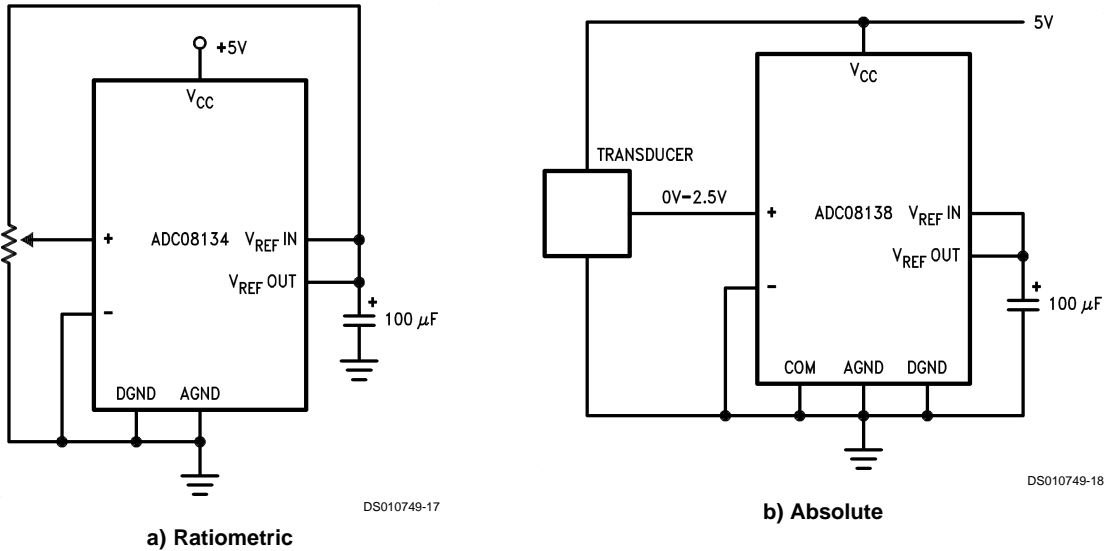
For the ADC08131, the output of the on-board reference is internally tied to the reference input. Consequently, the analog input span for this device is set at 0V to 2.5V. The pin  $V_{REFC}$  is provided for bypassing purposes and biasing external circuits as suggested above.

The maximum value of the reference is limited to the  $V_{CC}$  supply voltage. The minimum value, however, can be quite

**Functional Description** (Continued)

small (see Typical Performance Characteristics) to allow direct conversions of transducer outputs providing less than a 5V output span. Particular care must be taken with regard

to noise pickup, circuit layout and system error voltage sources when operating with a reduced span due to the increased sensitivity of the converter (1 LSB equals  $V_{REF}/256$ ).



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**FIGURE 2. Reference Examples**

**THE ANALOG INPUTS**

The most important feature of these converters is that they can be located right at the analog signal source and through just a few wires can communicate with a controlling processor with a highly noise immune serial bit stream. This in itself greatly minimizes circuitry to maintain analog signal accuracy which otherwise is most susceptible to noise pickup. However, a few words are in order with regard to the analog inputs should the input be noisy to begin with or possibly riding on a large common-mode voltage.

The differential input of these converters actually reduces the effects of common-mode input noise, a signal common to both selected “+” and “-” inputs for a conversion (60 Hz is most typical). The time interval between sampling the “+” input and then the “-” input is 1/2 of a clock period. The change in the common-mode voltage during this short time interval can cause conversion errors. For a sinusoidal common-mode signal this error is:

$$V_{error(max)} = V_{PEAK}(2\pi f_{CM}) \left( \frac{0.5}{f_{CLK}} \right)$$

where  $f_{CM}$  is the frequency of the common-mode signal,  
 $V_{PEAK}$  is its peak voltage value  
 and  $f_{CLK}$  is the A/D clock frequency.

For a 60Hz common-mode signal to generate a 1/4 LSB error ( $\approx 5$  mV) with the converter running at 250kHz, its peak value would have to be 6.63V which would be larger than allowed as it exceeds the maximum analog input limits.

Source resistance limitation is important with regard to the DC leakage currents of the input multiplexer. While operating near or at maximum speed bypass capacitors should not be used if the source resistance is greater than 1kΩ. The worst-case leakage current of  $\pm 1\mu A$  over temperature will create a 1mV input error with a 1kΩ source resistance. An op

amp RC active low pass filter can provide both impedance buffering and noise filtering should a high impedance signal source be required.

