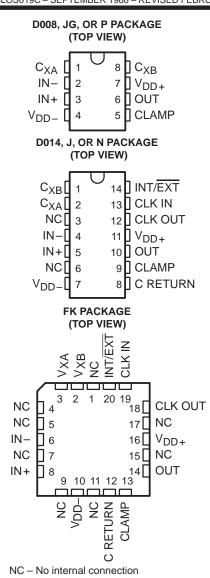
- Extremely Low Offset Voltage ... 1 μV Max
- Extremely Low Change on Offset Voltage With Temperature . . . 0.003 $\mu\text{V/}^\circ\text{C}$ Typ
- Low Input Offset Current 500 pA Max at T_A = - 55°C to 125°C
- A_{VD} . . . 135 dB Min
- CMRR and k_{SVR} . . . 120 dB Min
- Single-Supply Operation
- Common-Mode Input Voltage Range Includes the Negative Rail
- No Noise Degradation With External Capacitors Connected to V_{DD}_

description

The TLC2652 and TLC2652A are high-precision chopper-stabilized operational amplifiers using Texas Instruments Advanced LinCMOS[™] process. This process in conjunction with unique chopper-stabilization circuitry produces opera tional amplifiers whose performance matches or exceeds that of similar devices available today.

Chopper-stabilization techniques make possible extremely high dc precision by continuously nulling input offset voltage even during variation in temperature, time, common-mode voltage, and power supply voltage. In addition, low-frequency noise voltage is significantly reduced. This high precision, coupled with the extremely high input impedance of the CMOS input stage, makes the TLC2652 and TLC2652A an ideal choice for low-level signal processing applications such as strain gauges, thermocouples, and other transducer amplifiers. For applications that require extremely low noise and higher usable bandwidth, use the TLC2654 or TLC2654A device, which has a chopping frequency of 10 kHz.



The TLC2652 and TLC2652A input common-mode range includes the negative rail, thereby providing superior performance in either single-supply or split-supply applications, even at power supply voltage levels as low as ± 1.9 V.

Two external capacitors are required for operation of the device; however, the on-chip chopper-control circuitry is transparent to the user. On devices in the 14-pin and 20-pin packages, the control circuitry is made accessible to allow the user the option of controlling the clock frequency with an external frequency source. In addition, the clock threshold level of the TLC2652 and TLC2652A requires no level shifting when used in the single-supply configuration with a normal CMOS or TTL clock input.

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PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.



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On products compliant to MIL-PRF-38535, all parameters are tested unless otherwise noted. On all other products, production processing does not necessarily include testing of all parameters.

description (continued)

Innovative circuit techniques are used on the TLC2652 and TLC2652A to allow exceptionally fast overload recovery time. If desired, an output clamp pin is available to reduce the recovery time even further.

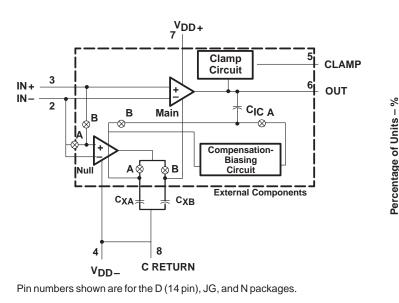
The device inputs and output are designed to withstand – 100-mA surge currents without sustaining latch-up. Additionally the TLC2652 and TLC2652A incorporate internal ESD-protection circuits that prevent functional failures at voltages up to 2000 V as tested under MIL-STD-883C, Method 3015.2; however, care should be exercised in handling these devices as exposure to ESD may result in degradation of the device parametric performance.

The C-suffix devices are characterized for operation from 0°C to 70°C. The I-suffix devices are characterized for operation from -40°C to 85°C. The Q-suffix devices are characterized for operation from -40°C to 125°C. The M-suffix devices are characterized for operation over the full military temperature range of -55°C to 125°C.

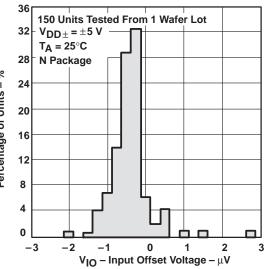
	AVAILABLE OPTIONS											
				PA	CKAGED DEVICES	3						
	Viomax		8 PIN			14 PIN		20 PIN	CHIP			
TA	AT 25°C	SMALL OUTLINE (D008)	CERAMIC DIP (JG)	PLASTIC DIP (P)	SMALL OUTLINE (D014)	CERAMIC DIP (J)	PLASTIC DIP (N)	CHIP CARRIER (FK)	FORM (Y)			
0°C to 70°C	1 μV 3 μV	TLC2652AC-8D TLC2652C-8D		TLC2652ACP TLC2652CP	TLC2652AC-14D TLC2652C-14D	 	TLC2652ACN TLC2652CN		TLC2652Y			
-40°C to 85°C	1 μV 3 μV	TLC2652AI-8D TLC2652A-8D		TLC2652AIP TLC2652IP	TLC2652AI-14D TLC2652I-14D		TLC2652AIN TLC2652IN		_			
-40°C to 125°C	3.5 μV	TLC2652Q-8D	_	_	—	—	—	—	_			
-55°C to 125°C	3 μV 3.5 μV	TLC2652AM-8D TLC2652M-8D	TLC2652AMJG TLC2652MJG	TLC2652AMP TLC2652MP	TLC2652AM-14D TLC2652M-14D	TLC2652AMJ TLC2652MJ	TLC2652AMN TLC2652MN	TLC2652AMFK TLC2652MFK	_			

The D008 and D014 packages are available taped and reeled. Add R suffix to the device type (e.g., TLC2652AC-8DR). Chips are tested at 25°C.

functional block diagram



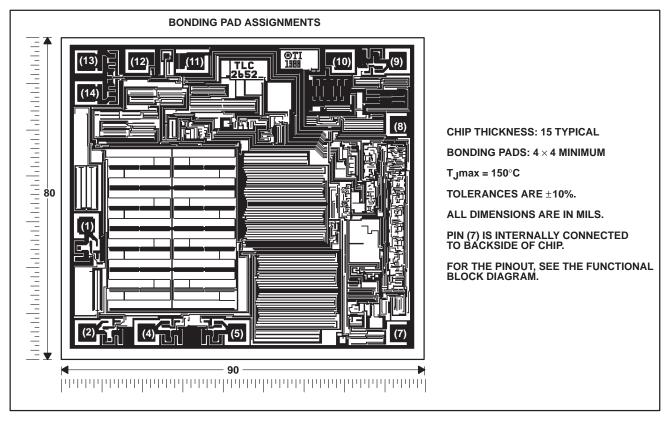
DISTRIBUTION OF TLC2652 INPUT OFFSET VOLTAGE





TLC2652Y chip information

This chip, when properly assembled, displays characteristics similar to the TLC2652C. Thermal compression or ultrasonic bonding may be used on the doped-aluminum bonding pads. Chips may be mounted with conductive epoxy or a gold-silicon preform.





absolute maximum ratings over operating free-air temperature range (unless otherwise noted)[‡]

Supply voltage V_{DD+} (see Note 1)8 VSupply voltage V_{DD-} (see Note 1)-8 VDifferential input voltage, V_{ID} (see Note 2)±16 VInput voltage, V_{I} (any input, see Note 1)±8 VVoltage range on CLK IN and INT/EXT $V_{DD} - \text{to } V_{DD-} + 5.2 V$ Input current, I_{I} (each input)±5 mAOutput current, I_{O} ±50 mADuration of short-circuit current at (or below)25 °C (see Note 3)Current into CLK IN and INT/EXT±5 mAContinuous total dissipationSee Dissipation Rating TableOperating free-air temperature range, T_A : C suffix-40°C to 85°CQ suffix-40°C to 125°CStorage temperature range-65°C to 150°CCase temperature for 60 seconds: FK package260°CLead temperature 1,6 mm (1/16 inch) from case for 10 seconds: D, N, or P package260°CLead temperature 1,6 mm (1/16 inch) from case for 60 seconds: J or JG package300°C

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. All voltage values, except differential voltages, are with respect to the midpoint between VDD+ and VDD-.

