

DATA SHEET

TDA8001 Smart card interface

Product specification
Supersedes data of 1995 Feb 01
File under Integrated Circuits, IC02

1996 Dec 12

Smart card interface

TDA8001

FEATURES

- Protected I/O line
- V_{CC} regulation (5 V ±5%, 100 mA max. with controlled rise and fall times)
- V_{PP} generation (12.5, 15 or 21 V ±2.5%, 50 mA max., with controlled rise and fall times) (only at TDA8001 and TDA8001T)
- Clock generation (up to 10 MHz), with synchronous frequency doubling
- Overload, thermal and card extraction protections
- Current limitation in case of short-circuit
- Idle mode and special circuitry for spikes killing during powering on and off
- Two voltage supervisors (digital and analog supplies)
- Automatic activation and deactivation sequences through an independent internal clock
- Enhanced ESD protections on card side (4 kV min.)
- Easy chaining for multiple card readers
- ISO 7816 compatibility.

APPLICATIONS

- Pay TV (multistandards conditional access system, videoguard, newsript)
- Multi-application smart card readers (banking, vending machine, electronic payment identification).

GENERAL DESCRIPTION

The TDA8001 is a complete, low-cost analog interface which can be positioned between an asynchronous smart card (ISO 7816) and a microcontroller. It is directly compatible with the new Datacom chip verifier.

The complete supply, protection and control functions are realized with only a few external components, making this product very attractive for consumer applications (see Chapter "Application information").

ORDERING INFORMATION

| TYPE NUMBER | PACKAGE | | |
|------------------------|---------|--|----------|
| | NAME | DESCRIPTION | VERSION |
| TDA8001; TDA8001A | DIP28 | plastic dual in-line package; 28 leads (600 mil) | SOT117-1 |
| TDA8001T; TDA8001AT | SO28 | plastic small outline package; 28 leads; body width 7.5 mm | SOT136-1 |

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QUICK REFERENCE DATA

| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|-----------|--|--|----------|------|----------|------------------|
| V_{DD} | supply voltage | | 6.7 | – | 18 | V |
| I_{DD} | supply current | idle mode; $V_{DD} = 12\text{ V}$ | – | 32 | – | mA |
| | | active modes; unloaded | – | 45 | – | mA |
| V_{th2} | threshold voltage on V_{SUP} | | 4.5 | – | 4.72 | V |
| V_{th4} | threshold voltage on V_{DD} | | 6 | – | 6.5 | V |
| V_{CC} | card supply voltage | including static and dynamic loads on 100 nF capacitor | 4.75 | 5.0 | 5.25 | V |
| I_{CC} | card supply current | operating | – | – | –100 | mA |
| | | detection | – | –150 | – | mA |
| | | limitation | – | – | –200 | mA |
| V_H | high voltage supply for V_{PP} | | – | – | 30 | V |
| V_{PP} | card programming voltage (only at TDA8001 and TDA8001T) (P = 5, 12.5, 15 and 21 V) | including static and dynamic loads on 100 nF capacitor | P – 2.5% | – | P + 2.5% | V |
| I_{PP} | programming current (read or write mode) | operating | – | – | –50 | mA |
| | | detection | – | –75 | – | mA |
| | | limitation | – | – | –100 | mA |
| SR | slew rate on V_{CC} and V_{PP} (rise and fall) | maximum load capacitor 150 nF | – | 0.38 | – | V/ μ s |
| t_{de} | deactivation cycle duration | | 75 | 100 | 125 | μ s |
| f_{clk} | clock frequency | | 0 | – | 8 | MHz |
| P_{tot} | continuous total power dissipation | TDA8001; $T_{amb} = +70\text{ }^\circ\text{C}$; see Fig.10 | – | – | 0.92 | W |
| | | TDA8001T; $T_{amb} = +70\text{ }^\circ\text{C}$; see Fig.11 | – | – | 2 | W |
| T_{amb} | operating ambient temperature | | 0 | – | +70 | $^\circ\text{C}$ |

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BLOCK DIAGRAM

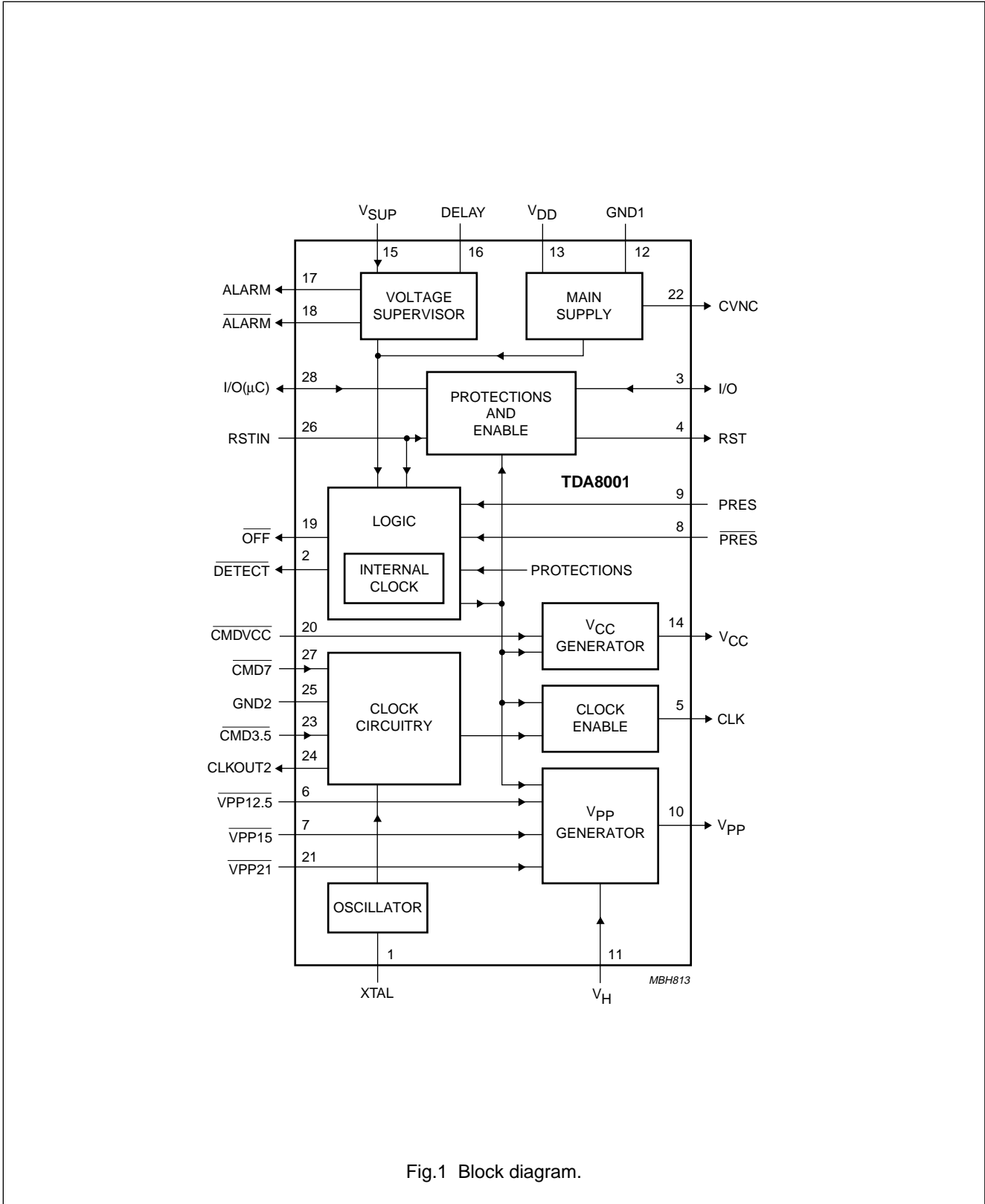


Fig.1 Block diagram.

Smart card interface

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PINNING

| SYMBOL | PIN | | DESCRIPTION |
|-------------------------------------|---------------------|-----------------------|---|
| | TDA8001 TDA8001T | TDA8001A TDA8001AT | |
| XTAL | 1 | 1 | crystal connection |
| $\overline{\text{DETECT}}$ | 2 | 2 | card extraction open collector output (active LOW) |
| I/O | 3 | 3 | data line to/from the card |
| RST | 4 | 4 | card reset output |
| CLK | 5 | 5 | clock output to the card |
| $\overline{\text{VPP12.5}}$ | 6 | – | control input for applying the 12.5 V programming voltage (active LOW) |
| n.c. | – | 6 | not connected |
| $\overline{\text{VPP15}}$ | 7 | – | control input for applying the 15 V programming voltage (active LOW) |
| n.c. | – | 7 | not connected |
| $\overline{\text{PRES}}$ | 8 | 8 | card presence contact input (active LOW) |
| PRES | 9 | 9 | card presence contact input (active HIGH) |
| V _{PP} | 10 | – | card programming voltage output |
| n.c. | – | 10 | not connected |
| V _H | 11 | 11 | HIGH voltage supply for V _{PP} generation |
| GND1 | 12 | 12 | ground 1 |
| V _{DD} | 13 | 13 | positive supply voltage |
| V _{CC} | 14 | 14 | card supply output voltage |
| V _{SUP} | 15 | 15 | voltage supervisor input |
| DELAY | 16 | 16 | external capacitor connection for delayed reset timing |
| ALARM | 17 | 17 | open-collector reset output for the microcontroller (active HIGH) |
| $\overline{\text{ALARM}}$ | 18 | 18 | open-collector reset output for the microcontroller (active LOW) |
| $\overline{\text{OFF}}$ | 19 | 19 | open-collector interrupt output to the microcontroller (active LOW) |
| $\overline{\text{CMDVCC}}$ | 20 | 20 | control input for applying supply voltage to the card (active LOW) |
| $\overline{\text{VPP21}}$ | 21 | – | control input for applying the 21 V programming voltage (active LOW) |
| n.c. | – | 21 | not connected |
| CVNC | 22 | 22 | internally generated 5 V reference, present when V _{DD} is on; to be decoupled externally (100 nF) |
| CMD3.5 or CDMTC | 23 | 23 | control input for having the crystal frequency divided-by-4 at pin CLK |
| CLKOUT2 | 24 | 24 | clock output to the microcontroller, or any other R4590 (crystal frequency divided by two) |
| GND2 | 25 | 25 | ground 2 |
| RSTIN | 26 | 26 | card reset input from the microcontroller (active HIGH) |
| $\overline{\text{CMD7}}$ or CDMS | 27 | 27 | control input for having the crystal frequency divided by 2 at pin CLK |
| I/O(μC) | 28 | 28 | data line to/from the microcontroller |

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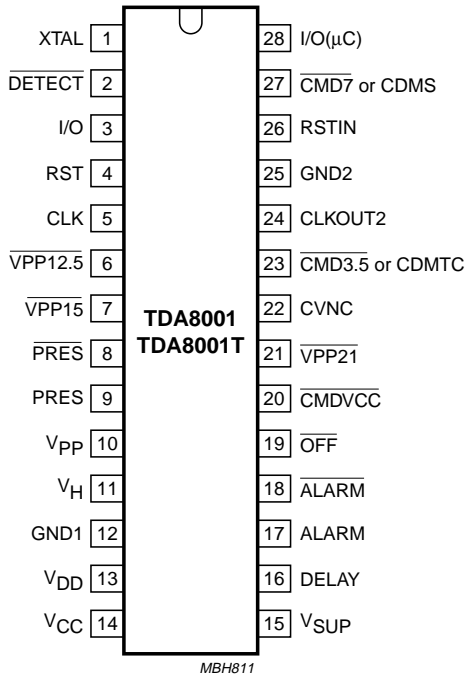


Fig.2 Pin configuration.

