PEREGRINE SEMICONDUCTOR

PRODUCT SPECIFICATION

PE3335

3.0 GHz Integer-N PLL for Low Phase Noise Applications

Features

- 3.0 GHz operation
- ÷10/11 dual modulus prescaler
- Internal phase detector with charge pump
- Serial, parallel or hardwired programmable
- Available in 44-lead PLCC and miniature 48-lead MLP package
- Ultra-low phase noise

Product Description

Peregrine's PE3335 is a high performance integer-N PLL capable of frequency synthesis up to 3.0 GHz. The superior phase noise performance of the PE3335 makes it ideal for applications such as LMDS / MMDS / WLL basestations and demanding terrestrial systems.

The PE3335 features a 10/11 dual modulus prescaler, counters, phase comparator and a charge pump as shown in Figure 1. Counter values are programmable through either a serial or parallel interface and can also be directly hard wired.

The PE3335 is optimized for terrestrial applications. Fabricated in Peregrine's patented UTSi® (Ultra Thin Silicon) CMOS technology, the PE3335 offers excellent RF performance with the economy and integration of conventional CMOS.

Figure 1. Block Diagram

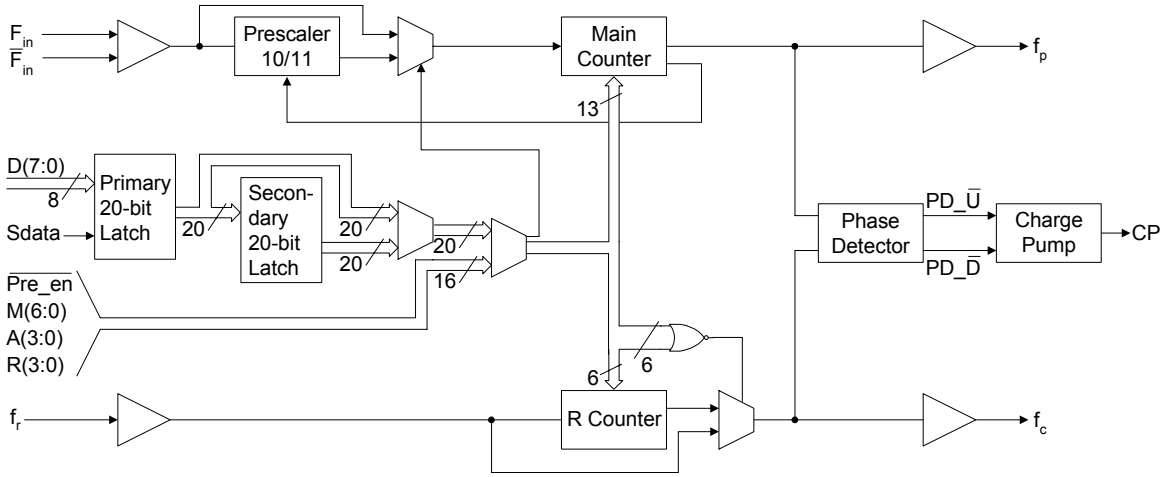
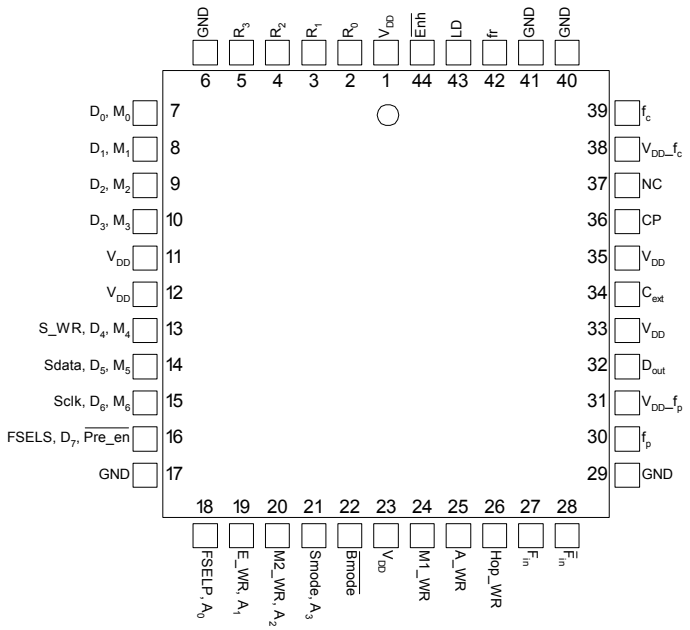
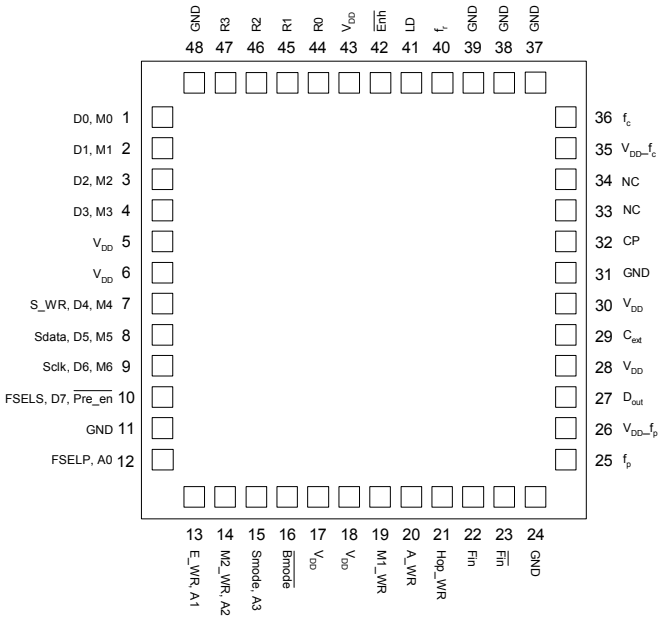