2. Differential voltages are at IN+ with respect to IN-.

3. The output may be shorted to either supply. Temperature and/or supply voltages must be limited to ensure that the maximum dissipation rating is not exceeded.

	DISSIPATION RATING TABLE										
PACKAGE	$T_A \le 25^{\circ}C$ POWER RATING	DERATING FACTOR ABOVE T _A = 25°C	T _A = 70°C POWER RATING	T _A = 85°C POWER RATING	T _A = 125°C POWER RATING						
D008	725 mV	5.8 mW/°C	464 mW	377 mW	145 mW						
D014	950 mV	7.6 mW/°C	608 mW	494 mW	190 mW						
FK	1375 mV	11.0 mW/°C	880 mW	715 mW	275 mW						
J	1375 mV	11.0 mW/°C	880 mW	715 mW	275 mW						
JG	1050 mV	8.4 mW/°C	672 mW	546 mW	210 mW						
N	1575 mV	12.6 mW/°C	1008 mW	819 mW	315 mW						
Р	1000 mV	8.0 mW/°C	640 mW	520 mW	200 mW						

recommended operating conditions

	CS	SUFFIX	15	SUFFIX	Q	SUFFIX	M SUFFIX		UNIT	
	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	UNIT	
Supply voltage, $V_{DD\pm}$	±1.9	±8	±1.9	±8	±1.9	±8	±1.9	±8	V	
Common-mode input voltage, V_{IC}	V _{DD} -	V _{DD+} -1.9	V							
Clock input voltage	V _{DD-}	V _{DD-} +5	V _{DD-}	V _{DD-} +5	V _{DD} -	V _{DD-} +5	V _{DD} -	V _{DD-} +5	V	
Operating free-air temperature, T_A	0	70	-40	85	-40	125	-55	125	°C	



TLC2652C TLC2652AC PARAMETER **TEST CONDITIONS** T_A† UNIT MIN TYP MAX MIN TYP MAX 25°C 0.6 3 0.5 1 VIO Input offset voltage μV 4.35 2.35 Full range Temperature coefficient of 0.03 μV/°C Full range 0.003 0.003 0.03 ανιο input offset voltage Input offset voltage long-term $R_S = 50 \Omega$ 25°C 0.003 0.06 0.003 0.02 μV/mo $V_{IC} = 0,$ drift (see Note 4) 25°C 2 2 Input offset current pА 10 Full range 100 100 25°C 4 4 pА Input bias current IΒ Full range 100 100 -5 -5 Common-mode input voltage $R_S = 50 \Omega$ V VICR Full range to to range 3.1 3.1 25°C 4.7 4.8 4.7 4.8 Maximum positive peak See Note 5 V VOM+ $R_L = 10 \text{ k}\Omega$, output voltage swing Full range 4.7 4.7 25°C -4.7 -4.9 -4.7 -4.9 Maximum negative peak VOM- $R_L = 10 \text{ k}\Omega$, See Note 5 V output voltage swing Full range -4.7 -4.7 25°C 120 150 150 135 Large-signal differential $V_{O} = \pm 4 V,$ AVD $R_L = 10 \ k\Omega$ dB voltage amplification Full range 120 130 Internal chopping frequency 25°C 450 450 fch Hz 25°C 25 25 Clamp on-state current $R_L = 100 \text{ k}\Omega$ μΑ Full range 25 25 25°C 100 100 Clamp off-state current $V_{O} = -4 V \text{ to } 4 V$ pА 100 100 Full range $V_{O} = 0,$ 25°C 120 140 120 140 Common-mode rejection $V_{IC} = V_{ICR}$ min, R_S = 50 Ω CMRR dB ratio Full range 120 120 $V_{DD\pm} = \pm 1.9 V \text{ to } \pm 8 V,$ 120 25°C 135 120 135 Supply-voltage rejection ratio **k**SVR dB

electrical characteristics at specified free-air temperature, V_{DD} \pm = ±5 V (unless otherwise noted)

[†] Full range is 0° to 70°C.

IDD

 $(\Delta V_{DD\pm}/\Delta V_{IO})$

Supply current

NOTES: 4. Typical values are based on the input offset voltage shift observed through 168 hours of operating life test at T_A = 150°C extrapolated at T_A = 25° using the Arrhenius equation and assuming an activation energy of 0.96 eV.

Full range

25°C

Full range

 $R_S = 50 \Omega$

120

1.5

2.4

2.5

120

1.5

2.4

2.5

mΑ

5. Output clamp is not connected.

 $V_{O} = 0,$



operating characteristics specified free-air temperature, $V_{DD\pm} = \pm 5 V$

-	•		-		_					
	DADAMETED	TEST	- +	TLC2652C			TL	C2652A	С	
	PARAMETER		T _A †	MIN TY		MAX	MIN	TYP	MAX	UNIT
SR+			25°C	2	2.8		2	2.8		
5K+	Positive slew rate at unity gain	$V_0 = \pm 2.3 V,$	Full range	1.5			1.5			V/μs
0.0		$R_L = 10 k\Omega,$ C _L = 100 pF	25°C	2.3	3.1		2.3	3.1		Mar
SR-	Negative slew rate at unity gain		Full range	1.8			1.8			V/μs
V	Equivalent input noise voltage	f = 10 Hz	25°C		94			94	140	140 35 nV/√Hz
Vn	(see Note 6)	f = 1 kHz	25°C		23			23	35	
	Peak-to-peak equivalent input	f = 0 to 1 Hz	25°C		0.8			0.8		
V _{N(PP)}	noise voltage	f = 0 to 10 Hz	25°C		2.8			2.8		μV
I _n	Equivalent input noise current	f = 10 kHz	25°C		0.004			0.004		fA/√Hz
	Gain-bandwidth product	f = 10 kHz, R _L = 10 kΩ, C _L = 100 pF	25°C		1.9			1.9		MHz
φm	Phase margin at unity gain	R _L = 10 kΩ, C _L = 100 pF	25°C		48°			48°		

[†]Full range is 0° to 70°C.