**OPTIONAL ADJUSTMENTS**

**Zero Error**

The zero of the A/D does not require adjustment. If the minimum analog input voltage value,  $V_{IN(MIN)}$ , is not ground a zero offset can be done. The converter can be made to output 0000 0000 digital code for this minimum input voltage by biasing any  $V_{IN} (-)$  input at this  $V_{IN(MIN)}$  value. This utilizes the differential mode operation of the A/D.

The zero error of the A/D converter relates to the location of the first riser of the transfer function and can be measured by grounding the  $V_{IN} (-)$  input and applying a small magnitude positive voltage to the  $V_{IN} (+)$  input. Zero error is the difference between the actual DC input voltage which is necessary to just cause an output digital code transition from 0000 0000 to 0000 0001 and the ideal 1/2 LSB value (1/2 LSB = 9.8mV for  $V_{REF} = 5.000V_{DC}$ ).

**Full Scale**

A full-scale adjustment can be made by applying a differential input voltage which is 1 1/2 LSB down from the desired analog full-scale voltage range and then adjusting the magnitude of the  $V_{REF IN}$  input for a digital output code which is just changing from 1111 1110 to 1111 1111 (See figure entitled “Span Adjust;  $0V \leq V_{IN} \leq 3V$ ”). This is possible only with the ADC08134 and ADC08138. (The reference is internally connected to  $V_{REF IN}$  of the ADC08131).

## Functional Description (Continued)

### Adjusting for an Arbitrary Analog Input Voltage Range

If the analog zero voltage of the A/D is shifted away from ground (for example, to accommodate an analog input signal which does not go to ground), this new zero reference should be properly adjusted first. A  $V_{IN (+)}$  voltage which equals this desired zero reference plus  $\frac{1}{2}$  LSB (where the LSB is calculated for the desired analog span, using  $1 \text{ LSB} = \text{analog span}/256$ ) is applied to selected "+" input and the zero reference voltage at the corresponding "-" input should then be adjusted to just obtain the  $00_{\text{HEX}}$  to  $01_{\text{HEX}}$  code transition.

The full-scale adjustment should be made [with the proper  $V_{IN (-)}$  voltage applied] by forcing a voltage to the  $V_{IN (+)}$  input which is given by:

$$V_{IN (+)} \text{ fs adj} = V_{MAX} - 1.5 \left[ \frac{V_{MAX} - V_{MIN}}{256} \right]$$

where:

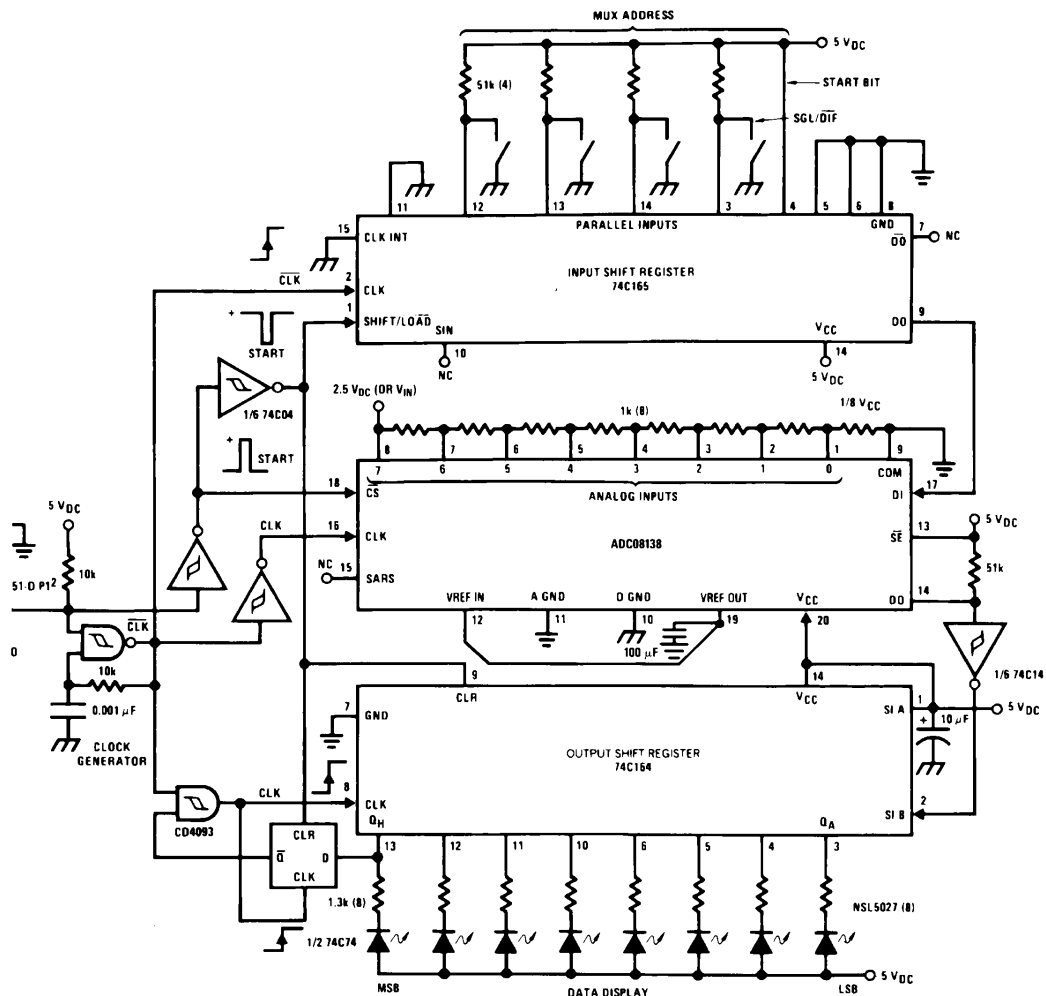
$V_{MAX}$  = the high end of the analog input range and