Figure 2. Pin Configuration



44-lead PLCC



48-lead MLPQ

Table 1. Pin Descriptions

Pin No. (44-lead PLCC)	Pin No. (48-lead MLPQ)	Pin Name	Interface Mode	Type	Description
1	43	V_{DD}	ALL	(Note 1)	Power supply input. Input may range from 2.85 V to 3.15 V. Bypassing recommended.
2	44	R_0	Direct	Input	R Counter bit0 (LSB).
3	45	R_1	Direct	Input	R Counter bit1.
4	46	R_2	Direct	Input	R Counter bit2.
5	47	R_3	Direct	Input	R Counter bit3.
6	48	GND	ALL	(Note 1)	Ground.
7	1	D_0	Parallel	Input	Parallel data bus bit0 (LSB).
		M_0	Direct	Input	M Counter bit0 (LSB).
8	2	D_1	Parallel	Input	Parallel data bus bit1.
		M_1	Direct	Input	M Counter bit1.
9	3	D_2	Parallel	Input	Parallel data bus bit2.
		M_2	Direct	Input	M Counter bit2.
10	4	D_3	Parallel	Input	Parallel data bus bit3.
		M_3	Direct	Input	M Counter bit3.
11	5	V_{DD}	ALL	(Note 1)	Same as pin 1 (MLP48 pin 43).
12	6	V_{DD}	ALL	(Note 1)	Same as pin 1 (MLP48 pin 43).

Pin No. (44-lead PLCC)	Pin No. (48-lead MLPQ)	Pin Name	Interface Mode	Type	Description
13	7	S_WR	Serial	Input	Serial load enable input. While S_WR is "low", Sdata can be serially clocked. Primary register data are transferred to the secondary register on S_WR or Hop_WR rising edge.
		D_4	Parallel	Input	Parallel data bus bit4
		M_4	Direct	Input	M Counter bit4
14	8	Sdata	Serial	Input	Binary serial data input. Input data entered MSB first.
		D_5	Parallel	Input	Parallel data bus bit5.
		M_5	Direct	Input	M Counter bit5.
15	9	Sclk	Serial	Input	Serial clock input. Sdata is clocked serially into the 20-bit primary register (E_WR "low") or the 8-bit enhancement register (E_WR "high") on the rising edge of Sclk.
		D_6	Parallel	Input	Parallel data bus bit6.
		M_6	Direct	Input	M Counter bit6.
16	10	FSELS	Serial	Input	Selects contents of primary register (FSELS=1) or secondary register (FSELS=0) for programming of internal counters while in Serial Interface Mode.
		D_7	Parallel	Input	Parallel data bus bit7 (MSB).
		$\overline{\text{Pre\_en}}$	Direct	Input	Prescaler enable, active "low". When "high", F_{in} bypasses the prescaler.
17	11	GND	ALL		Ground.
18	12	FSELP	Parallel	Input	Selects contents of primary register (FSELP=1) or secondary register (FSELP=0) for programming of internal counters while in Parallel Interface Mode.
		A_0	Direct	Input	A Counter bit0 (LSB).
19	13	E_WR	Serial	Input	Enhancement register write enable. While E_WR is "high", Sdata can be serially clocked into the enhancement register on the rising edge of Sclk.
			Parallel	Input	Enhancement register write. D[7:0] are latched into the enhancement register on the rising edge of E_WR.
		A_1	Direct	Input	A Counter bit1.
20	14	M2_WR	Parallel	Input	M2 write. D[3:0] are latched into the primary register (R[5:4], M[8:7]) on the rising edge of M2_WR.
		A_2	Direct	Input	A Counter bit2.
21	15	Smode	Serial, Parallel	Input	Selects serial bus interface mode ($\overline{\text{Bmode}}$=0, Smode=1) or Parallel Interface Mode ($\overline{\text{Bmode}}$=0, Smode=0).
		A_3	Direct	Input	A Counter bit3 (MSB).
22	16	$\overline{\text{Bmode}}$	ALL	Input	Selects direct interface mode ($\overline{\text{Bmode}}$=1).
23	17,18	V_{DD}	ALL	(Note 1)	Same as pin 1 (MLP48 pin 43).
24	19	M1_WR	Parallel	Input	M1 write. D[7:0] are latched into the primary register ($\overline{\text{Pre\_en}}$, M[6:0]) on the rising edge of M1_WR.
25	20	A_WR	Parallel	Input	A write. D[7:0] are latched into the primary register (R[3:0], A[3:0]) on the rising edge of A_WR.
26	21	Hop_WR	Serial, Parallel	Input	Hop write. The contents of the primary register are latched into the secondary register on the rising edge of Hop_WR.
27	22	F_{in}	ALL	Input	Prescaler input from the VCO. 3.0 GHz max frequency.