NOTE 6: This parameter is tested on a sample basis for the TLC2652A. For other test requirements, please contact the factory. This statement has no bearing on testing or nontesting of other parameters.



electrical characteristics at specified free-air temperature, $V_{DD} \pm = \pm 5 V$ (unless otherwise noted)

		TEAL		- +	1	TLC2652I		Т	_C2652A	J	
	PARAMETER		NDITIONS	T _A †	MIN	TYP	MAX	MIN	TYP	MAX	UNIT
V/- a				25°C		0.6	3		0.5	1	
VIO	Input offset voltage			Full range			4.95			2.95	μV
αΛΙΟ	Temperature coefficient of input offset voltage			Full range		0.003	0.03		0.003	0.03	μV/°C
	Input offset voltage long-term drift (see Note 4)	V _{IC} = 0,	R _S = 50 Ω	25°C		0.003	0.06		0.003	0.02	μV/mo
lio	Input offset current]		25°C		2			2		pА
IO	input onset current			Full range			150			150	рА
IВ	Input bias current			25°C		4			4		pА
IB	input bias current			Full range			150			150	рл
VICR	Common-mode input voltage range	R _S = 50 Ω		Full range	-5 to 3.1			-5 to 3.1			V
Vari	Maximum positive peak	$P_{\rm i} = 10 \rm kO$	See Note 5	25°C	4.7	4.8		4.7	4.8		v
VOM+	output voltage swing	$K_{L} = 10 K_{22},$	See Note 5	Full range	4.7			4.7			v
Vom-	Maximum negative peak	$P_1 = 10 kO$	See Note 5	25°C	-4.7	-4.9		-4.7	-4.9		v
VOM−	output voltage swing	INC - 10 K32,	See Note 5	Full range	-4.7			-4.7			v
AVD	Large-signal differential	$V_{0} = \pm 4 V$	RL = 10 kΩ	25°C	120	150		135	150		dB
AVD	voltage amplification	v0 = ± + v,	NL = 10 K32	Full range	120			125			ub
	Internal chopping frequency			25°C		450			450		Hz
	Clamp on-state current	R _I = 100 kΩ		25°C	25			25			μA
	Clamp on-state current	111 = 100 K22		Full range	25			25			μΑ
	Clamp off-state current	$V_{O} = -4 V t_{O}$	n 4 V	25°C			100			100	pА
		10- 10	0 + 0	Full range			100			100	P/1
CMRR	Common-mode rejection	$V_{O} = 0,$		25°C	120	140		120	140		귀머
CIVIER	ratio	$V_{IC} = V_{ICR}n$ R _S = 50 Ω	1in,	Full range	120			120			dB
k SVR	Supply-voltage rejection	$V_{DD\pm} = \pm 1.9$	9 V to ±8 V,	25°C	120	135		120	135	135	dB
"SVK	ratio ($\Delta V_{DD\pm}/\Delta V_{IO}$)	V _O = 0,	$R_S = 50 \Omega$	Full range	120			120			gR
DD	Supply current	$V_{O} = 0,$	No load	25°C		1.5	2.4		1.5	2.4	mA
עטי	Supply current	¹ ⁰ ^{- 0} ,	NO IOAU	Full range			2.5			2.5	

[†]Full range is –40° to 85°C.

NOTES: 4. Typical values are based on the input offset voltage shift observed through 168 hours of operating life test at $T_A = 150^{\circ}C$ extrapolated at $T_A = 25^{\circ}$ using the Arrhenius equation and assuming an activation energy of 0.96 eV.

5. Output clamp is not connected.



operating characteristics at specified free-air temperature, V_{DD±} = ± 5 V

-	•		-		_					
	DADAMETED	TEST	- +	TLC2652I			TL	C2652A	N.	
PARAMETER		CONDITIONS	T _A †	MIN	TYP	MAX	MIN	TYP	MAX	UNIT
<u>ер.</u>			25°C	2	2.8		2	2.8		Mue
SR+	Positive slew rate at unity gain	$V_0 = \pm 2.3 V,$	Full range	1.4			1.4			V/μs
SR-	Negative slew rate at unity gain	R _L = 10 kΩ, C _L = 100 pF	25°C	2.3	3.1		2.3	3.1		Mue
5K-	- regaine siew rate at unity gain		Full range	1.7			1.7			V/μs
V	Equivalent input noise voltage	f = 10 Hz	25°C		94			94	140	140 35 nV/√Hz
Vn	(see Note 6)	f = 1 kHz	25°C		23			23	35	
	Peak-to-peak equivalent input	f = 0 to 1 Hz	25°C		0.8			0.8		
VN(PP)	noise voltage	f = 0 to 10 Hz	25°C		2.8			2.8		μV
I _n	Equivalent input noise current	f = 1 kHz	25°C		0.004			0.004		pA/√Hz
	Gain-bandwidth product	f = 10 kHz, R _L = 10 kΩ, C _L = 100 pF	25°C		1.9			1.9		MHz
φm	Phase margin at unity gain	R _L = 10 kΩ, C _L = 100 pF	25°C		48°			48°		

[†]Full range is −40° to 85°C.

NOTE 6: This parameter is tested on a sample basis for the TLC2652A. For other test requirements, please contact the factory. This statement has no bearing on testing or nontesting of other parameters.



TLC2652Q TLC2652AM T_A† **TLC2652M** PARAMETER **TEST CONDITIONS** UNIT MAX MIN TYP TYP MAX MIN 25°C 0.6 3.5 0.5 3 Input offset voltage Vio μV (see Note 7) 10 8 Full range Temperature coefficient of Full range 0.003 0.03* 0.003 0.03* μV/°C ανιο input offset voltage Input offset voltage 25°C 0.02* 0.003 0.06* 0.003 μV/mo $V_{IC} = 0,$ $R_S = 50 \Omega$ long-term drift (see Note 4) 25°C 2 2 Input offset current pА 10 500 Full range 500 25°C 4 4 IΒ Input bias current pА Full range 500 500 -5 -5 Common-mode input $R_S = 50 \Omega$ Full range V VICR to to voltage range 3.1 3.1 4.7 4.7 25°C 4.8 4.8 Maximum positive peak V VOM+ $R_I = 10 k\Omega$, See Note 5 output voltage swing Full range 4.7 4.7 25°C -4.7 -4.9 -4.7 -4.9Maximum negative peak $R_I = 10 k\Omega$, See Note 5 V VOMoutput voltage swing Full range -4.7 -4.7 25°C 120 150 135 150 Large-signal differential AVD $V_{O} = \pm 4 V$, $R_L = 10 \ k\Omega$ dB voltage amplification Full range 120 120 25°C 450 450 Internal chopping frequency Ηz fch 25°C 25 25 Clamp on-state current $V_0 = -5 V \text{ to } 5 V$ μΑ Full range 25 25 25°C 100 100 Clamp off-state current $R_I = 100 k\Omega$ pА 500 500 Full range $V_{O} = 0$, 25°C 120 140 120 140 Common-mode rejection CMRR VIC = VICRmin, dB ratio Full range $R_{S} = 50 \Omega$ 120 120 $V_{DD\pm} = \pm 1.9 \text{ V to } \pm 8 \text{ V},$ 25°C 120 135 120 135 Supply-voltage rejection dB **k**SVR ratio ($\Delta V_{DD\pm}/\Delta V_{IO}$) Full range 120 120 $V_{O} = 0$, $R_S = 50 \Omega$ 25°C 1.5 2.4 1.5 2.4 IDD Supply current $V_{O} = 0$, No load mΑ Full range 2.5 2.5

electrical characteristics at specified free-air temperature, V_{DD} \pm = ±5 V (unless otherwise noted)

* On products compliant to MIL-PRF-38535, this parameter is not production tested.

[†] Full range is -40° to 125°C for Q suffix, -55° to 125°C for M suffix.

NOTES: 4. Typical values are based on the input offset voltage shift observed through 168 hours of operating life test at $T_A = 150^{\circ}C$ extrapolated at $T_A = 25^{\circ}$ using the Arrhenius equation and assuming an activation energy of 0.96 eV.