$V_{MIN}$  = the low end (the offset zero) of the analog range. (Both are ground referenced.)

The  $V_{REFIN}$  (or  $V_{CC}$ ) voltage is then adjusted to provide a code change from  $FE_{\text{HEX}}$  to  $FF_{\text{HEX}}$ . This completes the adjustment procedure.

## Applications

A "Stand-Alone" Hook-Up for ADC08138 Evaluation



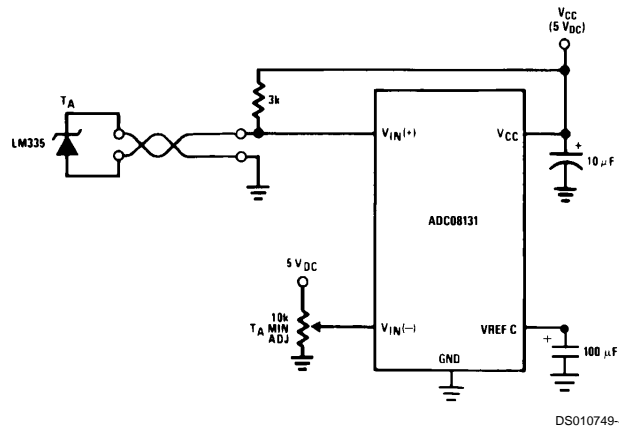
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\*Pinouts shown for ADC08138.  
For all other products tie to pin functions as shown.

