ROMless 8-bit microcontroller OM5202

DESCRIPTION

The OM5202 8-Bit ROMless Microcontroller is manufactured in an advanced CMOS process and is a derivative of the 80C51 microcontroller family. The OM5202 has the same instruction set as the 80C51.

See also:
– OM5232 — 8K bytes mask programmable ROM
– OM5234 — 16k bytes mask programmable ROM
– OM5238 — 32K bytes mask programmable ROM

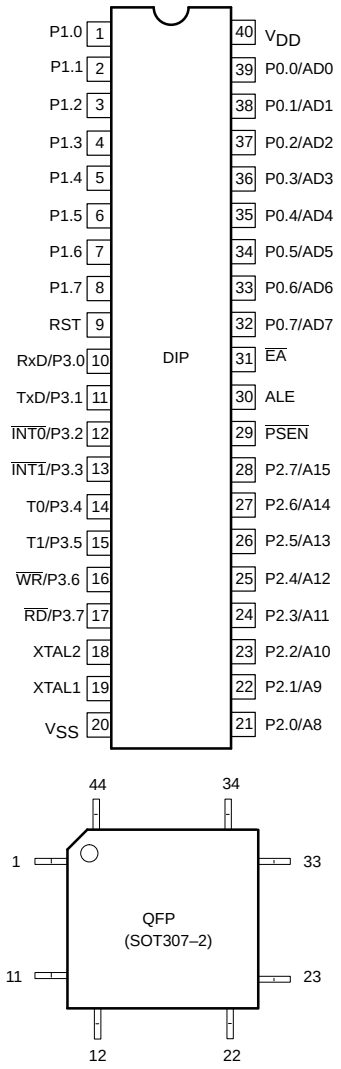
This device provides architectural enhancements that make it applicable in a variety of applications for general control systems. The OM5202 contains no read-only program memory, a volatile 256 × 8 read/write data memory, four 8-bit I/O ports, two 16-bit timer/event counters (identical to the timers of the 80C51), a multi-source, two-priority-level, nested interrupt structure, UART and on-chip oscillator and timing circuits. The OM5202 can be expanded with standard TTL compatible memories and logic.

The device also functions as an arithmetic processor having facilities for both binary and BCD arithmetic plus bit-handling capabilities. The instruction set consists of over 100 instructions: 49 one-byte, 45 two-byte and 17 three-byte. With a 16MHz crystal, 58% of the instructions are executed in 0.75µs and 40% in 1.5µs. Multiply and divide instructions require 3µs.

FEATURES

- 80C51 central processing unit
- no internal ROM, externally up to 64k bytes
- 256 × 8 RAM, expandable externally to 64k bytes
- Two standard 16-bit timer/counters
- Four 8-bit I/O ports
- Two open drain I/O's (P1.6, P1.7)
- Full-duplex UART facilities
- Power control modes
  - Idle mode
  - Power-down mode
- Operating frequency range: 1.2 to 16 MHz
- Operating ambient temperature range: 0 to +70°C

PIN CONFIGURATIONS



SEE PAGE 2 FOR QFP PIN FUNCTIONS.

PART NUMBER SELECTION

PHILIPS PART ORDER NUMBER PART MARKING	PACKAGE NUMBER	TEMPERATURE RANGE °C, PACKAGE	FREQUENCY MHz
OM5202/FBP	SOT129	0 to +70, Plastic Dual In–line Package, 40 leads	1.2 to 16
OM5202/FBB	SOT307–2	0 to +70, Plastic Quad Flat Pack, 44 leads	1.2 to 16

EQUIVALENT TYPES

Details are as specified by the data sheet for the equivalent type:

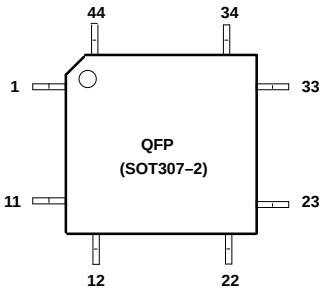
OM5202 = P80C652 without I^2C function.

OM5232 = P83C652 without I^2C function.

OM5234 = P83C654 without I^2C function.

OM5238 = P83C528 without I^2C function.

