

DATA SHEET

For a complete data sheet, please also download:

- The IC04 LOCMOS HE4000B Logic Family Specifications HEF, HEC
- The IC04 LOCMOS HE4000B Logic Package Outlines/Information HEF, HEC

HEF4076B

MSI

Quadruple D-type register with
3-state outputs

Product specification
File under Integrated Circuits, IC04

January 1995

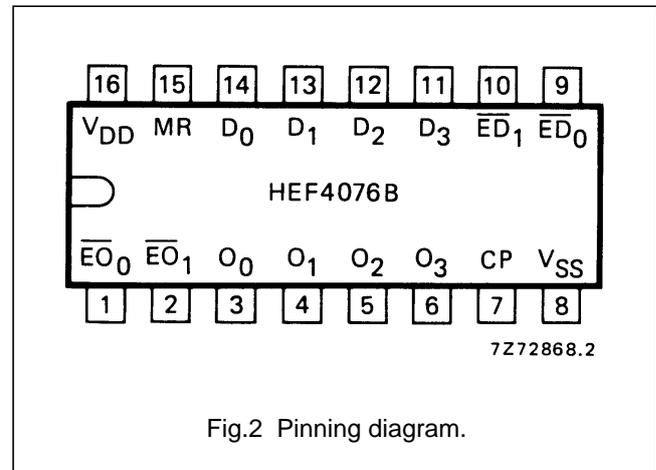
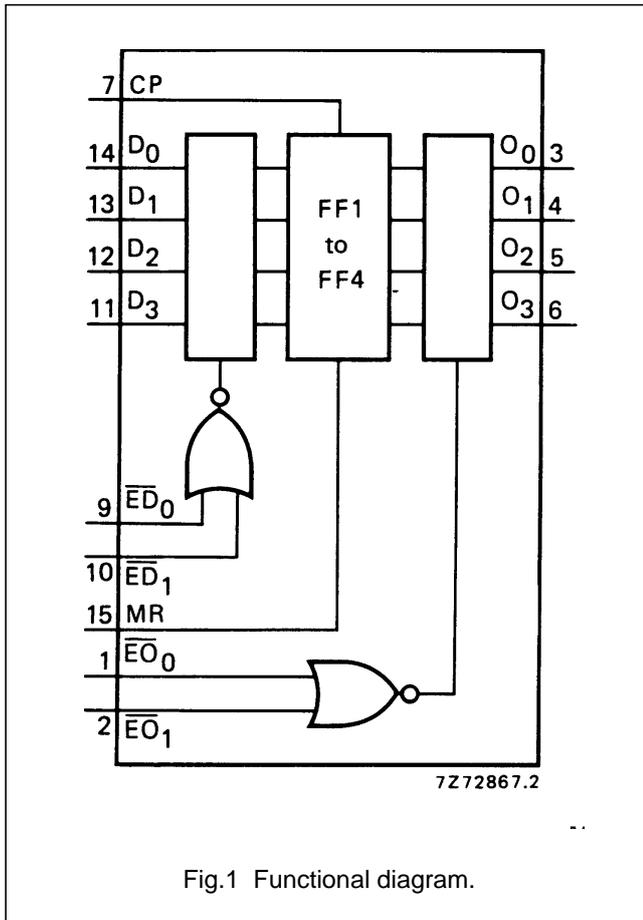
Quadruple D-type register with 3-state outputs

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DESCRIPTION

The HEF4076B is a quadruple edge-triggered D-type flip-flop with four data inputs (D_0 to D_3), two active LOW data enable inputs (\overline{ED}_0 and \overline{ED}_1), a common clock input (CP), four 3-state outputs (O_0 to O_3), two active LOW output enable inputs (\overline{EO}_0 and \overline{EO}_1), and an overriding asynchronous master reset input (MR).

Information on D_0 to D_3 is stored in the four flip-flops on the LOW to HIGH transition of CP if both \overline{ED}_0 and \overline{ED}_1 are LOW. A HIGH on either \overline{ED}_0 or \overline{ED}_1 prevents the flip-flops from changing on the LOW to HIGH transition of CP, independent of the information on D_0 to D_3 . When both \overline{EO}_0 and \overline{EO}_1 are LOW, the contents of the four flip-flops are available at O_0 to O_3 . A HIGH on either \overline{EO}_0 or \overline{EO}_1 forces O_0 to O_3 into the high impedance OFF-state. A HIGH on MR resets all four flip-flops, independent of all other input conditions.



