## DESCRIPTION

The SC1405B is a Dual-MOSFET Driver with an internal Overlap Protection Circuit to prevent shoot-through from $\mathrm{V}_{\text {IN }}$ to GND in the main switching and synchronous MOSFET's. Each driver is capable of driving a 3000 pF load in 15 ns rise/fall time and has ULTRAFAST propagation delay from input transition to the gate of the power FET's. The Overlap Protection circuit ensures that the second FET does not turn on until the top FET source has reached a voltage low enough to prevent shoot-through. The delay between the bottom gate going low to the top gate transitioning to high is externally programmable via a capacitor for optimal reduction of switching losses at the operating frequency. The bottom FET may be disabled at light loads by keeping S_MOD low to trigger asynchronous operation, thus saving the bottom FET's gate drive current and inductor ripple current. An internal voltage reference allows threshold adjustment for an Output OverVoltage protection circuitry, independent of the PWM feedback loop. Under-Voltage-Lock-Out circuit is included to guarantee that both driver outputs are low when the 5 V logic level is less than or equal to 4.4 V (typ) at supply ramp up ( 4.35 V at supply ramp down). A CMOS output provides status indication of the 5 V supply. A low enable input places the IC in stand-by mode thereby reducing supply current to less than $10 \mu \mathrm{~A}$. SC1405B is offered in a high pitch (.025" lead spacing) TSSOP package.

## FEATURES

- Fast rise and fall times (15ns with 3000pf load)
- 14 ns max. Propagation delay (BG going low)
- Adaptive/programmable shoot-through protection
- Wide input voltage range (4.5-25V)
- Programmable delay between MOSFET's
- Power saving asynchronous mode control
- Output overvoltage protection/overtemp shutdown
- Under-Voltage lock-out and power ready signal
- Less than $10 \mu \mathrm{~A}$ stand-by current ( $\mathrm{EN}=\mathrm{low}$ )
- Power ready output signal
- Improved drive version of SC1405TS
- High frequency (to 1.2 MHz ) operation allows use of small inductors and low cost caps in place of electrolytics


## APPLICATIONS

- High Density/Fast transient power supplies
- Motor Drives/Class-D amps
- Portable computers


## ORDERING INFORMATION

| DEVICE $^{(1)}$ | PACKAGE | TEMP. RANGE (T ${ }_{\mathbf{J}}$ ) |
| :---: | :---: | :---: |
| SC1405B | TSSOP-14 | $0-125^{\circ} \mathrm{C}$ |

Note:
(1) Add suffix ‘TR’ for tape and reel.

## PIN CONFIGURATION

BLOCK DIAGRAM



HIGH SPEED SYNCHRONOUS POWER MOSFET SMART DRIVER

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## ABSOLUTE MAXIMUM RATINGS

| Parameter | Symbol | Conditions | Maximum | Units |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {CC }}$ Supply Voltage | $\mathrm{V}_{\text {MAX5 }} \mathrm{V}$ |  | 7 | V |
| BST to PGND | $\mathrm{VMAX}_{\text {BST-PGND }}$ |  | 30 | V |
| BST to DRN | $V^{\prime \prime} \mathrm{MAX}_{\text {BST-DRN }}$ |  | 7 | V |
| DRN to PGND | VMAX ${ }_{\text {DRN-PGN }}$ |  | 25 | V |
| OVP_S to PGND | VMAX ${ }_{\text {OVP_S-PGND }}$ |  | 10 | V |
| Input pin | CO |  | -0.3 to 7.3 | V |
| Continuous Power Dissipation | Pd | $\begin{aligned} & \text { Tamb }=25^{\circ} \mathrm{C}, \mathrm{~T}_{J}=125^{\circ} \mathrm{C} \\ & \text { Tcase }=25^{\circ} \mathrm{C}, \mathrm{~T}_{j}=125^{\circ} \mathrm{C} \end{aligned}$ | $\begin{aligned} & 0.66 \\ & 2.56 \end{aligned}$ | W |
| Thermal Resistance Junction to Case | $\theta_{\text {Jc }}$ |  | 40 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Thermal Resistance Junction to Ambient | $\theta_{\text {JA }}$ |  | 150 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Operating Temperature Range | T |  | 0 to +125 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $\mathrm{T}_{\text {STG }}$ |  | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |
| Lead Temperature (Soldering) 10 sec | $\mathrm{T}_{\text {LEAD }}$ |  | 300 | ${ }^{\circ} \mathrm{C}$ |