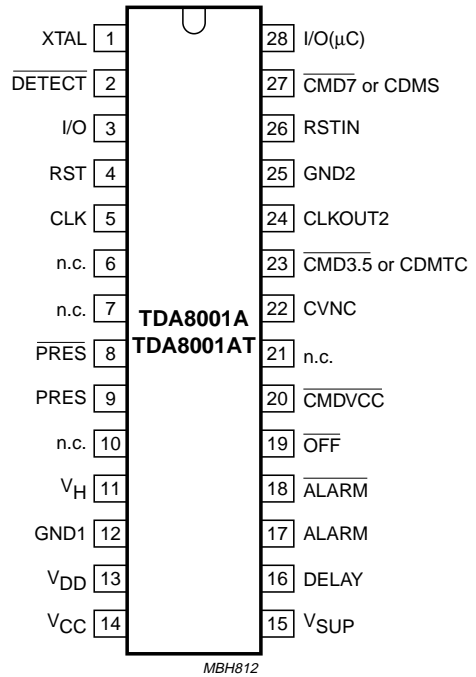


Fig.3 Pin configuration.

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FUNCTIONAL DESCRIPTION

Power supply

The circuit operates within a supply voltage range of 6.7 to 18 V. V_{DD} and GND are the supply pins. All card contacts remain inactive during power up or down.

POWER UP

The logic part is powered first and is in the reset condition until V_{DD} reaches V_{th1} . The sequencer is blocked until V_{DD} reaches $V_{th4} + V_{hys4}$.

POWER DOWN

When V_{DD} falls below V_{th4} , an automatic deactivation of the contacts is performed.

Voltage supervisor

This block surveys the 5 V supply of the microcontroller (V_{SUP}) in order to deliver a defined reset pulse and to avoid any transients on card contacts during power up or down of V_{SUP} . The voltage supervisor remains active even if V_{DD} is powered-down.

POWER ON

As long as V_{SUP} is below $V_{th2} + V_{hys2}$ the capacitor C_{DEL} , connected to pin DELAY, will be discharged. When V_{SUP} rises to the threshold level, C_{DEL} will be recharged. ALARM and \overline{ALARM} remain active, and the sequencer is blocked until the voltage on the DELAY line reaches V_{th3} .

POWER DOWN (see Fig.4)

If V_{SUP} falls below V_{th2} , C_{DEL} will be discharged, ALARM and \overline{ALARM} become active, and an automatic deactivation of the contacts is performed.

Clock circuitry (see Fig.5)

The clock signal (CLK) can be applied to the card in two different methods:

1. Generation by a crystal oscillator: the crystal, or the ceramic resonator (4 to 16 MHz) is connected to the XTAL pin.
2. Use of a signal frequency (up to 20 MHz), already present in the system and connected to the XTAL pin via a 10 nF capacitor (see Fig.14). In both cases the frequency is first divided-by-two.

If $\overline{CMD7}$ (respectively $\overline{CMD3.5}$) is LOW, the clock signal (its frequency again divided by two) is enabled and buffered before being fed to the CLK pin.

$\overline{CMD3.5}$ and internal ENRST are sampled in order to give the first clock pulse the correct width, and to avoid false pulses during frequency change.

The CLKOUT2 pins may be used to clock a microcontroller or an other TDA8001. The signal $\frac{1}{2} f_{xtal}$ is available when the circuit is powered up.

State diagram

Once activated, the circuit has six possible modes of operation:

- Idle
- Activation
- Read
- Write
- Deactivation
- Fault.

Figure 6 shows the way these modes are accessible.

IDLE MODE

After reset, the circuit enters the IDLE state. A minimum number of circuits are active while waiting for the microcontroller to start a session.

- All card contacts are inactive
- I/O(μ C) is high impedance
- Voltage generators are stopped
- Oscillator or XTAL input is running, delivering CLKOUT2
- Voltage supervisors are active.

The \overline{DETECT} line is HIGH if a card is present (PRES and \overline{PRES} active) and LOW if a card is not present. The OFF line is HIGH if no hardware problem is detected.

ACTIVATION SEQUENCE

From the IDLE mode, the circuit enters the ACTIVATION mode when the microcontroller sets the \overline{CMDVCC} line (active LOW). The I/O(μ C) signal must not be LOW. The internal circuitry is activated, the internal clock starts and the sequence according to ISO7816 is performed:

- V_{CC} rises from 0 to 5 V
- V_{PP} rises from 0 to 5 V and I/O is enabled
- CLK and RST are enabled.

The time interval between steps 1 and 2 is 16 μ s, and 64 μ s between steps 2 and 3 (see Fig.7).

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READ MODE

When the activation sequence is completed and, after the card has replied its Answer-to-Reset, the TDA8001 will be in the READ mode. Data is exchanged between the card and the microcontroller via the I/O line.

WRITE MODE

Cards with EPROM memory need a programming voltage (V_{PP}). When it is required to write to the internal memory of the card, the microcontroller sets one of the $\overline{VPP12.5}$, $\overline{VPP15}$ and $\overline{VPP21}$ lines LOW, according to the programming value given in the Answer-to-Reset. V_{PP} rises from 5 V to the selected value with a typical slew rate of $0.38 \text{ V}/\mu\text{s}$. In order to respect the ISO 7816 slopes, the circuit generates V_{PP} by charging and discharging an internal capacitor. The voltage on this capacitor is then amplified by a power stage gain of 5, powered via an external supply pin V_H (30 V max).

DEACTIVATION SEQUENCE (see Fig.8)

When the session is completed, the microcontroller sets the \overline{CMDVCC} line to its HIGH state. The circuit then executes an automatic deactivation sequence by counting the sequencer back:

- RST falls to LOW and CLK is stopped
- I/O(μC) becomes high impedance and V_{PP} falls to 0 V
- V_{CC} falls to 0 V.

The circuit returns to the IDLE mode on the next rising edge of the clock.

PROTECTIONS

Main fault conditions are monitored by the circuit:

- Short-circuit or overcurrent on V_{CC}
- Short-circuit or overcurrent on V_{PP}
- Card extraction during transaction
- Overheating problem
- V_{SUP} drop-out
- V_{DD} drop-out.

When one of these fault conditions is detected, the circuit pulls the interrupt line \overline{OFF} to its active LOW state and returns to the FAULT mode. The current on I/O is internally limited to 5 mA.

FAULT MODE (see Fig.9)

When a fault condition is written to the microcontroller via the \overline{OFF} line, the circuit initiates a deactivation sequence. After the deactivation sequence has been completed, the \overline{OFF} line is reset to its HIGH state after the microcontroller has reset the \overline{CMDVCC} line HIGH.

