## ML9261/62

60-Bit Vacuum Fluorescent Display Tube Grid/Anode Driver

## GENERAL DESCRIPTION

The ML9261/62 is a monolithic IC designed for directly driving the grid and anode of the vacuum fluorescent display (VFD) tube. The device contains a 60-bit shift register, a 60-bit register circuit, and 60 VFD tube driving circuits on a single chip.

Display data is serially stored in the shift register at the rising edge of a clock pulse.
Setting the $\overline{\mathrm{CL}}$ pin low allows all the VFD tube driving circuits to be driven low, which makes it possible to set the display blanking.

Also, setting both of the $\overline{\mathrm{CL}}$ and CHG pins high allows all the VFD tube driving circuits to be driven high, which provides the easy testing of all lights after final assembly of a VFD tube panel.

## FEATURES

- Logic Supply Voltage $\left(\mathrm{V}_{\mathrm{CC}}\right):+3.3 \mathrm{~V} \pm 10 \%$ or $+5.0 \mathrm{~V} \pm 10 \%$
- Driver Supply Voltage ( $\mathrm{V}_{\mathrm{HV}}$ ): +60V
- Driver Output Current
$\mathrm{I}_{\mathrm{OHVH1}}$ (Only one driver output : "H") : $-40 \mathrm{~mA}\left(\mathrm{~V}_{\mathrm{DISP}}=40 \mathrm{~V}\right)$
$\mathrm{I}_{\mathrm{OHVH2} 2}$ (All the driver outputs : "H") : $-120 \mathrm{~mA}\left(\mathrm{~V}_{\text {DISP }}=40 \mathrm{~V}\right)$
$\mathrm{I}_{\mathrm{OHVL}}: 1 \mathrm{~mA}$
- Directly connected to VFD tube by using push-pull output (Pull-down resistors are not needed)
- Data Transfer Speed: 4MHz
- Package :

70-pin plastic SSOP (SSOP70-P-500-0.80-K) (Product names : ML9261MB and ML9262MB)

## BLOCK DIAGRAM



## INPUT AND OUTPUT CONFIGURATION

## PIN CONFIGURATION (TOP VIEW)

## ML9261



70-Pin Plastic SSOP
(SSOP70-P-500-0.80-K)

## PIN CONFIGURATION (TOP VIEW)

ML9262


70-Pin Plastic SSOP
(SSOP70-P-500-0.80-K)

## PIN DESCRIPTION

| Symbol | Type | Description |
| :---: | :---: | :---: |
| CLK | 1 | Shift register clock input pin. <br> Shift register reads data from DIN while the CLK pin is low and the data in the shift register is shifted from one stage to the next stage at the rising edge of the clock. |
| DIN | 1 | Serial data input pin of the shift register. Display data (positive logic) is input in the DIN pin in synchronization with clock. |
| DOUT | 0 | Serial data output pin of the shift register. <br> Data is output from the DOUT pin in synchronization with the CLK signal. |
| LS | 1 | Latch strobe input pin. <br> The contents of the parallel outputs (P01 to P060) of the shift register are read at the rising edge of LS (edge-triggered). When the CLK rises while LS is high, the parallel outputs (P01 to P060) and latch outputs ( 01 to 060) go low. |
| $\overline{\text { CL }}$ | 1 | Clear input pin with a built-in pull-down resistor. <br> The $\overline{C L}$ pin is normally set high. <br> If the CL pin is high and the CHG pin is low, the driver outputs (HV01 to HV60) are in phase with the corresponding register outputs ( 01 to 060). <br> If the $\overline{\text { CL }}$ pin is high and the CHG pin is high, the driver outputs (HV01 to HV60) are high irrespective of the states of the register outputs. <br> If the $\overline{\mathrm{CL}}$ pin is set low, the driver outputs are driven low irrespective of the states of the CHG pin and register outputs. <br> This allows display blanking to be set. |
| CHG | 1 | Input for testing (with a pull-down resistor). <br> The $\overline{\mathrm{CL}}$ pin is normally set low. <br> If the CHG pin is low and the $\overline{C L}$ pin is high, the driver outputs (HV01 to HV60) are in phase with the corresponding register outputs ( 01 to 060 ). <br> If the CHG pin is low and the $\overline{\text { CL }}$ pin is low, the driver outputs (HV01 to HV60) are low irrespective of the states of the register outputs. <br> If the CHG pin is set high, the driver outputs are driven high irrespective of the states of the register outputs. <br> This provides the easy testing of all lights after final assembly. |
| VH01-60 | 0 | High voltage driver outputs for driving VFD tube. <br> If the $\overline{\mathrm{CL}}$ pin is high and the CHG pin is low, the driver outputs are in phase with the corresponding register outputs ( 01 to 060 ). <br> The direct connection to the grid or anode of a VFD tube eliminates pull-down resistors. |
| $V_{\text {DISP }}$ |  | Power supply pin for driver circuits of VFD tube |
| $V_{D D}$ |  | Power supply pin for logic |
| D-GND |  | GND pin for driver circuits of a VFD tube. <br> Since the D-GND is not be connected to L-GND, connect this pin to the external L-GND. |
| L-GND |  | GND pin for the logic circuits. <br> Since the L-GND pin is not be connected to D-GND, connect this pin to the external D-GND |