NOTE:
(1) Specification refers to application circuit in Figure 1.

## ELECTRICAL CHARACTERISTICS (DC OPERATING SPECIFICATIONS)

Unless specified: $-0<\theta_{j}<125^{\circ} \mathrm{C} ; \mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V} ; 4 \mathrm{~V} \leq \mathrm{V}_{\mathrm{BST}} \leq 26 \mathrm{~V}$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| POWER SUPPLY |  |  |  |  |  |  |
| Supply Voltage | $\mathrm{V}_{\mathrm{cc}}$ | $\mathrm{V}_{\mathrm{Cc}}$ | 4.15 | 5 | 6.0 | V |
| Quiescent Current | Iq_stby | $\mathrm{EN}=0 \mathrm{~V}$ |  |  | 10 | $\mu \mathrm{A}$ |
| Quiescent Current, operating | Iq_op | $\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V}, \mathrm{CO}=0 \mathrm{~V}$ |  | 1 |  | ma |
| PRDY |  |  |  |  |  |  |
| High Level Output Voltage | $\mathrm{V}_{\mathrm{OH}}$ | $V_{C C}=4.6 \mathrm{~V}$, lload $=10 \mathrm{~mA}$ | 4.5 | 4.55 |  | V |
| Low Level Output Voltage | $\mathrm{V}_{\text {OL }}$ | $\begin{gathered} \mathrm{V}_{\mathrm{CC}}<\mathrm{UVLO} \text { threshold, lload }= \\ 10 \mu \mathrm{~A} \end{gathered}$ |  | 0.1 | 0.2 | V |
| DSPS_DR |  |  |  |  |  |  |
| High Level Output Voltage | $\mathrm{V}_{\mathrm{OH}}$ | $\mathrm{V}_{\mathrm{cc}}=4.6 \mathrm{~V}$, Cload $=100 \mathrm{pF}$ | 4.15 |  |  | V |
| Low Level Output Voltage | $\mathrm{V}_{\mathrm{OL}}$ | $\mathrm{V}_{\mathrm{CC}}=4.6 \mathrm{~V}$, Cload $=100 \mathrm{pF}$ |  |  | 0.05 | V |
| UNDER-VOLTAGE LOCKOUT |  |  |  |  |  |  |
| Start Threshold | $\mathrm{V}_{\text {START }}$ |  | 4.2 | 4.4 | 4.6 | V |
| Hysteresis | Vhys ${ }_{\text {uvLo }}$ |  |  | 0.05 |  | V |
| Logic Active Threshold | $\mathrm{V}_{\text {ACT }}$ | EN is low |  |  | 1.5 | V |

HIGH SPEED SYNCHRONOUS POWER
SC1405B MOSFET SMART DRIVER

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ELECTRICAL CHARACTERISTICS (DC OPERATING SPECIFICATIONS) Cont.