Pin No. (44-lead PLCC)	Pin No. (48-lead MLPQ)	Pin Name	Interface Mode	Type	Description
28	23	$\overline{F}_{in}$	ALL	Input	Prescaler complementary input. A bypass capacitor should be placed as close as possible to this pin and be connected in series with a 50 Ω resistor directly to the ground plane.
29	24	GND	ALL		Ground.
30	25	f_p	ALL	Output	Monitor pin for main divider output. Switching activity can be disabled through enhancement register programming or by floating or grounding V_{DD} pin 31.
31	26	V_{DD}-f_p	ALL	(Note 1)	V_{DD} for f_p. Can be left floating or connected to GND to disable the f_p output.
32	27	Dout	Serial, Parallel	Output	Data Out. The MSEL signal and the raw prescaler output are available on Dout through enhancement register programming.
33	28	V_{DD}	ALL	(Note 1)	Same as pin 1 (MLP48 pin 43).
34	29	Cext	ALL	Output	Logical “NAND” of PD_$\overline{U}$ and PD_$\overline{D}$ terminated through an on chip, 2 kΩ series resistor. Connecting Cext to an external capacitor will low pass filter the input to the inverting amplifier used for driving LD.
35	30	V_{DD}	ALL	(Note 1)	Same as pin 1 (MLP48 pin 43).
36	32	CP	ALL	Output	Charge pump current is sourced when f_c leads f_p and sinked when f_c lags f_p.
37	33,34	NC	ALL		No connection.
38	35	V_{DD}-f_c	ALL	(Note 1)	V_{DD} for f_c can be left floating or connected to GND to disable the f_c output.
39	36	f_c	ALL	Output	Monitor pin for reference divider output. Switching activity can be disabled through enhancement register programming or by floating or grounding V_{DD} pin 38.
40	31,37	GND	ALL		Ground.
41	38,39	GND	ALL		Ground.
42	40	f_r	ALL	Input	Reference frequency input.
43	41	LD	ALL	Output	Lock detect and open drain logical inversion of Cext. When the loop is in lock, LD is high impedance, otherwise LD is a logic low (“0”).
44	42	$\overline{Enh}$	Serial, Parallel	Input	Enhancement mode. When asserted low (“0”), enhancement register bits are functional.

Note 1: All V_{DD} pins are connected by diodes and must be supplied with the same positive voltage level.
V_{DD}-f_p and V_{DD}-f_c are used to power the f_p and f_c outputs and can alternatively be left floating or connected to GND to disable the f_p and f_c outputs.

Note 2: All digital input pins have 70 kΩ pull-down resistors to ground.

Table 2. Absolute Maximum Ratings

Symbol	Parameter/Conditions	Min	Max	Units
V_{DD}	Supply voltage	-0.3	4.0	V
V_I	Voltage on any input	-0.3	V_{DD} + 0.3	V
I_I	DC into any input	-10	+10	mA
I_O	DC into any output	-10	+10	mA
T_{stg}	Storage temperature range	-65	150	°C

Table 3. Operating Ratings

Symbol	Parameter/Conditions	Min	Max	Units
V_{DD}	Supply voltage	2.85	3.15	V
T_A	Operating ambient temperature range	-40	85	°C

Table 4. ESD Ratings

Symbol	Parameter/Conditions	Level	Units
V_{ESD}	ESD voltage (Human Body Model)	1000	V

Note 1: Periodically sampled, not 100% tested. Tested per MIL-STD-883, M3015 C2

Electrostatic Discharge (ESD) Precautions

When handling this UTSi device, observe the same precautions that you would use with other ESD-sensitive devices. Although this device contains circuitry to protect it from damage due to ESD, precautions should be taken to avoid exceeding the rating specified in Table 4.

Latch-Up Avoidance

Unlike conventional CMOS devices, UTSi CMOS devices are immune to latch-up.

Table 5. DC Characteristics

V_{DD} = 3.0 V, -40° C < T_A < 85° C, unless otherwise specified

Symbol	Parameter	Conditions	Min	Typ	Max	Units
I_{DD}	Operational supply current; Prescaler disabled Prescaler enabled	V_{DD} = 2.85 to 3.15 V		 10 24	 31	 mA mA
Digital Inputs: All except f_r, R_0, F_{in}, $\overline{F}_{in}$						
V_{IH}	High level input voltage	V_{DD} = 2.85 to 3.15 V	0.7 x V_{DD}			V
V_{IL}	Low level input voltage	V_{DD} = 2.85 to 3.15 V			0.3 x V_{DD}	V
I_{IH}	High level input current	V_{IH} = V_{DD} = 3.15 V			+70	µA
I_{IL}	Low level input current	V_{IL} = 0, V_{DD} = 3.15 V	-1			µA
Reference Divider input: f_r						
I_{IHR}	High level input current	V_{IH} = V_{DD} = 3.15 V			+100	µA
I_{ILR}	Low level input current	V_{IL} = 0, V_{DD} = 3.15 V	-100			µA
R0 Input (Pull-up Resistor): R_0						
I_{IHRO}	High level input current	V_{IH} = V_{DD} = 3.15 V			+5	µA
I_{ILRO}	Low level input current	V_{IL} = 0, V_{DD} = 3.15 V	-5			µA
Counter output D_{out}						
V_{OLD}	Output voltage LOW	I_{out} = 6 mA			0.4	V
V_{OHD}	Output voltage HIGH	I_{out} = -3 mA	V_{DD} - 0.4			V
Lock detect outputs: Cext, LD						
V_{OLC}	Output voltage LOW, Cext	I_{out} = 100 mA			0.4	V
V_{OHC}	Output voltage HIGH, Cext	I_{out} = -100 mA	V_{DD} - 0.4			V
V_{OLLD}	Output voltage LOW, LD	I_{out} = 6 mA			0.4	V
Charge Pump output: CP						
I_{CP} - Source	Drive current	V_{CP} = V_{DD} / 2	-2.6	-2	-1.4	mA
I_{CP} – Sink	Drive current	V_{CP} = V_{DD} / 2	1.4	2	2.6	mA
I_{CPL}	Leakage current	1.0 V < V_{CP} < V_{DD} – 1.0 V	-1	1		µA
I_{CP} – Source vs. I_{CP} Sink	Sink vs. source mismatch	VCP = V_{DD} / 2, T_A = 25° C			15	%
I_{CP} vs. V_{CP}	Output current magnitude variation vs. voltage	1.0 V < V_{CP} < V_{DD} – 1.0 V T_A = 25° C			15	%