## ABSOLUTE MAXIMUM RATINGS

| Parameter | Symbol | Condition | Rating | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Supply Voltage (1) *1 | $V_{\text {D }}$ | Applicable to logic supply pin | -0.3 to +6.5 | V |
| Supply Voltage (2) *1, *2 | $V_{\text {DISP }}$ | Applicable to driver supply pin | -0.3 to +65 | V |
| Input Voltage *1 | VIN | Applicable to all input pins | -0.3 to $\mathrm{V}_{\mathrm{DD}}+0.3$ | V |
| Output Voltage *1 | $\mathrm{V}_{0}$ | Applicable to DOUT | -0.3 to $\mathrm{V}_{\text {DD }}+0.3$ | V |
| Output Current | 10 | Applicable to HV01 to 60 | -50 to 0.0 | mA |
| Withstand Output Voltage *1, *2 | Vhvo | Applicable to HVO1 to 60 | -0.3 to $\mathrm{V}_{\text {DISP }}+0.3$ | V |
| Power Dissipation | $\mathrm{P}_{\mathrm{D}}$ | $\mathrm{Ta} \leq 25^{\circ} \mathrm{C}$ | 860 | mW |
| Package Thermal Resistance *3 | $\mathrm{R}_{\mathrm{j}-\mathrm{a}}$ | $\mathrm{Ta}>25^{\circ} \mathrm{C}$ | 145 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Storage Temperature | TSTG | - | -55 to +150 | ${ }^{\circ} \mathrm{C}$ |

Notes: *1 Supply Voltage with respect to L-GND and D-GND
*2 Permanent damage may be caused if the voltage is supplied over the rating value.
*3 Package Thermal Resistance (between junction and ambient)
The junction temperature (Tj) expressed by the equation indicated below should not exceed $150^{\circ} \mathrm{C}$.
$\mathrm{T}_{\mathrm{j}}=\mathrm{P} \times \mathrm{R}_{\mathrm{j}-\mathrm{a}}+\mathrm{Ta}$ ( $\mathrm{P}:$ Maximum power consumption)

## RECOMMENDED OPERATING CONDITIONS-1

Unit Power Supply: 5.0V (Typ.)

