# SN65LVDS95 LVDS SERDES TRANSMITTER

SLLS297F - MAY 1998 - REVISED FEBRUARY 2000

**DGG PACKAGE** 

(TOP VIEW)

- 21:3 Data Channel Compression at up to 1.36 Gigabits per Second Throughput **Suited for Point-to-Point Subsystem Communication With Very Low EMI**
- 21 Data Channels Plus Clock in Low-Voltage TTL and 3 Data Channels Plus **Clock Out Low-Voltage Differential**
- Operates From a Single 3.3-V Supply and 250 mW (Typ)
- 5-V Tolerant Data Inputs
- 'LVDS95 Has Rising Clock Edge Triggered Inputs
- **Bus Pins Tolerate 6-kV HBM ESD**
- Packaged in Thin Shrink Small-Outline Package With 20 Mil Terminal Pitch
- Consumes <1 mW When Disabled
- Wide Phase-Lock Input Frequency Range 20 MHz to 65 MHz
- No External Components Required for PLL
- Inputs Meet or Exceed the Requirements of ANSI EIA/TIA-644 Standard
- **Industrial Temperature Qualified**  $T_A = -40^{\circ}C$  to  $85^{\circ}C$
- Replacement for the National DS90CR215

#### 48**|** D3 D4 [ 47 D2 V<sub>CC</sub> 🛮 2 D5 🛮 3 46 GND D6 **□** 4 45 D1 GND [ 44 D0 5 43 NC D7 [ 6 D8 **∏** 7 42 LVDSGND V<sub>CC</sub> **∏** 8 41 YOM D9 **∏** 9 40 Y0P D10 **□** 10 39 Y1M GND I 11 38 Y1P 37 LVDSV<sub>CC</sub> D11 [ 12 D12 [ 13 36 LVDSGND V<sub>CC</sub> [] 14 35 Y2M 34 Y2P D13 **1** 15 D14 **□** 16 33 CLKOUTM 17 32 CLKOUTP GND [ 31 LVDSGND D15 [ 18 30 T PLLGND 19 D16 [ 29 PLLV<sub>CC</sub> D17 [ 20 V<sub>CC</sub> [] 21 28 PLLGND 27 SHTDN D18 22 D19 1 23 26 CLKIN 24 25 D20 GND

#### description

The SN65LVDS95 LVDS serdes (serializer/deserializer) transmitter contains three 7-bit parallel-load serial-out shift registers, a 7x clock synthesizer, and four low-voltage differential signaling (LVDS) line drivers in a single integrated circuit. These functions allow 21 bits of single-ended LVTTL data to be synchronously transmitted over 4 balanced-pair conductors for receipt by a compatible receiver, such as the SN65LVDS96.

When transmitting, data bits D0 through D20 are each loaded into registers of the SN65LVDS95 on the rising edge of the input clock signal (CLKIN). The frequency of CLKIN is multiplied seven times and then used to serially unload the data registers in 7-bit slices. The three serial streams and a phase-locked clock (CLKOUT) are then output to LVDS output drivers. The frequency of CLKOUT is the same as the input clock, CLKIN.

The SN65LVDS95 requires no external components and little or no control. The data bus appears the same at the input to the transmitter and output of the receiver with data transmission transparent to the user(s). The only user intervention is the possible use of the shutdown/clear (SHTDN) active-low input to inhibit the clock and shut off the LVDS output drivers for lower power consumption. A low level on this signal clears all internal registers to a low level.

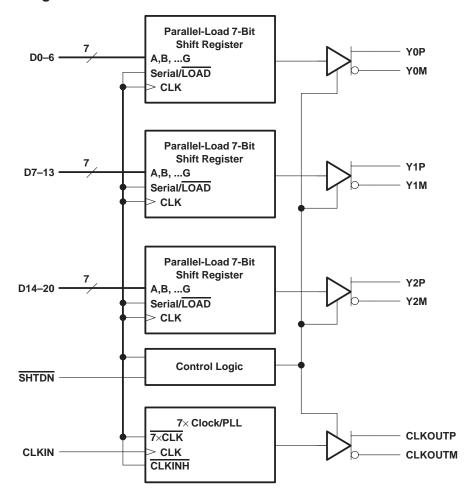
The SN65LVDS95 is characterized for operation over ambient air temperatures of -40°C to 85°C.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