PINNING

- D_0 to D_3 data inputs
- \overline{ED}_0 , \overline{ED}_1 data enable inputs (active LOW)
- \overline{EO}_0 , \overline{EO}_1 output enable inputs (active LOW)
- CP clock input (LOW to HIGH, edge-triggered)
- MR master reset input
- O_0 to O_3 data outputs

FAMILY DATA, I_{DD} LIMITS category MSI

See Family Specifications

- HEF4076BP(N): 16-lead DIL; plastic (SOT38-1)
- HEF4076BD(F): 16-lead DIL; ceramic (cerdip) (SOT74)
- HEF4076BT(D): 16-lead SO; plastic (SOT109-1)
- (): Package Designator North America

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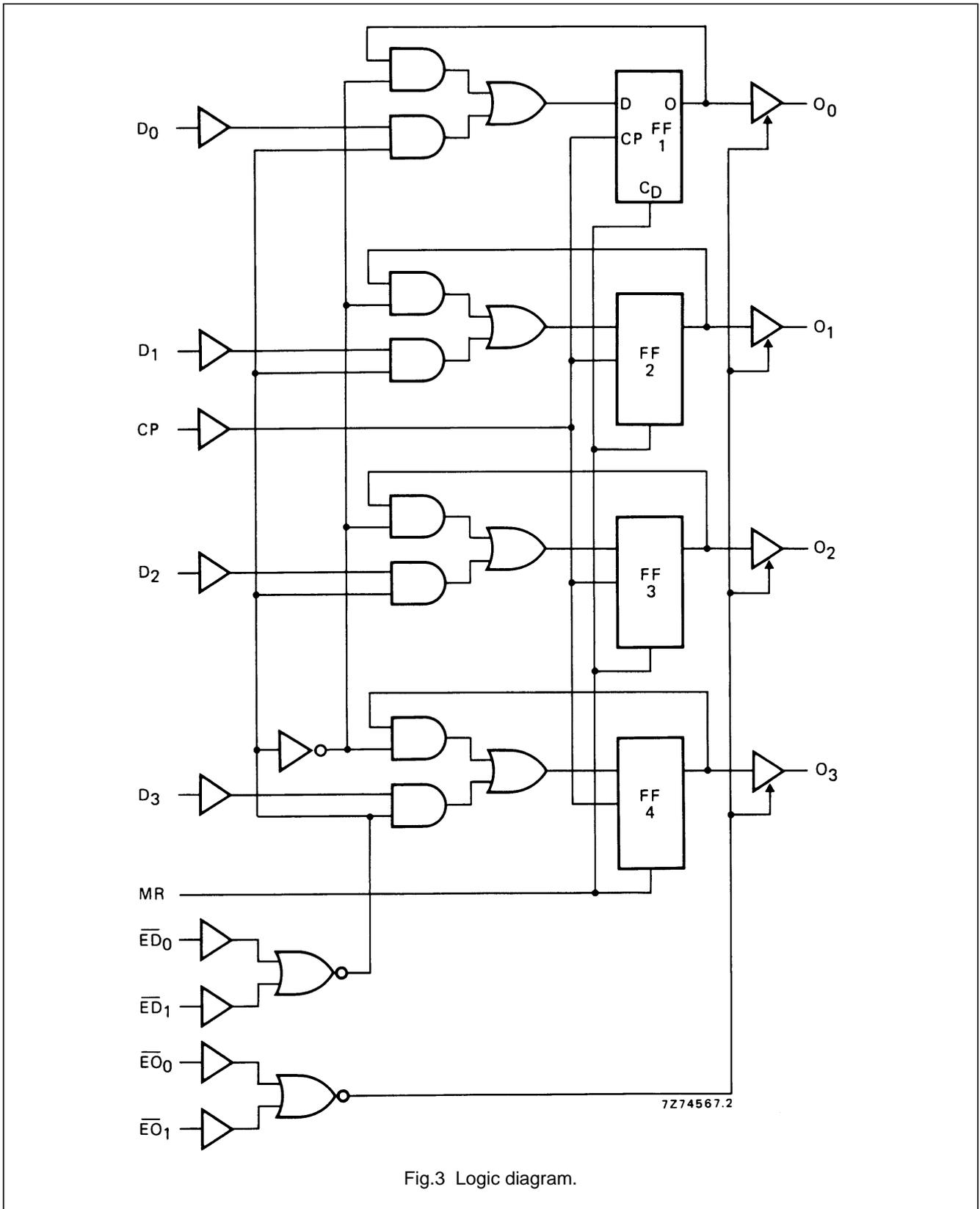


Fig.3 Logic diagram.