| Parameter | Symbol | Condition | Min | Typ. | Max | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Power Supply (1) | $\mathrm{V}_{\mathrm{DD}}$ | - | 4.5 | 5.0 | 5.5 | V |
| Power Supply (2) | $\mathrm{V}_{\mathrm{DISP}}$ | - | 20 | - | 60 | V |
| "H" Input Voltage | $\mathrm{V}_{\mathrm{IH}}$ | Applicable to all inputs | $0.7 \mathrm{~V}_{\mathrm{DD}}$ | - | - | V |
| "L" Input Voltage | $\mathrm{V}_{\mathrm{IL}}$ | Applicable to all inputs | - | - | $0.3 \mathrm{~V}_{\mathrm{DD}}$ | V |
| Driver Output Current | $\mathrm{I}_{\text {OHVH1 }}$ | Only 1 output is ON. | - | - | -40 | mA |
|  | $\mathrm{I}_{\text {OHVH2 }}$ | All outputs are ON. | - | - | -120 | mA |
| CLK Frequency | $\mathrm{f}_{\mathrm{CLK}}$ | - | - | - | 4.0 | MHz |
| Operating Temperature | $\mathrm{T}_{\mathrm{OP}}$ | - | -40 | - | +85 | ${ }^{\circ} \mathrm{C}$ |

## RECOMMENDED OPERATING CONDITIONS-2

Unit Power Supply: 3.3V (Typ.)

| Parameter | Symbol | Condition | Min | Typ. | Max | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Power Supply (1) | $\mathrm{V}_{\mathrm{DD}}$ | - | 3.0 | 3.3 | 3.6 | V |
| Power Supply (2) | $\mathrm{V}_{\mathrm{DISP}}$ | - | 20 | - | 60 | V |
| "H" Input Voltage | $\mathrm{V}_{\mathrm{IH}}$ | Applicable to all inputs | $0.8 \mathrm{~V}_{\mathrm{DD}}$ | - | - | V |
| "L" Input Voltage | $\mathrm{V}_{\mathrm{IL}}$ | Applicable to all inputs | - | - | $0.2 \mathrm{~V}_{\mathrm{DD}}$ | V |
| Driver Output Current | $\mathrm{I}_{\text {OHVH1 }}$ | Only 1 output is ON. | - | - | -40 | mA |
|  | $\mathrm{I}_{\text {OHVH2 }}$ | All outputs are ON. | - | - | -120 | mA |
| CLK Frequency | $\mathrm{f}_{\mathrm{CLK}}$ | - | - | - | 4.0 | MHz |
| Operating Temperature | $\mathrm{T}_{\text {OP }}$ | - | -40 | - | +85 | ${ }^{\circ} \mathrm{C}$ |

## ELECTRICAL CHARACTERISTICS

## DC Characteristics-1

$\left(V_{D D}=4.5\right.$ to $5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{DISP}}=40 \mathrm{~V}, \mathrm{Ta}=-40$ to $\left.+85^{\circ} \mathrm{C}\right)$