Table 6. AC Characteristics

V_{DD} = 3.0 V, -40° C < T_A < 85° C, unless otherwise specified

Symbol	Parameter	Conditions	Min	Max	Units
Control Interface and Latches (see Figures 3, 4, 5)					
f_{Clk}	Serial data clock frequency			10	MHz
t_{ClkH}	Serial clock HIGH time		30		ns
t_{ClkL}	Serial clock LOW time		30		ns
t_{DSU}	Sdata set-up time after Sclk rising edge, D[7:0] set-up time to M1_WR, M2_WR, A_WR, E_WR rising edge		10		ns
t_{DHLD}	Sdata hold time after Sclk rising edge, D[7:0] hold time to M1_WR, M2_WR, A_WR, E_WR rising edge		10		ns
t_{PW}	S_WR, M1_WR, M2_WR, A_WR, E_WR pulse width		30		ns
t_{CWR}	Sclk rising edge to S_WR rising edge. S_WR, M1_WR, M2_WR, A_WR falling edge to Hop_WR rising edge		30		ns
t_{CE}	Sclk falling edge to E_WR transition		30		ns
t_{WRC}	S_WR falling edge to Sclk rising edge. Hop_WR falling edge to S_WR, M1_WR, M2_WR, A_WR rising edge		30		ns
t_{EC}	E_WR transition to Sclk rising edge		30		ns
t_{MDO}	MSEL data out delay after Fin rising edge	C_L = 12 pf		8	ns
Main Divider (Including Prescaler)					
F_{in}	Operating frequency		500	3000	MHz
P_{Fin}	Input level range	External AC coupling	-5	5	dBm
Main Divider (Prescaler Bypassed)					
F_{in}	Operating frequency		50	300	MHz
P_{Fin}	Input level range	External AC coupling	-5	5	dBm
Reference Divider					
f_r	Operating frequency	(Note 1)	(Note 2)	100	MHz
P_{fr}	Reference input power	Single ended input	-2	10	dBm
V_{fr}	Input sensitivity	External AC coupling (Note 3)	0.5		V_{P-P}
Phase Detector					
f_c	Comparison frequency	(Note 1)		20	MHz

Note 1: Parameter is guaranteed through characterization only and is not tested.

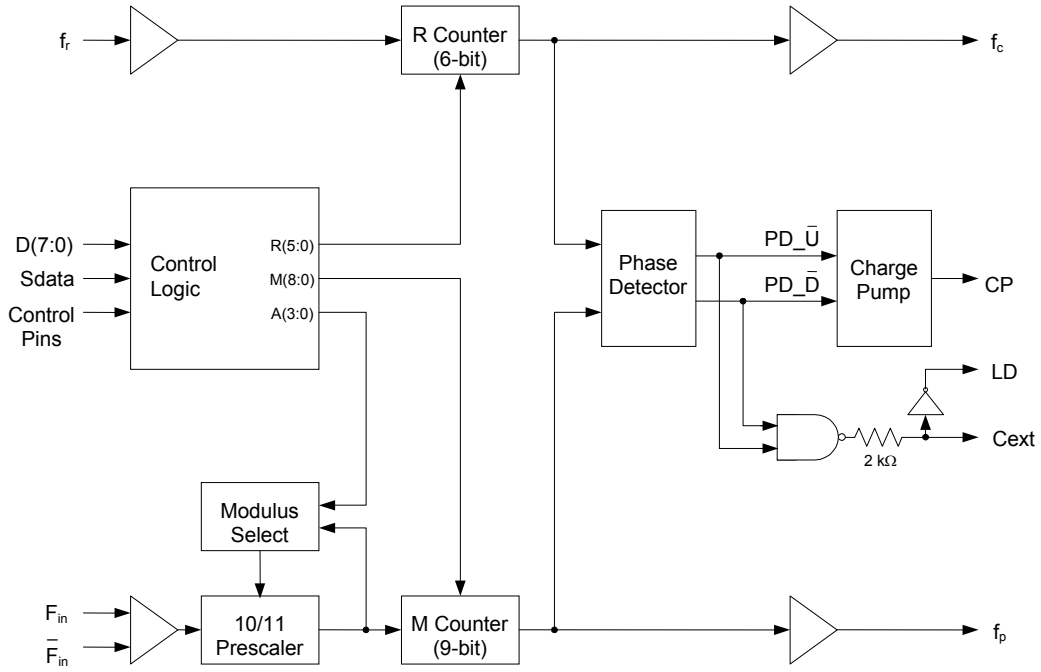
Note 2: Running at low frequencies (< 10 MHz sinewave), the device will still be functional but may cause phase noise degradation. Inserting a low-noise amplifier to square up the edges is recommended at lower input frequencies.

Note 3: CMOS logic levels may be used if DC coupled. For optimum phase noise performance, the reference input falling edge rate should be faster than 80mV/ns.