5. Output clamp is not connected.

 This parameter is not production tested. Thermocouple effects preclude measurement of the actual V_{IO} of these devices in high speed automated testing. V_{IO} is measured to a limit determined by the test equipment capability at the temperature extremes. The test ensures that the stabilization circuitry is performing properly.



operating characteristics specified free-air temperature, V_{DD±} = ± 5 V

	PARAMETER	TEST CONDITIONS	τ _A †	TLC2652Q TLC2652M TLC2652AM			UNIT
				MIN	TYP	MAX	
SR+	Positive slew rate at unity gain		25°C	2	2.8		V/µs
SKT	Positive siew fate at unity gain	$V_0 = \pm 2.3 V$,	Full range	1.3			v/µs
SR-	Negative slew rate at unity gain	R _L = 10 kΩ, C _L = 100 pF	25°C	2.3	3.1		V/µs
31-	Negative siew rate at unity gain	-	Full range	1.6			v/µS
V	Equivalant input poise voltage	f = 10 Hz	25°C		94		nV/√Hz
Vn	Equivalent input noise voltage	f = 1 kHz	25°C		23		
VNUDD	Peak-to-peak equivalent input noise voltage	f = 0 to 1 Hz	25°C		0.8		μV
V _{N(PP)}	reak-to-peak equivalent input hoise voltage	f = 0 to 10 Hz	25°C		2.8		μv
In	Equivalent input noise current	f = 1 kHz	25°C		0.004		pA/√Hz
	Gain-bandwidth product	f = 10 kHz, R _L = 10 kΩ, C _L = 100 pF	25°C		1.9		MHz
[¢] m	Phase margin at unity gain	R _L = 10 kΩ, C _L = 100 pF	25°C		48°		

 † Full range is -40° to 125°C for the Q suffix, -55° to 125°C for the M suffix.



electrical characteristics at V_DD \pm = ±5 V, T_A = 25°C (unless otherwise noted)

				т	LC2652	Y		
	PARAMETER	TEST C	ONDITIONS	MIN	TYP	MAX	UNIT	
VIO	Input offset voltage				0.6	3	μV	
10	Input offset voltage long-term drift (see Note 4)		-		0.003	0.006	μV/mo	
IIO	Input offset current	$V_{IC} = 0,$	$R_S = 50 \Omega$		2		pА	
IIB	Input bias current				4		pА	
VICR	Common-mode input voltage range	R _S = 50 Ω		-5 to 3.1			V	
VOM+	Maximum positive peak output voltage swing	R _L = 10 kΩ,	See Note 5	4.7	4.8		V	
VOM-	Maximum negative peak output voltage swing	R _L = 10 kΩ,	See Note 5	-4.7	-4.9		V	
AVD	Large-signal differential voltage amplification	$V_{O} = \pm 4 V$,	RL = 10 kΩ	120	150		dB	
f _{ch}	Internal chopping frequency				450		Hz	
	Clamp on-state current	RL = 100 kΩ		25			μΑ	
	Clamp off-state current	$V_{O} = -4 V to$	4 V			100	pА	
CMRR	Common-mode rejection ratio	$V_{O} = 0,$ R _S = 50 Ω	$V_{IC} = V_{ICR}min$,	120	140		dB	
k _{SVR}	Supply-voltage rejection ratio ($\Delta V_{DD\pm}/\Delta V_{IO}$)	$V_{DD\pm} = \pm 1.9$ R _S = 50 Ω	V to ± 8 V, V _O = 0,	120	135		dB	
IDD	Supply current	V _O = 0,	No load		1.5	2.4	mA	

NOTES: 4. Typical values are based on the input offset voltage shift observed through 168 hours of operating life test at $T_A = 150^{\circ}C$ extrapolated at $T_A = 25^{\circ}$ using the Arrhenius equation and assuming an activation energy of 0.96 eV.

5. Output clamp is not connected.

operating characteristics at V_{DD\pm} = ±5 V, T_A = 25°C

	PARAMETER	TEST CONDITIONS	Т	TLC2652Y			
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
SR+	Positive slew rate at unity gain	$V_{O} = \pm 2.3 \text{ V}, R_{L} = 10 \text{ k}\Omega,$	2	2.8		V/µs	
SR-	Negative slew rate at unity gain	C _L = 100 pF	2.3	3.1		V/µs	
V	Equivalent input noise voltage	f = 10 Hz		94			
Vn	vn	Equivalent input noise voltage	f = 1 kHz		23		nV/√Hz
Variation	Pook to pook aquivalant input poice valtage	f = 0 to 1 Hz		0.8			
VN(PP)	Peak-to-peak equivalent input noise voltage	f = 0 to 10 Hz		2.8		μV	
In	Equivalent input noise current	f = 1 kHz				pA/√Hz	
	Gain-bandwidth product	$ f = 10 \text{ kHz}, \qquad R_L = 10 \text{ k}\Omega, \\ C_L = 100 \text{ pF} $		1.9		MHz	
[¢] m	Phase margin at unity gain	$R_L = 10 \text{ k}\Omega$, $C_L = 100 \text{ pF}$		48°			



Phase margin

Phase shift

φm

TYPICAL CHARACTERISTICS

FIGURE Vio Normalized input offset voltage vs Chopping frequency 1 2 vs Common-mode input voltage IΒ Input bias current vs Chopping frequency 3 vs Free-air temperature 4 vs Chopping frequency 5 Input offset current 10 vs Free-air temperature 6 7 Clamp current vs Output voltage V(OPP) Maximum peak-to-peak output voltage vs Frequency 8 vs Output current 9, 10 Vом Maximum peak output voltage vs Free-air temperature 11, 12 13 vs Frequency Large-signal differential voltage amplification AVD vs Free-air temperature 14 vs Supply voltage 15 Chopping frequency vs Free-air temperature 16 vs Supply voltage 17 Supply current IDD vs Free-air temperature 18 19 vs Supply voltage Short-circuit output current los vs Free-air temperature 20 21 vs Supply voltage SR Slew rate vs Free-air temperature 22 23 Small-signal Pulse response Large-signal 24 vs Chopping frequency Peak-to-peak equivalent input noise voltage 25, 26 VN(PP) ٧n Equivalent input noise voltage vs Frequency 27 vs Supply voltage 28 Gain-bandwidth product vs Free-air temperature 29