| Parameter | Symbol Applicable pin |  | Condition |  | Min | Typ. | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| "H" Input Voltege | $\mathrm{V}_{\mathrm{IH}}$ | All inputs | - |  | $0.7 \mathrm{~V}_{\mathrm{DD}}$ | - | - | V |
| "L" Input Voltage | $\mathrm{V}_{\text {IL }}$ | All inputs | - |  | - | - | $0.3 \mathrm{~V}_{\text {DD }}$ | V |
| "H" Input Current | $\mathrm{l}_{1+1}$ | DIN, CLK, LS | $\mathrm{V}_{\mathrm{DD}}=\mathrm{V}_{1 \mathrm{IN}}=5.5 \mathrm{~V}$ |  | -1.0 | - | +1.0 | $\mu \mathrm{A}$ |
|  | $\mathrm{I}_{\mathrm{H} 2}$ | $\overline{\mathrm{CL}}, \mathrm{CHG}$ | $\mathrm{V}_{\mathrm{DD}}=\mathrm{V}_{1 \mathrm{I}}=5.5 \mathrm{~V}$ |  | 5.0 | - | 80 | $\mu \mathrm{A}$ |
| "L" Input Current | IIL | All inputs | $\mathrm{V}_{\mathrm{DD}}=5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{IN}}=0 \mathrm{~V}$ |  | -1.0 | - | +1.0 | $\mu \mathrm{A}$ |
| Input Capacitance | $\mathrm{C}_{\text {IN }}$ | All inputs | $\mathrm{Ta}=25^{\circ} \mathrm{C}$ |  | - | 15 | - | pF |
| "H" Output Voltage | $\mathrm{V}_{\mathrm{OH} 1}$ | DOUT | $\mathrm{I}_{\mathrm{OH}}=-0.1 \mathrm{~mA}$ |  | $V_{\text {DD }}-1$ | - | - | V |
|  | $\mathrm{V}_{\text {OH2 }}$ | HV01 to 60 | $\mathrm{IOH}_{\mathrm{OH}}=-40 \mathrm{~mA}$ |  | $V_{\text {DISP }}-4$ | - | - | V |
| "L" Output Voltage | $\mathrm{V}_{\text {OL1 }}$ | DOUT | $10 \mathrm{~L}=0.1 \mathrm{~mA}$ |  | - | - | 1.1 | V |
|  | $\mathrm{V}_{\text {OL2 }}$ | HV01 to 60 | $10 \mathrm{~L}=1 \mathrm{~mA}$ |  | - | - | 3.0 | V |
| Supply Current (Design Goal) | $\mathrm{I}_{\text {D1 } 1}$ | $V_{D D}$ | No load | All inputs: "L" | - | - | 10.0 | $\mu \mathrm{A}$ |
|  | IDD2 | $V_{D D}$ |  | All inputs: "H" | - | - | 10.0 | $\mu \mathrm{A}$ |
|  | ldisp1 | $V_{\text {DISP }}$ |  | All inputs: "L" | - | - | 10.0 | $\mu \mathrm{A}$ |
|  | IDISP2 | $V_{\text {DISP }}$ |  | All inputs: "H" | - | - | 10.0 | $\mu \mathrm{A}$ |

## DC Characteristics-2

( $\mathrm{V}_{\mathrm{DD}}=3.0$ to $3.6 \mathrm{~V}, \mathrm{~V}_{\mathrm{DISP}}=40 \mathrm{~V}, \mathrm{Ta}=-40$ to $+85^{\circ} \mathrm{C}$ )

| Parameter | Symbol Applicable pin |  | Condition |  | Min | Typ. | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| "H" Input Voltege | $\mathrm{V}_{\mathrm{IH}}$ | All inputs | - |  | $0.8 \mathrm{~V}_{\mathrm{DD}}$ | - | - | V |
| "L" Input Voltage | $\mathrm{V}_{\text {IL }}$ | All inputs | - |  | - | - | $0.2 \mathrm{~V}_{\text {DD }}$ | V |
| "H" Input Current | $\mathrm{I}_{\mathrm{H} 1}$ | DIN, CLK, LS | $\mathrm{V}_{\mathrm{DD}}=\mathrm{V}_{\text {IN }}=3.3 \mathrm{~V}$ |  | -1.0 | - | +1.0 | $\mu \mathrm{A}$ |
|  | $\mathrm{l}_{\mathrm{H} 2}$ | $\overline{\mathrm{CL}}$, CHG | $\mathrm{V}_{\mathrm{DD}}=\mathrm{V}_{\text {IN }}=3.3 \mathrm{~V}$ |  | 2.0 | - | 50 | $\mu \mathrm{A}$ |
| "L" Input Current | IIL | All inputs | $\mathrm{V}_{\mathrm{DD}}=3.3 \mathrm{~V}, \mathrm{~V}_{\mathrm{IN}}=0 \mathrm{~V}$ |  | -1.0 | - | +1.0 | $\mu \mathrm{A}$ |
| Input Capacitance | $\mathrm{Cl}_{\text {IN }}$ | All inputs | $\mathrm{Ta}=25^{\circ} \mathrm{C}$ |  | - | 15 | - | pF |
| "H" Output Voltage | $\mathrm{V}_{\text {OH1 }}$ | DOUT | $\mathrm{IOH}_{\mathrm{H}}=-0.1 \mathrm{~mA}$ |  | $\mathrm{V}_{\text {DD }}$-1 | - | - | V |
|  | $\mathrm{V}_{\text {OH2 }}$ | HV01 to 60 | $\mathrm{l}_{\mathrm{OH}}=-40 \mathrm{~mA}$ |  | $V_{\text {DISP }}-4$ | - | - | V |
| "L" Output Voltage | $\mathrm{V}_{\text {OL1 }}$ | DOUT | $\mathrm{l}_{0 \mathrm{~L}}=0.1 \mathrm{~mA}$ |  | - | - | 1.1 | V |
|  | $\mathrm{V}_{\text {OL2 }}$ | HV01 to 60 | $10 \mathrm{~L}=1 \mathrm{~mA}$ |  | - | - | 3.0 | V |
| Supply Current (Design Goal) | $\mathrm{I}_{\text {D1 } 1}$ | $V_{D D}$ | No load | All inputs: "L" | - | - | 10.0 | $\mu \mathrm{A}$ |
|  | IDD2 | $V_{D D}$ |  | All inputs: "H" | - | - | 10.0 | $\mu \mathrm{A}$ |
|  | IDISP1 | $V_{\text {DISP }}$ |  | All inputs: "L" | - | - | 10.0 | $\mu \mathrm{A}$ |
|  | IDISP2 | $V_{\text {DISP }}$ |  | All inputs: "H" | - | - | 10.0 | $\mu \mathrm{A}$ |