# functional block diagram



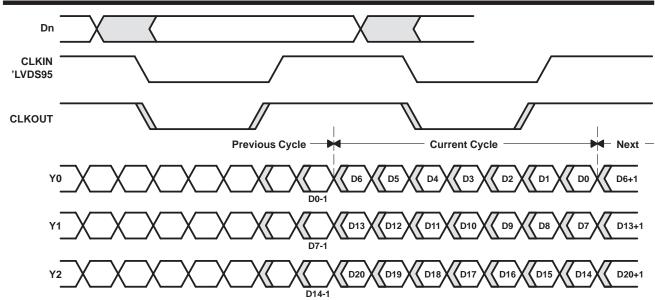
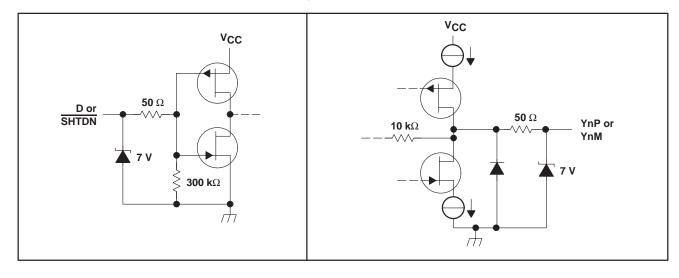


Figure 1. 'LVDS95 Load and Shift Sequences

# equivalent input and output schematic diagrams



# absolute maximum ratings over operating free-air temperature (unless otherwise noted)†

| Supply voltage range, V <sub>CC</sub> (see Note 1)        |                                |
|---|--------------------------------|
| Voltage range at any output terminal, VO                  |                                |
| Voltage range at any input terminal, V <sub>1</sub>       | –0.5 V to 5.5 V                |
| Electrostatic discharge (see Note 2): Bus pins (Class 3A) | 6 KV                           |
| Bus pins (Class 2B)                                       | 400 V                          |
| All pins (Class 3A)                                       | 6 KV                           |
| All pins (Class 2B)                                       | 200 V                          |
| Continuous total power dissipation                        | (see Dissipation Rating Table) |
| Operating free-air temperature range, T <sub>A</sub>      | –40°C to 85°C                  |
| Storage temperature range, T <sub>stq</sub>               | –65°C to 150°C                 |
| Lead temperature 1,6 mm (1/16 inch) from case for 10 sec  |                                |

<sup>†</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. All voltage values are with respect to the GND terminals.

#### **DISSIPATION RATING TABLE**

| PACKAGE | ACKAGE $T_A \le 25^{\circ}C$ DERATING FACTOR $\ddagger$ POWER RATING ABOVE $T_A = 25^{\circ}C$ P |            | T <sub>A</sub> = 70°C<br>POWER RATING | T <sub>A</sub> = 85°C<br>POWER RATING |
|---------|--|------------|---------------------------------------|---------------------------------------|
| DGG     | 1316 mW  | 13.1 mW/°C | 724 mW                                | 526 mW                                |

<sup>&</sup>lt;sup>‡</sup> This is the inverse of the junction-to-ambient thermal resistance when board-mounted and with no air flow.

## recommended operating conditions

|  | MIN | NOM | MAX | UNIT |
|--|-----|-----|-----|------|
| Supply voltage, V <sub>CC</sub>                | 3   | 3.3 | 3.6 | V    |
| High-level input voltage, VIH                  | 2   |     |     | V    |
| Low-level input voltage, V <sub>IL</sub>       |     |     | 0.8 | V    |
| Differential load impedance, Z <sub>L</sub>    | 90  |     | 132 | Ω    |
| Operating free-air temperature, T <sub>A</sub> | -40 |     | 85  | °C   |

<sup>2.</sup> This rating is measured using MIL-STD-883C Method, 3015.7.