vs Supply voltage

vs Frequency

vs Free-air temperature

vs Load capacitance

30

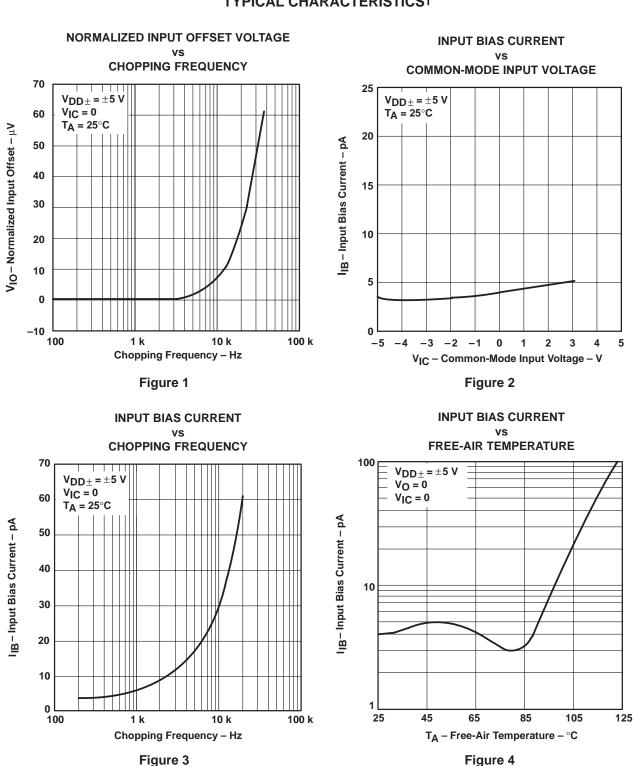
31

32

13

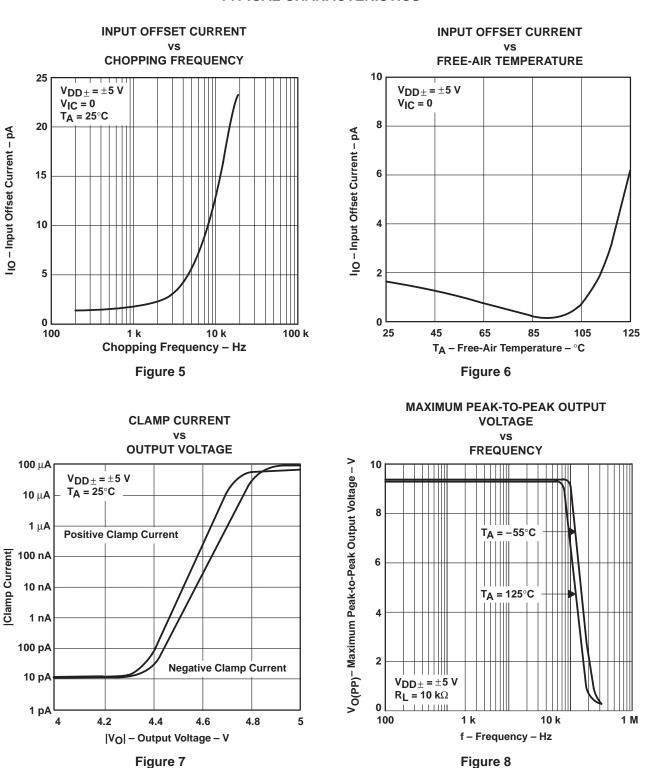
Table of Graphs





TYPICAL CHARACTERISTICS[†]





TYPICAL CHARACTERISTICS[†]

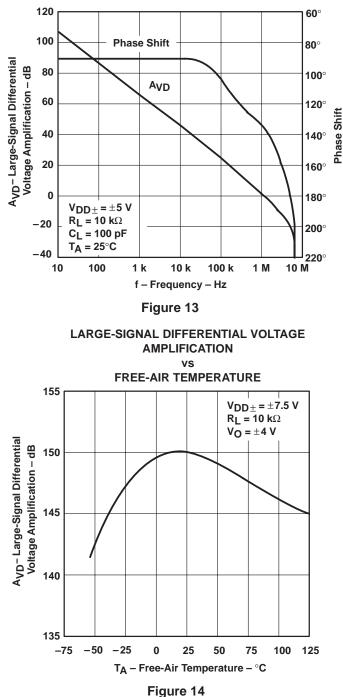


MAXIMUM PEAK OUTPUT VOLTAGE MAXIMUM PEAK OUTPUT VOLTAGE vs vs **OUTPUT CURRENT OUTPUT CURRENT** 5 7.5 V_{DD±} = ±5 V T_A = 25°C $V_{DD\pm} = \pm 7.5 V$ |V_{OM}| – Maximum Peak Output Voltage – V |V_{OM}| – Maximum Peak Output Voltage – V T_A = 25°C 4.8 7.3 VOM+ VOM-VOM-VOM+ 4.6 7.1 4.4 6.9 4.2 4 6.7 0 0.4 0.8 1.2 1.6 2 0 0.4 0.8 1.2 2 1.6 IO - Output Current - mA IO - Output Current - mA Figure 9 Figure 10 MAXIMUM PEAK OUTPUT VOLTAGE MAXIMUM PEAK OUTPUT VOLTAGE vs vs FREE-AIR TEMPERATURE FREE-AIR TEMPERATURE 5 8 V_{OM} – Maximum Peak Output Voltage – V V_{OM} – Maximum Peak Output Voltage – V 2.5 4 $V_{DD\pm} = \pm 5 V$ $V_{DD\pm} = \pm 7.5 V$ $R_L = 10 k\Omega$ $R_L = 10 k\Omega$ 0 0 -2.5 -5 -8 -75 -50 -25 25 50 75 100 125 0 -75 -50 -25 0 25 50 75 100 125 T_A – Free-Air Temperature – °C T_A – Free-Air Temperature – °C Figure 11 Figure 12

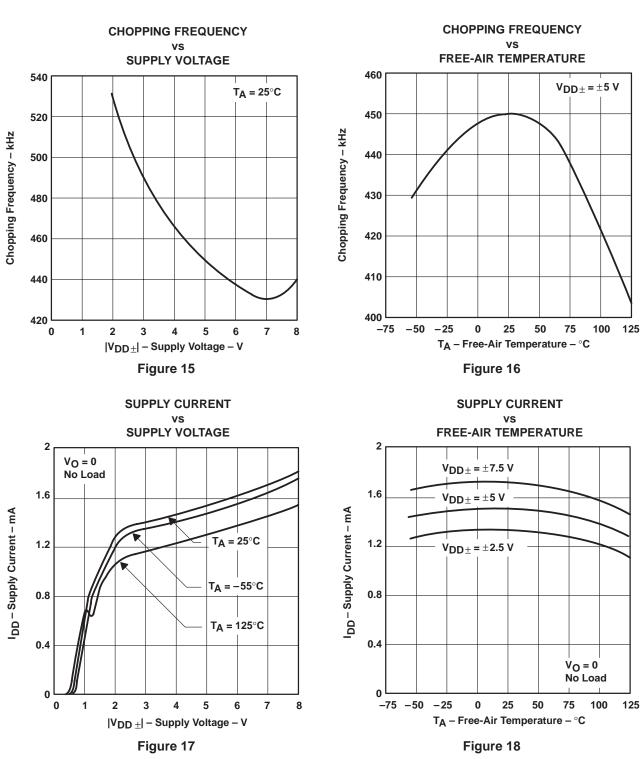
TYPICAL CHARACTERISTICS[†]



TYPICAL CHARACTERISTICS[†] LARGE-SIGNAL DIFFERENTIAL VOLTAGE AMPLIFICATION AND PHASE SHIFT VS FREQUENCY

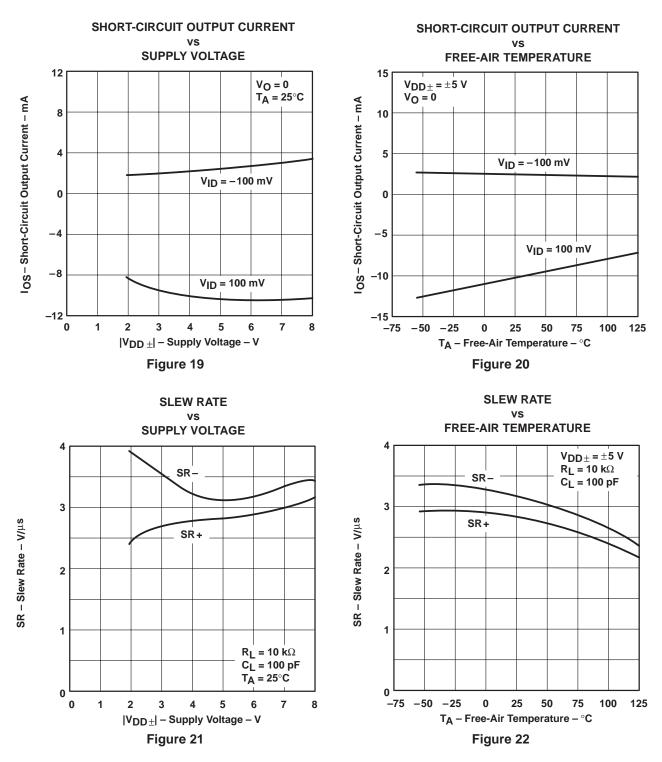






TYPICAL CHARACTERISTICS[†]