Functional Description

The PE3335 consists of a prescaler, counters, a phase detector, a charge pump and control logic. The dual modulus prescaler divides the VCO frequency by either 10 or 11, depending on the value of the modulus select. Counters “R” and “M” divide the reference and prescaler output, respectively, by integer values stored in a 20-bit register. An additional counter (“A”) is used in the modulus select logic. The phase-frequency detector generates up and down frequency control signals. The control logic includes a selectable chip interface. Data can be written via serial bus, parallel bus, or hardwired direct to the pins. There are also various operational and test modes and lock detect.

Figure 3. Functional Block Diagram



Main Counter Chain

The main counter chain divides the RF input frequency, F_{in}, by an integer derived from the user defined values in the "M" and "A" counters. It is composed of the 10/11 dual modulus prescaler, modulus select logic, and 9-bit M counter. Setting Pre_en "low" enables the 10/11 prescaler. Setting Pre_en "high" allows F_{in} to bypass the prescaler and powers down the prescaler.

The output from the main counter chain, f_p, is related to the VCO frequency, F_{in}, by the following equation:

$$f_p = F_{in} / [10 \times (M + 1) + A] \quad (1)$$
$$\text{where } A \leq M + 1,\ 1 \leq M \leq 511$$

When the loop is locked, F_{in} is related to the reference frequency, f_r, by the following equation:

$$F_{in} = [10 \times (M + 1) + A] \times (f_r / (R+1)) \quad (2)$$
$$\text{where } A \leq M + 1,\ 1 \leq M \leq 511$$

A consequence of the upper limit on A is that F_{in} must be greater than or equal to 90 x (f_r / (R+1)) to obtain contiguous channels. Programming the M Counter with the minimum value of "1" will result in a minimum M Counter divide ratio of "2".

When the prescaler is bypassed, the equation becomes:

$$F_{in} = (M + 1) \times (f_r / (R+1)) \quad (3)$$
$$\text{where } 1 \leq M \leq 511$$

In Direct Interface Mode, main counter inputs M_7 and M_8 are internally forced low.

Reference Counter

The reference counter chain divides the reference frequency, f_r, down to the phase detector comparison frequency, f_c.

The output frequency of the 6-bit R Counter is related to the reference frequency by the following equation:

$$f_c = f_r / (R + 1) \quad (4)$$
$$\text{where } 0 \leq R \leq 63$$

Note that programming R equal to "0" will pass the reference frequency, f_r, directly to the phase detector.

In Direct Interface Mode, R Counter inputs R_4 and R_5 are internally forced low ("0").

Register Programming

Parallel Interface Mode

Parallel Interface Mode is selected by setting the Bmode input "low" and the Smode input "low".

Parallel input data, D[7:0], are latched in a parallel fashion into one of three, 8-bit primary register sections on the rising edge of M1_WR, M2_WR, or A_WR per the mapping shown in Table 7 on page 10. The contents of the primary register are transferred into a secondary register on the rising edge of Hop_WR according to the timing diagram shown in Figure 4. Data are transferred to the counters as shown in Table 7 on page 10.

The secondary register acts as a buffer to allow rapid changes to the VCO frequency. This double buffering for "ping-pong" counter control is programmed via the FSELP input. When FSELP is "high", the primary register contents set the counter inputs. When FSELP is "low", the secondary register contents are utilized.

Parallel input data, D[7:0], are latched into the enhancement register on the rising edge of E_WR according to the timing diagram shown in Figure 4. This data provides control bits as shown in Table 8 on page 10 with bit functionality enabled by asserting the Enh input "low".

Serial Interface Mode

Serial Interface Mode is selected by setting the Bmode input "low" and the Smode input "high".

While the E_WR input is "low" and the S_WR input is "low", serial input data (Sdata input), B_0 to B_{19}, are clocked serially into the primary register on the rising edge of Sclk, MSB (B_0) first. The contents from the primary register are transferred into the secondary register on the rising edge of either S_WR or Hop_WR according to the timing diagram shown in Figures 4-5. Data are transferred to the counters as shown in Table 7 on page 10.

The double buffering provided by the primary and secondary registers allows for "ping-pong" counter control using the FSELS input. When FSELS is "high", the primary register contents set the counter inputs. When FSELS is "low", the secondary register contents are utilized.

While the E_WR input is "high" and the S_WR input is "low", serial input data (Sdata input), B_0 to B_7, are clocked serially into the enhancement register on the rising edge of Sclk, MSB (B_0) first. The enhancement register is double buffered to prevent

inadvertent control changes during serial loading, with buffer capture of the serially entered data performed on the falling edge of E_WR according to the timing diagram shown in Figure 5. After the falling edge of E_WR, the data provide control bits as shown in Table 8 with bit functionality enabled by asserting the $\overline{Enh}$ input "low".

Direct Interface Mode

Direct Interface Mode is selected by setting the $\overline{Bmode}$ input "high".

Counter control bits are set directly at the pins as shown in Table 7. In Direct Interface Mode, main counter inputs M_7 and M_8, and R Counter inputs R_4 and R_5 are internally forced low ("0").

Table 7. Primary Register Programming

Interface Mode	$\overline{Enh}$	$\overline{Bmode}$	Smode	R_5	R_4	M_8	M_7	$\overline{Pre\_en}$	M_6	M_5	M_4	M_3	M_2	M_1	M_0	R_3	R_2	R_1	R_0	A_3	A_2	A_1	A_0
Parallel	1	0	0	M2_WR rising edge load				M1_WR rising edge load								A_WR rising edge load							
				D_3	D_2	D_1	D_0	D_7	D_6	D_5	D_4	D_3	D_2	D_1	D_0	D_7	D_6	D_5	D_4	D_3	D_2	D_1	D_0
Serial*	1	0	1	B_0	B_1	B_2	B_3	B_4	B_5	B_6	B_7	B_8	B_9	B_{10}	B_{11}	B_{12}	B_{13}	B_{14}	B_{15}	B_{16}	B_{17}	B_{18}	B_{19}
Direct	1	1	X	0	0	0	0	Pre_en	M_6	M_5	M_4	M_3	M_2	M_1	M_0	R_3	R_2	R_1	R_0	A_3	A_2	A_1	A_0

*Serial data clocked serially on Sclk rising edge while E_WR "low" and captured in secondary register on S_WR rising edge.

