

# PixiPoint<sup>™</sup> Z Serial UR7HCPXZ-S440

Advanced "Click-to-Select" No-Drift<sup>™</sup> Pointing Stick Controller

### HID & SYSTEM MANAGEMENT PRODUCTS, MOUSECODER™ FAMILY

### DESCRIPTION

**FEATURES** 

The PixiPoint<sup>™</sup> Z Serial mouse encoder is a cost-effective, highfunctionality IC for strain gauge "miniature joysticks" with Z-axis functionality, such as the CTS series 106, 108 & 109. Ideal for portable and other systems that need to interface a mouse to a serial port, the low-power (typically less than 3mA) PixiPoint<sup>™</sup> Z offers an advanced algorithm for enhanced motion control.

The IC implements the Tap (select) and Double Tap (execute) and Press Hold (drag) functions in firmware. No special drivers are needed to access these "Z" functions. Other special features provided by the IC include CleanStop™, which allows the cursor to stop exactly when you want it to and EasyDrag<sup>™</sup>, which reduces the speed of the cursor during drag, making it easier to handle.

The PixiPoint<sup>™</sup> Z utilizes a special, patented signal conditioning circuit which enables a low-cost, simple and real estate-saving implementation. Just a few low tolerance external components are needed.

Serial transmission use speed of 1200 Baud with 7N1 framing. The IC, a CMOS device operating at 4 MHz, utilizes the standard serial mouse protocol, including Plug-n-Play identification for MouseWheel support.

The PixiPoint<sup>™</sup> Z IC is also available for PS/2-enabled systems.

- Interfaces the system via serial port, making it ideal for non-PC systems
- Accurate No-Drift<sup>™</sup> cursor control via Semtech's advanced algorithm
- Interfaces strain gauge "miniature joysticks" with Z-Axis functionality, such as those from CTS
- Implements the Tap (select), Double Tap (execute) and Press Hold (drag) in firmware - no special serial drivers required
- EasyDrag<sup>™</sup> feature reduces the speed of the cursor during drag, making it easier to handle

### **APPLICATIONS**

Handhelds/Notebooks

**PIN ASSIGNMENTS** 

Smart Phones

- Offers CleanStop™ so cursor stops when you want it to
- Supports Scrolling (MouseWheel) • Low-power consumption of typically less than 3mA makes it
- ideal for battery-operated systems • Operates at 3-5V in extended
- temperature range
- Uses small 32-pin 7mm X 7mm LQFP package
- Inexpensive, turn-key solution
- Utilizes sophisticated, patented signal conditioning circuit requiring less than 15 components
- Customized versions available
- Internet appliances
- Instrumentation



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# ORDERING CODE Package Options Pitch in mm's TA=-20° C to +85° C 32-pin, Plastic LQFP 0.5 UR7HCPXZ-S440-FG Other Materials Type Order number PixiPoint™ Z Serial EK Evaluation Kit EVK7-PXZ-S440-XXX Note 1: XX= Optional Customization XXX= Denotes Revision number

### **BLOCK DIAGRAM**

**PixiPoint™ Z Serial** 





### FUNCTIONAL DESCRIPTION

The UR7HCPXZ-S440 consists functionally of four major sections (see Functional Diagram, previous page). These are the PixiPoint<sup>TM</sup> Z Interface, the 16-Bit Timer, the Oscillator Circuit and the Serial Communication Port. All sections communicate with each other and operate concurrently.

### SIGNAL CONDITIONING CIRCUIT

The PixiPoint<sup>™</sup> Z sensor is a flexible (but very firm) "beam" with four Strain Gauges – one on each of the sides. If force is applied precisely in the X direction, then it will produce a change of resistance of only the two X gauges. Force in the Y direction will cause changes only in the Y gauges. One of the pair of the gauges will increase, while the other will concurrently decrease in resistance.

If the user presses on the sensor from the top (Z-Axis), all of the strain gauges will decrease the resistance.