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| OVERVOLTAGE PROTECTION |  |  |  |  |  |  |
| Trip Threshold | $\mathrm{V}_{\text {TRIP }}$ |  | 1.145 | 1.2 | 1.255 | V |
| Hysteresis | Vhys ${ }_{\text {ovp }}$ |  |  | 0.8 |  | V |
| S_MOD |  |  |  |  |  |  |
| High Level Input Voltage | $\mathrm{V}_{\text {IH }}$ |  | 2.0 |  |  | V |
| Low Level Input Voltage | $\mathrm{V}_{\text {IL }}$ |  |  |  | 0.8 | V |
| ENABLE |  |  |  |  |  |  |
| High Level Input Voltage | $\mathrm{V}_{\text {IH }}$ |  | 2.0 |  |  | V |
| Low Level Input Voltage | $\mathrm{V}_{\text {IL }}$ |  |  |  | 0.8 | V |
| CO |  |  |  |  |  |  |
| High Level Input Voltage | $\mathrm{V}_{\text {IH }}$ |  | 2.0 |  |  | V |
| Low Level Input Voltage | $\mathrm{V}_{\text {IL }}$ |  |  |  | 0.8 | V |
| THERMAL SHUTDOWN |  |  |  |  |  |  |
| Over Temperature Trip Point | $\mathrm{T}_{\text {OtP }}$ |  |  | 165 |  | ${ }^{\circ} \mathrm{C}$ |
| Hysteresis | $\mathrm{T}_{\mathrm{HYST}}$ |  |  | 10 |  | ${ }^{\circ} \mathrm{C}$ |
| HIGH-SIDE DRIVER |  |  |  |  |  |  |
| Peak Output Current | $\mathrm{I}_{\text {PKH }}$ |  |  | 2 |  | A |
| Output Resistance | $\mathrm{Rsrc}_{\text {TG }}$ <br> Rsink $_{\text {TG }}$ | $\begin{gathered} \text { duty cycle }<2 \%, \text { tpw }<100 \mu \mathrm{~s}, \\ \mathrm{~T}_{J}=125^{\circ} \mathrm{C}, \mathrm{~V}_{\text {BST }}-\mathrm{V}_{\text {DRN }}=4.5 \mathrm{~V}, \\ \mathrm{~V}_{T \mathrm{TG}}=4.0 \mathrm{~V}(\mathrm{src})+\mathrm{V}_{\text {DRN }} \\ \text { or } \mathrm{V}_{\text {TG }}=0.5 \mathrm{~V}(\text { sink })+\mathrm{V}_{\text {DRN }} \end{gathered}$ |  | 1 <br> . 7 |  | $\Omega$ <br> $\Omega$ |
| LOW-SIDE DRIVER |  |  |  |  |  |  |
| Peak Output Current | $\mathrm{I}_{\text {PKL }}$ |  |  | 2 |  | A |
| Output Resistance | Rsrc $_{\text {BG }}$ <br> Rsink ${ }_{B G}$ | $\begin{gathered} \text { duty cycle }<2 \%, \text { tpw }<100 \mu \mathrm{~s}, \\ \mathrm{~T}_{J}=125^{\circ} \mathrm{C} \\ \mathrm{~V}_{\mathrm{V}^{5} 5}=4.6 \mathrm{~V}, \mathrm{~V}_{\mathrm{BG}}=4 \mathrm{~V}(\mathrm{src}), \\ \text { or } \mathrm{V}_{\text {LowDR }}=0.5 \mathrm{~V}(\text { sink }) \end{gathered}$ |  | $\begin{aligned} & 1.2 \\ & 1.0 \end{aligned}$ |  | $\Omega$ $\Omega$ |

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ELECTRICAL CHARACTERISTICS (DC OPERATING SPECIFICATIONS) Cont.