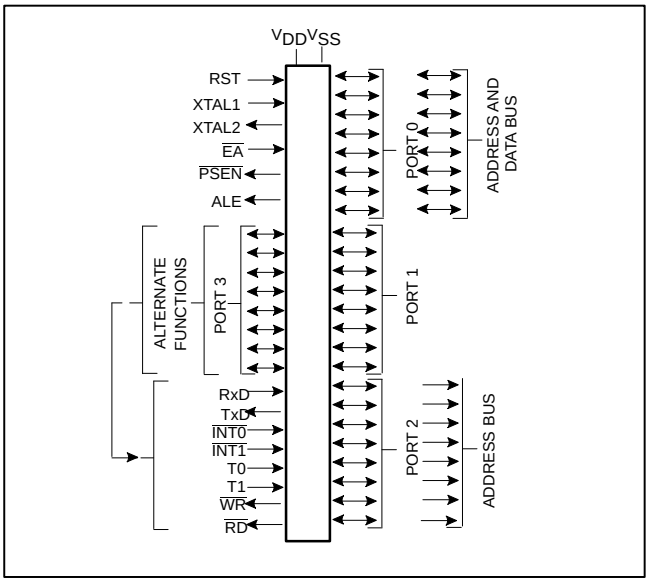
QFP PIN FUNCTIONS



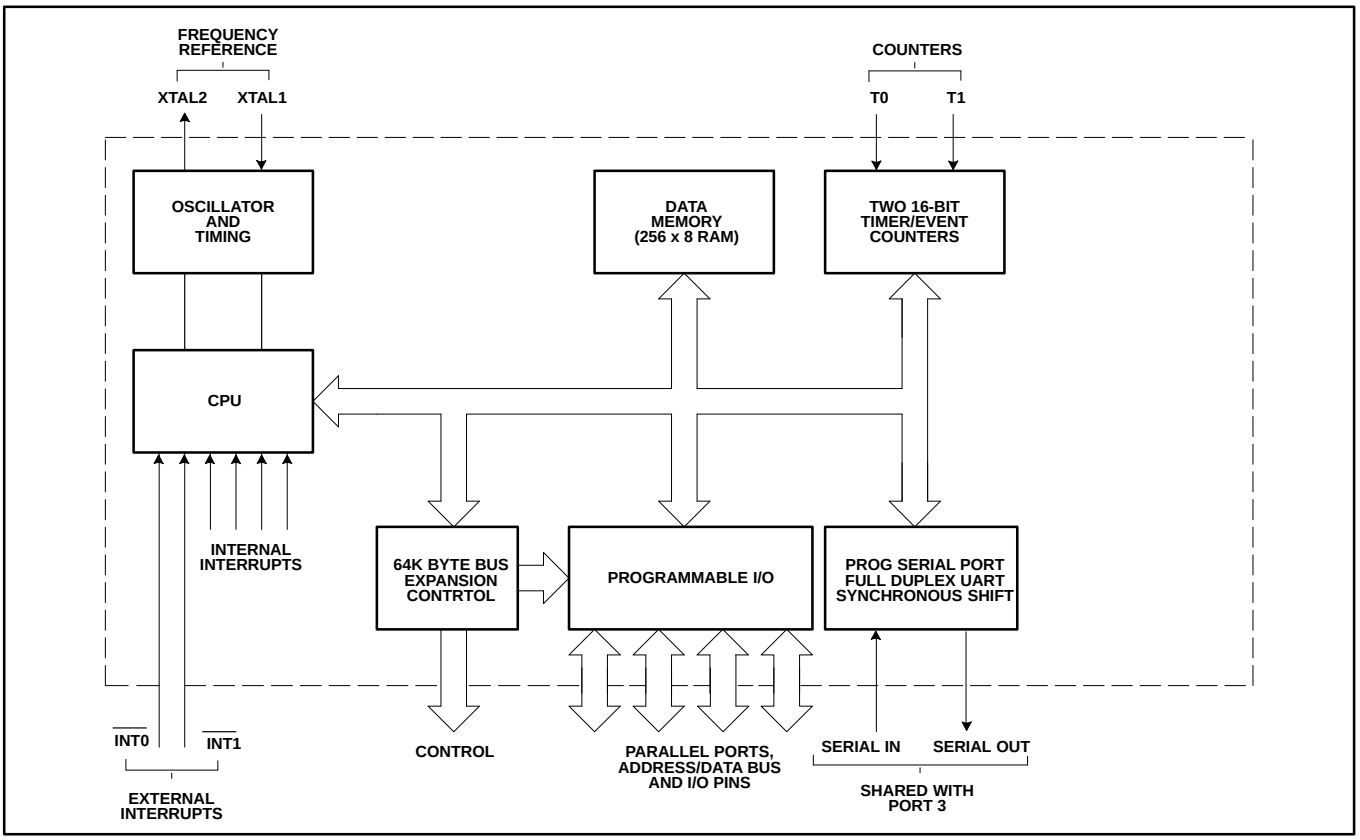
Pin	Function	Pin	Function	Pin	Function
1	P1.5	16	V_{SS1}	31	P0.6/AD6
2	P1.6	17	NC	32	P0.5/AD5
3	P1.7	18	P2.0/A8	33	P0.4/AD4
4	RST	19	P2.1/A9	34	P0.3/AD3
5	P3.0/RxD	20	P2.2/A10	35	P0.2/AD2
6	V_{SS4}	21	P2.3/A11	36	P0.1/AD1
7	P3.1/TxD	22	P2.4/A12	37	P0.0/AD0
8	P3.2/$\overline{INT0}$	23	P2.5/A13	38	V_{DD}
9	P3.3/$\overline{INT1}$	24	P2.6/A14	39	V_{SS3}
10	P3.4/T0	25	P2.7/A15	40	P1.0
11	P3.5/T1	26	$\overline{PSEN}$	41	P1.1
12	P3.6/$\overline{WR}$	27	ALE	42	P1.2
13	P3.7/$\overline{RD}$	28	V_{SS2}	43	P1.3
14	XTAL2	29	$\overline{EA}/V_{PP}$	44	P1.4
15	XTAL1	30	P0.7/AD7		

NOTE:
1. Due to EMC improvements, all V_{SS} pins (6, 16, 28, 39) must be connected to V_{SS}.

LOGIC SYMBOL



BLOCK DIAGRAM



PIN DESCRIPTIONS

MNEMONIC	PIN NUMBER DIP	PIN NUMBER QFP	TYPE	NAME AND FUNCTION
V_{SS}	20	6, 16, 28, 39	I	**Ground:** 0V reference. With the QFP package all V_{SS} pins (V_{SS1} to V_{SS4}) must be connected.
V_{DD}	40	38	I	**Power Supply:** This is the power supply voltage for normal, idle, and power-down operation.
P0.0–0.7	39–32	37–30	I/O	**Port 0:** Port 0 is an open-drain, bidirectional I/O port. Port 0 pins that have 1s written to them float and can be used as high-impedance inputs. Port 0 is also the multiplexed low-order address and data bus during accesses to external program and data memory. In this application, it uses strong internal pull-ups when emitting 1s.
P1.0–P1.5	1–6	40–44, 1	I/O	**Port 1:** Port 1 is an 8-bit bidirectional I/O port with internal pull-ups, except P1.6 and P1.7 which are open drain. Port 1 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, port 1 pins that are externally pulled low will source current because of the internal pull-ups. (See DC Electrical Characteristics: I_{IL}). Alternate functions include:
P1.6	7	2	I/O	open drain output
P1.7	8	3	I/O	open drain output
P2.0–P2.7	21–28	18–25	I/O	**Port 2:** Port 2 is an 8-bit bidirectional I/O port with internal pull-ups. Port 2 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, port 2 pins that are externally being pulled low will source current because of the internal pull-ups. (See DC Electrical Characteristics: I_{IL}). Port 2 emits the high-order address byte during fetches from external program memory and during accesses to external data memory that use 16-bit addresses (MOVX @DPTR). In this application, it uses strong internal pull-ups when emitting 1s. During accesses to external data memory that use 8-bit addresses (MOV @Ri), port 2 emits the contents of the P2 special function register.
P3.0–P3.7	10–17	5, 7–13	I/O	**Port 3:** Port 3 is an 8-bit bidirectional I/O port with internal pull-ups. Port 3 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, port 3 pins that are externally being pulled low will source current because of the pull-ups. (See DC Electrical Characteristics: I_{IL}). Port 3 also serves the special features of the 80C51 family, as listed below:
	10	5	I	**RxD (P3.0):** Serial input port
	11	7	O	**TxD (P3.1):** Serial output port
	12	8	I	**$\overline{\text{INT0}}$ (P3.2):** External interrupt
	13	9	I	**$\overline{\text{INT1}}$ (P3.3):** External interrupt
	14	10	I	**T0 (P3.4):** Timer 0 external input
	15	11	I	**T1 (P3.5):** Timer 1 external input
	16	12	O	**$\overline{\text{WR}}$ (P3.6):** External data memory write strobe
	17	13	O	**$\overline{\text{RD}}$ (P3.7):** External data memory read strobe
RST	9	4	I	**Reset:** A high on this pin for two machine cycles while the oscillator is running, resets the device. An internal diffused resistor to V_{SS} permits a power-on reset using only an external capacitor to V_{DD}.
ALE	30	27	I/O	**Address Latch Enable:** Output pulse for latching the low byte of the address during an access to external memory. In normal operation, ALE is emitted at a constant rate of 1/6 the oscillator frequency. Note that one ALE pulse is skipped during each access to external data memory.
$\overline{\text{PSEN}}$	29	26	O	**Program Store Enable:** Read strobe to external program memory via Port 0 and Port 2. It is activated twice each machine cycle during fetches from the external program memory. When executing out of external program memory two activations of $\overline{\text{PSEN}}$ are skipped during each access to external data memory. $\overline{\text{PSEN}}$ is not activated (remains HIGH) during no fetches from external program memory. $\overline{\text{PSEN}}$ can sink/source 8 LSTTL inputs and can drive CMOS inputs without external pull–ups.
$\overline{\text{EA}}$	31	29	I	**External Access:** If during a RESET, $\overline{\text{EA}}$ is held at TTL, level HIGH, the CPU executes out of the internal program memory ROM provided the Program Counter is less than 16384. If during a RESET, $\overline{\text{EA}}$ is held a TTL LOW level, the CPU executes out of external program memory. $\overline{\text{EA}}$ is not allowed to float.
XTAL1	19	15	I	**Crystal 1:** Input to the inverting oscillator amplifier and input to the internal clock generator circuits.
XTAL2	18	14	O	**Crystal 2:** Output from the inverting oscillator amplifier.