# electrical characteristics over recommended operating conditions (unless otherwise noted)

|                   | PARAMETER   | TEST CONDITIONS   | MIN   | TYP <sup>†</sup> | MAX   | UNIT |
|-------------------|---|---|-------|------------------|-------|------|
| VIT               | Input voltage threshold   |   |       | 1.4              |       | V    |
| IVODI             | Differential steady-state output voltage magnitude  |   | 247   |                  | 454   |      |
| Δ V <sub>OD</sub> | Change in the steady-state differential output voltage magnitude between opposite binary states | $R_L$ = 100 Ω, See Figure 3   |       |                  | 50    | mV   |
| Voc(ss)           | Steady-state common-mode output voltage   | See Figure 3  | 1.125 |                  | 1.375 | V    |
| VOC(PP)           | Peak-to-peak common-mode output voltage   | See Figure 3  |       | 80               | 150   | mV   |
| lН                | High-level input current  | VIH = VCC   |       |                  | 20    | μΑ   |
| Ι <sub>Ι</sub> L  | Low-level input current   | V <sub>IL</sub> = 0 V   |       |                  | ±10   | μΑ   |
| laa               | Short-circuit output current  | VOX = 0 V   |       |                  | ±24   | mA   |
| los               |   | V <sub>OD</sub> = 0 V   |       |                  | ±12   | mA   |
| loz               | High-impedance state output current   | $V_O = 0 V \text{ to } V_{CC}$  |       |                  | ±10   | μΑ   |
|                   | Quiescent current (average)   | Disabled, all inputs at GND   |       |                  | 280   | μΑ   |
| ICC(AVG)          |   | Enabled, $R_L = 100 \Omega$ (4 places),<br>Worst-case pattern (see Figure 4),<br>$t_C = 15.38 \text{ ns}$ |       | 85               | 110   | mA   |
| Ci                | Input capacitance   |   |       | 3                |       | pF   |

<sup>†</sup> All typical values are  $V_{CC}$  = 3.3 V,  $T_A$  = 25°C.

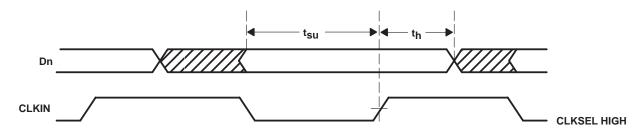
# timing requirements

|                 |  | MIN               | NOM            | MAX               | UNIT |
|-----------------|--|-------------------|----------------|-------------------|------|
| t <sub>C</sub>  | Input clock period   | 15.4              | t <sub>C</sub> | 50                | ns   |
| t <sub>W</sub>  | High-level input clock pulse width duration                        | 0.4t <sub>C</sub> |                | 0.6t <sub>C</sub> | ns   |
| t <sub>t</sub>  | Input signal transition time                                       |                   |                | 5                 | ns   |
| t <sub>su</sub> | Data setup time, D0 through D27 before CLKIN↑ ('95) (see Figure 2) | 3                 |                |                   | ns   |
| th              | Data hold time, D0 through D27 after CLKIN↑ ('95) (see Figure 2)   | 1.5               |                |                   | ns   |