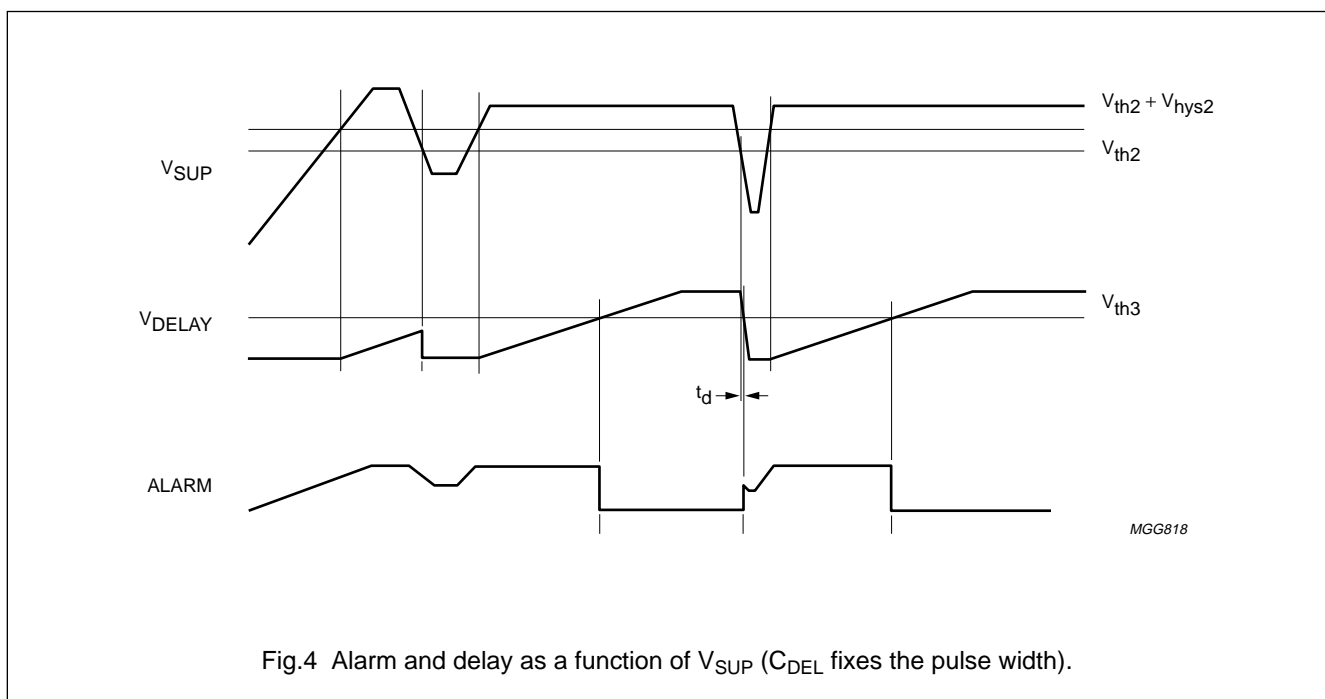
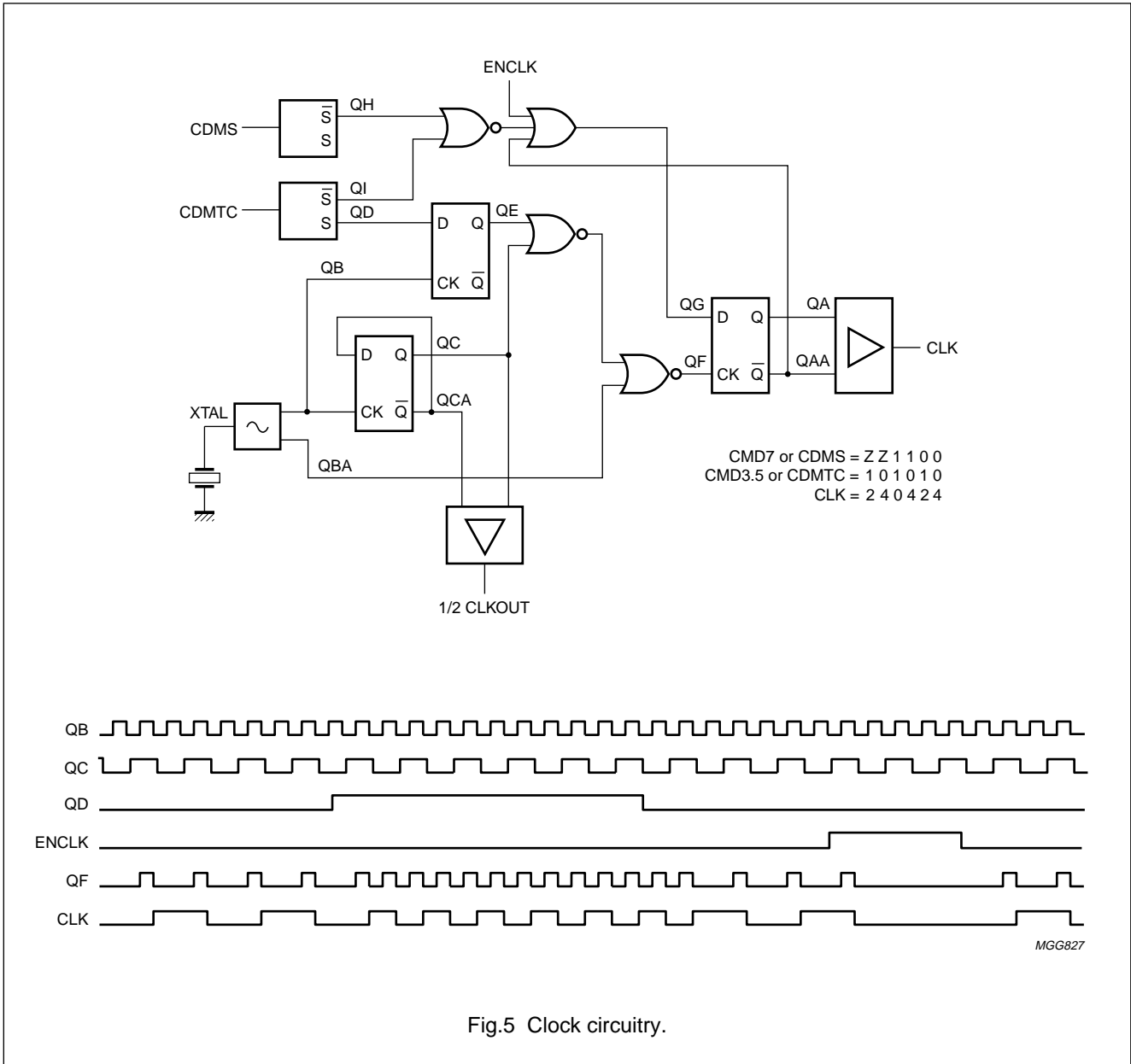


Fig.4 Alarm and delay as a function of V_{SUP} (C_{DEL} fixes the pulse width).

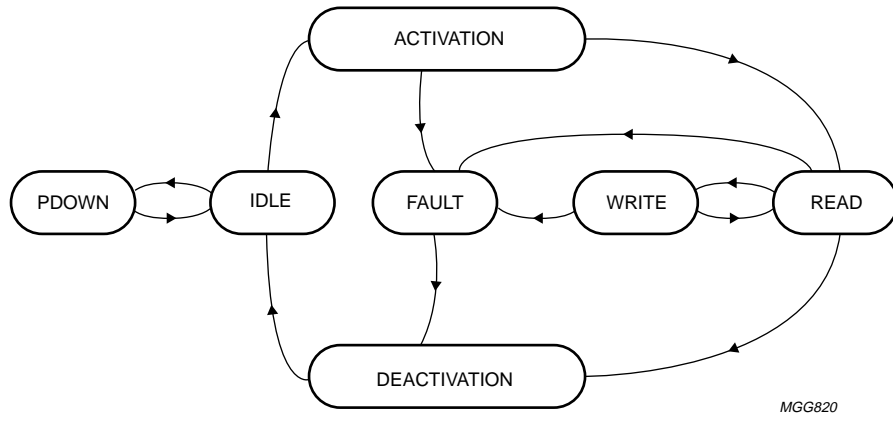
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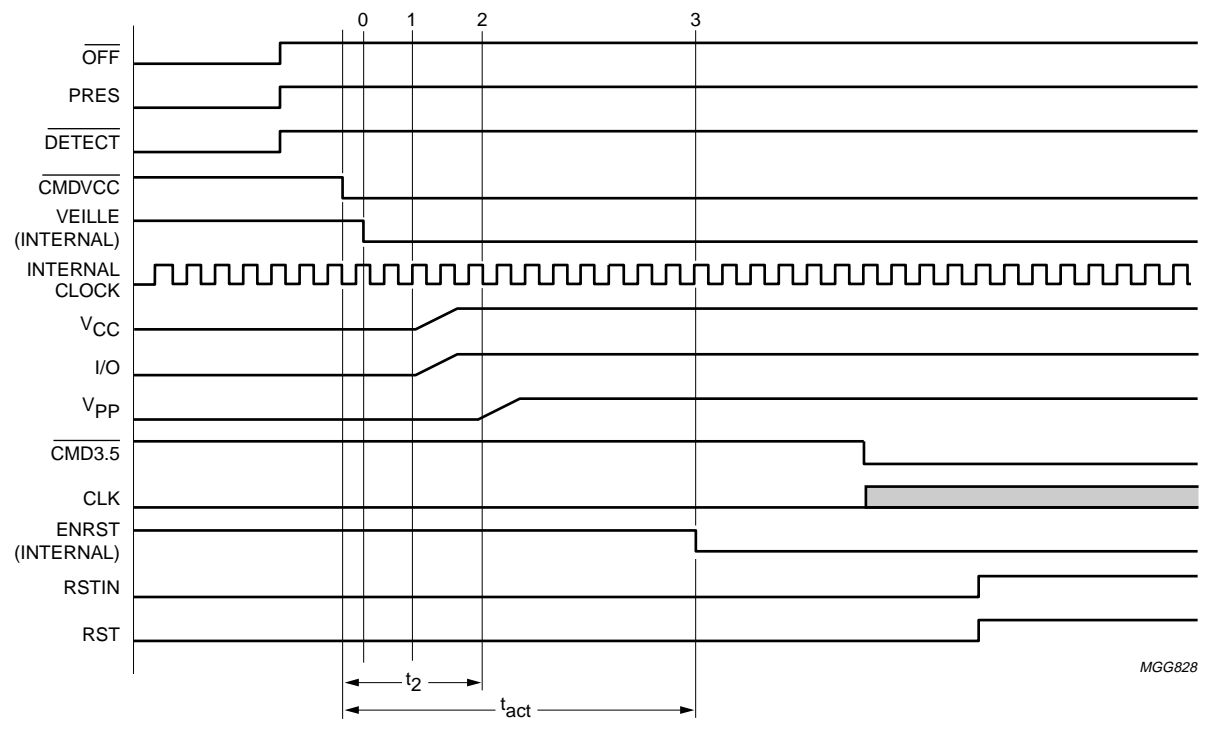
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MGG820

Fig.6 State diagram.



MGG828

Fig.7 Activation sequence.

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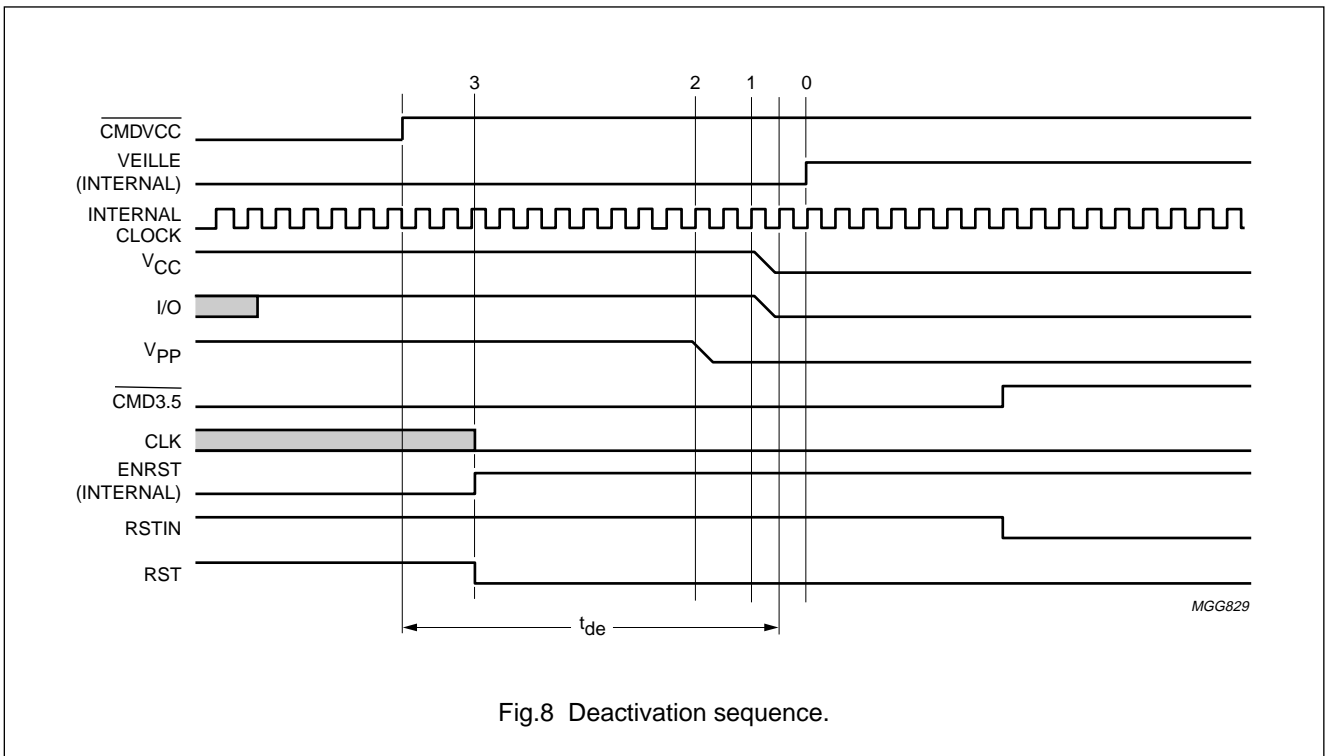


Fig.8 Deactivation sequence.