When a test current is passed through the gauges, these resistance changes are converted into the voltage changes. These signals are very small, typically under 1 mV Full Scale.

The patented Signal Conditioning Circuit balances and amplifies the incoming signals for digitizing by a built-in A/D converter.

### PIN DEFINITIONS

Pin #	Туре	Name and Function
8	<u>P</u>	Power Supply: +5V
11	Р	Ground
7	<u>P</u>	Ground
9	I	Oscillator Input: external clock input or one
		side of the Ceramic Resonator with built-in Load
		Capacitors
10	0	Oscillator Output: open for external clock
		input or other side of the Ceramic Resonator with
		built-in Load Capacitors
6	1	Reset: apply 0V to provide orderly start-up
26	1	Request to Send: High = Disable TX
27	1	Transmit to Host: Idle High
18	I/O (nd)	Left Button: active low, strobed sampling
19	I/O (nd)	Middle Button: active low, strobed sampling
20	I/O (nd)	Scroll Button: active low, strobed sampling
21	I/O (nd)	Right Button: active low, strobed sampling
12	I/O	Sensor's Excitation Driver
13	I/O	Sensor's Excitation Driver: connect to DRV_XY0
14	I/O	Sensor's Excitation Driver
15	I/O	Sensor's Excitation Driver: connect to Z_SIG0
4	I/O	Sensor's Excitation Driver
2	0	Select X: control line for analog multiplexer
3	0	Select Z: control line for analog multiplexer
22	0	Multiplexer Inhibit Signal: active high
5	AI	Reference Voltage for built-in A/D
1	AI	Analog to Digital Converter Input
31	I/O	Digital to Analog Converter Output
32	<u>I/O</u>	Offset: resets the offset circuit during inactivity
23	I/O	Switched Power Driver
24	<u>I/O</u>	Switched Power Driver: connect to SP0
25	I/O	Switched Power Driver: connect to SP0
28	I/O	Switched Power Driver: connect to SP0
29	I/O	Switched Power Driver: connect to SP0
30	I/O	Switched Power Driver: connect to SP0
17	I/O(nd)	Sensor Select Pin: Float - CTS, Low - Bokum
16	I/O(nd)	<b>ZTAP Z Enable Pin:</b> Float - Enabled, Low - Disable
	Pin #           8           11           7           9           10           6           26           27           18           19           20           21           12           13           14           15           4           2           5           1           31           32           23           24           25           28           29           30           17           16	Pin #         Type           8         P           11         P           7         P           9         I           10         O           6         I           26         I           27         I           18         I/O (nd)           20         I/O (nd)           21         I/O (nd)           12         I/O           13         I/O           14         I/O           20         O           33         O           22         O           33         O           22         O           33         I/O           23         I/O           23         I/O           24         I/O           25         I/O           28         I/O           29         I/O           30         I/O           16         I/O(nd)

**Note:** An underscore before a pin mnemonic denotes an active low signal. For SENSOR\_SEL and ZTAP\_EN Pins: Upon power-up they are inputs with pull-up. After initialization, the chip will switch the pull-ups off and drive these pins low. Selection of a particular mode is made by connecting the pin to ground or leaving it not connected (floating). **Pin Types Legend:** AI=Analog Input; I=Input; O=Output; I/O=Input or Output;

I/O (nd)=Input or Output with N-channel Open Drain driver

### SIGNAL CONDITIONING CIRCUIT (CON'T)

Semtech's proprietary circuit can correct a significant imbalance between the gauges in each X and Y pair (+/- 25%), allowing relaxed manufacturing tolerances for the sensors, interconnecting cabling, and temperature-shift induced errors (no performance degradation over the full operating temperature range and for large temperature gradients between the paired gauges).