NOTE:
To avoid “latch-up” effect at power-on, the voltage on any pin at any time must not be higher than V_{DD} + 0.5V or V_{SS} – 0.5V, respectively.

Table 1. OM5202 Special Function Registers

SYMBOL	DESCRIPTION	DIRECT ADDRESS	BIT ADDRESS, SYMBOL, OR ALTERNATIVE PORT FUNCTION MSB							LSB	RESET VALUE
ACC*	Accumulator	E0H	E7	E6	E5	E4	E3	E2	E1	E0	00H
B*	B Register	F0H	F7	F6	F5	F4	F3	F2	F1	F0	00H
DPTR:	Data Pointer (2 bytes)										
DPH	Data Pointer High	83H									00H
DPL	Data Pointer Low	82H									00H
			AF	AE	AD	AC	AB	AA	A9	A8	
IE*#	Interrupt Enable	A8H	EA		ES1	ES0	ET1	EX1	ET0	EX0	0x000000B
			BF	BE	BD	BC	BB	BA	B9	B8	
IP*#	Interrupt Priority	B8H	–		PS1	PS0	PT1	PX1	PT0	PX0	xx000000B
			87	86	85	84	83	82	81	80	
P0*	Port 0	80H	AD7	AD6	AD5	AD4	AD3	AD2	AD1	AD0	FFH
			97	96	95	94	93	92	91	90	
P1*#	Port 1	90H	SDA	SCL							FFH
			A7	A6	A5	A4	A3	A2	A1	A0	
P2*	Port 2	A0H	A15	A14	A13	A12	A11	A10	A9	A8	FFH
			B7	B6	B5	B4	B3	B2	B1	B0	
P3*	Port 3	B0H	$\overline{RD}$	$\overline{WR}$	T1	T0	$\overline{INT1}$	$\overline{INT0}$	TXD	RXD	FFH
PCON	Power Control	87H	SMOD	–	–	–	GF1	GF0	PD	IDL	0xxx0000B
			9F	9E	9D	9C	9B	9A	99	98	
S0CON*#	Serial 0 Port Control	98H	SM0	SM1	SM2	REN	TB8	RB8	TI	RI	00H
S0BUF#	Serial 0 Data Buffer	99H									xxxxxxxxB
			D7	D6	D5	D4	D3	D2	D1	D0	
PSW*	Program Status Word	D0H	CY	AC	F0	RS1	RS0	OV	F1	P	00H
	reserved (Note 1)	DAH									00H
SP	Stack Pointer	81H									07H
	reserved (Note 1)	DBH									00H
	reserved (Note 1)	D9H									F8H
	reserved (Note 1)	D8H									00000000B
			8F	8E	8D	8C	8B	8A	89	88	
TCON*	Timer Control	88H	TF1	TR1	TF0	TR0	IE1	IT1	IE0	IT0	00H
TH1	Timer High 1	8DH									00H
TH0	Timer High 0	8CH									00H
TL1	Timer Low 1	8BH									00H
TL0	Timer Low 0	8AH									00H
TMOD	Timer Mode	89H	GATE	C/$\overline{T}$	M1	M0	GATE	C/$\overline{T}$	M1	M0	00H

* SFRs are bit addressable.

\# SFRs are modified from or added to the 80C51 SFRs.

NOTE

1. Reserved for I^2C; not supported in OM5202

ROM CODE EXTERNAL (OM5202)

The MOVC instructions are the only instructions that have access to program code in the external program memory. The $\overline{EA}$ input is latched during RESET.

OSCILLATOR CHARACTERISTICS

XTAL1 and XTAL2 are the input and output, respectively, of an inverting amplifier. The pins can be configured for use as an on-chip oscillator, as shown in the Logic Symbol, page 2.

To drive the device from an external clock source, XTAL1 should be driven while XTAL2 is left unconnected. There are no requirements on the duty cycle of the external clock signal, because the input to the internal clock circuitry is through a divide-by-two flip-flop. However, minimum and maximum high and low times specified in the data sheet must be observed.

Reset

A reset is accomplished by holding the RST pin high for at least two machine cycles (24 oscillator periods), while the oscillator is running. To insure a good power-on reset, the RST pin must be high long enough to allow the oscillator time to start up (normally a few milliseconds) plus two machine cycles. At power-on, the voltage on V_{DD} and RST must come up at the same time for a proper start-up.