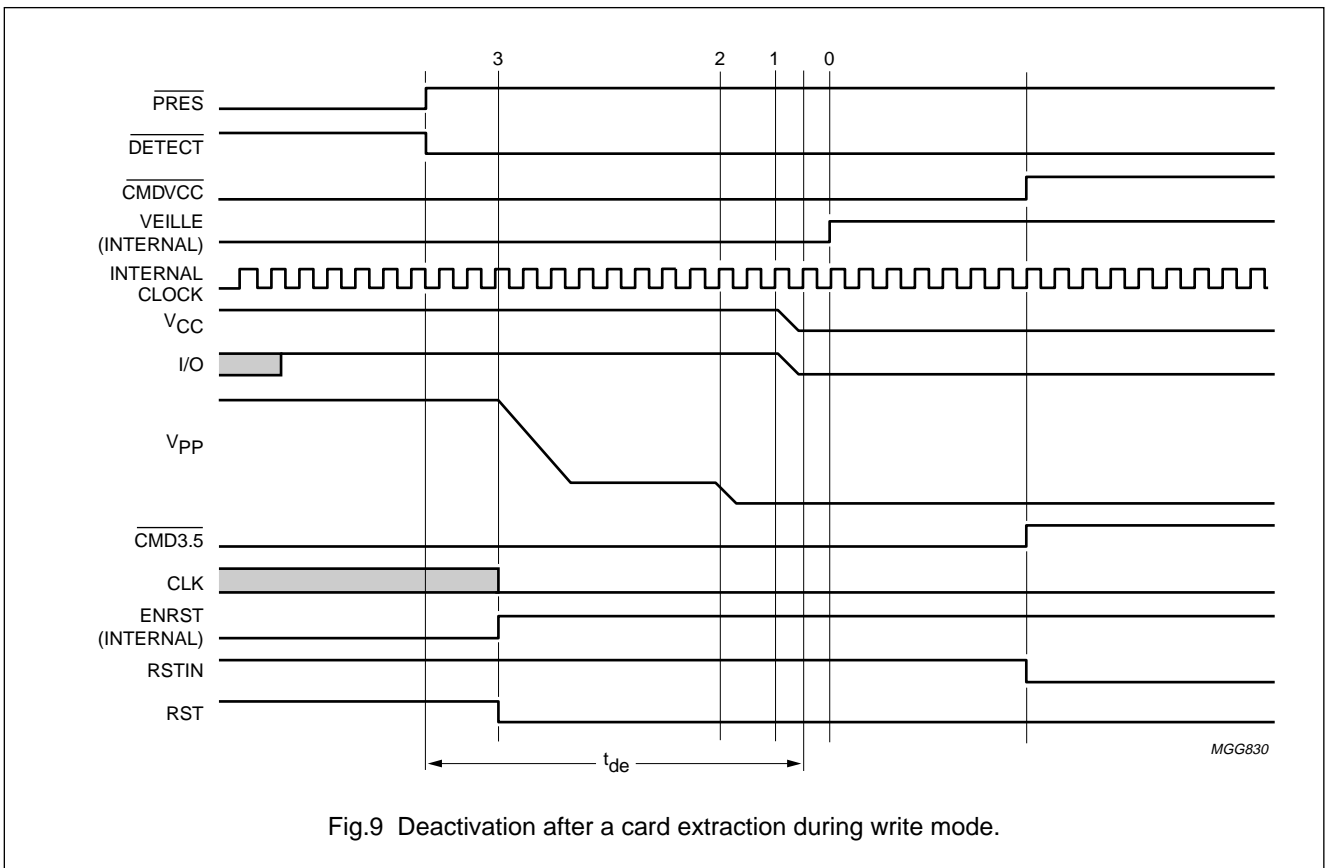


Fig.9 Deactivation after a card extraction during write mode.

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LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 134).

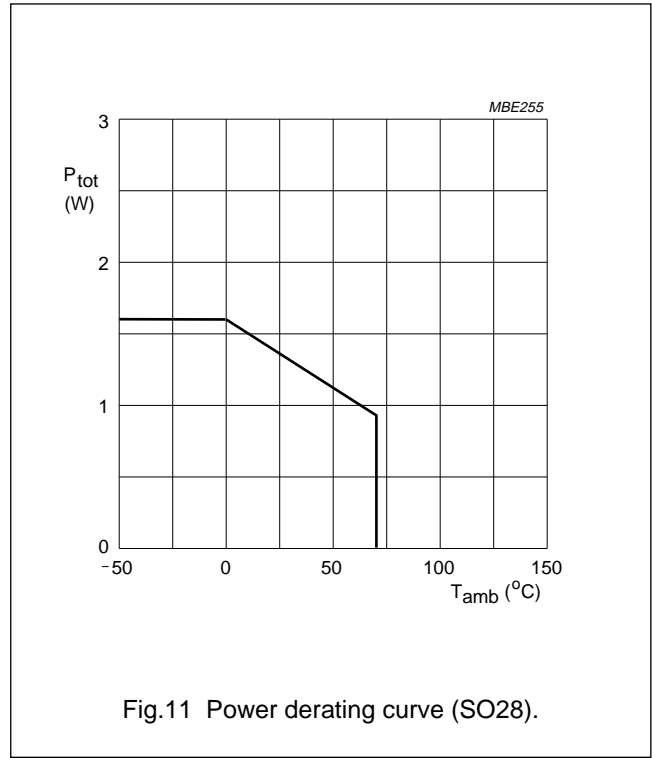
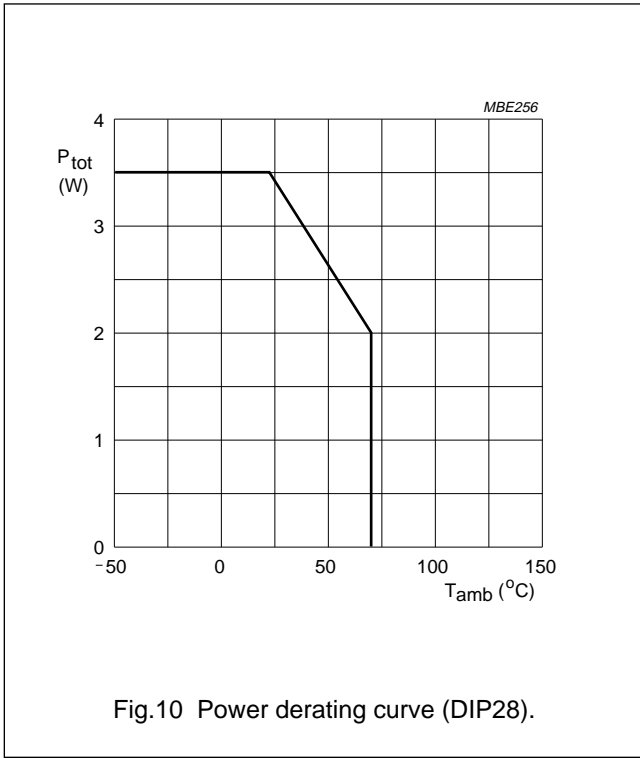
| SYMBOL | PARAMETER | CONDITIONS | MIN. | MAX. | UNIT |
|------------------|---|---|------|------------------|------|
| V _{DD} | supply voltage | | -0.3 | 18 | V |
| V _{x1} | voltage on pins $\overline{VPP21}$, $\overline{VPP15}$, $\overline{VPP12.5}$, \overline{PRES} , \overline{PRES} , \overline{CMDVCC} , \overline{OFF} , \overline{ALARM} , \overline{DETECT} and \overline{RSTIN} | | 0 | V _{DD} | V |
| V _H | voltage on pin V _H | | 0 | 30 | V |
| V _{PP} | voltage on pin V _{PP} | | 0 | V _H | V |
| V _{SUP} | voltage on pin V _{SUP} | | 0 | 12 | V |
| V _{x2} | voltage on pins \overline{ALARM} and \overline{DELAY} | | 0 | V _{SUP} | V |
| V _{x3} | voltage on pins XTAL, I/O(μ C), $\overline{CLKOUT2}$, $\overline{CMD7}$, $\overline{CMD3.5}$ and \overline{CVNC} | | 0 | 6.0 | V |
| V _{x4} | voltage on pins I/O, \overline{RST} , \overline{CLK} and V _{CC} | duration < 1 ms | 0 | 7.0 | V |
| P _{tot} | continuous total power dissipation | TDA8001; T _{amb} = +70 °C; note 1; see Fig.10 | - | 2 | W |
| | | TDA8001T; T _{amb} = +70 °C; note 1; see Fig.11 | - | 0.92 | W |
| T _{stg} | storage temperature | | -55 | +150 | °C |
| V _{es} | electrostatic voltage on pins I/O, V _{CC} , V _{PP} , \overline{RST} , \overline{CLK} , \overline{PRES} and \overline{PRES} | | -6 | +6 | kV |
| | electrostatic voltage on other pins | | -2 | +2 | kV |

Note

1. $P_{tot} = V_{DD} \times (I_{DD(unloaded)} + \sum I_{signals}) + I_{CC} \times (V_{DD} - V_{CC}) + \max.\{(V_H - V_{PP}) \times I_{PP(read)} + (V_H - V_{PP}) \times I_{PP(write)}\} + V_H \times I_{H(unloaded)} + V_{SUP} \times I_{SUP} + (V_{DD} - CVNC) \times I_{CVNC}$, where 'signals' means all signal pins, except supply pins.

