

# SM3903

## 4-Bit Single-Chip Microcomputer (For Remote Control)

### DESCRIPTION

The SM3903 is a CMOS 4-bit single-chip microcomputer incorporating 4-bit parallel processing function, carrier output circuit for remote control, ROM, RAM, 15-stage divider. Provided with 132 segments LCD drive circuit, this microcomputer is applicable to remote control system with a Low power consumption.

### FEATURES

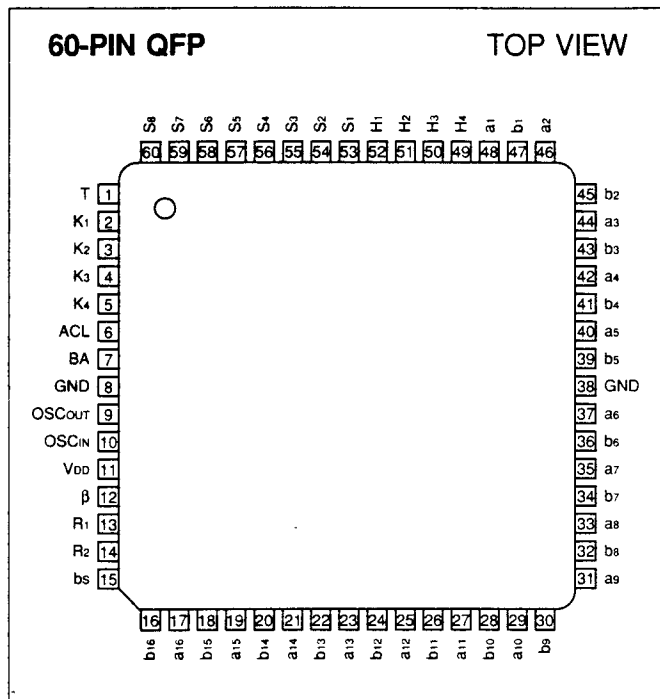
- ROM capacity : 2 772 x 8 bits
- RAM capacity : 128 x 4 bits (including 32 x 4 bits display RAM)
- Instruction sets : 49
- Subroutine nesting : 2 levels
- I/O Port :
 