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| AC OPERATING SPECIFICATIONS |  |  |  |  |  |  |
| HIGH-SIDE DRIVER |  |  |  |  |  |  |
| rise time | $\mathrm{tr}_{\text {TG }}$, | $\mathrm{Cl}=3 \mathrm{nF}, \mathrm{V}_{\mathrm{BST}}-\mathrm{V}_{\mathrm{DRN}}=4.6 \mathrm{~V}$, |  | 14 | 23 | ns |
| fall time | $\mathrm{tf}_{T G}$ | $\mathrm{Cl}=3 \mathrm{nF}, \mathrm{V}_{\text {BST }}-\mathrm{V}_{\text {DRN }}=4.6 \mathrm{~V}$, |  | 12 | 19 | ns |
| propagation delay time, TG going high | $\mathrm{tpdh}_{\text {TG }}$ | $\begin{gathered} \mathrm{CI}=3 \mathrm{nF}, \mathrm{~V}_{\text {BST }}-\mathrm{V}_{\text {DRN }}=4.6 \mathrm{~V}, \\ C-\text { delay }=0 \end{gathered}$ |  | 20 | 32 | ns |
| propagation delay time, TG going low | $\mathrm{tpdl}_{\text {TG }}$ | $\mathrm{Cl}=3 \mathrm{nF}, \mathrm{V}_{\mathrm{BST}}-\mathrm{V}_{\mathrm{DRN}}=4.6 \mathrm{~V}$, |  | 15 | 24 | ns |
| LOW-SIDE DRIVER |  |  |  |  |  |  |
| rise time | $\mathrm{tr}_{\mathrm{BG}}$ | $\mathrm{Cl}=3 \mathrm{nF}, \mathrm{V}_{\mathrm{V} 5}=4.6 \mathrm{~V}$, |  | 15 | 24 | ns |
| fall time | $\mathrm{tr}_{\mathrm{BG}}$ |  |  | 13 | 21 | ns |
| propagation delay time BG going high | $\mathrm{tpdh}_{\text {BGHI }}$ | $\begin{gathered} \mathrm{CI}=3 \mathrm{nF}, \mathrm{~V}_{\mathrm{v} 55}=4.6 \mathrm{~V} \\ \mathrm{DRN} \leq 1 \mathrm{~V} \end{gathered}$ |  | 12 | 19 | ns |
| progagation delay time BG going low | $\mathrm{tpdl}_{\mathrm{BG}}$ |  |  | 7 | 12 | ns |
| UNDER-VOLTAGE LOCKOUT |  |  |  |  |  |  |
| V_5 ramping up | $\mathrm{tpdh}_{\text {UvLo }}$ | EN is High |  |  | 10 | us |
| V_5 ramping down | tpdl ${ }_{\text {UVLO }}$ | EN is High |  |  | 10 | us |
| PRDY |  |  |  |  |  |  |
| EN is transitioning from low to high | tpdhPRDY | V_5 $\geq$ UVLO threshold, Delay measured from $\mathrm{EN} \geq 2.0 \mathrm{~V}$ to PRDY $\geq 3.5 \mathrm{~V}$ |  |  | 10 | $\mu \mathrm{s}$ |
| EN is transitioning from high to low | $\mathrm{tpdh}_{\text {UvLO }}$ | V_5 $\geq$ UVLO threshold. Delay measured from $\mathrm{EN} \leq 0.8 \mathrm{~V}$ tp PRDY $\leq 10 \%$ of $V \_5$ |  |  | 500 | $\mu \mathrm{s}$ |
| DSPS_DR |  |  |  |  |  |  |
| rise/fall time | $\mathrm{tr}_{\text {DSPS DR, }}$ <br> $t f_{\text {DSPS DR }}$ | $\mathrm{CI}=100 \mathrm{pf}, \mathrm{V} \_5=4.6 \mathrm{~V}$, |  |  | 20 | ns |
| propagation delay, DSPS_DR going high | tpdh ${ }_{\text {DSPS_DR }}$ | S_MOD goes high and BG goes high or S_MOD goes low |  |  | 10 | ns |
| propagation delay DSPS_DR goes low | tpdl ${ }_{\text {DSPS_DR }}$ | S_MOD goes high and BG goes low |  |  | 10 | ns |
| OVERVOLTAGE PROTECTION |  |  |  |  |  |  |
| propagation delay OVP_S going high | tpdhovp_s | $\begin{gathered} \mathrm{V} \_5=4.6 \mathrm{~V}, \mathrm{~T}_{\mathrm{J}}=125^{\circ} \mathrm{C}, \mathrm{OVP}_{-S} \geq \\ 1.2 \mathrm{~V} \text { to } \mathrm{BG}>90 \% \text { of } \mathrm{V} \_5 \end{gathered}$ |  |  | 1 | $\mu \mathrm{s}$ |