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HANDLING

Every pin withstands the ESD test according to MIL-STD-883C class 3 for card contacts, class 2 for the remaining. Method 3015 (HBM 1500 Ω, 100 pF) 3 pulses positive and 3 pulse negative on each pin referenced to ground.

THERMAL CHARACTERISTICS

| SYMBOL | PARAMETER | VALUE | UNIT |
|---------------------|---|-------|------|
| R _{th j-a} | thermal resistance from junction to ambient in free air | | |
| | SOT117-1 | 30 | K/W |
| | SOT136-1 | 70 | K/W |

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CHARACTERISTICS

$V_{DD} = 12\text{ V}$; $V_H = 25\text{ V}$; $V_{SUP} = 5\text{ V}$; $T_{amb} = 25\text{ °C}$; unless otherwise specified.

| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|---|--|--------------------------------------|---------------|------|------|---------------|
| Supply | | | | | | |
| V_{DD} | supply voltage | | 6.7 | – | 18 | V |
| I_{DD} | supply current | idle mode; $V_{DD} = 8\text{ V}$ | 20 | 30 | 38 | mA |
| | | idle mode; $V_{DD} = 18\text{ V}$ | 22 | 34 | 42 | mA |
| | | active mode; unloaded | 35 | 45 | 55 | mA |
| V_{th1} | threshold voltage for power-on reset | | – | 3.0 | 4.0 | V |
| V_{th4} | threshold voltage on V_{DD} (falling) | | 6.0 | – | 6.5 | V |
| V_{hys4} | hysteresis on V_{th4} | | 50 | – | 200 | mV |
| Voltage supervisor | | | | | | |
| V_{SUP} | voltage supply for the supervisor | | – | 5.0 | – | V |
| I_{SUP} | input current at V_{SUP} | | – | 1.8 | 2.4 | mA |
| V_{th2} | threshold voltage on V_{SUP} (falling) | | 4.5 | – | 4.72 | V |
| V_{hys2} | hysteresis on V_{th2} | | 10 | – | 80 | mV |
| V_{th3} | threshold voltage on DELAY | | 2.35 | – | 2.65 | V |
| I_{DEL} | output current at DELAY | pin grounded (charge) | –5 | – | –2 | μA |
| | | $V_{DEL} = 4\text{ V}$ (discharge) | 6 | – | – | mA |
| V_{DEL} | voltage on pin DELAY | | – | – | 3.5 | V |
| ALARM, ALARM (open-collector outputs) | | | | | | |
| I_{OH} | HIGH level output current on pin ALARM | $V_{OH} = 5\text{ V}$ | – | – | 25 | μA |
| V_{OL} | LOW level output voltage on pin ALARM | $I_{OL} = 2\text{ mA}$ | – | – | 0.4 | V |
| I_{OL} | LOW level output current on pin ALARM | $V_{OL} = 0\text{ V}$ | – | – | –25 | μA |
| V_{OH} | HIGH level output voltage on pin ALARM | $I_{OH} = -2\text{ mA}$ | $V_{SUP} - 1$ | – | – | V |
| t_d | delay between V_{SUP} and ALARM | $C_{DEL} = 47\text{ nF}$; see Fig.4 | – | – | 10 | μs |
| t_{pulse} | ALARM pulse width | $C_{DEL} = 47\text{ nF}$ | 15 | – | 50 | ms |
| Interrupt lines OFF and DETECT (open-collector) | | | | | | |
| I_{OH} | HIGH level output current | $V_{OH} = 5\text{ V}$ | – | – | 25 | μA |
| V_{OL} | LOW level output voltage | $I_{OL} = 1\text{ mA}$ | – | – | 0.4 | V |
| Logic inputs (CMDVCC, VPP21, VPP15, VPP12.5, CMD7, CMD3.5, PRES, PRES and RSTIN); note 1 | | | | | | |
| V_{IL} | LOW level input voltage | | – | – | 0.8 | V |
| V_{IH} | HIGH level input voltage | | 1.5 | – | – | V |
| I_{IL} | LOW level input current | $V_{IL} = 0\text{ V}$ | – | – | –10 | μA |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|---|-----------------------------|--|-------------------|------|-------------------|------------------|
| I_{IH} | HIGH level input current | $V_{IH} = 5\text{ V}$ | – | – | 10 | μA |
| Reset output to the card (RST) | | | | | | |
| V_{IDLE} | output voltage in IDLE | | – | – | 0.4 | V |
| V_{OL} | LOW level output voltage | $I_{OL} = 200\ \mu\text{A}$ | – | – | 0.45 | V |
| V_{OH} | HIGH level output voltage | $I_{OH} = -200\ \mu\text{A}$ | 4.3 | – | V_{CC} | V |
| | | $I_{OH} = -10\ \mu\text{A}$ | $V_{CC} - 0.7$ | – | V_{CC} | V |
| t_{RST} | delay between RSTIN and RST | RST enabled; see Fig.7 | – | – | 2 | μs |
| Clock output to the card (CLK) | | | | | | |
| V_{IDLE} | output voltage in IDLE | | – | – | 0.4 | V |
| V_{OL} | LOW level output voltage | $I_{OL} = 200\ \mu\text{A}$ | – | – | 0.4 | V |
| V_{OH} | HIGH level output voltage | $I_{OH} = -200\ \mu\text{A}$ | 2.4 | – | V_{CC} | V |
| | | $I_{OH} = -20\ \mu\text{A}$ | $0.7V_{CC}$ | – | V_{CC} | V |
| | | $I_{OH} = -10\ \mu\text{A}$ | $V_{CC} - 0.7$ | – | V_{CC} | V |
| t_r | rise time | $C_L = 30\ \text{pF}$; note 2 | – | – | 14 | ns |
| t_f | fall time | $C_L = 30\ \text{pF}$; note 2 | – | – | 14 | ns |
| δ | duty factor | $C_L = 30\ \text{pF}$; note 2 | 45 | – | 55 | % |
| Card programming voltage (V_{PP}) | | | | | | |
| V_{PP} | output voltage | idle mode | – | – | 0.4 | V |
| | | read mode | $V_{CC} - 4\%$ | – | $V_{CC} + 4\%$ | V |
| | | write mode; $I_{PP} < 50\ \text{mA}$ | $P - 2.5\%^{(3)}$ | – | $P + 2.5\%^{(3)}$ | V |
| | | $\Delta I_{PP}/\Delta t < 40\ \text{mA}/100\ \text{ns}$; note 4 | $P - 2.5\%^{(3)}$ | – | $P + 2.5\%^{(3)}$ | V |
| I_{PP} | output current | active; from 0 to P ⁽³⁾ | – | – | –50 | mA |
| | | V_{PP} shorted to GND | – | – | –100 | mA |
| SR | slew rate | up or down | 0.3 | 0.4 | 0.5 | V/ μs |
| High voltage input (V_H) | | | | | | |
| V_H | input voltage | | – | – | 30 | V |
| I_H | input current at V_H | idle mode; active mode; unloaded | 4 | – | 6 | mA |
| | | $P = 5\ \text{V}$ | 5 | – | 9 | mA |
| | | $P = 12.5\ \text{V}$ | 6.5 | – | 10.5 | mA |
| | | $P = 15\ \text{V}$ | 7 | – | 11 | mA |
| | | $P = 21\ \text{V}$ | 8 | – | 12 | mA |
| $V_H - V_{PP}$ | voltage drop | | – | – | 2.2 | V |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|---|--|---|------|------|------------------------|------|
| Card supply voltage (V_{CC}) | | | | | | |
| V _{CC} | output voltage | idle mode; active mode | – | – | 0.4 | V |
| | | I _{CC} < 100 mA | 4.75 | – | 5.25 | V |
| | | ΔI _{PP} /Δt < 100 mA/100 ns; note 4 | 4.75 | – | 5.25 | V |
| I _{CC} | output current | V _{CC} from 0 to 5 V | – | – | –100 | mA |
| | | V _{CC} shorted to GND | – | – | –200 | mA |
| SR | slew rate | up or down | 0.3 | 0.4 | 0.5 | V/μs |
| 5 V reference output voltage (CVNC) | | | | | | |
| V _{CVNC} | output voltage at pin CVNC | | 4.5 | 5.0 | 5.5 | V |
| I _{CVNC} | output current at pin CVNC | | – | – | –50 | mA |
| Crystal connection (XTAL) | | | | | | |
| R _{xtal(neg)} | negative resistance at pin XTAL | 2 MHz < f _i < 16 MHz; note 5 | – | – | 300 | Ω |
| V _{xtal} | DC voltage at pin XTAL | | 3.0 | – | 4.0 | V |
| f _{xtal} | resonant frequency | | 4 | – | 16 | MHz |
| | external frequency | | 0 | – | 20 | MHz |
| Clock output (CLKOUT2) | | | | | | |
| f _{CLKOUT2} | frequency on CLKOUT2 | | 1 | – | 8 | MHz |
| V _{OL} | LOW level output voltage | I _{OL} = 2 mA | – | – | 0.4 | V |
| V _{OH} | HIGH level output voltage | I _{OH} = –200 μA | 3.0 | – | – | V |
| | | I _{OH} = –10 μA | 4.0 | – | – | V |
| t _r , t _f | rise and fall times | C _L = 15 pF; note 2 | – | – | 25 | ns |
| δ | duty factor | C _L = 15 pF; note 2 | 40 | – | 60 | % |
| Data line [I/O, I/O(μC)] | | | | | | |
| V _{OH} | HIGH level output voltage on pin I/O | 4.5 V < V _{SUP} < 5.5 V; 4.5 V < V _{I/O(μC)} < 5.5 V; I _{OH} = –20 μA | 4.0 | – | V _{CC} + 0.1 | V |
| | | 4.5 V < V _{SUP} < 5.5 V; 4.5 V < V _{I/O(μC)} < 5.5 V; I _{OH} = –200 μA | 2.4 | – | – | V |
| V _{OL} | LOW level output voltage on pin I/O | I _{I/O} = 1 mA; I/O(μC) grounded | – | – | 100 | mV |
| I _{IL} | LOW level input current on pin I/O(μC) | I/O(μC) grounded | – | – | –500 | μA |
| V _{OH} | HIGH level output voltage on pin I/O(μC) | 4.5 V < V _{I/O} < 5.5 V | 4.0 | – | V _{SUP} + 0.2 | V |
| V _{OL} | LOW level output voltage on pin I/O(μC) | I _{I/O(μC)} = 1 mA; I/O grounded | – | – | 70 | mV |
| I _{IL} | LOW level input current on pin I/O | I/O grounded | – | – | –500 | μA |