### **BUILT-IN FEATURES**

Semtech utilizes the scroll button to switch the PixiPoint<sup>™</sup> Z from normal operation mode to scroll mode. When scroll button is pressed, the UR7HCPXZ-S440 will convert the Yaxis data to Z-axis data (scroll data) and output zero motion for X-axis and Y-axis. When the scroll button is released, the UR7HCPXZ-S440 outputs X/Y motion data and zero displacement for Z-Axis.

Tap - Select.

Double Tap — Execute.

Press Hold - Drag.

*EasyDrag*<sup>™</sup> — reduces the speed of the cursor when the user is dragging an object on the desktop, making it simple to accurately handle the object.

 $CleanStop^{\text{TM}}$  — ensures that the cursor stops the instant the user needs it to.

No special drivers are needed to access any of these features. Scrolling (MouseWheel) operations require IntelliMouse-compatible Driver with Plug-n-Play support.

### POWER CONSUMPTION

The UR7HCPXZ-S440 typically consumes less than 3mA. Low-power consumption makes it suitable for use in battery-operated systems.

### SERIAL COMMUNICATION

Communication through the serial port is uni-directional at a fixed speed of 1200 Baud, 7N1 protocol (7 data bits, 1 stop bit, no parity check).

The Host can reset the device at any time by setting the RTS line High. When RTS is set Low after a delay of at least 100ms, the device will respond with an Identification and Plug-n-Play strings. This procedure is known as "RTS Toggle Handshaking." When RTS goes low, the device will send the ID characters "MZ" (0x4D, 0x5A) indicating wheel capability to the Host. Then a ZERO motion report (0x40, 0x00, 0x00, 0x00) is sent as a separator, followed by the Plug and Play string "vvPNP0F0A\\MOUSE\PNP0F0A\USAR SERIAL PIXZ MOUSEcc."

Plug and Play is a sequence of ASCII characters with their codes reduced by 0x20. Note, vv is a version number, 2 Bytes, and cc is a Check Sum, 2 Bytes. For further information, please refer to "Plug and Play External COM Device Specification," available from Microsoft.

4-Byte Data Report is sent if motion is detected, or if buttons are pressed or released. Motion is reported relative to the last Report sent, in a Two's Complement form and eight (8) bit resolution. In other words, the Maximum Motion values are -128 to +127, saturated at min/max for faster speeds. Z3-Z0 is Z-displacement. It is 4-bit Two's Complement value from -8 to +7.



### HARDWARE INTERFACE FOR THE COMMUNICATION LINES

The TXD and RTS lines are CMOS logic-level signals, suitable for direct connection to the pins of an UART. Interfacing via the RS-232 port requires an addition of an inverting driver and receiver. Simple one-transistor inverting driver and receiver can also be utilized. Contact Semtech for more details.

FEATURES	
Byte 1	
b0 b1 b2 b3 b4 b5 b6	X6 X7: MSB of X Data Y6 Y7: MSB of Y Data Right Button Status, 1 = depressed Left Button Status, 1 = depressed Always=1
Byte 2	
b0 b1 b2 b3 b4 b5 b6	X0: LSB of X data X1 X2 X3 X4 X5 Always=0
Byte 3	
b0 b1 b2 b3 b4 b5 b6	Y0: LSB of Y data Y1 Y2 Y3 Y4 Y5 Always=0
Byte 4	
b0 b1 b2 b3 b4 b5 b6	Z0: LSB of Z data Z1 Z2 Z3: MSB of Z data Middle Button Status; 1=depressed Always=0 Always=0



SUGGESTED INTERFACING FOR THE PIXIPOINT™ Z SERIAL UR7HCPXZ-S440-FG





MECHANICAL INFORMATION FOR FG (32 PIN LQFP) PACKAGE





ΗD D

A1 A2		U A
	Detail F	

<u>etali F</u>



Recommended PCB Footprint

Symbol	Dimens	ion in Mill	imeters
Symbol	Min	Nom	Max
Α	_	-	1.7
A1	0	0.1	0.2
A2	_	1.4	_
b	0.3	0.35	0.45
С	0.105	0.125	0.175
D	6.9	7.0	7.1
E	6.9	7.0	7.1
е	_	0.8	_
HD	8.8	9.0	9.2
HE	8.8	9.0	9.2
L	0.3	0.5	0.7
L1	_	1.0	_
у	_	-	0.1
$\theta$	٥r		10Y
b2	_	0.5	_
12	1.0	_	_
MD	-	7.4	_
ME	_	7.4	_