# switching characteristics over recommended operating conditions (unless otherwise noted)

|                    | PARAMETER   | TEST CONDITIONS  | MIN                     | TYP <sup>†</sup>        | MAX                     | UNIT |
|--------------------|---|--|-------------------------|-------------------------|-------------------------|------|
| t <sub>O</sub>     | Delay time, CLKOUT serial bit position 0  |  | -0.20                   | 0                       | 0.20                    | ns   |
| t <sub>1</sub>     | Delay time, CLKOUT↑ serial bit position 1                                       | 1  | 1/7t <sub>C</sub> -0.20 |                         | 1/7t <sub>C</sub> +0.20 | ns   |
| t <sub>2</sub>     | Delay time, CLKOUT↑ serial bit position 2                                       | 1  | 2/7t <sub>C</sub> -0.20 | 2/7t <sub>C</sub> +0.20 | ns                      |      |
| t <sub>3</sub>     | Delay time, CLKOUT↑ serial bit position 3                                       | $t_C = 15.38 \text{ ns } (\pm 0.2\%),$   | 3/7t <sub>C</sub> -0.20 | 3/7t <sub>C</sub> +0.20 | ns                      |      |
| t <sub>4</sub>     | Delay time, CLKOUT↑ serial bit position 4                                       | Input clock jitter  < 50 ps‡,<br>  See Figure 5  | 4/7t <sub>C</sub> -0.20 |                         | 4/7t <sub>C</sub> +0.20 | ns   |
| t <sub>5</sub>     | Delay time, CLKOUT↑ serial bit position 5                                       | Jess i gare e  | 5/7t <sub>C</sub> -0.20 |                         | 5/7t <sub>C</sub> +0.20 | ns   |
| t <sub>6</sub>     | Delay time, CLKOUT↑ serial bit position 6                                       |  | 6/7t <sub>C</sub> -0.20 |                         | 6/7t <sub>C</sub> +0.20 | ns   |
| t <sub>sk(o)</sub> | Output skew, t <sub>n</sub> -n/7 t <sub>C</sub>                                 |  | -0.20                   |                         | 0.20                    | ns   |
| t <sub>7</sub>     | Delay time, CLKIN <sup>↑</sup> to CLKOUT <sup>↑</sup>                           | $t_C$ = 15.38 ns (±0.2%),<br> Input clock jitter  < 50 ps <sup>‡</sup> ,<br>See Figure 5 |                         | 4.2                     |                         | ns   |
| A4                 | 0 to tale to the to the 5 %   | $t_{\rm C}$ = 15.38 ns + 0.75 sin(2 $\pi$ 500E3t) $\pm$ 0.05 ns, See Figure 6            | ±80 ±80                 |                         |                         | ps   |
| ∆tC(O)             | Output clock cycle-to-cycle jitter§   | $t_{\rm C}$ = 15.38 ns + 0.75 sin(2 $\pi$ 2E6t)<br>±0.05 ns, See Figure 6                |                         | ±300                    |                         | ps   |
| t <sub>W</sub>     | High-level output clock pulse duration  |  |                         | 4/7 t <sub>C</sub>      |                         | ns   |
| t <sub>t</sub>     | Differential output voltage transition time (t <sub>r</sub> or t <sub>f</sub> ) | See Figure 3   | 260                     | 700                     | 1500                    | ps   |
| t <sub>en</sub>    | Enable time, SHTDN↑ to phase lock (Yn valid)                                    | See Figure 7   |                         | 1                       |                         | ms   |
| <sup>t</sup> dis   | Disable time, SHTDN↓ to off-state (CLKOUT low)                                  | See Figure 8   |                         | 250                     |                         | ns   |

## PARAMETER MEASUREMENT INFORMATION



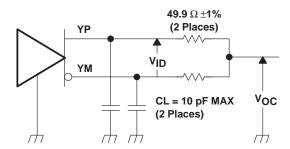
NOTE: All input timing is defined at 1.4 V on an input signal with a 10% to 90% rise or fall time of less than 5 ns.

Figure 2. Setup and Hold Time Definition

<sup>†</sup> All typical values are V<sub>CC</sub> = 3.3 V, T<sub>A</sub> = 25°C. ‡ [Input clock jitter] is the magnitude of the change in the input clock period.

<sup>§</sup> The output clock jitter is the change in the output clock period from one cycle to the next cycle observed over 15,000 cycles.

# PARAMETER MEASUREMENT INFORMATION



NOTE: The lumped instrumentation capacitance for any single ended voltage measurement is less than or equal to 10 pF. When making measurements at YP or YM, the complementary output shall be similarly loaded.