Idle Mode

In the idle mode, the CPU puts itself to sleep while all of the on-chip peripherals stay active. The instruction to invoke the idle mode is the last instruction executed in the normal operating mode before the idle mode is activated. The CPU contents, the on-chip RAM, and all of the special function registers remain intact during this mode. The idle mode can be terminated either by any enabled interrupt (at which time the process is picked up at the interrupt service routine and continued), or by a hardware reset which starts the processor in the same manner as a power-on reset.

Power-Down Mode

In the power-down mode, the oscillator is stopped and the instruction to invoke power-down is the last instruction executed. Only the contents of the on-chip RAM are preserved. A hardware reset is the only way to terminate the power-down mode. The control bits for the reduced power modes are in the special function register PCON. Table 2 shows the state of the I/O ports during low current operating modes.

Table 2. External Pin Status During Idle and Power-Down Mode

MODE	PROGRAM MEMORY	ALE	$\overline{PSEN}$	PORT 0	PORT 1	PORT 2	PORT 3
Idle	External	1	1	Float	Data	Address	Data
Power-down	External	0	0	Float	Data	Data	Data

Serial Control Register (S1CON) – See Table 3

S1CON (D8H)	CR2	ENS1	STA	STO	SI	AA	CR1	CR0

Bits CR0, CR1 and CR2 determine the serial clock frequency that is generated in the master mode of operation.

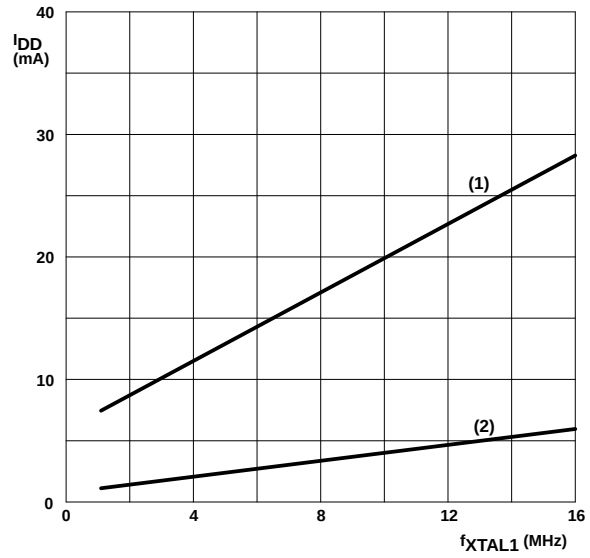
Table 3. Serial Clock Rates

CR2	CR1	CR0	BIT FREQUENCY (kHz) AT f_{OSC} 6MHz	12MHz	16MHz	f_{OSC} DIVIDED BY
0	0	0	23	47	62.5	256
0	0	1	27	54	71	224
0	1	0	31.25	62.5	83.3	192
0	1	1	37	75	100	160
1	0	0	6.25	12.5	17	960
1	0	1	50	100	133	120
1	1	0	100	200	267	60
1	1	1	0.24 < 62.5 0 to 255	0.49 < 62.5 0 to 254	0.65 < 55.6 0 to 253	96 × (256 – (reload value Timer 1)) reload value range Timer 1 (in mode 2)

ABSOLUTE MAXIMUM RATINGS[1, 2, 3]

PARAMETER	RATING	UNIT
Storage temperature range	–65 to +150	°C
Voltage on any other pin to V_{SS}	–0.5 to + 6.5	V
Input, output current on any single pin	±5	mA
Power dissipation (based on package heat transfer limitations, not device power consumption)	1	W

NOTES:
1. Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any conditions other than those described in the AC and DC Electrical Characteristics section of this specification is not implied.
2. This product includes circuitry specifically designed for the protection of its internal devices from the damaging effects of excessive static charge. Nonetheless, it is suggested that conventional precautions be taken to avoid applying greater than the rated maxima.
3. Parameters are valid over operating temperature range unless otherwise specified. All voltages are with respect to V_{SS} unless otherwise noted.



(1) MAXIMUM OPERATING MODE: $V_{DD} = V_{DDmax}$
(2) MAXIMUM IDLE MODE: $V_{DD} = V_{DDmax}$
These values are valid within the specified frequency range.

Figure 1. I_{DD} vs. Frequency

DC ELECTRICAL CHARACTERISTICS

V_{SS} = 0V, V_{DD} = 5.0V ±10%. Operating temperature range 0 to 70°C.

SYMBOL	PARAMETER	TEST CONDITIONS	LIMITS		UNIT
			MIN.	MAX.	
V_{IL}	Input low voltage, except $\overline{EA}$, P1.6, P1.7		–0.5	$0.2V_{DD}$–0.1	V
V_{IL1}	Input low voltage to $\overline{EA}$		–0.5	$0.2V_{DD}$–0.3	V
V_{IL2}	Input low voltage to P1.6, P1.7		–0.5	$0.3V_{DD}$	V
V_{IH}	Input high voltage, except XTAL1, RST, P1.6, P1.7		$0.2V_{DD}$+0.9	V_{DD}+0.5	V
V_{IH1}	Input high voltage, XTAL1, RST		$0.7V_{DD}$	V_{DD}+0.5	V
V_{IH2}	Input high voltage, P1.6, P1.7		$0.7V_{DD}$	6.0	V
V_{OL}	Output low voltage, ports 1, 2, 3, except P1.6, P1.7	I_{OL} = 1.6mA [7), 8)]		0.45	V
V_{OL1}	Output low voltage, port 0, ALE, $\overline{PSEN}$	I_{OL} = 3.2mA [7), 8)]		0.45	V
V_{OL2}	Output low voltage, P1.6, P1.7	I_{OL} = 3.0mA		0.4	V
V_{OH}	Output high voltage, ports 1, 2, 3, ALE, $\overline{PSEN}$ [9)]	I_{OH} = –60µA I_{OH} = –25µA I_{OH} = –10µA	2.4 $0.75V_{DD}$ $0.9V_{DD}$		V V V
V_{OH1}	Output high voltage; port 0 in external bus mode	I_{OH} = –800µA I_{OH} = –300µA I_{OH} = –80µA	2.4 $0.75V_{DD}$ $0.9V_{DD}$		V V V
I_{IL}	Logical 0 input current, ports 1, 2, 3, except P1.6, P1.7	V_{IN} = 0.45V		–50	µA
I_{TL}	Logical 1-to-0 transition current, ports 1, 2, 3, except P1.6, P1.7	See note 6)		–650	µA
I_{L1}	Input leakage current, port 0, $\overline{EA}$	0.45V < V_I < V_{DD}		±10	µA
I_{L2}	Input leakage current, P1.6, P1.7	0V < V_I < 6.0V 0V < V_{DD} < 6.0V		±10	µA
I_{DD}	Power supply current: Active mode @ 16MHz [2), 10)] Idle mode @ 16MHz [3), 10)] Power down mode [4), 5)]	See note 1) V_{DD}=6.0V		 26.5 6 50	 mA mA µA
R_{RST}	Internal reset pull-down resistor		50	150	kΩ
C_{IO}	Pin capacitance	Freq.=1MHz		10	pF