Input	6
Output	10

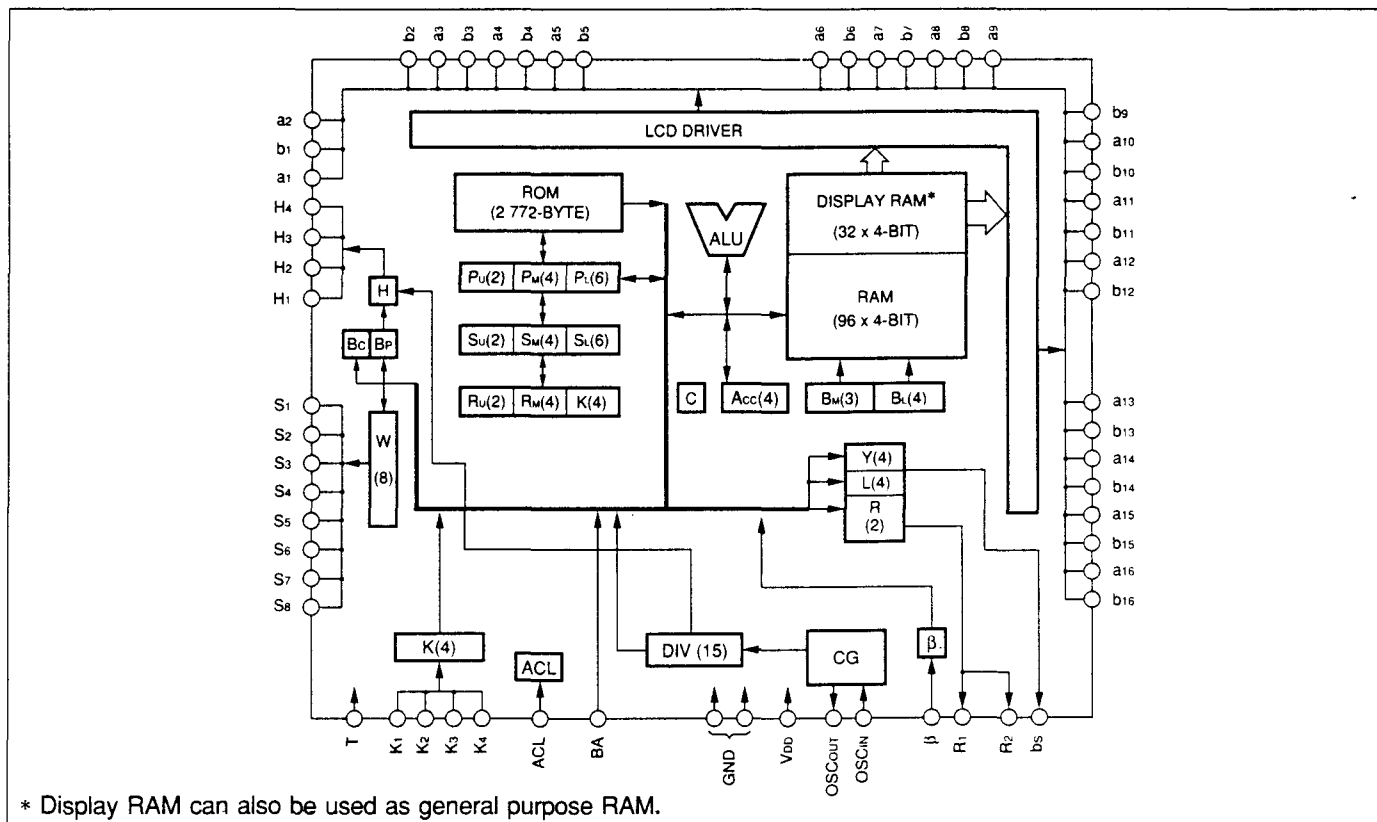
  - 33 (Used as LCD segment output port)
  - 4 (Used as LCD common output port)
- Built-in main clock oscillator for system clock
- Signal generation for real time clock
- Built-in 15 stages divider circuit for real time clock
- Built-in carrier output circuit for remote control
- Built-in LCD driver : 132 segments (1/3 bias, 1/4 duty cycle)
- Built-in carrier output circuit for remote control
 

Carrier frequency	32.768 kHz
Basic oscillation frequency (main clock)	32.768 kHz
Duty cycle	1/2
- Instruction cycle time : 61  $\mu$ s (TYP., 32.768 kHz, at -3 V)
- Standby function
- Supply voltage : -2.6 to -3.2 V
- Package : 60-pin QFP(QFP060-P-1414)

### PIN CONNECTIONS



## BLOCK DIAGRAM



## Nomenclature

ALU	: Arithmetic logic unit	W	: 8-bit shift register
Acc	: Accumulator	$\beta$	: Independent input register
ACL	: Auto clear circuit	$B_M, B_L$	: RAM address register
C	: Carry F/F	$B_P, B_C$	: Backplate signal generator circuit
$P_U, P_M, P_L$	: Program counter	H, L, Y	: 4-bit F/F
$S_U, S_M, S_L$	: Stack register of program counter	R	: Control register for remote control output
$R_U, R_M, R_L$	: Stack register of program counter	K	: Key input F/F
DIV	: Divider	CG	: Clock Generator

## PIN DESCRIPTION

SYMBOL	I/O	CIRCUIT TYPE	FUNCTION
$a_i, b_i$	O		Segment output ports ( $i = 1$ to 16)
$b_s$			
$H_1-H_4$	O		Common output ports
$S_1-S_8$	O		Strobe output ports
T	I		Test input port (normally connected to GND)
$K_1-K_4$	I	pull-down	Key input ports
$OSC_{IN}$			Crystal oscillator
$OSC_{OUT}$			
BA, $\beta$	I	pull-up	Independent input ports
GND, $V_{DD}$			Power supply
$R_1, R_2$	O		Remote control carrier output
ACL	I	pull-down	Auto clear input port

## ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	RATING	UNIT	NOTE
Supply voltage	V <sub>DD</sub>	-3.5 to +0.3	V	1
	V <sub>IN</sub>	V <sub>DD</sub> to +0.3	V	
Operating temperature	T <sub>OPR</sub>	0 to +50	°C	
Storage temperature	T <sub>STG</sub>	-20 to +125	°C	

## NOTE :

1. The maximum applicable voltage on any pin with respect to GND.

## RECOMMENDED OPERATING CONDITIONS

PARAMETER	SYMBOL	RATING	UNIT
Supply voltage	V <sub>DD</sub>	-3.2 to -2.6	V
Crystal oscillation frequency	fosc	32.768 (TYP.)	kHz

## DC CHARACTERISTICS

(V<sub>DD</sub> = -3.2 to -2.9 V, T<sub>a</sub> = 25°C)

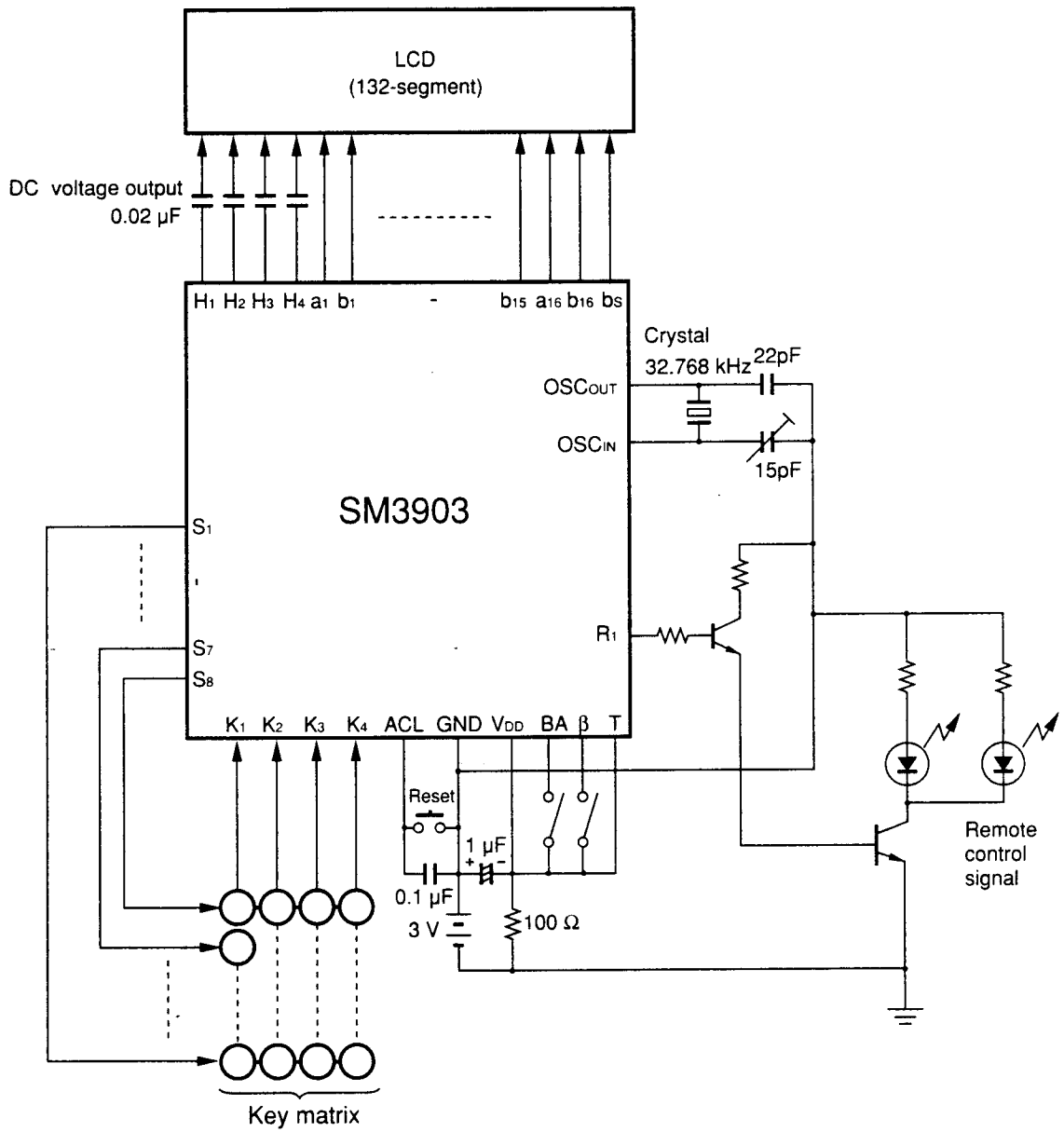
PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNIT	NOTE
Input voltage	V <sub>IH1</sub>		-0.6			V	1
	V <sub>IL1</sub>				V <sub>DD</sub> +0.6	V	
	V <sub>IH2</sub>		-0.3			V	2
	V <sub>IL2</sub>				V <sub>DD</sub> +0.3	V	
Input current	I <sub>IH</sub>	V <sub>IN</sub> = 0 V			15	μA	3
	I <sub>IL</sub>	V <sub>IN</sub> = V <sub>DD</sub>			15	μA	4
Output voltage	V <sub>OH</sub>	I <sub>OUT</sub> = 50 μA to V <sub>DD</sub>	-0.5			V	5
	V <sub>OL</sub>	I <sub>OUT</sub> = 5 μA to GND			V <sub>DD</sub> +0.5	V	
	V <sub>OA</sub>	V <sub>DD</sub> = -3.0 V No load	-0.3	0	0	V	6
	V <sub>OB</sub>		-1.3	-1.0	-0.7	V	
	V <sub>OC</sub>		-2.3	-2.0	-1.7	V	
	V <sub>OD</sub>		-3.0	-3.0	-2.7	V	
Output current	I <sub>SO</sub>	V <sub>OUT</sub> = -0.2 V	100			μA	7
	I <sub>SIN</sub>	V <sub>OUT</sub> = V <sub>DD</sub> +0.2 V	100			μA	
Supply current	I <sub>DA</sub>	During full-range operation		40		μA	8
	I <sub>DS</sub>	When system clock is stationary		12		μA	