MSB (first in) ↑ ... ↑ (last in) LSB

Table 8. Enhancement Register Programming

Interface Mode	$\overline{Enh}$	$\overline{Bmode}$	Smode	Reserved	Reserved	Reserved	Power down	Counter load	MSEL output	Prescaler output	f_c, f_p $\overline{OE}$
Parallel	0	X	0	E_WR rising edge load							
				D_7	D_6	D_5	D_4	D_3	D_2	D_1	D_0
Serial*	0	X	1	B_0	B_1	B_2	B_3	B_4	B_5	B_6	B_7

*Serial data clocked serially on Sclk rising edge while E_WR "high" and captured in the double buffer on E_WR falling edge.

MSB (first in) ↑ ... ↑ (last in) LSB

Figure 4. Parallel Interface Mode Timing Diagram

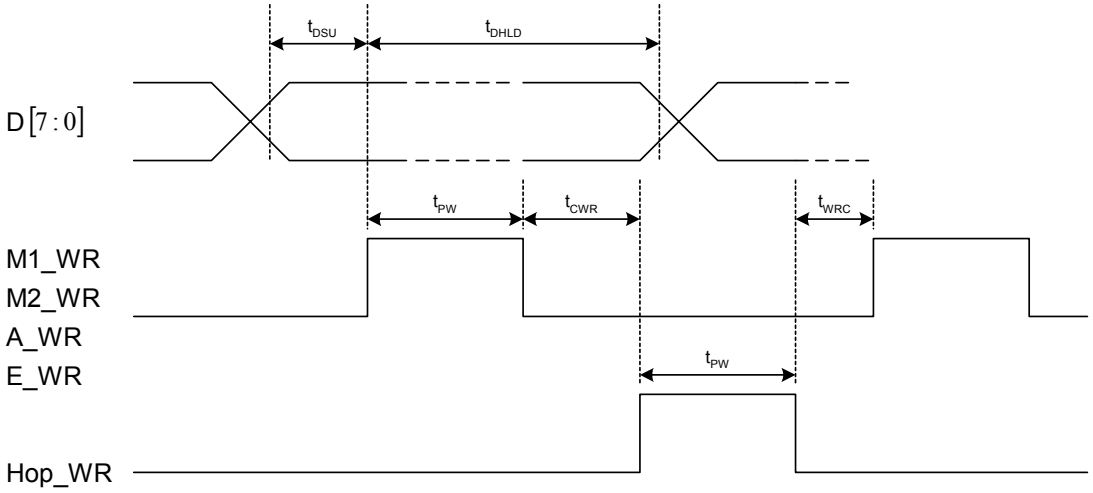
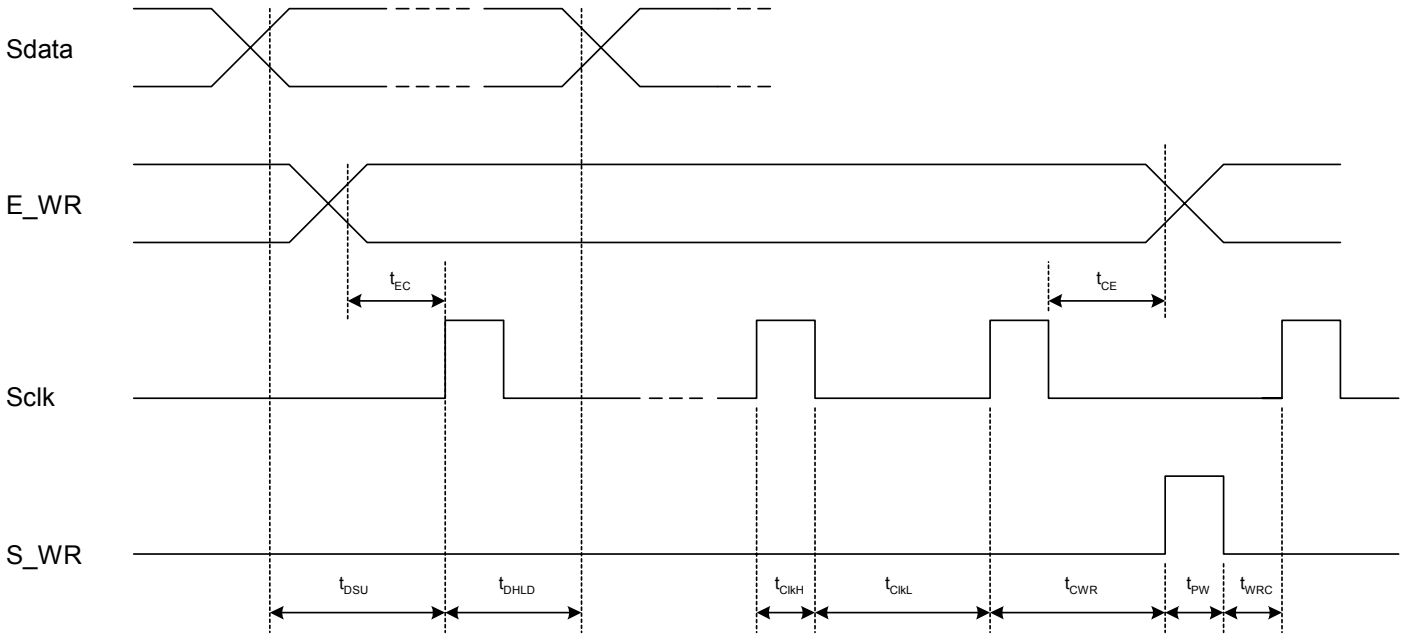


Figure 5. Serial Interface Mode Timing Diagram



Enhancement Register

The functions of the enhancement register bits are shown below with all bits active “high”.