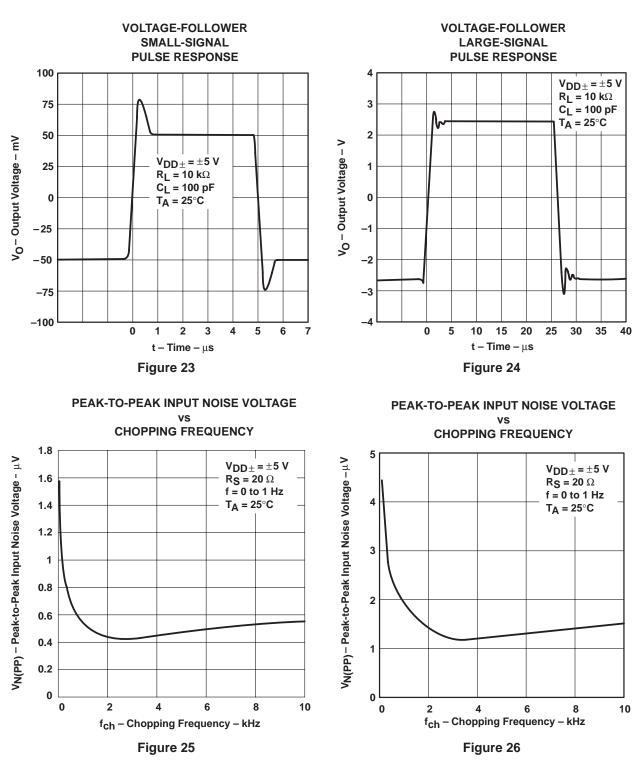




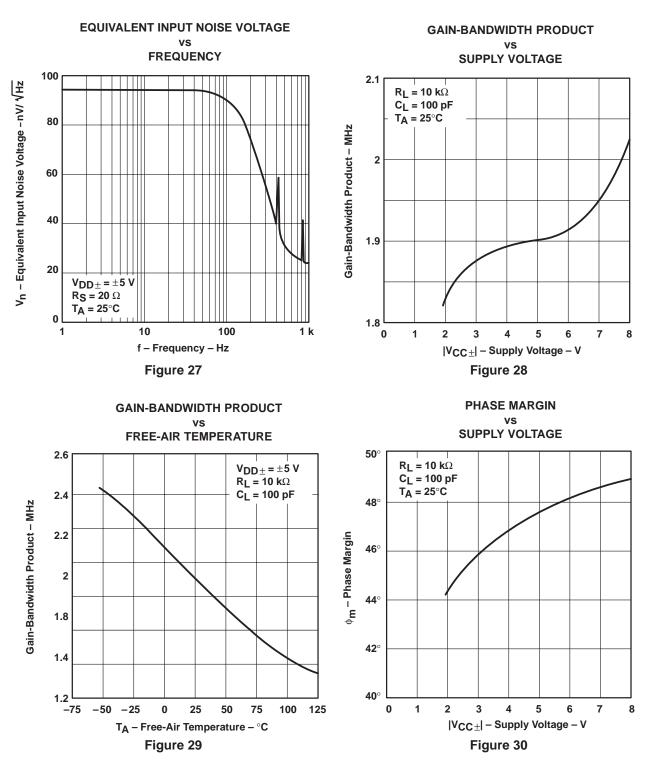
TYPICAL CHARACTERISTICS[†]



TYPICAL CHARACTERISTICS

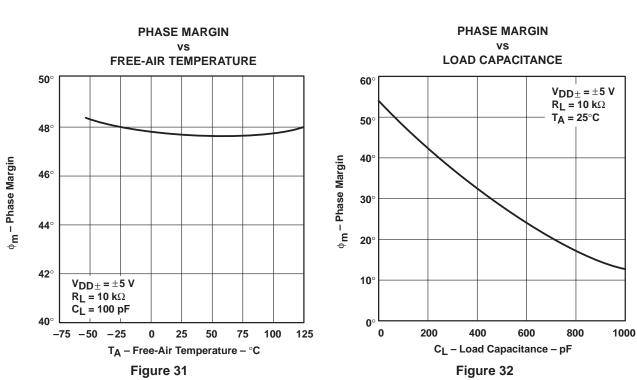






TYPICAL CHARACTERISTICS[†]





TYPICAL CHARACTERISTICS[†]

[†]Data at high and low temperatures are applicable only within the rated operating free-air temperature ranges of the various devices.

APPLICATION INFORMATION

capacitor selection and placement

The two important factors to consider when selecting external capacitors C_{XA} and C_{XB} are leakage and dielectric absorption. Both factors can cause system degradation, negating the performance advantages realized by using the TLC2652.

Degradation from capacitor leakage becomes more apparent with the increasing temperatures. Low-leakage capacitors and standoffs are recommended for operation at $T_A = 125$ °C. In addition, guard bands are recommended around the capacitor connections on both sides of the printed circuit board to alleviate problems caused by surface leakage on circuit boards.

Capacitors with high dielectric absorption tend to take several seconds to settle upon application of power, which directly affects input offset voltage. In applications where fast settling of input offset voltage is needed, it is recommended that high-quality film capacitors, such as mylar, polystyrene, or polypropylene, be used. In other applications, however, a ceramic or other low-grade capacitor can suffice.

Unlike many choppers available today, the TLC2652 is designed to function with values of C_{XA} and C_{XB} in the range of 0.1 μ F to 1 μ F without degradation to input offset voltage or input noise voltage. These capacitors should be located as close as possible to the C_{XA} and C_{XB} pins and returned to either V_{DD-} or C RETURN. On many choppers, connecting these capacitors to V_{DD-} causes degradation in noise performance. This problem is eliminated on the TLC2652.



TLC2652, TLC2652A, TLC2652Y Advanced LinCMOS[™] PRECISION CHOPPER-STABILIZED OPERATIONAL AMPLIFIERS

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APPLICATION INFORMATION

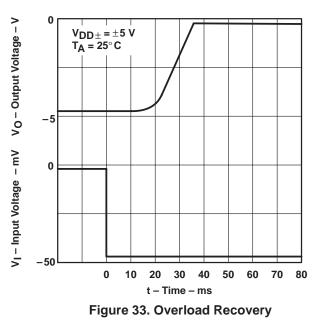
internal/external clock

The TLC2652 has an internal clock that sets the chopping frequency to a nominal value of 450 Hz. On 8-pin packages, the chopping frequency can only be controlled by the internal clock; however, on all 14-pin packages and the 20-pin FK package, the device chopping frequency can be set by the internal clock or controlled externally by use of the INT/EXT and CLK IN pins. To use the internal 450-Hz clock, no connection is necessary. If external clocking is desired, connect INT/EXT to V_{DD-} and the external clock to CLK IN. The external clock trip point is 2.5 V above the negative rail; however, CLK IN can be driven from the negative rail to 5 V above the negative rail. If this level is exceeded, damage could occur to the device unless the current into CLK IN is limited to ± 5 mA. When operating in the single-supply configuration, this feature allows the TLC2652 to be driven

directly by 5-V TTL and CMOS logic. A divide-by-two frequency divider interfaces with CLK IN and sets the clock chopping frequency. The duty cycle of the external is not critical but should be kept between 30% and 60%.

overload recovery/output clamp

When large differential input voltage conditions are applied to the TLC2652, the nulling loop attempts to prevent the output from saturating by driving C_{XA} and C_{XB} to internally-clamped voltage levels. Once the overdrive condition is removed, a period of time is required to allow the built-up charge to dissipate. This time period is defined as overload recovery time (see Figure 33). Typical overload recovery time for the TLC2652 is significantly faster than competitive products; however, if required, this time can be reduced further by use of internal clamp circuitry accessible through CLAMP if required.