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## PIN DESCRIPTION

| Pin \# | Pin Name | Pin Function |
| :---: | :---: | :---: |
| 1 | OVP_S | Overvoltage protection sense. External scaling resistors required to set protection threshold. |
| 2 | EN | When high, this pin enables the internal circuitry of the device. When low, TG, BG and PRDY are forced low and the supply current (5V) is less than $10 \mu \mathrm{~A}$. |
| 3 | GND | Logic GND. |
| 4 | CO | TTL-level input signal to the MOSFET drivers. |
| 5 | S_MOD | When low, this signal forces $B G$ to be low. When high, $B G$ is not a function of this signal. |
| 6 | DELAY_C | Sets the additional propagation delay for BG going low to TG going high. Total propagation delay $=20 \mathrm{~ns}+1 \mathrm{~ns} / \mathrm{pF}$. |
| 7 | PRDY | This pin indicates the status of 5 V . When 5 V is less than 4.4 V (typ) this output is driven low. When 5 V is greater than or equals to 4.4 V (typ) this output is driven to 5 V level. This output has a 10 mA drive capability and $10 \mu \mathrm{~A}$ sink capability. |
| 8 | $\mathrm{V}_{\mathrm{CC}}$ | +5 V supply. $\mathrm{A} .22-1 \mu \mathrm{~F}$ ceramic capacitor should be connected from 5 V to PGND very close to this pin. |
| 9 | BG | Output drive for the synchronous MOSFET. |
| 10 | PGND | Power ground. Connect to the synchronous FET power ground. |
| 11 | DSPS_DR | Dynamic Set Point Switch Drive. TTL level output signal. When S_MOD is high, this pin follows the BG driver pin voltage. |
| 12 | DRN | This pin connects to the junction of the switching and synchronous MOSFET's. This pin can be subjected to a -2 V minimum relative to PGND without affecting operation. |
| 13 | TG | Output gate drive for the switching (high-side) MOSFET. |
| 14 | BST | Bootstrap pin. A capacitor is connected between BST and DRN pins to develop the floating bootstrap voltage for the high-side MOSFET. The capacitor value is typically between $0.1 \mu \mathrm{~F}$ and $1 \mu \mathrm{~F}$ (ceramic). |

NOTE:
(1) All logic level inputs and outputs are open collector TTL compatible.

## PIN CONFIGURATION



## APPLICATION CIRCUIT

## Typical Distributed Power Supply



Figure 1.
TIMING DIAGRAM


Figure 2.

HIGH SPEED SYNCHRONOUS POWER MOSFET SMART DRIVER

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## Figure 3 - APPLICATION EVALUATION

 BOARD SCHEMATICSC1405B/SC1142 Evaluation Board.
2 -Phase synchronous, Freq. $=1 \mathrm{MHz}$
lout=30A max. (without external heatsink)
SLOT1 connector included for operation with and simulating transient condition for the Pentium, Pentium II ${ }^{\text {TM }}$ processors.