Table 9. Enhancement Register Bit Functionality

Bit Function		Description
Bit 0	Reserved**	
Bit 1	Reserved**	
Bit 2	Reserved**	
Bit 3	Power down	Power down of all functions except programming interface.
Bit 4	Counter load	Immediate and continuous load of counter programming as directed by the $\overline{\text{Bmode}}$ and Smode inputs.
Bit 5	MSEL output	Drives the internal dual modulus prescaler modulus select (MSEL) onto the Dout output.
Bit 6	Prescaler output	Drives the raw internal prescaler output onto the Dout output.
Bit 7	f_p, f_c $\overline{\text{OE}}$	f_p, f_c outputs disabled.

** Program to 0

Phase Detector

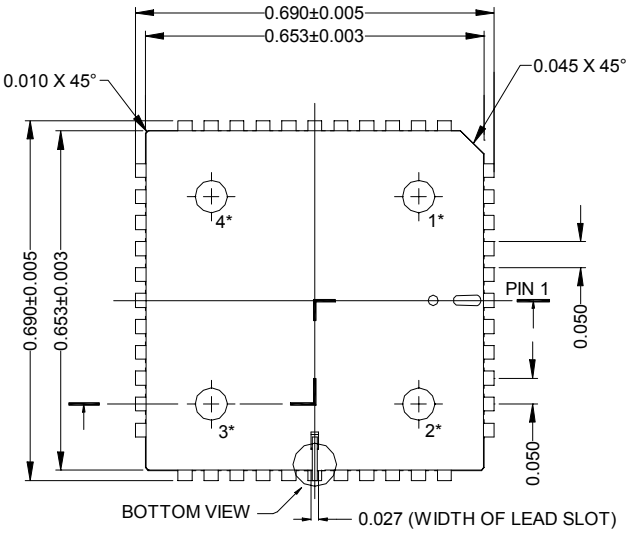
The phase detector is triggered by rising edges from the main Counter (f_p) and the reference counter (f_c). It has two outputs, PD_$\overline{\text{U}}$, and PD_$\overline{\text{D}}$. If the divided VCO leads the divided reference in phase or frequency (f_p leads f_c), PD_$\overline{\text{D}}$ pulses “low”. If the divided reference leads the divided VCO in phase or frequency (f_c leads f_p), PD_$\overline{\text{U}}$ pulses “low”. The width of either pulse is directly proportional to phase offset between the two input signals, f_p and f_c.

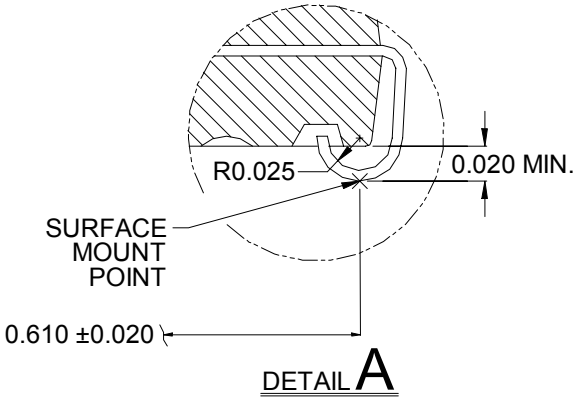
The signals from the phase detector couple directly to a charge pump. PD_$\overline{\text{U}}$ controls a current source at pin CP with constant amplitude and pulse duration approximately the same as PD_$\overline{\text{U}}$. PD_$\overline{\text{D}}$ similarly drives a current sink at pin CP. The current pulses from pin CP are low pass filtered externally and then connected to the VCO tune voltage. PD_$\overline{\text{U}}$ pulses result in a current source, which increases the VCO frequency; PD_$\overline{\text{D}}$ pulses result in a current sink, which decreases VCO frequency (for a positive Kv VCO).

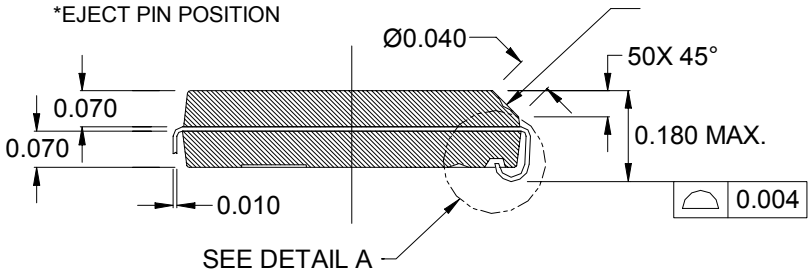
A lock detect output, LD is also provided, via the pin Cext. Cext is the logical “NAND” of PD_$\overline{\text{U}}$ and PD_$\overline{\text{D}}$ waveforms, which is driven through a series 2 kohm resistor. Connecting Cext to an external shunt capacitor provides low pass filtering of this signal. Cext also drives the input of an internal inverting comparator with an open drain output. Thus LD is an “AND” function of PD_$\overline{\text{U}}$ and PD_$\overline{\text{D}}$.