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FUNCTION TABLE

INPUTS					OUTPUTS
MR	CP	\overline{ED}_0	\overline{ED}_1	D_n	O_n
H	X	X	X	X	L
L	\nearrow	H	X	X	no change
L	\nearrow	X	H	X	no change
L	\nearrow	L	L	H	H
L	\nearrow	L	L	L	L
L	\searrow	X	X	X	no change

Notes

- $\overline{EO}_0 = \overline{EO}_1 = \text{LOW}$
When either \overline{EO}_0 or \overline{EO}_1 is HIGH, the outputs are disabled (high impedance OFF-state).
H = HIGH state (the more positive voltage)
L = LOW state (the less positive voltage)
X = state is immaterial
 \nearrow = positive-going transition
 \searrow = negative-going transition

AC CHARACTERISTICS

$V_{SS} = 0$ V; $T_{amb} = 25$ °C; $C_L = 50$ pF; input transition times ≤ 20 ns; see also waveforms Fig.4

	V_{DD} V	SYMBOL	MIN.	TYP.	MAX.	TYPICAL EXTRAPOLATION FORMULA			
Propagation delays	5	t_{PHL}		150	305	ns	123 ns + (0,55 ns/pF) C_L		
				CP \rightarrow O_n HIGH to LOW	60	120		ns	49 ns + (0,23 ns/pF) C_L
					45	85		ns	37 ns + (0,16 ns/pF) C_L
	5	t_{PLH}		160	320	ns	133 ns + (0,55 ns/pF) C_L		
				LOW to HIGH	65	130		ns	54 ns + (0,23 ns/pF) C_L
					45	90		ns	37 ns + (0,16 ns/pF) C_L
	5	t_{PHL}		95	190	ns	68 ns + (0,55 ns/pF) C_L		
				MR \rightarrow O_n HIGH to LOW	40	85		ns	29 ns + (0,23 ns/pF) C_L
					30	65		ns	22 ns + (0,16 ns/pF) C_L
Output transition times	5	t_{THL}		60	120	ns	10 ns + (1,0 ns/pF) C_L		
				HIGH to LOW	30	60		ns	9 ns + (0,42 ns/pF) C_L
					20	40		ns	6 ns + (0,28 ns/pF) C_L
	5	t_{TLH}		60	120	ns	10 ns + (1,0 ns/pF) C_L		
				LOW to HIGH	30	60		ns	9 ns + (0,42 ns/pF) C_L
					20	40		ns	6 ns + (0,28 ns/pF) C_L
3-state propagation times	5	t_{PHZ}		50	105	ns			
				Output disable times $\overline{EO}_n \rightarrow O_n$ HIGH	35	70		ns	
					30	65		ns	
	5	t_{PLZ}		45	90	ns			
				LOW	30	65		ns	
					30	60		ns	

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	V _{DD} V	SYMBOL	MIN.	TYP.	MAX.	TYPICAL EXTRAPOLATION FORMULA
Output enable times $\overline{E}O_n \rightarrow O_n$ HIGH	5	t _{PZH}		65	130	ns
	10			30	55	ns
	15			20	40	ns
LOW	5	t _{PZL}		60	120	ns
	10			25	50	ns
	15			20	35	ns