Figure 3

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BILL OF MATERIAL

| Item | Qty | Reference | Value | Manufacturer |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 3 | C4,C15,C28 | 1u,10V, Cer. | AVX, Murata |
| 2 | 3 | C5,C6, C7 | 1u,16V, Cer. | AVX, Murata |
| 3 | 1 | C8 | 1000uF, 16V | Nichicon, any |
| 4 | 1 | C9 | 100uF | Nichicon, any |
| 5 | 1 | C10 | 1000uf | Nichicon, any |
| 7 | 1 | C12 | 10uF | Nichicon, any |
| 8 | 12 | C13,C14,C16,C18,C19,C20,C21,C22,C24,C29,C31,C32 | 22u, 10V | Murata <br> (GRM235Y5V226Z010) |
| 9 | 2 | C17,C30 | 1500uf | Nichicon, Sanyo |
| 10 | 2 | C23,C25 | . 022 | Avx, any |
| 11 | 1 | C26 | . 01 | Avx, any |
| 12 | 7 | C11,C27,C35,C55,C56,C57,C58 | . 1 | Avx, any |
| 13 | 2 | C33,C34 | 10PF | Avx, any |
| 14 | 2 | D1,D2 | SS12 | General Instruments, any |
| 15 | 2 | D10,D11 | 5819 | General Instruments, any |
| 16 | 1 | J1 | Input |  |
| 17 | 2 | L1,L2 | .6uh | Falco, P/N: TO2508 (305) 662-9076 |
| 18 | 2 | Q1,Q3 | IR7811 | $\begin{array}{\|l} \text { Int. Rectifier } \\ \text { (310) 252-7099 } \end{array}$ |
| 19 | 2 | Q2,Q4 | FDB7030 | Fairchild Semi. (408) 822-2000 |
| 20 | 4 | R1,R9,R43,R44 | 10 | any |
| 21 | 1 | R6 | 1.5k | any |
| 22 | 1 | R7 | 100 | any |
| 23 | 1 | R8 | 6k | any |
| 24 | 1 | R10 | 20k | any |
| 25 | 1 | R11 | 300k | any |
| 26 | 4 | R12,R13,R14,R15 | 51 | any, Required in asynch. operation |
| 27 | 1 | R16 | 1K | any |
| 28 | 1 | R17 | TBD | any |
| 29 | 1 | R38 | 10k | any |
| 30 | 4 | R39,R40,R41,R42 | 0 | any |
| 31 | 1 | S1 | Vout Selector switch | Digikey |
| 32 | 1 | U2 | Pentium II ${ }^{\text {TM }}$ | Slot 1 Connector |
| 33 | 1 | U1 | SC1142CSW | Semtech, (805) 499-2111 |
| 34 | 2 | U7,U8 | SC1405B |  |

## APPLICATION INFORMATION:

SC1405B is the newest and the higher speed version of the SC1405TS. It is designed to drive Low Rds_On power MOSFET's with ultra-low rise/fall times and propagation delays. As the switching frequencies of PWM controllers is increased to reduce power supply and Class-D amplifier volume and cost, fast rise and fall times are necessary to minimize switching losses (TOP MOSFET) and reduce Dead-time (BOTTOM MOSFET). While Low Rds_On MOSFET's present a power saving in I ${ }^{2} R$ losses, the MOSFET's die area is larger and thus the effective input capacitance of the MOSFET is increased. Often a $50 \%$ decrease in Rds_On more than doubles the effective input gate charge, which must be supplied by the driver. The Rds_On power savings can be offset by the switching and dead-time losses with a sub-optimum driver. While discrete solution can achieve reasonable drive capability, implementing shoot-through, programmable delay and other housekeeping functions necessary for safe operation can become cumbersome and costly. The SC1405 family of parts presents a total solution for the high-speed, high power density applications. Wide input supply range of $4.5 \mathrm{~V}-25 \mathrm{~V}$ allows use in battery powered applications, new high voltage, distributed power servers as well as Class-D amplifiers.

## THEORY OF OPERATION

The control input (CO) to the SC1405B is typically supplied by a PWM controller that regulates the power supply output. (See Application Evaluation Schematic, Figure 3). The timing diagram demonstrates the sequence of events by which the top and bottom drive signals are applied. The shoot-through protection is implemented by holding the bottom FET off until the voltage at the phase node (intersection of top FET source, the output inductor and the bottom FET drain) has dropped below 1V. This assures that the top FET has turned off and that a direct current path does not exist between the input supply and ground, a condition which both the top and bottom FET's are on momentarily. The top FET is also prevented from turning on until the bottom FET is off. This time is internally set to 20ns (typical) and may be increased by adding a capacitor to the C-Delay pin. The delay is approximately $1 \mathrm{~ns} / \mathrm{pf}$ in addition to the internal 20 ns delay. The external capacitor may be needed if multiple High input capacitance MOSFET's are used in parallel and the fall time is substantially greater than 20 ns .