Figure 6. Package Drawing

44-lead PLCC



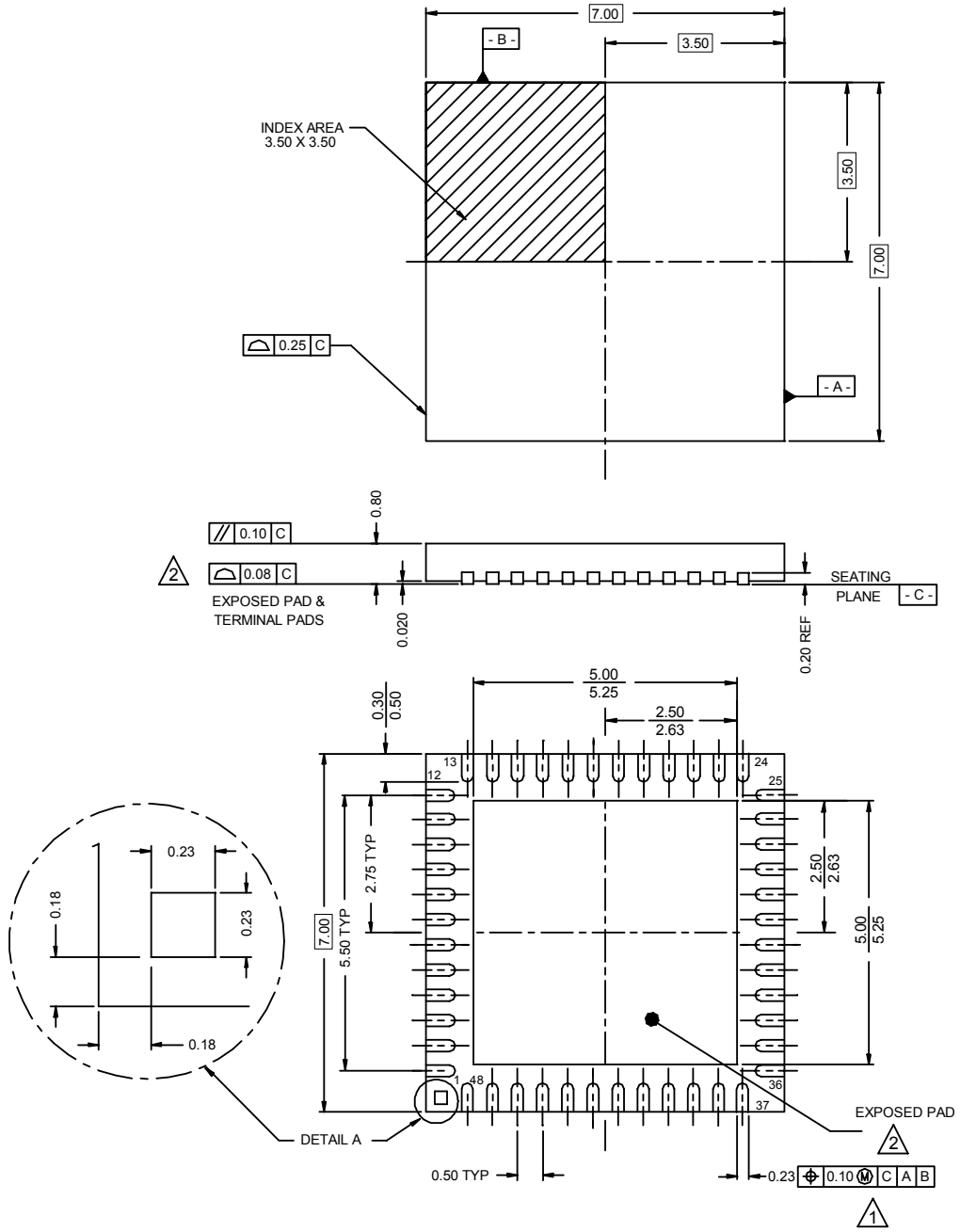




DIMENSIONS ARE IN INCHES
TOLERANCES ARE ± 0.004

Figure 7. Package Drawing

48-lead MLPQ



1. DIMENSION APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25 AND 0.30 FROM TERMINAL TIP.

2. COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.

Table 10. Ordering Information

Order Code	Part Marking	Description	Package	Shipping Method	Product Status
3335-21	PE3335		44-lead PLCC	26 units / Tube	Production
3335-22	PE3335		44-lead PLCC	500 units / T&R	Production
3335-23	PE3335		48-lead MLPQ	52 units / Tube	Evaluation Samples
3335-24	PE3335		48-lead MLPQ	4000 units / T&R	Evaluation Samples
3335-00	PE3335EK	PLCC Evaluation Board with Software	44-lead PLCC	1 / Box	Available
3335-01	PE3335EK	MLPQ Evaluation Board with Software	48-lead MLPQ	1 / Box	Available

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For a list of representatives in your area, please refer to our Web site at: ***http://www.peregrine-semi.com***

Data Sheet Identification

Advance Information

The product is in a formative or design stage. The data sheet contains design target specifications for product development. Specifications and features may change in any manner without notice.

Preliminary Specification

The data sheet contains preliminary data. Additional data may be added at a later date. Peregrine reserves the right to change specifications at any time without notice in order to supply the best possible product.

Product Specification

The data sheet contains final data. In the event Peregrine decides to change the specifications, Peregrine will notify customers of the intended changes by issuing a PCN (Product Change Notice).