A



## ELECTRICAL SPECIFICATIONS

<b>Absolute Maximum Ratings</b>			
Ratings	Symbol	Value	Unit
Supply Voltage	Vdd	-0.3 to 7.0	V
Input Voltage	Vin	Vss -0.3 to Vdd +0.3	V
Current Drain per Pin	1	20	mA
(not including Vss or Vdd)			
Operating Temperature	Та	T low to T high	°C
UR7HCPXZ-S440		-20 to +85	° C
Storage Temperature Range	Tstg	-40 to +125	° C
(not including Vss or Vdd) Operating Temperature UR7HCPXZ-S440 Storage Temperature Range	Ta Tstg	T low to T high -20 to +85 -40 to +125	0 0 0

### DC Electrical Characteristics, Temperature range=T low to T high unless otherwise noted)

Characteristic	Symbol	Min	Тур	Max	Unit
Supply Voltage		3.0	5.0	5.5	V
Output Voltage (10 µA load)	Voh	Vdd-0.1			V
	Vol			0.1	
Input High Voltage	Vih	0.8 x Vdd		Vdd	V
Input Low Voltage	Vil	Vss		0.2xVdd	V
Input Current	lin			+/- 1	μA
Supply Current					
(Vdd=5.0 Vdc+/-10%, Vss=0)	Idd		3.0	TBD	mA

Control Timing (Vdd=5.0 V	/dc +/-10%, Vss=0 V	dc, Temperatur	e range=T low to T	「high unless otherwi	se noted)
Characteristic	Symbol	Min	Тур	Max	Unit
Frequency of Operation	fosc				MHz
Crystal Option			4.0		
External Clock Option			4.0		

### Sensor Characteristics

Characteristic	Symbol	Min	Тур	Max	Unit
Resistance	Rx	2K		10K	Ohms
Matching	Rx1/Rx2	75		125	%
-	Ry1/Ry2	75		125	%



### PIXIPOINT™ Z SERIAL BILL OF MATERIALS FOR PAGE 6 SCHEMATIC

Description	Quantity	Manufacturer	Part#	Description
Consoltorou	Quantity	manufacturer	Γ αι t π	Description
		Conorio		
	· <u> </u>	Generic	Any	100pF, 5%, Ceramic, NPO or X/R
<u>C2, C3</u>	2	Generic	Any	.01uF, 10% Ceramic, X7R
C4	1	Generic	Any	.1uF, 10%, Ceramic, X7R or Z5U
C5	1	Generic	Any	47uF, 10%, Ceramic, X7R or Z5U
C8	1	Generic	Any	1uF, +80/-20% Ceramic X5R, Z5U, Y5V
ICs:				
U4	1	National	LMV321M5	Single OpAmp, Low Voltage, SOT23-5
U3	1	Generic	74HC4053	Tri 2-ch Analog Mux
U1	1	Semtech	UR7HCPXZ-S440-FG	PixiPoint <sup>™</sup> Z Controller
U2	1	TelCom	TC54VC2702ECB	Reset IC
Resistors:				
R2	1	Generic	Any	1k, 5%, 1/16W
R3	1	Generic	Any	3.16k, 1%, 1/16W
R1	1	Generic	Any	22k, 5%, 1/16W
R4,R5	2	Generic	Any	100k, 5%, 1/16W
Resonator:				
Y1	1	AVX	PBRC-4.00BR	4.00MHz Ceramic Resonator w/ Caps, SMT
Transistor:				
Q1	1	Zetex	BSS84ZXCT	MOSFET P Transistor, SMT, SOT-23



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