Smart card interface

TDA8001

| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|---------------------------------|--|---|------|------|------|------|
| V _{IDLE} | voltage on pin I/O outside a session | | – | – | 0.4 | V |
| Z _{IDLE} | impedance on pin I/O(μC) outside a session | | 10 | – | – | MΩ |
| R _{pu} | internal pull-up resistance between pin I/O and V _{CC} | | 8 | 10 | 12 | kΩ |
| t _r , t _f | rise and fall times | C _i = C _o = 30 pF | – | – | 0.5 | μs |
| Protections | | | | | | |
| T _{sd} | shut-down local temperature | | – | 135 | – | °C |
| I _{CC(sd)} | shut-down current at V _{CC} | | – | –150 | – | mA |
| I _{PP(sd)} | shut-down current at V _{PP} | | – | –75 | – | mA |
| I _{I/O(lim)} | current limitation on pin I/O | from I/O to I/O(μC) | 3 | – | 5 | mA |
| Timing | | | | | | |
| t _{act} | activation sequence duration | see Fig.7 | – | 110 | – | μs |
| t _{de} | deactivation sequence duration | see Fig.8 | – | 100 | – | μs |
| t ₃ | start of the window for sending CLK to the card | | – | – | 70 | μs |
| t ₅ | end of the window for sending CLK to the card | | 80 | – | – | μs |
| t _{st} | maximum pulse width on CMDV _{CC} before V _{CC} starts rising | | – | – | 30 | μs |

Notes

1. Pins $\overline{\text{CMDVCC}}$, $\overline{\text{VPP21}}$, $\overline{\text{VPP15}}$, $\overline{\text{VPP12.5}}$, $\overline{\text{CMD7}}$, $\overline{\text{CMD3.5}}$ and $\overline{\text{PRES}}$ are active LOW; pins RSTIN and PRES are active HIGH.
2. The transition time and duty cycle definitions are shown in Fig.12; $\delta = \frac{t_1}{t_1 + t_2}$.
3. P is the card programming voltage set by pin $\overline{\text{VPP12.5}}$, $\overline{\text{VPP15}}$ or $\overline{\text{VPP21}}$.
4. The tests for dynamic response of both V_{PP} and V_{CC} are performed at 1 Hz, 10 kHz, 100 kHz and 1 MHz, with a capacitive load of 100 nF.
5. This condition ensures proper starting of the oscillator with crystals having a series resistance up to 100 Ω.

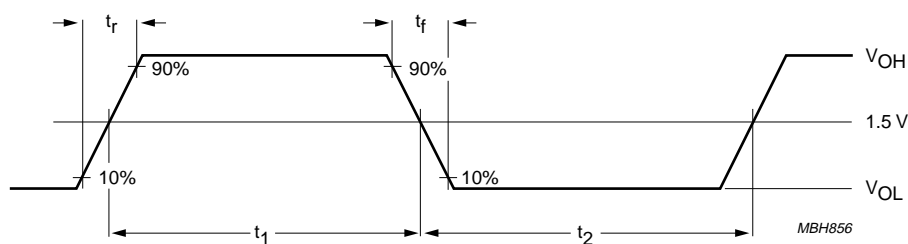


Fig.12 Definition of transition times.

Smart card interface

TDA8001

INTERNAL PIN CONFIGURATION

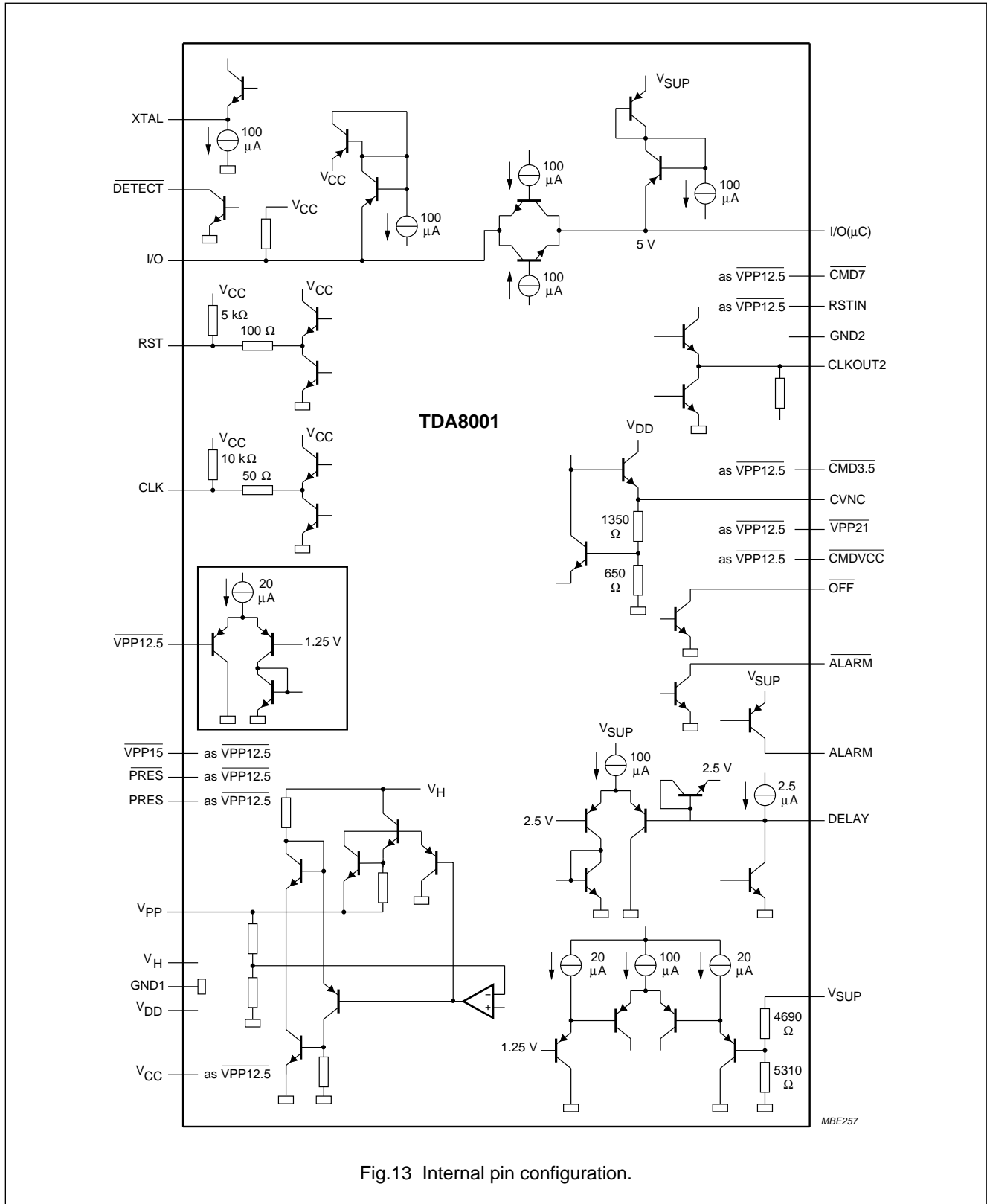


Fig.13 Internal pin configuration.

Smart card interface

TDA8001

APPLICATION INFORMATION

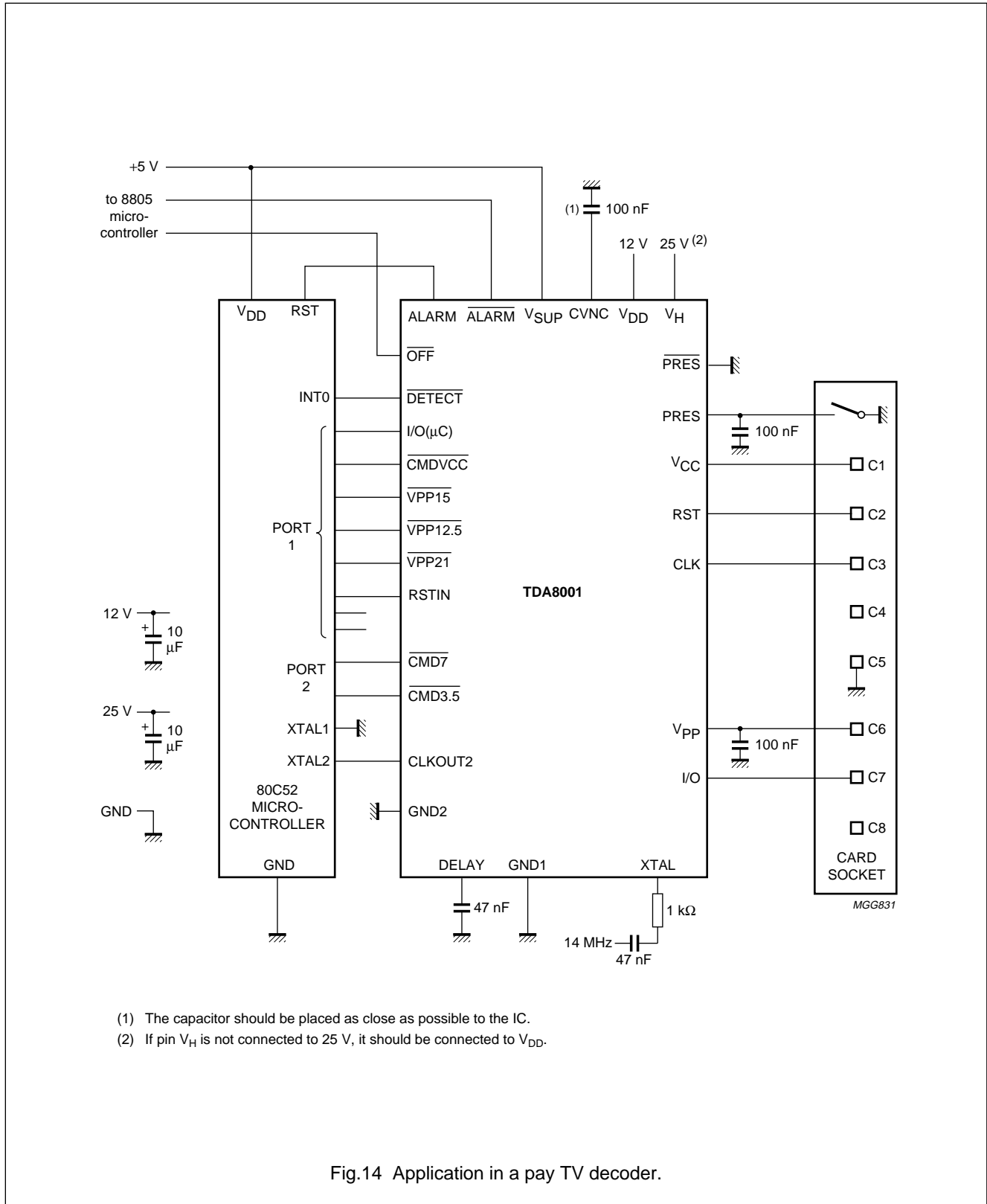


Fig.14 Application in a pay TV decoder.