## AC Characteristics-1

( $\mathrm{V}_{\mathrm{DD}}=4.5$ to $5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{DISP}}=40 \mathrm{~V}, \mathrm{Ta}=-40$ to $+85^{\circ} \mathrm{C}$ )

| Parameter | Symbol | Condition | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CLK Pulse Width | tw (CLK) |  | 80 | 150 | ns |
| DIN Setup Time | $\mathrm{tsu}_{\text {( }}(\mathrm{D}-\mathrm{CLK}$ ) |  | 50 | - | ns |
| DIN Hold Time | th (CLK-D) |  | 50 | - | ns |
| CLK-LS Setup Time | $\mathrm{t}_{\text {SU }}$ (CLK-LS) |  | 50 | - | ns |
| LS-CLK Setup Time | tsu (LS-CLK) | During normal operation | 50 | - | ns |
|  | tsu (L-CLK) | At display data reset | 50 | - | ns |
| CLK-LS Hold Time | $\mathrm{t}_{\mathrm{H}}$ (CLK-L) | At display data reset | 50 | - | ns |
| LS-CHG Setup Time | $\mathrm{t}_{\text {Su }}$ (LS-CHG) |  | 50 | - | ns |
| LS-CL Setup Time | $\mathrm{t}_{\text {SU }}(\mathrm{LS}-\overline{\mathrm{CL}})$ |  | 50 | - | ns |
| LS Pulse Width | $\mathrm{t}_{\mathrm{w}}$ (LS) |  | 80 | - | ns |
| CHG Pulse Width | $\mathrm{tw}_{\text {( }}$ (CHG) |  | 10 | - | $\mu \mathrm{s}$ |
| $\overline{\text { CL Pulse Width }}$ | tw ( $\overline{\mathrm{CL}}$ ) |  | 10 | - | $\mu \mathrm{S}$ |
| DOUT Delay time | tPD, tPRD | Load: 30pF | - | 50 | ns |
| Driver Output Delay Time | $\mathrm{t}_{\text {DLH }}$ | Load: $2.0 \mathrm{k} \Omega$ resistance in parallel with 20pF capacitance | - | 1.0 | $\mu \mathrm{S}$ |
|  | tDHL |  | - | 1.0 | $\mu \mathrm{S}$ |
|  | $\mathrm{t}_{\text {DRHL }}$ |  | - | 1.0 | $\mu \mathrm{s}$ |
| Driver Output Slew Rate | $\mathrm{t}_{\text {ti }}$ | Load: 2.0k $\Omega$ resistance in parallel with 20pF capacitance | - | 5.0 | $\mu \mathrm{s}$ |
|  | $\mathrm{t}_{\text {THL }}$ |  | - | 5.0 | $\mu \mathrm{s}$ |