The clamp is a switch that is automatically activated when the output is approximately 1 V from either supply rail. When connected to the inverting input (in parallel with the closed-loop feedback resistor), the closed-loop gain is reduced, and the TLC2652 output is prevented from going into saturation. Since the output must source sink current through the switch (see Figure 7), the maximum output voltage swing is slightly reduced.

thermoelectric effects

To take advantage of the extremely low offset voltage drift of the TLC2652, care must be taken to compensate for the thermoelectric effects present when two dissimilar metals are brought into contact with each other (such as device leads being soldered to a printed circuit board). Dissimilar metal junctions can produce thermoelectric voltages in the range of several microvolts per degree Celsius (orders of magnitude greater than the 0.01- μ V/°C typical of the TLC2652).

To help minimize thermoelectric effects, careful attention should be paid to component selection and circuit-board layout. Avoid the use of nonsoldered connections (such as sockets, relays, switches, etc.) in the input signal path. Cancel thermoelectric effects by duplicating the number of components and junctions in each device input. The use of low-thermoelectric-coefficient components, such as wire-wound resistors, is also beneficial.



APPLICATION INFORMATION

latch-up avoidance

Because CMOS devices are susceptible to latch-up due to their inherent parasitic thyristors, the TLC2652 inputs and output are designed to withstand – 100-mA surge currents without sustaining latch-up; however, techniques to reduce the chance of latch-up should be used whenever possible. Internal protection diodes should not, by design, be forward biased. Applied input and output voltages should not exceed the supply voltage by more than 300 mV. Care should be exercised when using capacitive coupling on pulse generators. Supply transients should be shunted by the use of decoupling capacitors (0.1 μ F typical) located across the supply rails as close to the device as possible.

The current path established if latch-up occurs is usually between the supply rails and is limited only by the impedance of the power supply and the forward resistance of the parasitic thyristor. The chance of latch-up occurring increases with increasing temperature and supply voltage.

electrostatic discharge protection

The TLC2652 incorporates internal ESD-protection circuits that prevent functional failures at voltages at or below 2000 V. Care should be exercised in handling these devices, as exposure to ESD may result in degradation of the device parametric performance.

theory of operation

Chopper-stabilized operational amplifiers offer the best dc performance of any monolithic operational amplifier. This superior performance is the result of using two operational amplifiers, a main amplifier and a nulling amplifier, plus oscillator-controlled logic and two external capacitors to create a system that behaves as a single amplifier. With this approach, the TLC2652 achieves submicrovolt input offset voltage, submicrovolt noise voltage, and offset voltage variations with temperature in the nV/°C range.

The TLC2652 on-chip control logic produces two dominant clock phases: a nulling phase and an amplifying phase. The term chopper-stabilized derives from the process of switching between these two clock phases. Figure 34 shows a simplified block diagram of the TLC2652. Switches A and B are make-before-break types.

During the nulling phase, switch A is closed shorting the nulling amplifier inputs together and allowing the nulling amplifier to reduce its own input offset voltage by feeding its output signal back to an inverting input node. Simultaneously, external capacitor C_{XA} stores the nulling potential to allow the offset voltage of the amplifier to remain nulled during the amplifying phase.

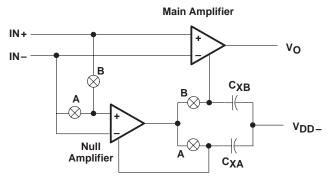


Figure 34. TLC2652 Simplified Block Diagram



TLC2652, TLC2652A, TLC2652Y Advanced LinCMOS[™] PRECISION CHOPPER-STABILIZED OPERATIONAL AMPLIFIERS

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APPLICATION INFORMATION

theory of operation (continued)

During the amplifying phase, switch B is closed connecting the output of the nulling amplifier to a noninverting input of the main amplifier. In this configuration, the input offset voltage of the main amplifier is nulled. Also, external capacitor C_{XB} stores the nulling potential to allow the offset voltage of the main amplifier to remain nulled during the next nulling phase.

This continuous chopping process allows offset voltage nulling during variations in time and temperature over the common-mode input voltage range and power supply range. In addition, because the low-frequency signal path is through both the null and main amplifiers, extremely high gain is achieved.

The low-frequency noise of a chopper amplifier depends on the magnitude of the component noise prior to chopping and the capability of the circuit to reduce this noise while chopping. The use of the Advanced LinCMOS process, with its low-noise analog MOS transistors and patent-pending input stage design, significantly reduces the input noise voltage.

The primary source of nonideal operation in chopper-stabilized amplifiers is error charge from the switches. As charge imbalance accumulates on critical nodes, input offset voltage can increase, especially with increasing chopping frequency. This problem has been significantly reduced in the TLC2652 by use of a patent-pending compensation circuit and the Advanced LinCMOS process.

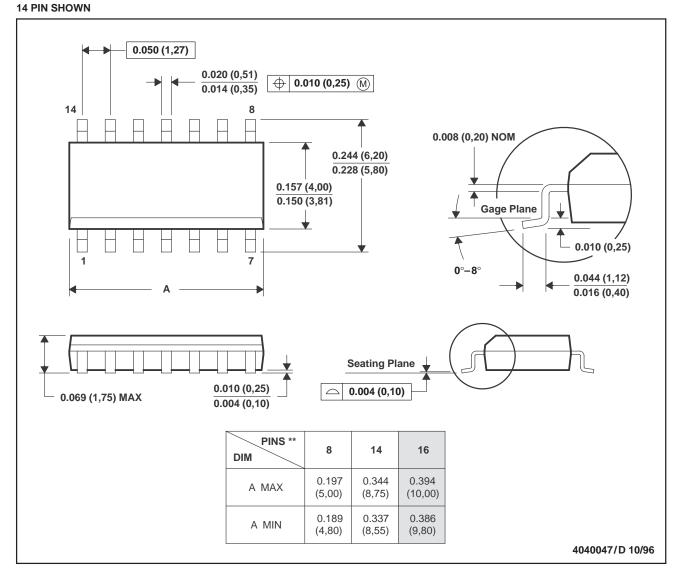
The TLC2652 incorporates a feed-forward design that ensures continuous frequency response. Essentially, the gain magnitude of the nulling amplifier and compensation network crosses unity at the break frequency of the main amplifier. As a result, the high-frequency response of the system is the same as the frequency response of the main amplifier. This approach also ensures that the slewing characteristics remain the same during both the nulling and amplifying phases.



MECHANICAL DATA

PLASTIC SMALL-OUTLINE PACKAGE

D (R-PDSO-G**)



NOTES: A. All linear dimensions are in inches (millimeters).

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).