NOTES FOR DC ELECTRICAL CHARACTERISTICS:

1. See Figures 9 through 11 for I_{DD} test conditions.
2. The operating supply current is measured with all output pins disconnected; XTAL1 driven with $t_r = t_f$ = 5ns; $V_{IL} = V_{SS}$ + 0.5V; $V_{IH} = V_{DD}$ –0.5V; XTAL2 not connected; $\overline{EA}$ = RST = Port 0 = P1.6 = P1.7 = V_{DD}. See Figure 9.
3. The idle mode supply current is measured with all output pins disconnected; XTAL1 driven with $t_r = t_f$ = 5ns; $V_{IL} = V_{SS}$ + 0.5V; $V_{IH} = V_{DD}$ –0.5V; XTAL2 not connected; Port 0 = P1.6 = P1.7 = V_{DD}; $\overline{EA}$ = RST = V_{SS}. See Figure 10.
4. The power-down current is measured with all output pins disconnected; XTAL2 not connected; Port 0 = P1.6 = P1.7 = V_{DD}; $\overline{EA}$ = RST = V_{SS}. See Figure 11.
5. 2V $\leq V_{PD} \leq V_{DD}$max.
6. Pins of ports 1 , 2, and 3 source a transition current when they are being externally driven from 1 to 0. The transition current reaches its maximum value when V_{IN} is approximately 2V.
7. Capacitive loading on ports 0 and 2 may cause spurious noise to be superimposed on the V_{OL}s of ALE and ports 1 and 3. The noise is due to external bus capacitance discharging into the port 0 and port 2 pins when these pins make 1-to-0 transitions during bus operations. In the worst cases (capacitive loading > 100pF), the noise pulse on the ALE pin may exceed 0.8V. In such cases, it may be desirable to qualify ALE with a Schmitt Trigger, or use an address latch with a Schmitt Trigger STROBE input.
8. Under steady state (non-transient) conditions, I_{OL} must be externally limited as follows: Maximum I_{OL} = 10mA per port pin; Maximum I_{OL} = 26mA total for Port 0; Maximum I_{OL} = 15mA total for Ports 1, 2, and 3; Maximum I_{OL} = 71mA total for all output pins. If I_{OL} exceeds the test conditions, V_{OL} may exceed the related specification. Pins are not guaranteed to sink current greater than the listed test conditions.
9. Capacitive loading on ports 0 and 2 may cause the V_{OH} on ALE and $\overline{PSEN}$ to momentarily fall below the $0.9V_{DD}$ specification when the address bits are stabilizing.
10. I_{DDMAX} for other frequencies can be derived from Figure 1, where FREQ is the external oscillator frequency in MHz. I_{DDMAX} is given in mA.

AC ELECTRICAL CHARACTERISTICS[1, 2]

SYMBOL	FIGURE	PARAMETER	16MHz CLOCK		VARIABLE CLOCK		UNIT
			MIN	MAX	MIN	MAX	
$1/t_{CLCL}$	2	Oscillator frequency			1.2	16	MHz
t_{LHLL}	2	ALE pulse width	85		$2t_{CLCL}-40$		ns
t_{AVLL}	2	Address valid to ALE low	8		$t_{CLCL}-55$		ns
t_{LLAX}	2	Address hold after ALE low	28		$t_{CLCL}-35$		ns
t_{LLIV}	2	ALE low to valid instruction in		150		$4t_{CLCL}-100$	ns
t_{LLPL}	2	ALE low to $\overline{PSEN}$ low	23		$t_{CLCL}-40$		ns
t_{PLPH}	2	$\overline{PSEN}$ pulse width	143		$3t_{CLCL}-45$		ns
t_{PLIV}	2	$\overline{PSEN}$ low to valid instruction in		83		$3t_{CLCL}-105$	ns
t_{PXIX}	2	Input instruction hold after $\overline{PSEN}$	0		0		ns
t_{PXIZ}	2	Input instruction float after $\overline{PSEN}$		38		$t_{CLCL}-25$	ns
t_{AVIV}	2	Address to valid instruction in		208		$5t_{CLCL}-105$	ns
t_{PLAZ}	2	$\overline{PSEN}$ low to address float		10		10	ns
Data Memory							
t_{RLRH}	3, 4	$\overline{RD}$ pulse width	275		$6t_{CLCL}-100$		ns
t_{WLWH}	3, 4	$\overline{WR}$ pulse width	275		$6t_{CLCL}-100$		ns
t_{RLDV}	3, 4	$\overline{RD}$ low to valid data in		148		$5t_{CLCL}-165$	ns
t_{RHDX}	3, 4	Data hold after $\overline{RD}$	0		0		ns
t_{RHDZ}	3, 4	Data float after $\overline{RD}$		55		$2t_{CLCL}-70$	ns
t_{LLDV}	3, 4	ALE low to valid data in		350		$8t_{CLCL}-150$	ns
t_{AVDV}	3, 4	Address to valid data in		398		$9t_{CLCL}-165$	ns
t_{LLWL}	3, 4	ALE low to $\overline{RD}$ or $\overline{WR}$ low	138	238	$3t_{CLCL}-50$	$3t_{CLCL}+50$	ns
t_{AVWL}	3, 4	Address valid to $\overline{WR}$ low or $\overline{RD}$ low	120		$4t_{CLCL}-130$		ns
t_{QVWX}	3, 4	Data valid to $\overline{WR}$ transition	3		$t_{CLCL}-60$		ns
t_{DW}	3, 4	Data setup time before $\overline{WR}$	288		$7t_{CLCL}-150$		ns
t_{WHQX}	3, 4	Data hold after $\overline{WR}$	13		$t_{CLCL}-50$		ns
t_{RLAZ}	3, 4	$\overline{RD}$ low to address float		0		0	ns
t_{WHLH}	3, 4	$\overline{RD}$ or $\overline{WR}$ high to ALE high	23	103	$t_{CLCL}-40$	$t_{CLCL}+40$	ns
Shift Register							
t_{XLXL}	5	Serial port clock cycle time[3]	0.75		$12t_{CLCL}$		µs
t_{QVXH}	5	Output data setup to clock rising edge[3]	492		$10t_{CLCL}-133$		ns
t_{XHQX}	5	Output data hold after clock rising edge[3]	80		$2t_{CLCL}-117$		ns
t_{XHDX}	5	Input data hold after clock rising edge[3]	0		0		ns
t_{XHDV}	5	Clock rising edge to input data valid[3]		492		$10t_{CLCL}-133$	ns
External Clock							
t_{CHCX}	6	High time[3]	20		20	$t_{CLCL} - t_{CLCX}$	ns
t_{CLCX}	6	Low time[3]	20		20	$t_{CLCL} - t_{CHCX}$	ns
t_{CLCH}	6	Rise time[3]		20		20	ns
t_{CHCL}	6	Fall time[3]		20		20	ns