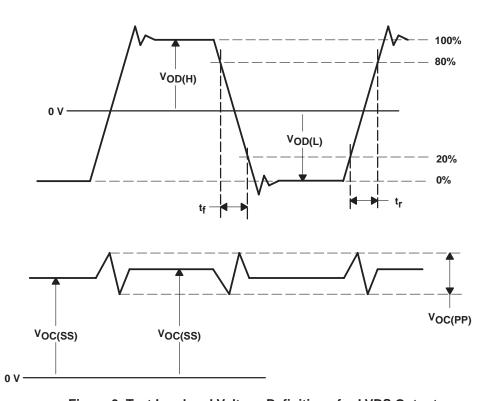


Figure 3. Test Load and Voltage Definitions for LVDS Outputs

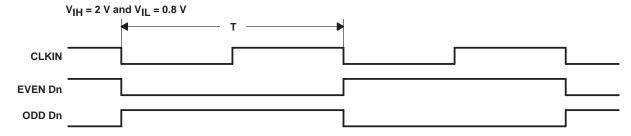
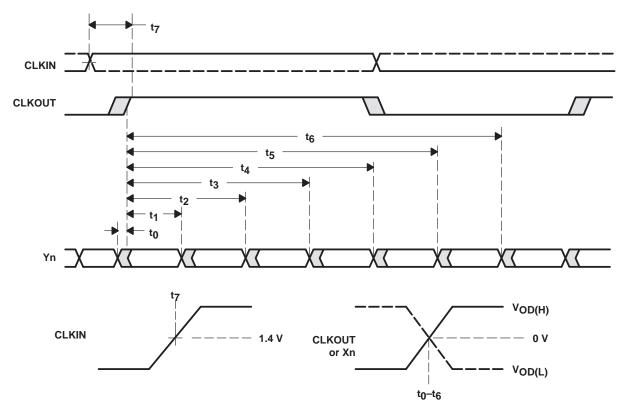


Figure 4. Worst-Case<sup>‡</sup> Power Test Pattern

<sup>&</sup>lt;sup>‡</sup> The worst-case test pattern produces nearly the maximum switching frequency for all of the LV-TTL outputs.



# PARAMETER MEASUREMENT INFORMATION



**Figure 5. Timing Definitions** 

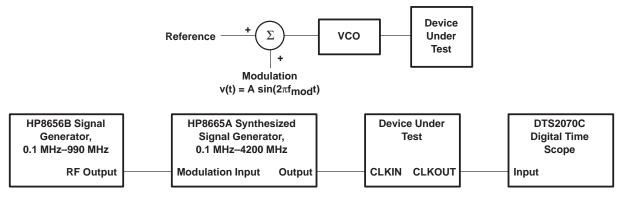


Figure 6. Clock Jitter Test Setup

## PARAMETER MEASUREMENT INFORMATION

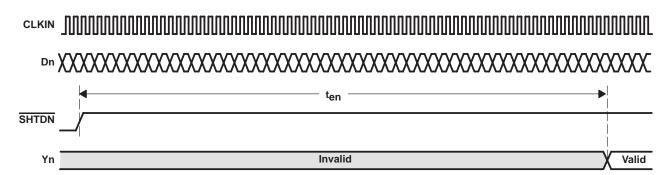


Figure 7. Enable Time Measurement Definition

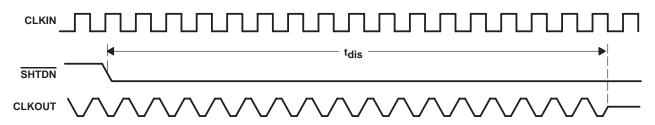


Figure 8. Disable Time Measurement Definition

## TYPICAL CHARACTERISTICS

#### **WORST-CASE SUPPLY CURRENT**

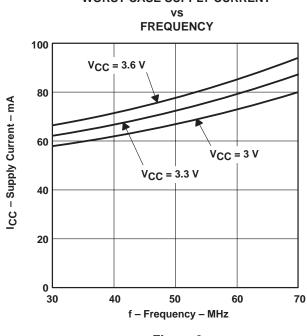


Figure 9



#### **APPLICATION INFORMATION**

#### 16-bit bus extension

In a 16-bit bus application (Figure 10), TTL data and clock coming from bus transceivers that interface the backplane bus arrive at the Tx parallel inputs of the LVDS serdes transmitter. The clock associated with the bus is also connected to the device. The on-chip PLL synchronizes this clock with the parallel data at the input. The data is then multiplexed into three different line drivers which perform the TTL to LVDS conversion. The clock is also converted to LVDS and presented to a separate driver. This synchronized LVDS data and clock at the receiver, which recovers the LVDS data and clock, performs a conversion back to TTL. Data is then demultiplexed into a parallel format. An on-chip PLL synchronizes the received clock with the parallel data, and then all are presented to the parallel output port of the receiver.