D. Falls within JEDEC MS-012

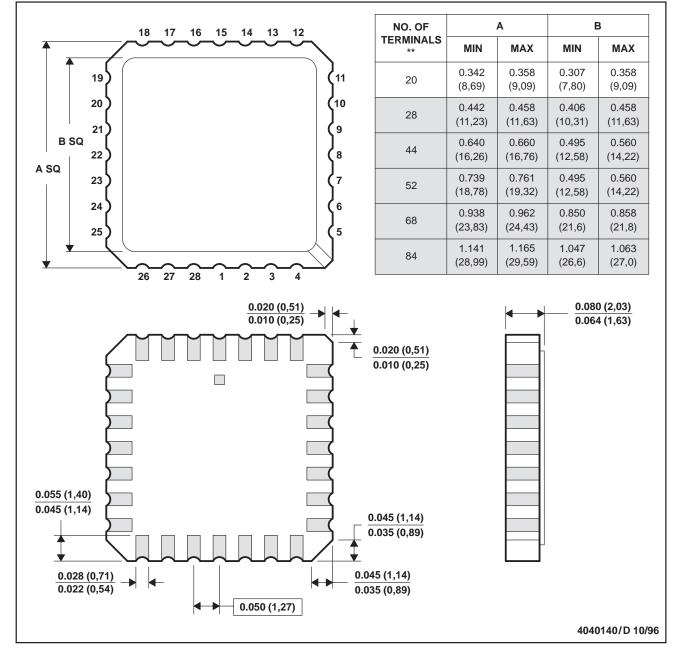


MECHANICAL DATA

FK (S-CQCC-N**)

LEADLESS CERAMIC CHIP CARRIER

28 TERMINAL SHOWN



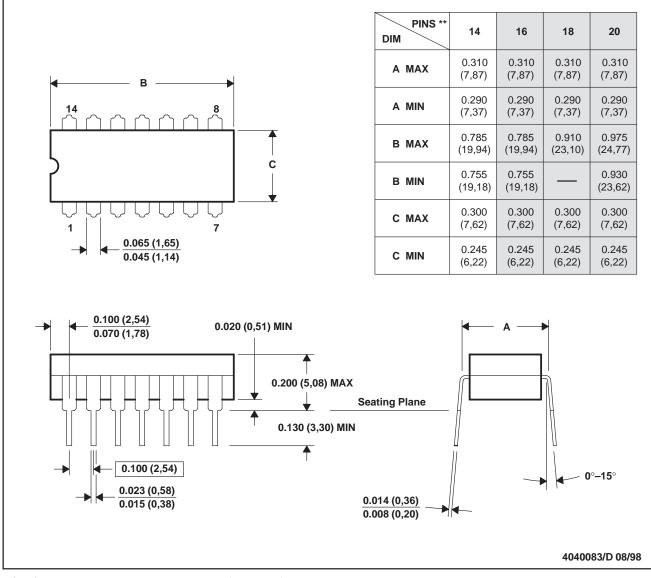
- B. This drawing is subject to change without notice.
- C. This package can be hermetically sealed with a metal lid.
- D. The terminals are gold plated.
- E. Falls within JEDEC MS-004



MECHANICAL DATA

CERAMIC DUAL-IN-LINE PACKAGE





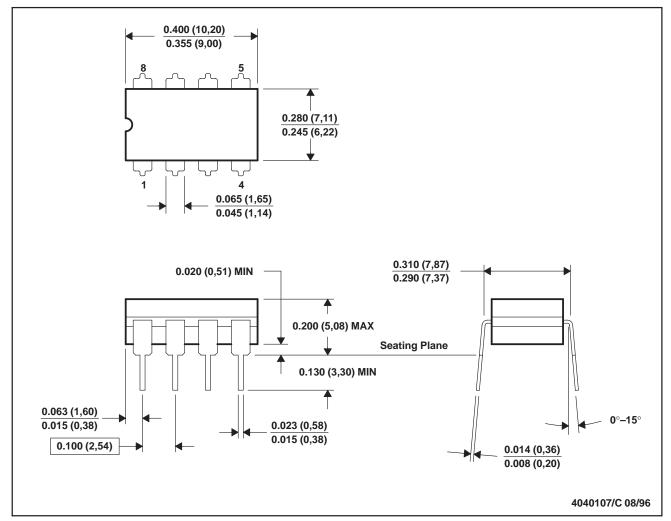
- B. This drawing is subject to change without notice.
- C. This package can be hermetically sealed with a ceramic lid using glass frit.
- D. Index point is provided on cap for terminal identification only on press ceramic glass frit seal only.
- E. Falls within MIL STD 1835 GDIP1-T14, GDIP1-T16, GDIP1-T18, GDIP1-T20, and GDIP1-T22.



MECHANICAL DATA

JG (R-GDIP-T8)

CERAMIC DUAL-IN-LINE PACKAGE



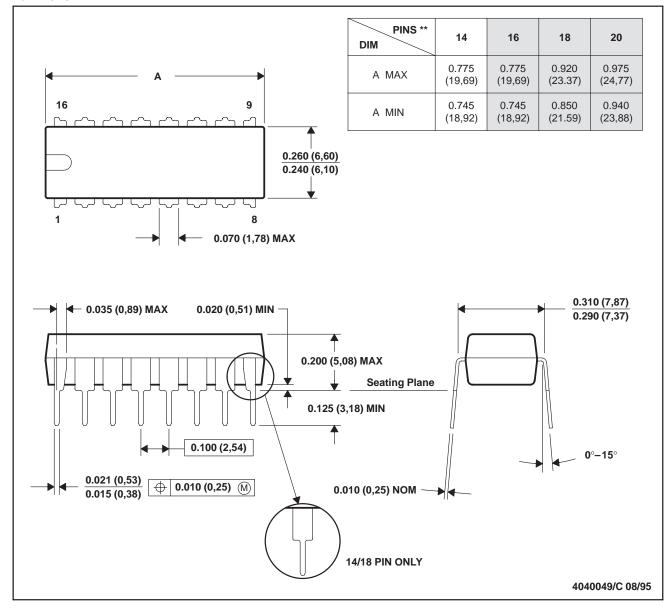
- B. This drawing is subject to change without notice.
- C. This package can be hermetically sealed with a ceramic lid using glass frit.
- D. Index point is provided on cap for terminal identification only on press ceramic glass frit seal only.
- E. Falls within MIL-STD-1835 GDIP1-T8



MECHANICAL DATA

PLASTIC DUAL-IN-LINE PACKAGE





NOTES: A. All linear dimensions are in inches (millimeters).

B. This drawing is subject to change without notice.

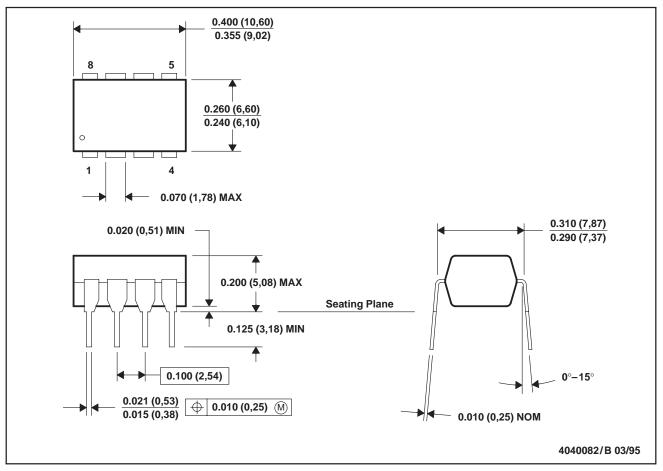
C. Falls within JEDEC MS-001 (20 pin package is shorter then MS-001.)



MECHANICAL DATA

P (R-PDIP-T8)

PLASTIC DUAL-IN-LINE PACKAGE



- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MS-001



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