NOTES:
1. Parameters are valid over operating temperature range unless otherwise specified.
2. Load capacitance for port 0, ALE, and $\overline{PSEN}$ = 100pF, load capacitance for all other outputs = 80pF.
3. These values are characterized but not 100% production tested.

EXPLANATION OF THE AC SYMBOLS

Each timing symbol has five characters. The first character is always 't' (= time). The other characters, depending on their positions, indicate the name of a signal or the logical status of that signal. The designations are:

A – Address
C – Clock
D – Input data
H – Logic level high
I – Instruction (program memory contents)
L – Logic level low, or ALE
P – $\overline{\text{PSEN}}$
Q – Output data
R – $\overline{\text{RD}}$ signal
t – Time
V – Valid
W – $\overline{\text{WR}}$ signal
X – No longer a valid logic level
Z – Float

Examples: t_{AVLL} = Time for address valid to ALE low.
t_{LLPL} = Time for ALE low to $\overline{\text{PSEN}}$ low.

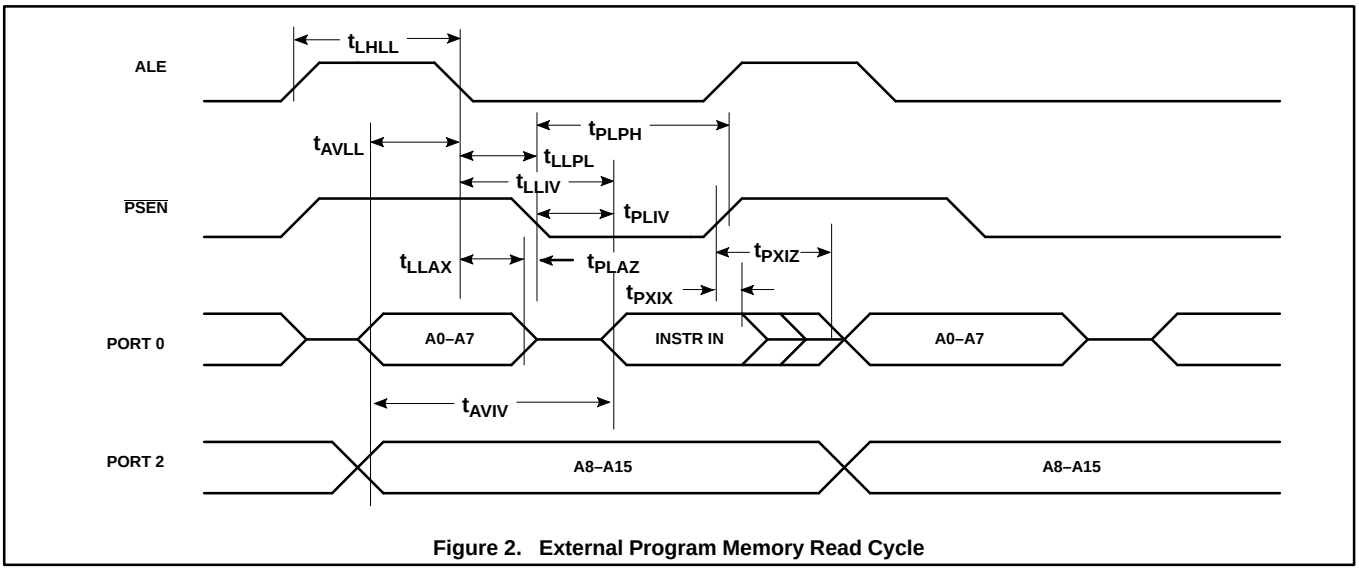


Figure 2. External Program Memory Read Cycle

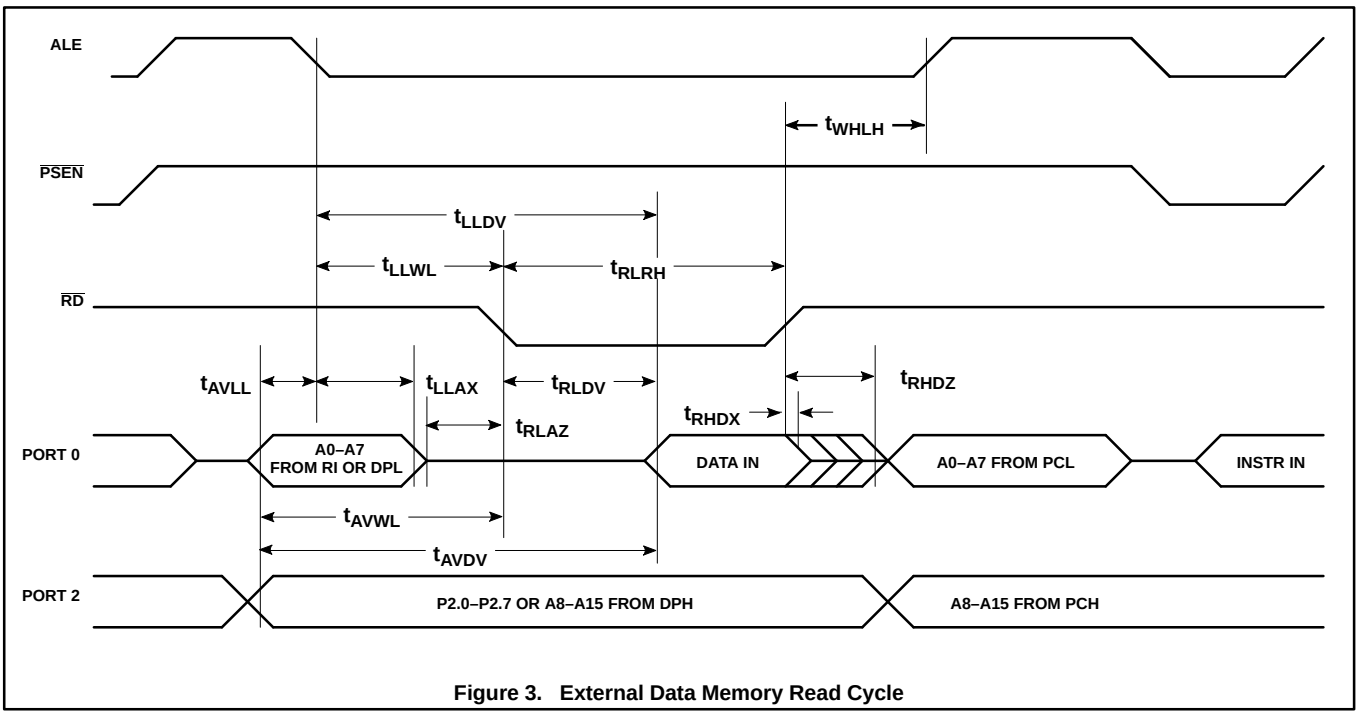


Figure 3. External Data Memory Read Cycle

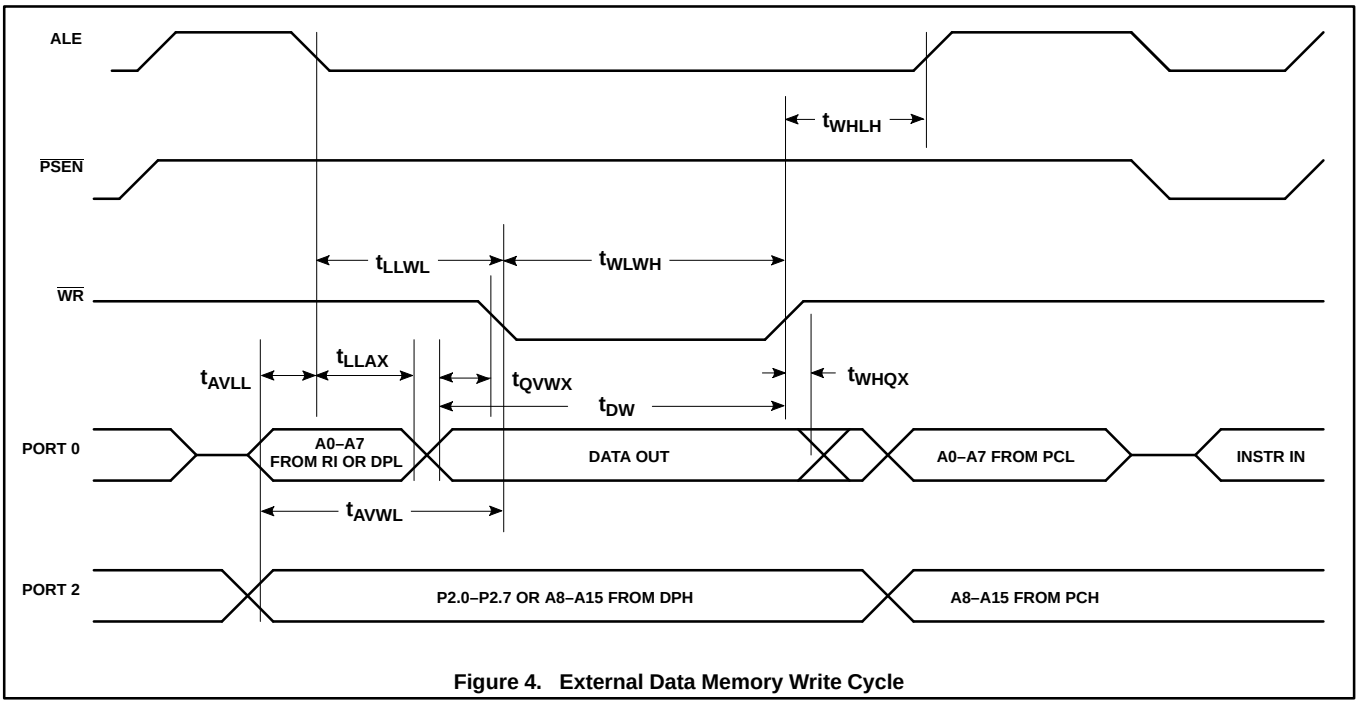


Figure 4. External Data Memory Write Cycle

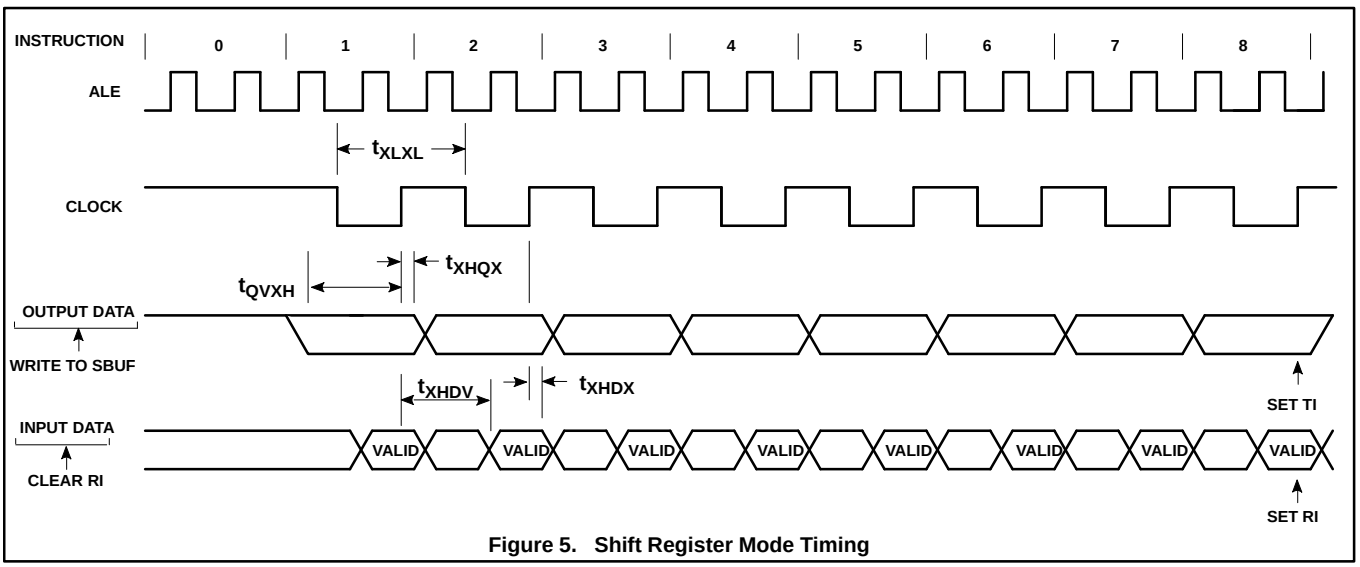


Figure 5. Shift Register Mode Timing

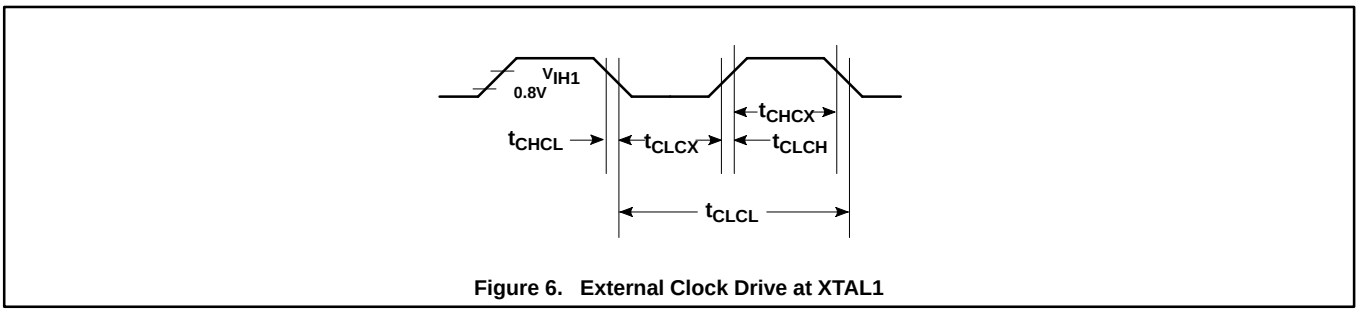
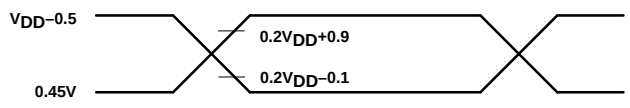
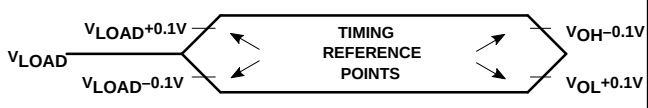


Figure 6. External Clock Drive at XTAL1



NOTE:
AC INPUTS DURING TESTING ARE DRIVEN AT $V_{DD}-0.5$ FOR A LOGIC '1' AND 0.45V FOR A LOGIC '0'. TIMING MEASUREMENTS ARE MADE AT V_{IH} MIN FOR A LOGIC '1' AND V_{IL} MAX FOR A LOGIC '0'.