It must be noted that increasing the dead-time by high values of C-Delay capacitor will reduce efficiency since
the parallel Shottkey or the bottom FET body diode will have to conduct during dead-time.

## LAYOUT GUIDELINES

As with any high speed, high current circuit, proper layout is critical in achieving optimum performance of the SC1405B. The Evaluation board schematic (Refer to figure 3) shows a dual phase synchronous design with all surface mountable components.
While components connecting to C-Delay, OVP_S, EN,S-MOD, DSPS_DR and PRDY are relatively noncritical, tight placement and short, wide traces must be used in layout of The Drives, DRN, and especially PGND pin. The top gate driver supply voltage is provided by bootstrapping the +5 V supply and adding it the phase node voltage (DRN). Since the bootstrap capacitor supplies the charge to the TOP gate, it must be less than . 5 " away from the SC1405. Ceramic X7R capacitors are a good choice for supply bypassing near the chip. The Vcc pin capacitor must also be less than .5 " away from the SC1405. The ground node of this capacitor, the SC1405 PGND pin and the Source of the bottom FET must be very close to each other, preferably with common PCB copper land and multiple vias to the ground plane (if used). The parallel Shottkey must be physically next to the Bottom FETS Drain and source. Any trace or lead inductance in these connections will drive current way from the Shottkey and allow it to flow through the FET's Body diode, thus reducing efficiency.

## PREVENTING INADVERTENT BOTTOM FET TURN-ON

At high input voltages, (12V and greater) a fast turn-on of the top FET creates a positive going spike on the Bottom FET's gate through the Miller capacitance, Crss of the bottom FET. The voltage appearing on the gate due to this spike is:

Vspike=Vin*crss/(Crass+ciss)
Where Ciss is the input gate capacitance of the bottom FET. This is assuming that the impedance of the drive path is too high compared to the instantaneous impedance of the capacitors. (since $\mathrm{dV} / \mathrm{dT}$ and thus the effective frequency is very high). If the BG pin of the SC1405B is very close to the bottom FET, Vspike will be reduced depending on trace inductance, rate if rise of current,etc.

While not shown in Figure 3, a capacitor may be added from the gate of the Bottom FET to its source, preferably less than .1" away. This capacitor will be added to Ciss in the above equation to reduce the effective spike voltage, Vspike.
The selection of the bottom MOSFET must be done with attention paid to the Crss/Ciss ratio. A low ratio reduces the Miller feedback and thus reduces Vspike. Also MOSFETs with higher Turn-on threshold voltages will conduct at a higher voltage and will not turn on during the spike. The MOSFET shown in the schematic (figure 3) has a 2 volt threshold and will require approximately 5 volts Vgs to be conducting, thus reducing the possibility of shoot-through. A zero ohm bottom FET gate resistor will obviously help keeping the gate voltage low. Ultimately, slowing down the top FET by adding gate resistance will reduce di/dt which will in turn make the effective impedance of the capacitors higher, thus allowing the BG driver to hold the bottom gate voltage low.

## RINGING ON THE PHASE NODE

The top MOSFET source must be close to the bottom MOSFET drain to prevent ringing and the possibility of the phase node going negative. This frequency is determined by:
$\mathrm{F}_{\text {ring }}=1 /\left(2 \Pi^{*} \operatorname{Sqrt}\left(\mathrm{~L}_{\mathrm{st}}{ }^{*}\right.\right.$ Coss $\left.)\right)$

## Where:

$\mathrm{L}_{\mathrm{st}}=$ The effective stray inductance of the top FET added to trace inductance of the connection between top FET's source and the bottom FET's drain added to the trace resistance of the bottom FET's ground connection.