## AC Characteristics-2

$\left(\mathrm{V}_{\mathrm{DD}}=3.0\right.$ to $3.6 \mathrm{~V}, \mathrm{~V}_{\mathrm{DISP}}=40 \mathrm{~V}, \mathrm{Ta}=-40$ to $+85^{\circ} \mathrm{C}$ )

| Parameter | Symbol | Condition | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CLK Pulse Width | tw (CLK) |  | 80 | 150 | ns |
| DIN Setup Time | $\mathrm{t}_{\text {SU }}$ (D-CLK) |  | 50 | - | ns |
| DIN Hold Time | $\mathrm{t}_{\mathrm{H}}$ (CLK-D) |  | 50 | - | ns |
| CLK-LS Setup Time | $\mathrm{t}_{\text {SU }}$ (CLK-LS) |  | 50 | - | ns |
| LS-CLK Setup Time | tsu (LS-CLK) | During normal operation | 50 | - | ns |
|  | tsu (L-CLK) | At display data reset | 50 | - | ns |
| CLK-LS | $\mathrm{t}_{\mathrm{H}}$ (CLK-L) | At display data reset | 50 | - | ns |
| LS-CHG Setup Time | tsu (LS-CHG) |  | 50 | - | ns |
| LS-CL Setup Time | $\mathrm{t}_{\text {Su }}(\mathrm{LS}-\overline{\mathrm{CL}})$ |  | 50 | - | ns |
| LS Pulse Width | $\mathrm{tw}_{\mathrm{w}}$ (LS) |  | 80 | - | ns |
| CHG Pulse Width | tw (CHG) |  | 10 | - | $\mu \mathrm{S}$ |
| $\overline{\text { CL Pulse Width }}$ | $\mathrm{tw}_{\mathrm{w}}(\overline{\mathrm{CL}})$ |  | 10 | - | $\mu \mathrm{S}$ |
| DOUT Delay time | $\mathrm{t}_{\text {PD }}$, tPRD | Load: 30pF | - | 50 | ns |
| Driver Output Delay Time | $\mathrm{t}_{\text {DLH }}$ | Load: 2.0k $\Omega$ resistance in parallel with 20pF capacitance | - | 3.0 | $\mu \mathrm{S}$ |
|  | $\mathrm{t}_{\text {DHL }}$ |  | - | 3.0 | $\mu \mathrm{s}$ |
|  | $\mathrm{t}_{\text {DRHL }}$ |  | - | 3.0 | $\mu \mathrm{s}$ |
| Driver Output Slew Rate | $\mathrm{t}_{\text {TLH }}$ | Load: $2.0 \mathrm{k} \Omega$ resistance in parallel with 20pF capacitance | - | 5.0 | $\mu \mathrm{s}$ |
|  | $\mathrm{t}_{\text {THL }}$ |  | - | 5.0 | $\mu \mathrm{S}$ |




## FUNCTIONAL DESCRIPTION

## Display Data Reset

When the power is turned on, the shift register outputs (PO1 to PO60) and register outputs (O1 to O60) are indeterminate. Consequently the display of a VFD tube may flickers because unnecessary driver outputs go high. To prevent such flicker, it is required to perform the following operations.

1. Turn on the logic power supply while the $\overline{\mathrm{CL}}$ input is kept low.
2. Set the LS input high.
3. Switch the CLK input from a low level to a high level at least once.

By performing the above operations, the shift register outputs (PO1 to PO60) and register outputs (O1 to O60) all are set low.
4. Enter display data.
5. Set the $\overline{\mathrm{CL}}$ input high.

## Data Transfer

Write display data by using a serial transfer.
Serial data is input in the shift register at the rising edge of a CLK input pulse.
When the LS input rises, display data is written in the latch.

## Driver Output Control

1. To turn on or off driver outputs by using display data transfered into the shift register, set the $\overline{\mathrm{CL}}$ input high and set the CHG input low.
2. To set all the driver outputs low, set the $\overline{\mathrm{CL}}$ input low.
3. To set all the driver outputs high, set the $\overline{\mathrm{CL}}$ input and CHG input high at a time.