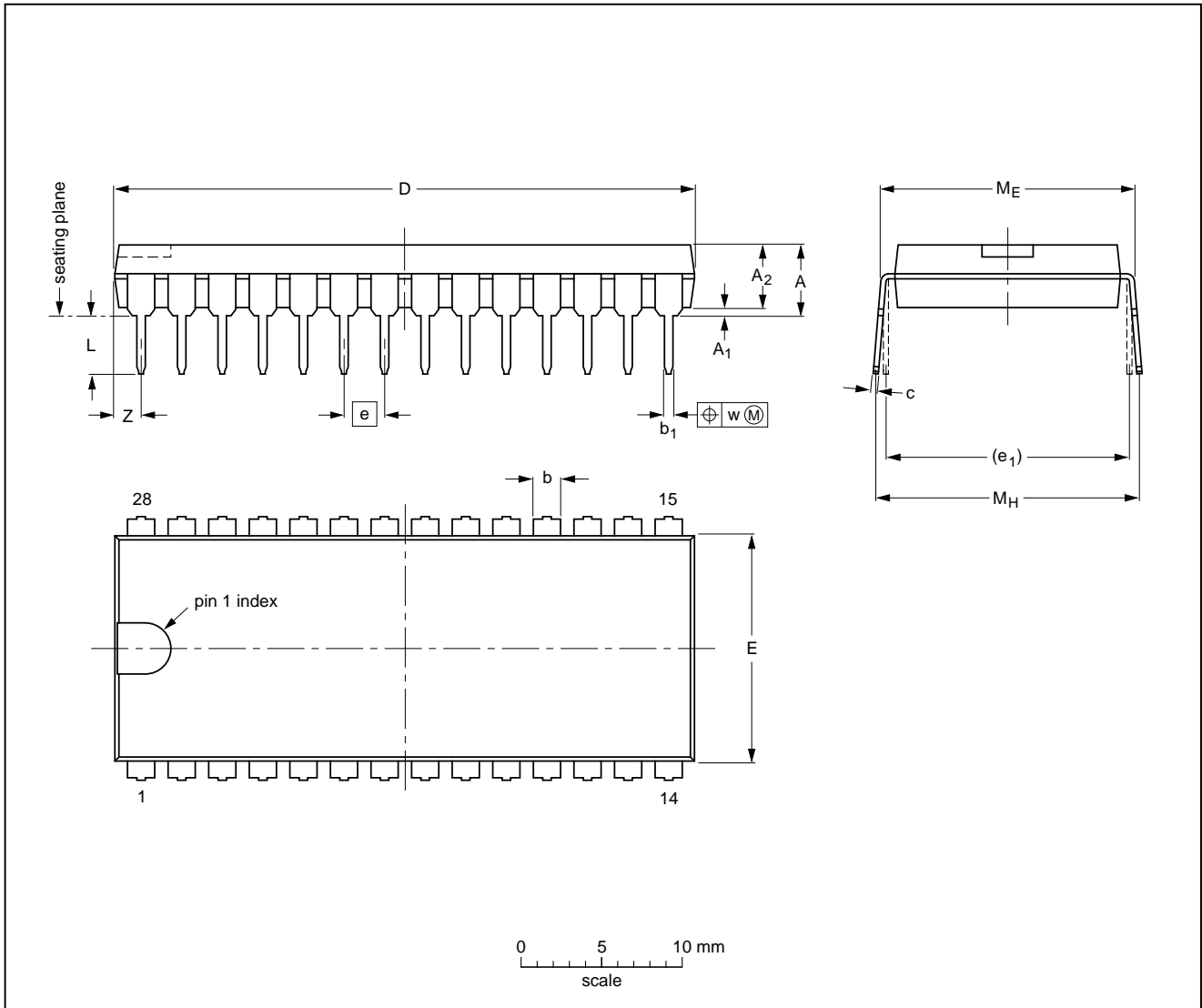
Smart card interface

TDA8001

PACKAGE OUTLINES

DIP28: plastic dual in-line package; 28 leads (600 mil)

SOT117-1



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

| UNIT | A max. | A ₁ min. | A ₂ max. | b | b ₁ | c | D ⁽¹⁾ | E ⁽¹⁾ | e | e ₁ | L | M _E | M _H | w | Z ⁽¹⁾ max. |
|--------|--------|---------------------|---------------------|----------------|----------------|----------------|------------------|------------------|------|----------------|--------------|----------------|----------------|------|-----------------------|
| mm | 5.1 | 0.51 | 4.0 | 1.7 1.3 | 0.53 0.38 | 0.32 0.23 | 36.0 35.0 | 14.1 13.7 | 2.54 | 15.24 | 3.9 3.4 | 15.80 15.24 | 17.15 15.90 | 0.25 | 1.7 |
| inches | 0.20 | 0.020 | 0.16 | 0.066 0.051 | 0.020 0.014 | 0.013 0.009 | 1.41 1.34 | 0.56 0.54 | 0.10 | 0.60 | 0.15 0.13 | 0.62 0.60 | 0.68 0.63 | 0.01 | 0.067 |

Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

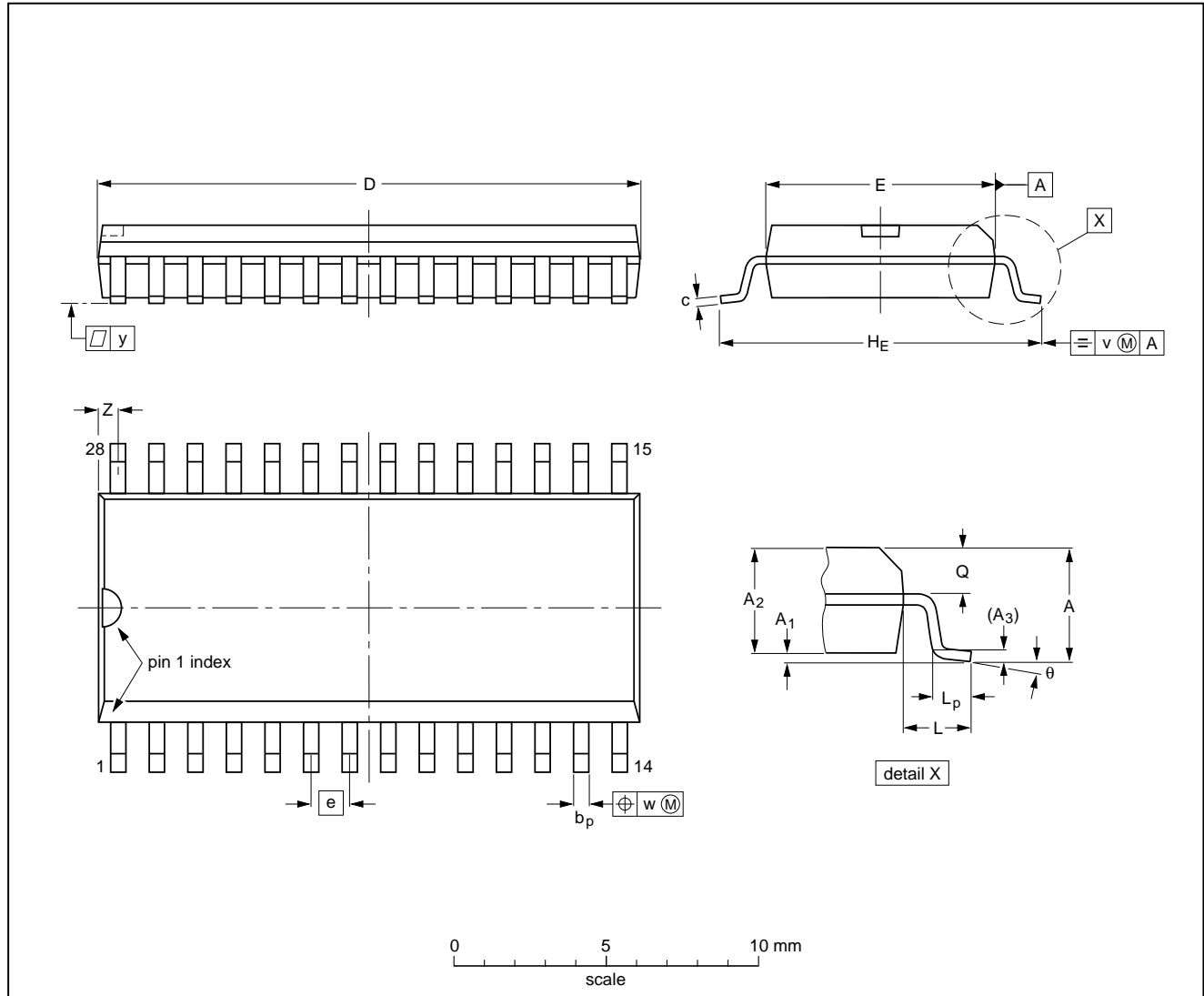
| OUTLINE VERSION | REFERENCES | | | | EUROPEAN PROJECTION | ISSUE DATE |
|-----------------|------------|----------|------|--|---------------------|----------------------|
| | IEC | JEDEC | EIAJ | | | |
| SOT117-1 | 051G05 | MO-015AH | | | | 92-11-17 95-01-14 |

Smart card interface

TDA8001

SO28: plastic small outline package; 28 leads; body width 7.5 mm

SOT136-1



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

| UNIT | A max. | A ₁ | A ₂ | A ₃ | b _p | c | D ⁽¹⁾ | E ⁽¹⁾ | e | H _E | L | L _p | Q | v | w | y | Z ⁽¹⁾ | θ |
|--------|--------|----------------|----------------|----------------|----------------|----------------|------------------|------------------|-------|----------------|-------|----------------|----------------|------|------|-------|------------------|----------|
| mm | 2.65 | 0.30 0.10 | 2.45 2.25 | 0.25 | 0.49 0.36 | 0.32 0.23 | 18.1 17.7 | 7.6 7.4 | 1.27 | 10.65 10.00 | 1.4 | 1.1 0.4 | 1.1 1.0 | 0.25 | 0.25 | 0.1 | 0.9 0.4 | 8° 0° |
| inches | 0.10 | 0.012 0.004 | 0.096 0.089 | 0.01 | 0.019 0.014 | 0.013 0.009 | 0.71 0.69 | 0.30 0.29 | 0.050 | 0.42 0.39 | 0.055 | 0.043 0.016 | 0.043 0.039 | 0.01 | 0.01 | 0.004 | 0.035 0.016 | |

Note

1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.

| OUTLINE VERSION | REFERENCES | | | | EUROPEAN PROJECTION | ISSUE DATE |
|-----------------|------------|----------|------|--|---------------------|----------------------|
| | IEC | JEDEC | EIAJ | | | |
| SOT136-1 | 075E06 | MS-013AE | | | | 91-08-13 95-01-24 |

Smart card interface

TDA8001

SOLDERING

Introduction

There is no soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and surface mounted components are mixed on one printed-circuit board. However, wave soldering is not always suitable for surface mounted ICs, or for printed-circuits with high population densities. In these situations reflow soldering is often used.