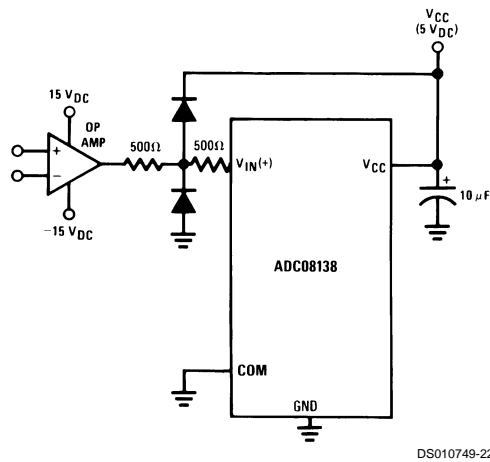


**Applications** (Continued)

**Low-Cost Remote Temperature Sensor**



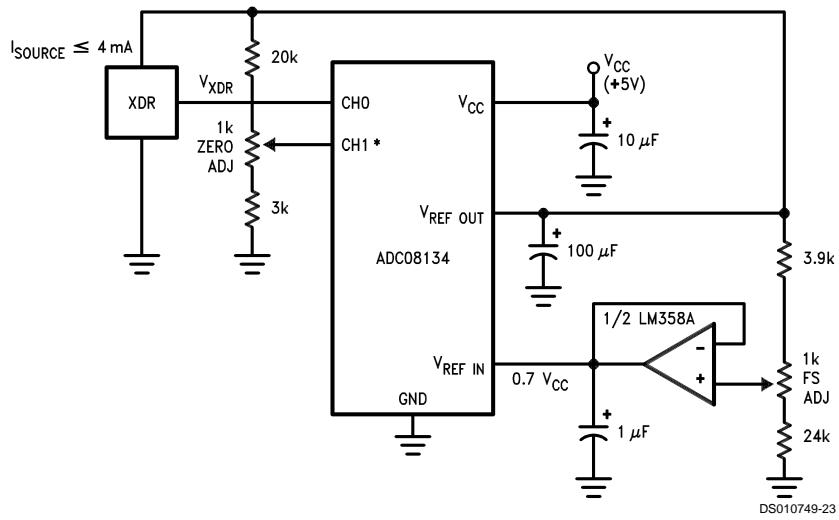
**Protecting the Input**



Diodes are 1N914

**Applications** (Continued)

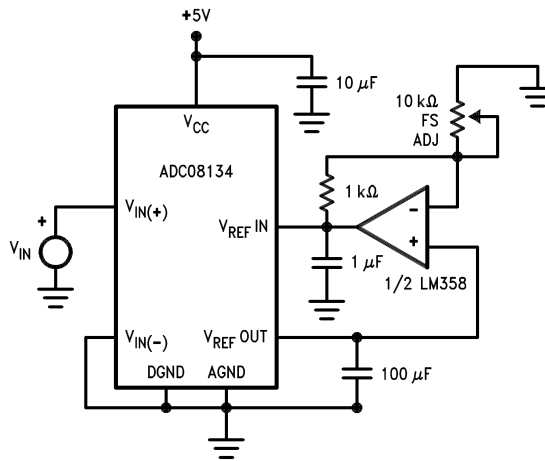
**Operating with Ratiometric Transducers**



DS010749-23

\* $V_{IN(-)} = 0.15 V_{REF}$   
 $15\% \text{ of } V_{REF} \leq V_{XDR} \leq 85\% \text{ of } V_{REF}$

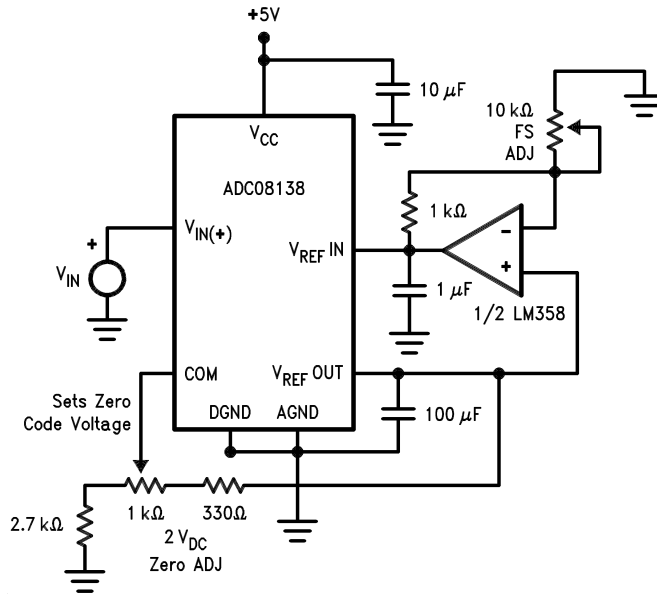
**Span Adjust;  $0V \leq V_{IN} \leq 3V$**