## Function Table

Shift register

| Input |  |  |  | Shift Register Parallel Out |  |  |  |  |  | Output |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CLK | DIN | LS | P01 | P02 |  | P059 | P060 | DOUT |  |  |
| $\boldsymbol{\sim}$ | H | L | H | P01n |  | P058n | P059n | P059n |  |  |
| $\boldsymbol{\sim}$ | L | L | L | P02n |  | P058n | P059n | P059n |  |  |
| L | X | L | P01n | P02n |  | P059n | P060n | P060n |  |  |
| $\boldsymbol{\sim}$ | X | H | L | L |  | L | L | L |  |  |

X: Don't Care
P01n to P059n: P01 to P059 data just before CLOCK rises.

Register

| Input |  | Shift Register Parallel Out | Latch Output |
| :---: | :---: | :---: | :---: |
| CLK | LS | POm | Om |
| X | $\boldsymbol{\Gamma}$ | H | H |
| X | $\boldsymbol{\Gamma}$ | L | L |
| X | $\boldsymbol{L}$ | X | No Change |
| $\boldsymbol{\Gamma}$ | H | L | L |

X: Don't Care, m: 1 to 60

Driver output

| Input |  |  |  | Latch Output | Output |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\overline{C L}$ | CHG | CLK | LS | Om | HVOm |
| H | L | X | X | H | H |
| H | L | X | X | L | L |
| H | H | X | X | X | H |
| L | X | X | X | X | L |
| X | X | ■ | H | L | L |

X: Don't Care, m: 1 to 60

## Test circuit



## PACKAGE DIMENSIONS

(Unit : mm)


Notes for Mounting the Surface Mount Type Package
The SOP, QFP, TSOP, SOJ, QFJ (PLCC), SHP and BGA are surface mount type packages, which are very susceptible to heat in reflow mounting and humidity absorbed in storage.
Therefore, before you perform reflow mounting, contact Oki's responsible sales person for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

## NOTICE

1. The information contained herein can change without notice owing to product and/or technical improvements. Before using the product, please make sure that the information being referred to is up-to-date.
2. The outline of action and examples for application circuits described herein have been chosen as an explanation for the standard action and performance of the product. When planning to use the product, please ensure that the external conditions are reflected in the actual circuit, assembly, and program designs.
3. When designing your product, please use our product below the specified maximum ratings and within the specified operating ranges including, but not limited to, operating voltage, power dissipation, and operating temperature.
4. Oki assumes no responsibility or liability whatsoever for any failure or unusual or unexpected operation resulting from misuse, neglect, improper installation, repair, alteration or accident, improper handling, or unusual physical or electrical stress including, but not limited to, exposure to parameters beyond the specified maximum ratings or operation outside the specified operating range.
5. Neither indemnity against nor license of a third party's industrial and intellectual property right, etc. is granted by us in connection with the use of the product and/or the information and drawings contained herein. No responsibility is assumed by us for any infringement of a third party's right which may result from the use thereof.
6. The products listed in this document are intended for use in general electronics equipment for commercial applications (e.g., office automation, communication equipment, measurement equipment, consumer electronics, etc.). These products are not authorized for use in any system or application that requires special or enhanced quality and reliability characteristics nor in any system or application where the failure of such system or application may result in the loss or damage of property, or death or injury to humans. Such applications include, but are not limited to, traffic and automotive equipment, safety devices, aerospace equipment, nuclear power control, medical equipment, and life-support systems.
7. Certain products in this document may need government approval before they can be exported to particular countries. The purchaser assumes the responsibility of determining the legality of export of these products and will take appropriate and necessary steps at their own expense for these.
8. No part of the contents contained herein may be reprinted or reproduced without our prior permission.
9. MS-DOS is a registered trademark of Microsoft Corporation.

Copyright 1999 Oki Electric Industry Co., Ltd.