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our "IC Package Databook" (order code 9398 652 90011).

DIP

SOLDERING BY DIPPING OR BY WAVE

The maximum permissible temperature of the solder is 260 °C; solder at this temperature must not be in contact with the joint for more than 5 seconds. The total contact time of successive solder waves must not exceed 5 seconds.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified maximum storage temperature ($T_{stg\ max}$). If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

REPAIRING SOLDERED JOINTS

Apply a low voltage soldering iron (less than 24 V) to the lead(s) of the package, below the seating plane or not more than 2 mm above it. If the temperature of the soldering iron bit is less than 300 °C it may remain in contact for up to 10 seconds. If the bit temperature is between 300 and 400 °C, contact may be up to 5 seconds.

SO

REFLOW SOLDERING

Reflow soldering techniques are suitable for all SO packages.

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several techniques exist for reflowing; for example, thermal conduction by heated belt. Dwell times vary between 50 and 300 seconds depending on heating method. Typical reflow temperatures range from 215 to 250 °C.

Preheating is necessary to dry the paste and evaporate the binding agent. Preheating duration: 45 minutes at 45 °C.

WAVE SOLDERING

Wave soldering techniques can be used for all SO packages if the following conditions are observed:

- A double-wave (a turbulent wave with high upward pressure followed by a smooth laminar wave) soldering technique should be used.
- The longitudinal axis of the package footprint must be parallel to the solder flow.
- The package footprint must incorporate solder thieves at the downstream end.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Maximum permissible solder temperature is 260 °C, and maximum duration of package immersion in solder is 10 seconds, if cooled to less than 150 °C within 6 seconds. Typical dwell time is 4 seconds at 250 °C.

A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

REPAIRING SOLDERED JOINTS

Fix the component by first soldering two diagonally-opposite end leads. Use only a low voltage soldering iron (less than 24 V) applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C. When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320 °C.

Smart card interface

TDA8001

DEFINITIONS

| | |
|---|---|
| Data sheet status | |
| Objective specification | This data sheet contains target or goal specifications for product development. |
| Preliminary specification | This data sheet contains preliminary data; supplementary data may be published later. |
| Product specification | This data sheet contains final product specifications. |
| Limiting values | |
| Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability. | |
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Philips Semiconductors – a worldwide company

Argentina: see South America

Australia: 34 Waterloo Road, NORTH RYDE, NSW 2113,
Tel. +61 2 9805 4455, Fax. +61 2 9805 4466

Austria: Computerstr. 6, A-1101 WIEN, P.O. Box 213,
Tel. +43 1 60 101, Fax. +43 1 60 101 1210

Belarus: Hotel Minsk Business Center, Bld. 3, r. 1211, Volodarski Str. 6,
220050 MINSK, Tel. +375 172 200 733, Fax. +375 172 200 773

Belgium: see The Netherlands

Brazil: see South America

Bulgaria: Philips Bulgaria Ltd., Energoproject, 15th floor,
51 James Bourchier Blvd., 1407 SOFIA,
Tel. +359 2 689 211, Fax. +359 2 689 102

Canada: PHILIPS SEMICONDUCTORS/COMPONENTS,
Tel. +1 800 234 7381

China/Hong Kong: 501 Hong Kong Industrial Technology Centre,
72 Tat Chee Avenue, Kowloon Tong, HONG KONG,
Tel. +852 2319 7888, Fax. +852 2319 7700

Colombia: see South America

Czech Republic: see Austria

Denmark: Prags Boulevard 80, PB 1919, DK-2300 COPENHAGEN S,
Tel. +45 32 88 2636, Fax. +45 31 57 1949

Finland: Sinikalliontie 3, FIN-02630 ESPOO,
Tel. +358 9 615800, Fax. +358 9 61580/xxx

France: 4 Rue du Port-aux-Vins, BP317, 92156 SURESNES Cedex,
Tel. +33 1 40 99 6161, Fax. +33 1 40 99 6427

Germany: Hammerbrookstraße 69, D-20097 HAMBURG,
Tel. +49 40 23 53 60, Fax. +49 40 23 536 300

Greece: No. 15, 25th March Street, GR 17778 TAVROS/ATHENS,
Tel. +30 1 4894 339/239, Fax. +30 1 4814 240

Hungary: see Austria

India: Philips INDIA Ltd, Shivsagar Estate, A Block, Dr. Annie Besant Rd.
Worli, MUMBAI 400 018, Tel. +91 22 4938 541, Fax. +91 22 4938 722

Indonesia: see Singapore

Ireland: Newstead, Clonskeagh, DUBLIN 14,
Tel. +353 1 7640 000, Fax. +353 1 7640 200

Israel: RAPAC Electronics, 7 Kehilat Saloniki St, TEL AVIV 61180,
Tel. +972 3 645 0444, Fax. +972 3 649 1007

Italy: PHILIPS SEMICONDUCTORS, Piazza IV Novembre 3,
20124 MILANO, Tel. +39 2 6752 2531, Fax. +39 2 6752 2557

Japan: Philips Bldg 13-37, Kohnan 2-chome, Minato-ku, TOKYO 108,
Tel. +81 3 3740 5130, Fax. +81 3 3740 5077

Korea: Philips House, 260-199 Itaewon-dong, Yongsan-ku, SEOUL,
Tel. +82 2 709 1412, Fax. +82 2 709 1415

Malaysia: No. 76 Jalan Universiti, 46200 PETALING JAYA, SELANGOR,
Tel. +60 3 750 5214, Fax. +60 3 757 4880

Mexico: 5900 Gateway East, Suite 200, EL PASO, TEXAS 79905,
Tel. +9-5 800 234 7381

Middle East: see Italy

Netherlands: Postbus 90050, 5600 PB EINDHOVEN, Bldg. VB,
Tel. +31 40 27 82785, Fax. +31 40 27 88399

New Zealand: 2 Wagener Place, C.P.O. Box 1041, AUCKLAND,
Tel. +64 9 849 4160, Fax. +64 9 849 7811

Norway: Box 1, Manglerud 0612, OSLO,
Tel. +47 22 74 8000, Fax. +47 22 74 8341

Philippines: Philips Semiconductors Philippines Inc.,
106 Valero St. Salcedo Village, P.O. Box 2108 MCC, MAKATI,
Metro MANILA, Tel. +63 2 816 6380, Fax. +63 2 817 3474

Poland: Ul. Lukiska 10, PL 04-123 WARSZAWA,
Tel. +48 22 612 2831, Fax. +48 22 612 2327

Portugal: see Spain

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Russia: Philips Russia, Ul. Usatcheva 35A, 119048 MOSCOW,
Tel. +7 095 247 9145, Fax. +7 095 247 9144

Singapore: Lorong 1, Toa Payoh, SINGAPORE 1231,
Tel. +65 350 2538, Fax. +65 251 6500

Slovakia: see Austria

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South Africa: S.A. PHILIPS Pty Ltd., 195-215 Main Road Martindale,
2092 JOHANNESBURG, P.O. Box 7430 Johannesburg 2000,
Tel. +27 11 470 5911, Fax. +27 11 470 5494

South America: Rua do Rocio 220, 5th floor, Suite 51,
04552-903 São Paulo, SÃO PAULO - SP, Brazil,
Tel. +55 11 821 2333, Fax. +55 11 829 1849

Spain: Balmes 22, 08007 BARCELONA,
Tel. +34 3 301 6312, Fax. +34 3 301 4107

Sweden: Kottbygatan 7, Akalla, S-16485 STOCKHOLM,
Tel. +46 8 632 2000, Fax. +46 8 632 2745

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Tel. +41 1 488 2686, Fax. +41 1 481 7730

Taiwan: PHILIPS TAIWAN Ltd., 23-30F, 66,
Chung Hsiao West Road, Sec. 1, P.O. Box 22978,
TAIPEI 100, Tel. +886 2 382 4443, Fax. +886 2 382 4444

Thailand: PHILIPS ELECTRONICS (THAILAND) Ltd.,
209/2 Sanpavuth-Bangna Road Prakanong, BANGKOK 10260,
Tel. +66 2 745 4090, Fax. +66 2 398 0793

Turkey: Talatpasa Cad. No. 5, 80640 GÜLTEPE/ISTANBUL,
Tel. +90 212 279 2770, Fax. +90 212 282 6707

Ukraine: PHILIPS UKRAINE, 4 Patrice Lumumba str., Building B, Floor 7,
252042 KIEV, Tel. +380 44 264 2776, Fax. +380 44 268 0461

United Kingdom: Philips Semiconductors Ltd., 276 Bath Road, Hayes,
MIDDLESEX UB3 5BX, Tel. +44 181 730 5000, Fax. +44 181 754 8421

United States: 811 East Arques Avenue, SUNNYVALE, CA 94088-3409,
Tel. +1 800 234 7381

Uruguay: see South America

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Yugoslavia: PHILIPS, Trg N. Pasica 5/v, 11000 BEOGRAD,
Tel. +381 11 625 344, Fax. +381 11 635 777

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