Figure 7. AC Testing Input/Output



NOTE:
FOR TIMING PURPOSES, A PORT IS NO LONGER FLOATING WHEN A 100MV CHANGE FROM LOAD VOLTAGE OCCURS, AND BEGINS TO FLOAT WHEN A 100mV CHANGE FROM THE LOADED V_{OH}/V_{OL} LEVEL OCCURS. $I_{OH}/I_{OL} \geq \pm$ 20mA.

Figure 8. Float Waveform

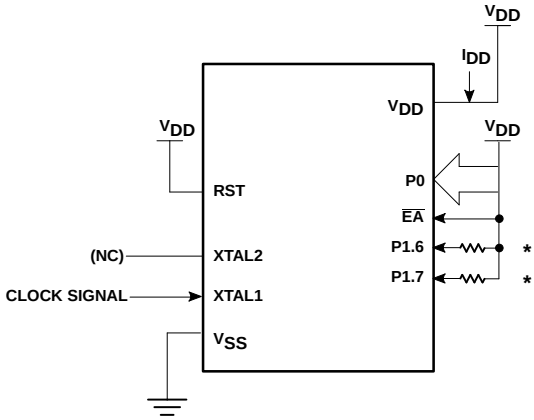


Figure 9. I_{DD} Test Condition, Active Mode
All other pins are disconnected

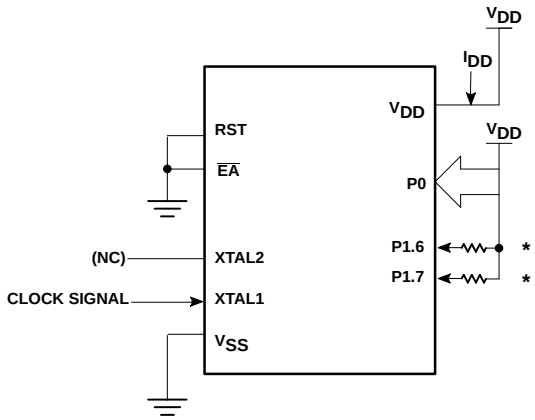


Figure 10. I_{DD} Test Condition, Idle Mode
All other pins are disconnected

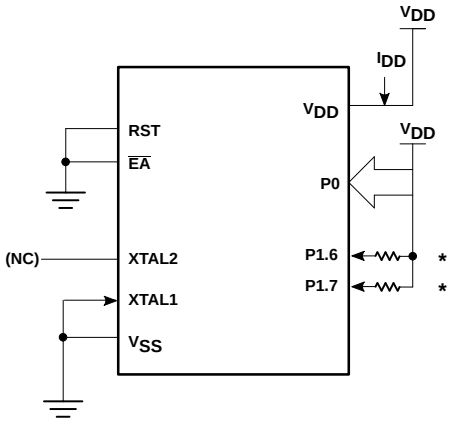


Figure 11. I_{DD} Test Condition, Power Down Mode
All other pins are disconnected. V_{DD} = 2V to 5.5V

NOTE:
* Ports 1.6 and 1.7 should be connected to V_{CC} through resistors of sufficiently high value such that the sink current into these pins does not exceed the I_{OL1} specification.