AC CHARACTERISTICS

V_{SS} = 0 V; T_{amb} = 25 °C; C_L = 50 pF; input transition times ≤ 20 ns

	V _{DD} V	SYMBOL	MIN.	TYP.	MAX.	TYPICAL EXTRAPOLATION FORMULA
Set-up times D _n → CP	5	t _{su}	10	-15	ns	see also waveforms Fig.4
	10		0	-10	ns	
	15		0	-5	ns	
$\overline{E}D_n \rightarrow CP$	5	t _{su}	0	-50	ns	
	10		0	-20	ns	
	15		0	-15	ns	
Hold times D _n → CP	5	t _{hold}	55	30	ns	
	10		20	10	ns	
	15		15	10	ns	
$\overline{E}D_n \rightarrow CP$	5	t _{hold}	25	-25	ns	
	10		10	-10	ns	
	15		5	-5	ns	
Minimum clock pulse width; LOW	5	t _{WCPL}	120	60	ns	
	10		45	20	ns	
	15		30	15	ns	
Minimum MR pulse width; HIGH	5	t _{WMRH}	55	25	ns	
	10		30	15	ns	
	15		20	10	ns	
Recovery time for MR	5	t _{RMR}	90	45	ns	
	10		35	15	ns	
	15		20	10	ns	
Maximum clock pulse frequency	5	f _{max}	4	8	MHz	
	10		11	22	MHz	
	15		16	32	MHz	

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	V_{DD} V	TYPICAL FORMULA FOR P (μ W)	
Dynamic power dissipation per package (P)	5 10 15	$2200 f_i + \sum (f_o C_L) \times V_{DD}^2$ $9300 f_i + \sum (f_o C_L) \times V_{DD}^2$ $24\,500 f_i + \sum (f_o C_L) \times V_{DD}^2$	where f_i = input freq. (MHz) f_o = output freq. (MHz) C_L = load capacitance (pF) $\sum (f_o C_L)$ = sum of outputs V_{DD} = supply voltage (V)

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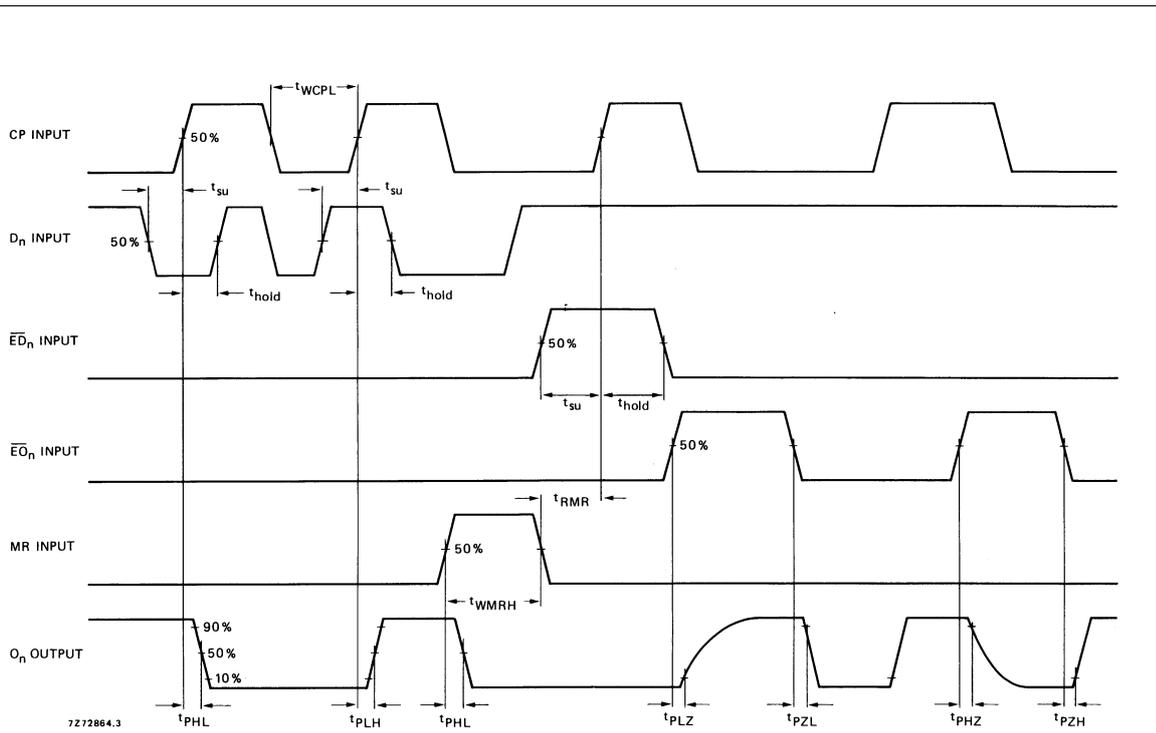


Fig.4 Waveforms showing propagation delays, output disable/enable times, minimum CP and MR pulse widths, set-up and hold times for D_n to CP and \overline{ED}_n to CP, and recovery time for MR. Set-up and hold times are shown as positive values but may be specified as negative values.