Coss=Drain to source capacitance of bottom FET. If there is a Shottkey used, the capacitance of the Shottkey is added to the value.

Although this ringing does not pose any power losses due to a fairly high $Q$, it could cause the phase node to go too far negative, thus causing improper operation, double pulsing or at worst driver damage. This ringing is also an EMI nuisance due to its high resonant frequency. Adding a capacitor, typically 1000-2000pf, in parallel with Coss can often eliminate the EMI issue. If double pulsing is caused due to excessive ringing, placing 4.7-10 ohm resistor between the phase node and the DRN pin of the SC1405 should eliminate the double pulsing. Proper layout will guarantee minimum ringing and elimi-
nate the need for external components. Use of SO8 or other surface mount MOSFETs will reduce lead inductance and their parasitic effects.

## ASYNCHRONOUS OPERATION

The SC1405B can be configured to operate in Asynchronous mode by pulling S-MOD to logic LOW, thus disabling the bottom FET drive. This has the effect of saving power at light loads since the bottom FET's gate capacitance does not have to charged at the switching frequency. There can be a significant savings since the bottom driver can supply up to 2 A pulses to the FET at the switching frequency. There is an additional efficiency benefit to operating in asynchronous mode. When operating in synchronous mode, the inductor current can go negative and flow in reverse direction when the bottom FET is on and the DC load is less than $1 / 2$ inductor ripple current. At that point, the inductor core and wire losses, depending on the magnitude of the ripple current, can be quite significant. Operating in asynchronous mode at light loads effectively only charges the inductor by as much as needed to supply the load current, since the inductor never completely discharges at light loads. DC regulation can be an issue depending on the type of controller used and minimum load required to maintain regulation. If there are no Shottkeys used in parallel with bottom FET, the FET's body diode will need to conduct in asynchronous mode. The high voltage drop of this diode must be considered when determining the criteria for this mode of operation.

## DSPS DR

This pin produces an output which is a logical duplicate of the bottom FET's gate drive, if S-MOD is held LOW.

## OVP_S/OVER TEMP SHUTDOWN

Output over-voltage protection may be implemented on the SC1405 independent of the PWM controller. A voltage divider from the output is compared with the internal bandgap voltage of 1.2 V (typical). Upon exceeding this voltage, the overvoltage comparator disables the top FET, while turning on the bottom FET to allow discharge of the output capacitors excessive voltage through the output inductor. There should be sufficient RC time constant as well as voltage headroom on the OVP_S pin to assure it does not enter overvoltage mode inadvertently. The SC1405 will shutdown if its Tj exceeds $165^{\circ} \mathrm{C}$.

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Performance diagrams, Application Evaluation Board. (Fig.3)



Vin $=12 \mathrm{~V}$,Vout $=1.6 \mathrm{~V}$ Top $\mathrm{FET}=\mathrm{IR} 7811$
FDB7030(BL) Qgd = 23nc

## OUTLINE DRAWING TSSOP-14



| DIMENSIONS (1) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DIM $^{N}$ | INCHES |  | MM |  | NOTE |
|  | MIN | MAX | MIN | MAX |  |
| A | .193 | .201 | 4.90 | 5.10 | (2) |
| B | .169 | .177 | 4.30 | 4.50 | (2) |
| C | .252 | BSC | 6.40 | BSC | - |
| D | .026 | BSC | .65 | BSC | - |
| E | .007 | .012 | .19 | .30 | - |
| F | .002 | .006 | .05 | .15 | - |
| G |  | .047 |  | 1.20 | - |
| J | .004 | .008 | .09 | .20 | - |
| K | $0^{\circ}$ | $8^{\circ}$ | $0^{\circ}$ | $8^{\circ}$ | - |
| L | .018 | .030 | .45 | .75 | - |

JEDEC MO-153AB1
(2) DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSIONS.
(1) CONTROLLING DIMENSIONS: MILLIMETERS.