## NOTES :

1. Applied to pins K<sub>1</sub>-K<sub>4</sub>, β.
2. Applied to pins ACL, BA.
3. Applied to pins K<sub>1</sub>-K<sub>4</sub>.
4. Applied to pin β.
5. Applied to pins S<sub>1</sub>-S<sub>8</sub>.
6. Applied to pins a<sub>1</sub>-a<sub>16</sub>, b<sub>1</sub>-b<sub>16</sub>, b<sub>s</sub>, H<sub>1</sub>-H<sub>4</sub>.
7. Applied to pins R<sub>1</sub>, R<sub>2</sub>.
8. No load condition when bleeder resistance is ON.

### SYSTEM CONFIGURATION EXAMPLE

- Remote control with LCD display



Singlechip LH7xxxx '790 '789 '791 SMxxxx 'K series MCU Microcontroller MPU Microprocessor  
ARM Advanced RISC Machines Databank LCD Controller LCD Driver Controllers Processors Portable  
Low Power Low Voltage High Performance Power curve MIPS MIPS/Watt Execution Cycle Multiplier  
High Speed Compact Handheld System on Chip System Integration Chip Integration Integration  
Superchip Standard Cell Core Core based IC VHDL Verilog Synthesis Chip on Board COB Chip on Flex  
COF Device on Board DOB Power Supply Controller Handy Products Development Tools Board Support  
Software Tools Tools 2.10 Software Support Emulators Evaluation Boards ICE In-Circuit Emulators  
ROM ICE SME Series Programmable User Configurable RTOS Real Time Operating Systems  
Third Party Support Software Hardware Yokogawa Digital Cosmic Compiler C Language C Like  
Assembler Linker Debugger Debug A/D D/A DAC Analog Digital 10-bit 4-bit 8-bit 16-bit 32-bit  
Address bus Data Bus