DS010749-24

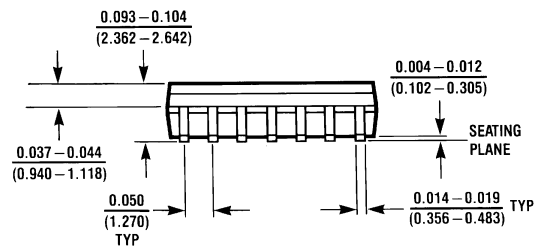
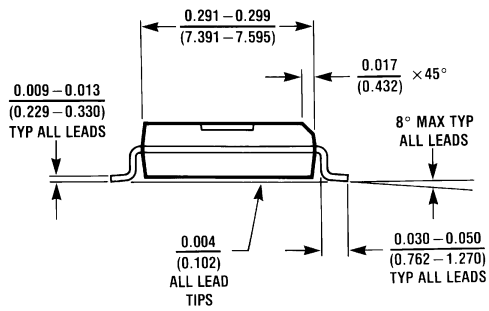
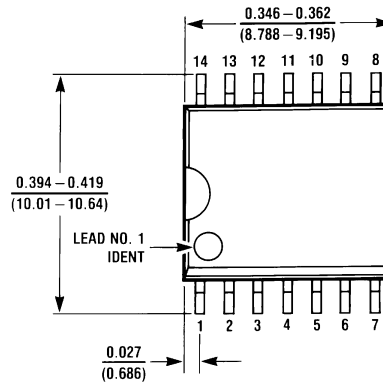
**Applications** (Continued)

Zero-Shift and Span Adjust:  $2V \leq V_{IN} \leq 5V$



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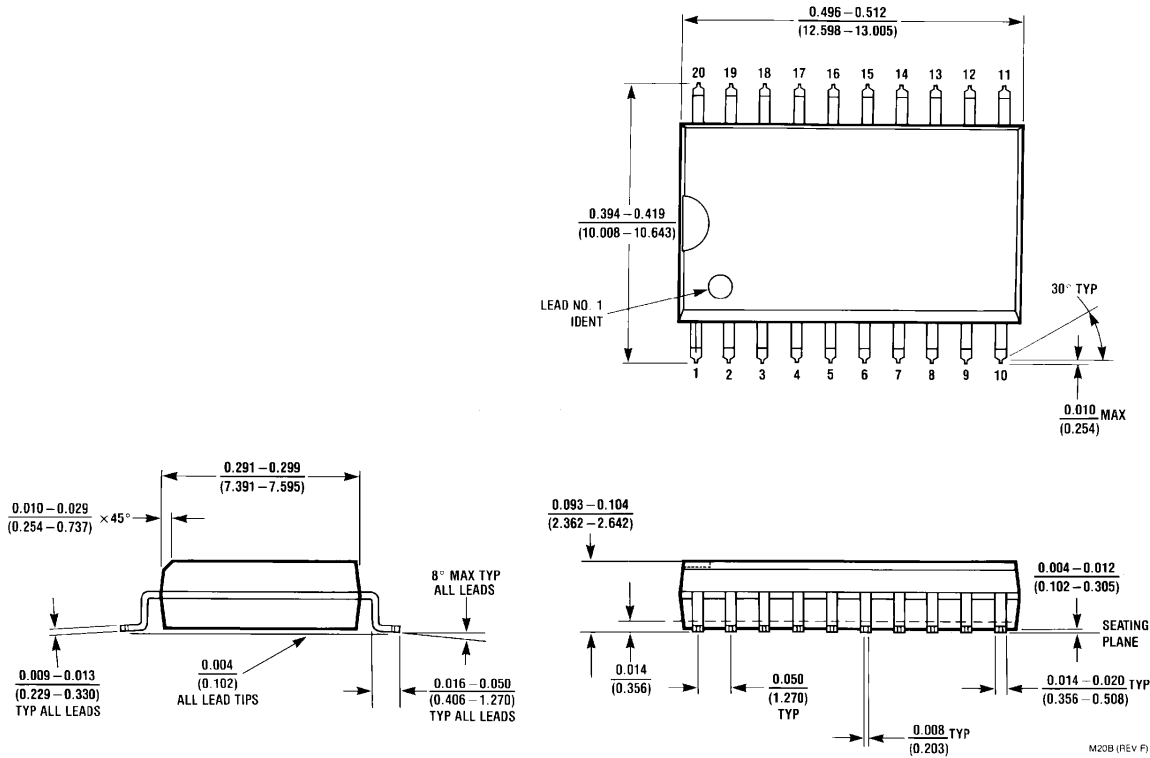
**Physical Dimensions** inches (millimeters) unless otherwise noted



M14B (REV D)

**Order Number ADC08134CIWM**  
**NS Package Number M14B**

**Physical Dimensions** inches (millimeters) unless otherwise noted (Continued)



**Order Number ADC08138CIWM**  
**NS Package Number M20B**

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**National Semiconductor Corporation**  
 Americas  
 Email: support@nsc.com

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 Deutsch Tel: +49 (0) 69 9508 6208  
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