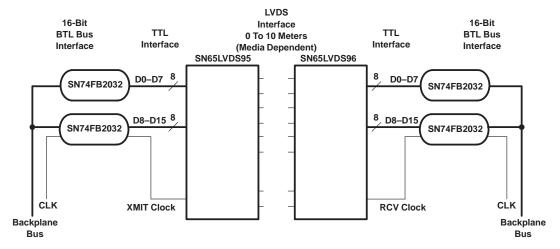


Figure 10. 16-Bit Bus Extension

#### 16-bit bus extension with parity

In the previous application we did not have a checking bit that would provide assurance that the data crosses the link. If we add a parity bit to the previous example, we would have a diagram similar to the one in Figure 11. The device following the SN74FB2032 is a low cost parity generator. Each transmit-side transceiver/parity generator takes the LVTTL data from the corresponding transceiver, performs a parity calculation over the byte, and then passes the bits with its calculated parity value on the parallel input of the LVDS serdes transmitter. Again, the on-chip PLL synchronizes this transmit clock with the eighteen parallel bits (16 data + 2 parity) at the input. The synchronized LVDS data/parity and clock arrive at the receiver.

The receiver performs the conversion from LVDS to LVTTL and the transceiver/parity generator performs the parity calculations. These devices compare their corresponding input bytes with the value received on the parity bit. The transceiver/parity generator will assert its parity error output if a mismatch is detected.



#### **APPLICATION INFORMATION**

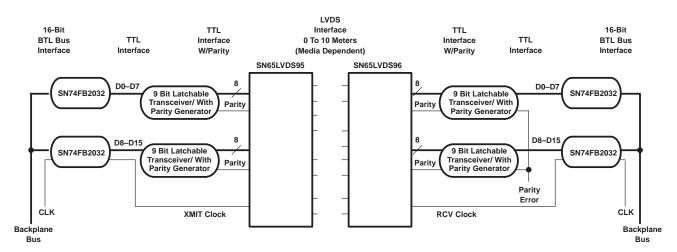


Figure 11. 16-Bit Bus Extension With Parity

#### low cost virtual backplane transceiver

Figure 12 represents LVDS serdes in an application as a virtual backplane transceiver (VBT). The concept of a VBT can be achieved by implementing individual LVDS serdes chipsets in both directions of subsystem serialized links.

Depending on the application, the designer will face varying choices when implementing a VBT. In addition to the devices shown in Figure 12, functions such as parity and delay lines for control signals could be included. Using additional circuitry, half-duplex or full-duplex operation can be achieved by configuring the clock and control lines properly.

The designer may choose to implement an independent clock oscillator at each end of the link and then use a PLL to synchronize LVDS serdes's parallel I/O to the backplane bus. Resynchronizing FIFOs may also be required.

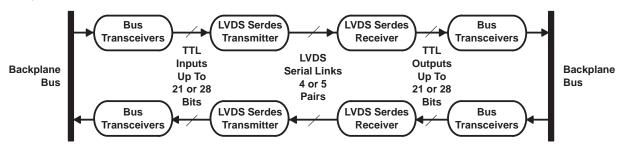


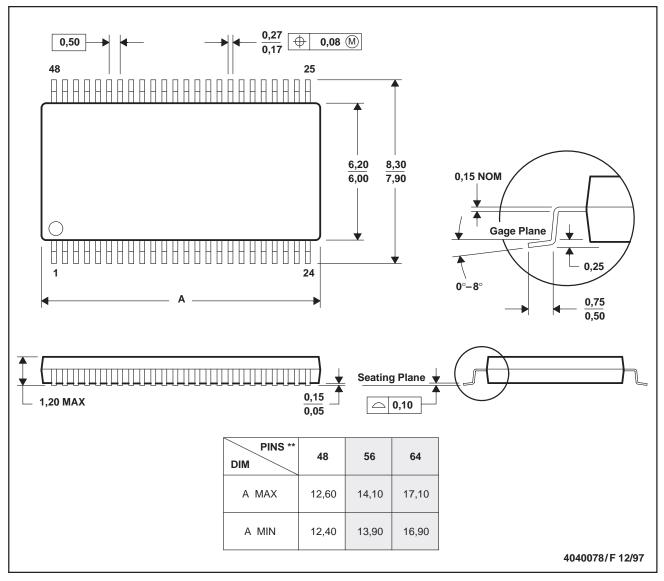
Figure 12. Virtual Backplane Transceiver

# **MECHANICAL DATA**

# DGG (R-PDSO-G\*\*)

#### PLASTIC SMALL-OUTLINE PACKAGE

## **48 PIN SHOWN**



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold protrusion not to exceed 0,15.
- D. Falls within JEDEC MO-153



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